Bayesian Learning Lecture 9 - HMC, Stan and Variational Inference (VI)

Bertil Wegmann

Department of Computer and Information Science Linköping University



Lecture overview

- Hamiltonian Monte Carlo
- Stan
- Variational Inference

Hamiltonian Monte Carlo

- When $\theta = (\theta_1, \dots, \theta_p)$ is **high-dimensional**, $p(\theta|y)$ usually located in some subregion of \mathbb{R}^p with complicated geometry.
- lacksquare MH: hard to find good proposal distribution $q\left(\cdot| heta^{(i-1)}
 ight)$.
- MH: use very small step sizes otherwise too many rejections.
- Hamiltonian Monte Carlo (HMC):
 - ▶ distant proposals and
 - high acceptance probabilities.
- HMC: add extra momentum parameters $\phi = (\phi_1, \dots, \phi_p)$ and sample from

$$p(\theta, \phi|y) = p(\theta|y) p(\phi)$$





Hamiltonian Monte Carlo

- Physics: Hamiltonian system $H(\theta, \phi) = U(\theta) + K(\phi)$, where U is the potential energy and K is the kinetic energy.
- Hamiltonian Dynamics

$$\frac{d\theta_{i}}{dt} = \frac{\partial H}{\partial \phi_{i}} = \frac{\partial K}{\partial \phi_{i}},$$
$$\frac{d\phi_{i}}{dt} = -\frac{\partial H}{\partial \theta_{i}} = -\frac{\partial U}{\partial \theta_{i}}$$

- Hockey puck sliding over a friction-less surface: illustration.
- Use $U(\theta) = -\log [p(\theta) p(y|\theta)]$.
- lacksquare Use $\phi \sim N\left(0,\mathsf{M}
 ight)$ where M is the mass matrix and

$$K\left(\phi
ight) = -\log\left[p\left(\phi
ight)
ight] = rac{1}{2}\phi^{T}\mathsf{M}^{-1}\phi + \mathsf{const}$$





Hamiltonian Monte Carlo

Hamiltonian Dynamics

$$\begin{split} \frac{d\theta_{i}}{dt} &= \left[\mathsf{M}^{-1}\phi\right]_{i},\\ \frac{d\phi_{i}}{dt} &= \frac{\partial \log p\left(\theta|\mathsf{y}\right)}{\partial \theta_{i}} \end{split}$$

which can be simulated using the leapfrog algorithm

$$\phi_{i}\left(t+\frac{\varepsilon}{2}\right) = \phi_{i}\left(t\right) + \frac{\varepsilon}{2} \frac{\partial \log p\left(\theta(t)|y\right)}{\partial \theta_{i}},$$

$$\theta\left(t+\varepsilon\right) = \theta\left(t\right) + \varepsilon \mathsf{M}^{-1}\phi(t),$$

$$\phi_{i}\left(t+\varepsilon\right) = \phi_{i}\left(t+\frac{\varepsilon}{2}\right) + \frac{\varepsilon}{2} \frac{\partial \log p\left(\theta(t)|y\right)}{\partial \theta_{i}},$$

where ε is the step size.

Discretization \Rightarrow acceptance probability drops with ε .

The Hamiltonian Monte Carlo algorithm

- Initialize $\theta^{(0)}$ and iterate for i=1,2,...
 - **11** Sample the starting **momentum** $\phi_s \sim N(0, M)$
 - 2 Simulate new values for (θ_p, ϕ_p) by iterating the leapfrog algorithm L times, starting in $(\theta^{(i-1)}, \phi_s)$.
 - 3 Compute the acceptance probability

$$\alpha = \min \left(1, \frac{p(\mathbf{y}|\theta_p)p(\theta_p)}{p(\mathbf{y}|\theta^{(i-1)})p(\theta^{(i-1)})} \frac{p\left(\phi_p\right)}{p\left(\phi_s\right)} \right)$$

- 4 With probability α set $\theta^{(i)} = \theta_p$ and $\theta^{(i)} = \theta^{(i-1)}$ otherwise.
- Tuning parameters: 1. stepsize ε , 2. number of leapfrog iterations L and 3. mass matrix M. No U-turn

Stan

- Stan is a probabilistic programming language based on HMC.
- Allows for Bayesian inference in many models with automatic implementation of the MCMC sampler.
- Named after Stanislaw Ulam (1909-1984), co-inventor of the Monte Carlo algorithm.
- Written in C++ but can be run from R using the package rstan



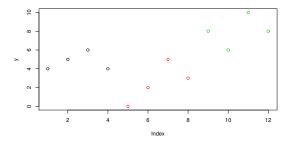
Stan logo



Stanislaw Ulam

Stan - toy example: three plants

Three plants were observed for four months, measuring the number of flowers



Stan Model 1: iid normal

```
y_i \stackrel{iid}{\sim} N\left(\mu, \sigma^2\right)
```

```
library (rstan)
v=c(4.5,6,4,0,2,5,3,8,6,10,8)
N=length(y)
StanModel = '
data (
int<lower=0> N; // Number of observations
int<lower=0> y[N]; // Number of flowers
}
parameters {
real mu;
real<lower=0> sigma2:
model [
mu ~ normal(0.100): // Normal with mean 0. st.dev. 100
sigma2 ~ scaled inv chi square(1.2); // Scaled-inv-chi2 with nu 1.sigma 2
for(i in 1:N){
v[i] ~ normal(mu,sqrt(sigma2));
٦,
```

Stan Model 2: multilevel normal

$$y_{t,p} \sim N\left(\mu_p, \sigma_p^2\right), \ \mu_p \sim N\left(\mu, \sigma^2\right)$$

```
StanModel <- '
data
int<lower=0> N: // Number of observations
int<lower=0> v[N]: // Number of flowers
int<lower=0> P: // Number of plants
transformed data {
int<lower=0> M: // Number of months
M = N / P:
parameters {
real mu:
real<lower=0> sigma2;
real mup[P]:
real sigmap2[P];
model {
mu ~ normal(0.100); // Normal with mean 0. st.dev. 100
sigma2 ~ scaled_inv_chi_square(1,2); // Scaled-inv-chi2 with nu 1, sigma 2
for(p in 1:P){
mup[p] ~ normal(mu,sqrt(sigma2));
for(m in 1:M) {
 v[M*(p-1)+m] ~ normal(mup[p],sqrt(sigmap2[p]));
3,1
```

Stan Model 3: multilevel Poisson

$$y_{t,p} \sim Poisson\left(\mu_{p}
ight)$$
 , $\mu_{p} \sim log N\left(\mu, \sigma^{2}
ight)$

```
StanModel <- '
data (
int<lower=0> N; // Number of observations
int<lower=0> v[N]; // Number of flowers
int<lower=0> P: // Number of plants
transformed data [
int<lower=0> M: // Number of months
M = N / P:
parameters {
real mu:
real<lower=0> sigma2;
real mup[P];
model {
mu ~ normal(0,100); // Normal with mean 0, st.dev. 100
sigma2 ~ scaled inv chi square(1.2): // Scaled-inv-chi2 with nu 1. sigma 2
for(p in 1:P){
mup[p] ~ lognormal(mu,sqrt(sigma2)); // Log-normal
for(m in 1:M) {
 v[M*(p-1)+m] ~ poisson(mup[p]); // Poisson
},
```

Stan: fit model and analyze output

```
data <- list(N=N, y=y, P=P)
warmup <- 1000
niter <- 2000
fit <- stan(file="StanModel.stan", data=data, warmup=warmup, iter=niter, chains=4, cores=2)
# Print the fitted model
print(fit,digits_summary=3)
# Extract posterior samples
postDraws <- extract(fit)
# Do traceplots of the first chain
par(mfrow = c(1,1))
plot(postDraws$mu[1:(niter-warmup)],type="1",ylab="mu",main="Traceplot")
# Do automatic traceplots of all chains
traceplot (fit)
# Bivariate posterior plots
pairs (fit)
```

Stan - useful links

- Getting started with RStan
- RStan vignette
- Stan Modeling Language User's Guide and Reference Manual
- Stan Case Studies

Variational Inference

- Let $\theta = (\theta_1, ..., \theta_p)$. Approximate the posterior $p(\theta|y)$ with a (simpler) distribution $q(\theta)$.
- Before: Normal approximation from optimization: $q(\theta) = N\left[\tilde{\theta}, J_{y}^{-1}(\tilde{\theta})\right]$.
- Mean field Variational Inference (VI): $q(heta) = \prod_{i=1}^p q_i(heta_i)$
- **Parametric VI**: Parametric family $q_{\lambda}(\theta)$ with parameters λ
- Find the $q(\theta)$ that minimizes the Kullback-Leibler distance between the true posterior p and the approximation q:

$$\mathit{KL}(q,p) = \int q(\theta) \ln rac{q(\theta)}{p(\theta|y)} d\theta = \mathit{E}_q \left[\ln rac{q(\theta)}{p(\theta|y)}
ight].$$





Mean field approximation

■ Mean field VI is based on factorized approximation:

$$q(\theta) = \prod_{i=1}^{p} q_i(\theta_i)$$

- No specific functional forms are assumed for the $q_i(\theta)$.
- Optimal densities can be shown to satisfy:

$$q_j(\theta) \propto \exp\left(E_{-\theta_j} \ln p(y, \theta)\right)$$

where $E_{-\theta_{i}}(\cdot)$ is the expectation with respect to $\prod_{k \neq j} q_{k}(\theta_{k})$.





Mean field approximation - algorithm

- Initialize: $q_2^*(\theta_2), ..., q_p^*(\theta_p)$
- Repeat until convergence:

- $\blacktriangleright \ q_p^*(\theta_p) \leftarrow \frac{\exp\bigl[E_{-\theta_p}\ln p(\mathbf{y},\theta)\bigr]}{\int \exp\bigl[E_{-\theta_p}\ln p(\mathbf{y},\theta)\bigr]d\theta_p}$
- Note: no assumptions about parametric form of the $q_i(heta)$.
- **O**ptimal $q_i(\theta)$ often **turn out** to be parametric (normal etc).
- Just update hyperparameters in the optimal densities.

Mean field approximation - Normal model

- Model: $X_i | \theta, \sigma^2 \stackrel{iid}{\sim} N(\theta, \sigma^2)$.
- Prior: $\theta \sim N(\mu_0, \tau_0^2)$ independent of $\sigma^2 \sim Inv \chi^2(\nu_0, \sigma_0^2)$.
- Mean-field approximation: $q(\theta, \sigma^2) = q_{\theta}(\theta) \cdot q_{\sigma^2}(\sigma^2)$.
- Optimal densities

$$\begin{split} q_{\theta}^*(\theta) &\propto \exp\left[E_{q(\sigma^2)} \ln p(\theta, \sigma^2, \mathbf{x})\right] \\ q_{\sigma^2}^*(\sigma^2) &\propto \exp\left[E_{q(\theta)} \ln p(\theta, \sigma^2, \mathbf{x})\right] \end{split}$$

Normal model - VB algorithm

■ Variational density for σ^2

$$\sigma^2 \sim \mathit{Inv} - \chi^2 \left(\tilde{\nu}_{\mathit{n}}, \tilde{\sigma}_{\mathit{n}}^2 \right)$$

where
$$\tilde{\nu}_n = \nu_0 + n$$
 and $\tilde{\sigma}_n = \frac{\nu_0 \sigma_0^2 + \sum_{i=1}^n (x_i - \tilde{\mu}_n)^2 + n \cdot \tilde{\tau}_n^2}{\nu_0 + n}$

■ Variational density for θ

$$\theta \sim N\left(\tilde{\mu}_n, \tilde{\tau}_n^2\right)$$

where

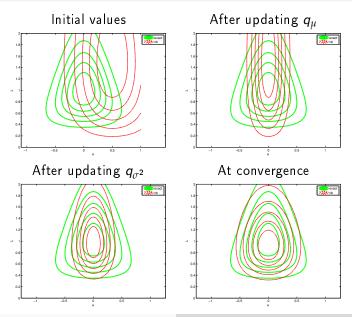
$$\tilde{\tau}_n^2 = \frac{1}{\frac{n}{\tilde{\sigma}_n^2} + \frac{1}{\tau_0^2}}$$

$$\tilde{\mu}_n = \tilde{w}\bar{x} + (1 - \tilde{w})\mu_0$$
,

where

$$\tilde{w} = \frac{\frac{n}{\tilde{\sigma}_n^2}}{\frac{n}{\tilde{\sigma}_n^2} + \frac{1}{\tau_0^2}}$$

Normal example from Murphy ($\lambda = 1/\sigma^2$)



Bayesian Learning

HMC, Stan and VI