Wuao Liu

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EDUCATION

University of Massachusetts Amherst

Ph.D. in Computer Science, advised by Prof. Grant Van Horn

University of Michigan, Ann Arbor

M.S. in Robotics, advised by Prof. Jason Corso

Aug. 2024 – Apr. 2029 (Expected)

Ann Arbor, MI

Aug. 2021 – Apr. 2023

Aug. 2021 – Apr. 2023

Hangzhou, China

B.Eng in Automation

Sept. 2017 – Jun. 2021

RESEARCH INTERESTS

Audio and Video Understanding; Large Language Models (LLMs); Machine Learning Applications on Robotics, Biodiversity and Conservation Problems.

EMPLOYMENT

Research Associate I at University of MichiganAnn Arbor, MIHost: Prof. Jason CorsoJul. 2023 – Apr. 2024Machine Learning Engineer Intern at Tencent AI LabShenzhen, ChinaHost: Dr. Peilin Zhao, Prof. Mingyang SunJul. 2021 – Aug. 2021

PUBLICATIONS

- 1. Liu, W., Li, Y., Qian, S., McConachie, D., Burchfiel, B., Corso, J. (2024). Enhancing Robotic Task Awareness through Progress Detection. Under Review for IROS.
- 2. Bellos, F., Li, Y., Liu, W., Corso, J. (2024). Can Large Language Models Reason about Goal-Oriented Tasks? In Proceedings of the EACL 2024, Workshop on the Scaling Behavior of Large Language Models.
- 3. Sun, M., Zhao, P., Liu, W. (2021). A Charging Scheduling Method, System, Equipment and Storage Medium. Chinese Patent CN202111203690.7.

RESEARCH EXPERIENCE

Learning Representations from Text and Visual Data in Augmented Reality

Ann Arbor, MI

Student Researcher | Advisor: Prof. Jason Corso

Sept. 2022 – Apr. 2024

- Developed an augmented reality (AR) assistant on a Microsoft HoloLens2 headset to guide users in performing complex, sequential tasks.
- Created an egocentric video dataset centered on human cooking activities, collected 242 videos following five distinct recipes, and annotated the videos with bounding boxes and temporal action boundaries.
- Implemented an object detection pipeline utilizing Faster-RCNN, achieving a mean Average Precision (mAP) of 93.696 on detecting 9 kitchen objects.
- Developed an advanced automatic speech recognition (ASR) pipeline based on OpenAI Whisper, enhancing user interaction and system accessibility.
- Pioneered research in zero-shot cooking step recognition by integrating LLMs such as GPT3.5-Turbo and LLaVa, pushing the boundaries of conventional methods.

Evaluation of LLMs on Goal-Oriented Tasks

Ann Arbor, MI

Summer Intern | Advisor: Prof. Jason Corso

May. 2023 – Aug. 2023

- Conducted a comprehensive study on the capabilities of LLMs, including GPT-3.5-Turbo, GPT-4, and LLaMa-2-13b, in understanding sequential actions and their ultimate goal.
- Designed prompt strategies such as zero-shot, few-shot, and two-stage hierarchical prompting. Proposed metrics to evaluate the accuracy of stepwise transition and task viability.
- Adapted instructional video datasets for evaluation by permuting the order of actions and conducted user study using MTurk.

Neural Radiance Field (NeRF) for Autonomous Driving

Summer Intern | Advisor: Prof. Katherine Skinner

Ann Arbor, MI May. 2022 – Aug. 2022

- Developed an open-source tool to collect RGB-D images in the CARLA simulator and visualize the corresponding camera poses for NeRF model training.
- Implemented a scene-specific NeRF and achieved a PSNR of 28.29 dB for novel view synthesis in urban autonomous driving scenarios.
- Gained hands-on experience with multi-camera calibration using the Kalibr toolbox and worked with various types of cameras, such as monochrome, event, RGB-D, and thermal cameras.

HONORS

CS Ph.D. Fellowship of University of Massachusetts Amherst	2024
 Outstanding Graduate Student (Top 1%), Zhejiang University 	2021
 Outstanding Undergraduate Thesis (4 / 152), Zhejiang University 	2021
 The ZJU-Chunzhen International Exchange Program Scholarship (\$5,000) 	2020
 Second-Class Scholarship for Academic Excellence (Top 10%), Zhejiang University 	2019
• Zhejiang Province Government Scholarship (Top 3%)	2018

SKILLS

- Programming Languages: Python, C++, C, MATLAB, LaTeX, SQL
- Tools: Linux, ROS, LCM, ZeroMQ, Git, Docker, Gazebo
- Packages: PyTorch, NumPy, OpenCV, CVXPY, PyBullet, GTSAM