



SENSORS SOFTWARE DEVELOPMENT KIT

USER MANUAL

VERSION 1.4

DECEMBER 4, 2020

Revision history

Manual version	SW version	Notes	Date
1.0	1.0	<ul style="list-style-type: none"> Initial version of this document 	August 2019
1.1	1.1	<ul style="list-style-type: none"> Updated sensors supported and software history Changed the wiringPi install method as recommended by its author. 	November 2019
1.2	1.2	<ul style="list-style-type: none"> Updated sensors supported and software history 	March 2020
1.3	1.3	<ul style="list-style-type: none"> Updated sensors supported and software history 	September 2020
1.4	1.5	<ul style="list-style-type: none"> Updated sensors supported and software history 	December 2020

* For SDK version history see chapter Software history

Abbreviations and abstract

Abbreviation	Name	Description
ADC	Analog to Digital converter	
ASIC	Application specific integrated circuit	
GPIO	General Purpose Input Output	
IDE	Integrated development environment	A set of tools for software development
I ² C	Inter-integrated circuit	Serial communication interface and protocol
MCU	Microcontroller	
SDK	Software development kit	Software development tool to integrate various Würth Elektronik eiSos products
SPI	Serial peripheral interface	Serial communication interface and protocol

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1 Introduction

The Würth Elektronik eiSos range of sensors provide advanced sensing capabilities to any embedded application. The built-in digital interface enables easy integration with any of the most commonly used host MCUs through industry standard serial communication interfaces like I²C. This also allows complete configuration and control of the sensor via software running on the host MCU.

The Sensors SDK is a set of software tools that enable quick software integration of Würth Elektronik eiSos sensors to application software on the host MCU. It consists of a set of platform-independent drivers for the sensors and sample applications developed on the Raspberry Pi platform written in C.

1.1 Motivation

A typical sensor from Würth Elektronik eiSos consists of the sensing element along with an ASIC which implements the control logic. All configurations of the sensors are done by writing specific values to a set of control registers on board. One or more status registers can be monitored to get the current status of the sensor and finally, the output is stored in the output registers. These sensors not only deliver the raw values of the physical parameter being sensed, but also perform several advanced functions like filtering, FIFO-storage, threshold detection, interrupt generation etc.

To use the complete feature set of such a sensor, control of all the necessary registers have to be implemented on the host MCU. This involves considerable effort for the user. The aim of the Sensors SDK is to minimize the effort required to integrate the sensor control software to the host application.

It contains the implementations of all the available functions of the sensors in pure C-code. In order to integrate any Würth Elektronik eiSos sensor to the application, the user has to simply port the corresponding C-code to his host MCU. This significantly reduces the time needed for developing the software interface to the sensor.

The steps for porting are explained in more detail in chapter 3.

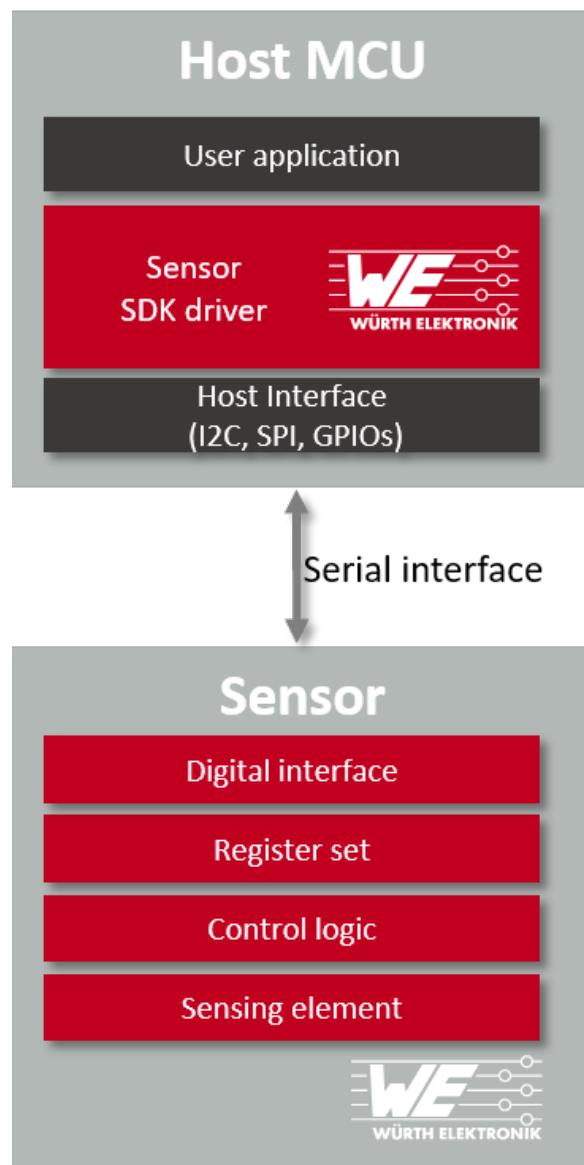


Figure 1: Sensors SDK driver as part of the end product

2 Sensors SDK overview

In this chapter, constituents of the Sensors SDK are described in details.

2.1 Platform-independent sensor drivers

This part of the Sensors SDK consists of a set of C header and source file per sensor. Every source file contains implementations for configuration and control of the sensors that is exposed to the application via functions and type declarations in the corresponding header file. Being platform independent and written in C enables easy porting of the drivers to any custom MCU platform.

2.2 Sample applications

In order to kick-start the application development, several sample applications that includes typical use-cases of the sensors are made available as a part of the Sensors SDK. These examples are developed on the Raspberry Pi platform. The Sensors SDK contains the complete source code for all the sample applications including the project files for the Code::Blocks IDE.



The sample applications were tested on Raspberry Pi 3 Model B with Raspbian Stretch and Raspberry Pi 3 Model B+ with Raspbian Buster. Code::Blocks version 17.12 was used as the IDE

These sample applications allow the user to take the sensor into operation. Additionally, the availability of the source code allows the user to try out several configurations and decide on the ones suitable for the application with minimal effort.

The sensors supported by the different versions of the Sensors SDK are shown in table 1.

SDK version	Sensor	Interface	Sensor type
1.0 and higher	WSEN-PADS (2511020213301)	I ² C	Absolute pressure sensor
1.1 and higher	WSEN-ITDS (2533020201601)	I ² C	Acceleration sensor
1.1 and higher	WSEN-PDUS (25131308XXX01)	I ² C	Differential pressure sensors
1.2 and higher	WSEN-TIDS (2521020222501)	I ² C	Temperature sensor
1.3 and higher	WSEN-HIDS (2523020210001)	I ² C and SPI	Humidity sensor
1.4 and higher	WSEN-PADS (2511020213301)	SPI	Absolute pressure sensor
1.4 and higher	WSEN-ITDS (2533020201601)	SPI	Acceleration sensor

Table 1: Sensor support in the Sensors SDK



The Differential pressure sensors with matchcode WSEN-PDUS work with 5V logic and should not be directly connected to Raspberry Pi. Hence, no sample applications (example directory) for this sensors are currently implemented for the Raspberry Pi platform.

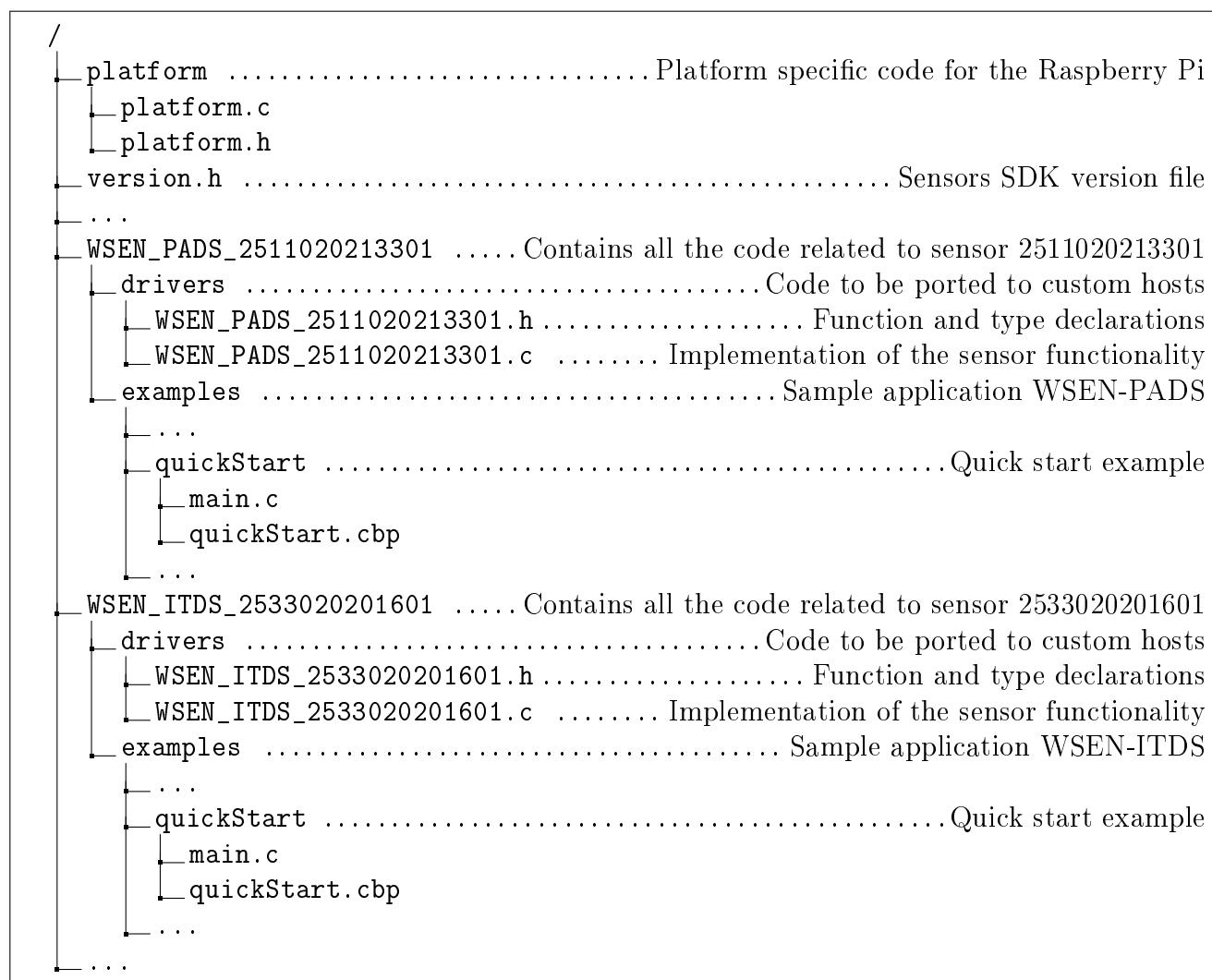
2.3 Contents of the Sensors SDK

The Sensors SDK is delivered as a compressed zip-file. All code related to a sensor supported by the Sensors SDK are placed under a sub directory named after the corresponding sensor.

Each sensor directory contains two sub-directories, **drivers** and **examples**. The sub-directory **drivers** contains the platform-independent code that can be used to port to the custom MCU.

The **examples** folder contains sample applications that run on the Raspberry-Pi. The sub-directory **platform** contains the platform-specific implementation for the Raspberry-Pi.

The current version of the Sensors SDK is specified in the **version.h** file.



3 Host integration

As described in chapter 2 the Sensors SDK has a platform independent driver component and Raspberry-pi specific examples which demonstrate the use of these drivers. In the following, the steps involved in porting the drivers to a custom platform is described.

The contents of the **drivers** directory has to be directly integrated into the custom project. For example, in case of WSEN_PADS, include the WSEN_PADS_2511020213301.h and WSEN_PADS_2511020213301.c files to the custom project.

The file **platform.h** declares platform specific functions that has to be implemented by the user on the custom host. For example, the access to I²C interface of the host is declared with the following functions.

```
/***
 * @brief Initialize the I2C Interface
 * @param I2C address
 * @retval Error Code
 */
int8_t I2CInit(int address);

/***
 * @brief Read data starting from the addressed register
 * @param -RegAdr : the register address to read from
 *           -NumByteToRead : number of bytes to read
 *           -pointer Data : the address store the data
 * @retval Error Code
int8_t ReadReg(uint8_t RegAdr, int NumByteToRead, uint8_t *Data);

/***
 * @brief Write data strarting from the addressed register
 * @param -RegAdr : Address to write in
 *           -NumByteToWrite : number of bytes to write
 *           -pointer Data : Address of the data to be written
 * @retval Error Code
 */
int8_t WriteReg(int RegAdr, int NumByteToWrite, uint8_t *Data);
```

Code 1: Code snippet for I²C interface

Here the definition of these functions, depending on the host peripherals, has to be implemented by the user. The function **I2CInit()** should initialize the I²C peripheral on the custom MCU and the functions **ReadReg()** and **WriteReg()** should enable reading/writing data bytes over the I²C bus.



Please refer to the user manual of the corresponding sensor for a detailed description of the characteristics of the digital interface being used.



The register read and write functions shall be implemented to read/write one byte at a time. Burst read/write operations can be implemented based on the host MCU peripheral and the sensor used.

The existing **platform.c** file, can be removed from the project as it contains the corresponding implementation for the Raspberry Pi.

On porting the aforementioned functions onto the custom MCU, the driver can be used seamlessly for the application development. The sample applications can be used as a starting point for further development.

4 Running Sensors SDK sample application on the Raspberry Pi

This chapter explains the steps involved in running the sample applications of the Sensors SDK on the Raspberry Pi platform.

4.1 Hardware connections

For creating custom applications on the basis of the Raspberry Pi, connect the pins of the sensor evaluation board to corresponding pins on the Raspberry Pi (power supply, ground, I²C). Figure 2 gives an overview of the pins of the Raspberry Pi used in the driver application examples. Refer to the respective user manuals of the evaluation boards for further details.

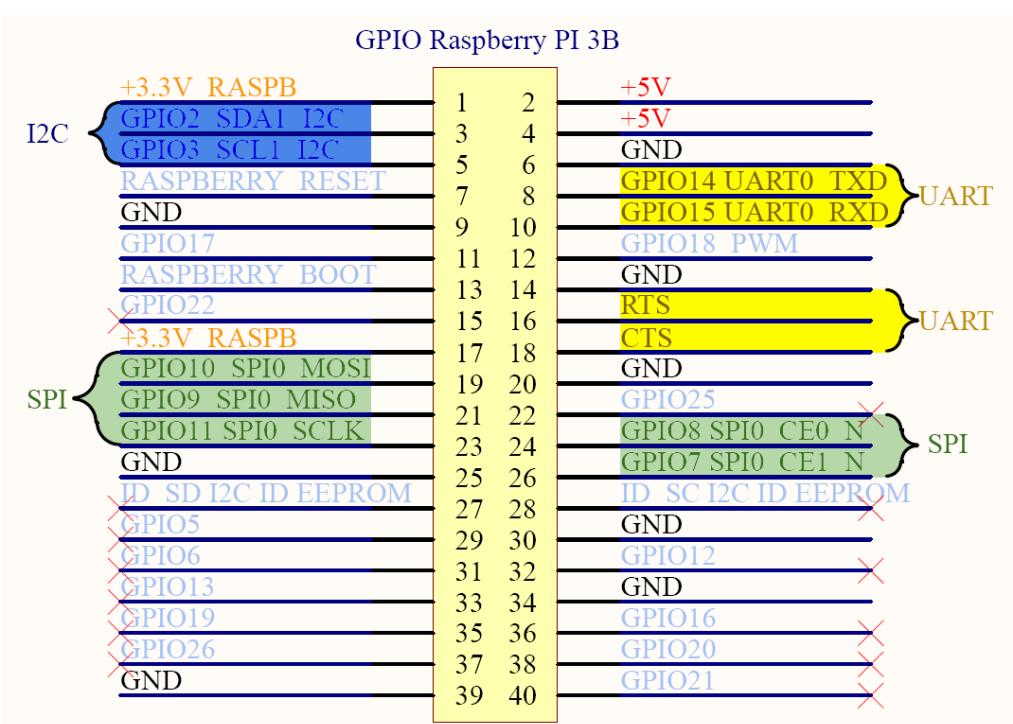


Figure 2: Pinout of 40-pin GPIO header of Raspberry Pi 3B

For example, figure 3 shows a block diagram for connecting a sensor via I²C interface to Raspberry Pi.

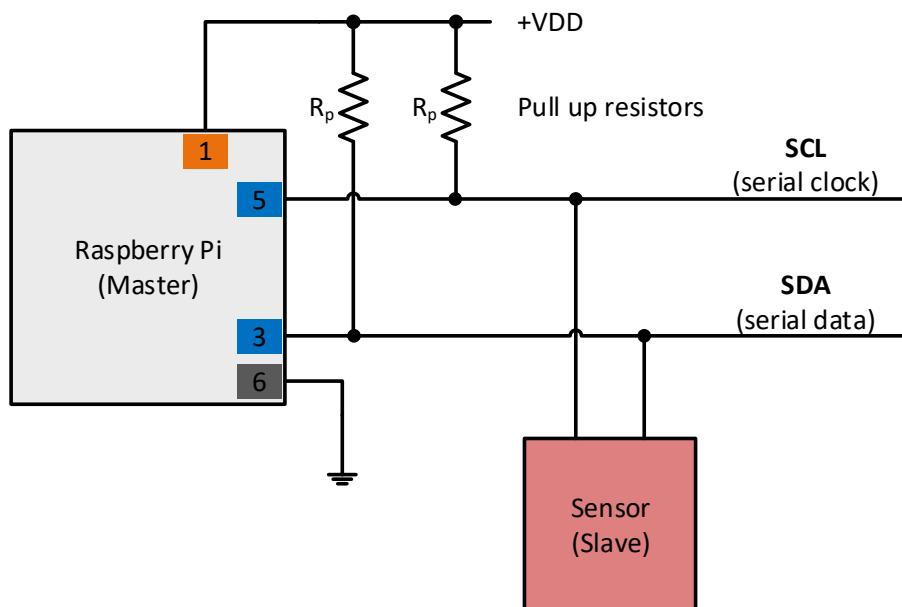


Figure 3: Connecting an I²C sensor to Raspberry Pi 3B

Alternatively, Würth Elektronik eiSos Amber-Pi, an add-on module for the Raspberry Pi can be used to connect the sensor evaluation board directly to the Raspberry Pi.

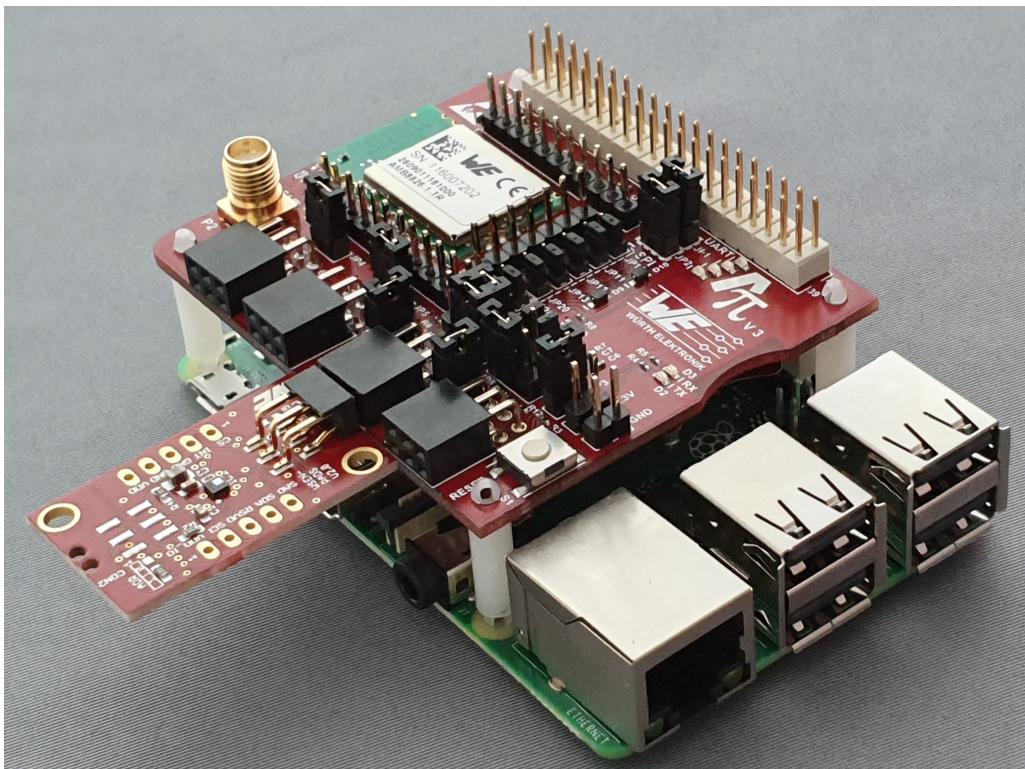


Figure 4: Sensor evaluation board with Amber-Pi

4.2 Install the Raspbian OS on the Raspberry Pi

1. First of all the Raspberry Pi has to be installed and configured.
 - a) Download the latest version of Raspbian with GUI from
<https://www.raspberrypi.org/downloads/raspbian/>
 - b) Install the Raspbian OS by writing its image on your SD-card. On a Windows machine the Win32DiskImager tool can be used, as described here
www.raspberrypi.org/documentation/installation/installing-images/windows.md
2. After installing the image on the SD card, insert it into the Raspberry Pi's SD card slot, connect your monitor, mouse and keyboard. Now the Raspberry Pi is ready to boot up. Please start it by powering it up.
3. After booting the Raspberry Pi, switch off the Bluetooth® interface by clicking on the Bluetooth® button on the right upper corner of the screen (see figure 5).
4. Then turn on the WiFi for connecting to the internet by clicking on the WiFi button on the right upper corner of the screen and selecting the WiFi of your choice.

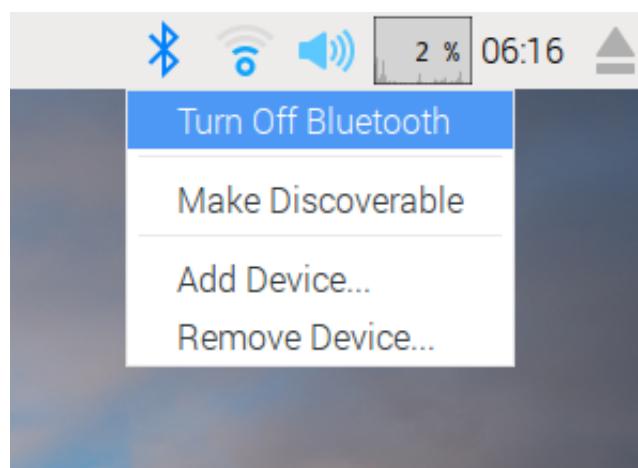


Figure 5: Switch off the Bluetooth® and connect to internet via WiFi

5. After connecting to the internet make sure your Raspberry Pi is up to date with the latest versions of Raspbian OS. To update the system open a terminal by clicking on the terminal symbol in the left upper corner (see figure 6).

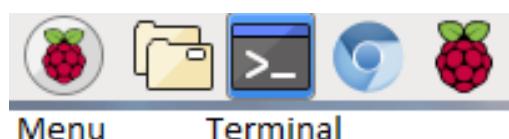


Figure 6: Terminal button

6. Then upgrade the Raspbian OS by typing in terminal:

```
sudo apt-get update
sudo apt-get upgrade
```

4.2.1 Configuring the peripherals

1. Next, the peripherals have to be enabled. To do so open the menu by clicking on the Raspberry Pi symbol on the left upper corner of the screen and open the **Preferences** → **Raspberry Pi Configuration** window (see figure 7). Enable the SPI, I²C and SERIAL interface.

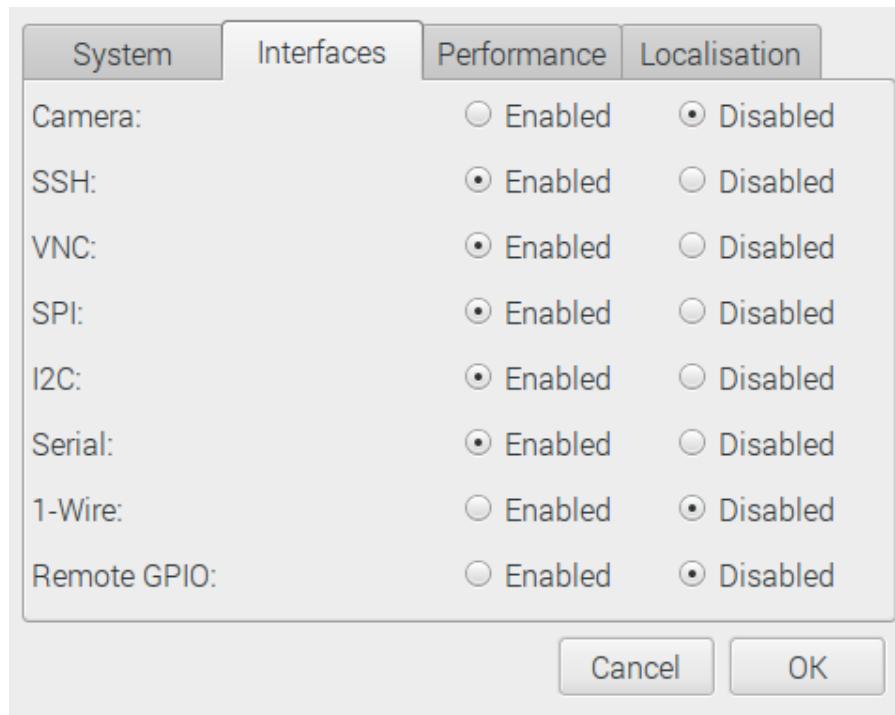


Figure 7: Raspberry Pi interface configuration

2. After enabling the interfaces a dialog should appear asking for a reboot to apply the changes. If no dialog appears reboot by clicking on the Raspberry symbol on the left upper corner of the screen and select **Shutdown**.
3. In order to use the peripherals as a non-root user, the local user has to be a member of the peripheral group. In order to check this, type in the following in the terminal,

groups

If the output contains GPIO, SPI and I²C, then skip the next step.

4. Add the current user to the groups by typing in the following commands in the terminal,

```
sudo adduser pi gpio
sudo adduser pi i2c
sudo adduser pi spi
```

Logout and login to update the user group settings.

4.3 Install the wiringPi library

The wiringPi library is used to easily access the peripherals of the Raspberry Pi.

1. First check if wiringPi is already installed. In a terminal type:

```
gpio -v
```

If you get the version number, then you have it installed already. In this case continue with 4.4.

If you want to work on a Raspberry Pi 4B make sure you have wiringPi version 2.52 (or newer) installed.

2. If it is not installed, install wiringPi as described in <http://www.wiringpi.com/download-and-install/> or <http://wiringpi.com/wiringpi-updated-to-2-52-for-the-raspberry-pi-4b/>.

4.4 Install the Sensors SDK

The Sensors SDK was developed in the Code::Blocks development environment.

1. Thus first download and install the software Code::Blocks. Therefore open a terminal and type:

```
sudo apt-get install codeblocks
```

2. Now download the Sensors SDK driver as zip file from (www.we-online.de/wcs-software) to the location **~/Downloads**
3. The file is going to be extracted to the folder **~/Projects**. If the folder does not exist create it by typing in terminal:

```
mkdir ~/Projects
```

4. Now extract the Sensors SDK to **~/Projects** by typing in terminal:

```
unzip ~/Downloads/WSEN_SDK.zip -d ~/Projects
```

5. Then start the desired project via Code::Blocks by typing in terminal. For example,

```
codeblocks ~/Projects/WSEN_SDK/WSEN_PADS_2511020213301/
examples/quickStart/quickstart.cbp &
```

6. Now include the wiringPi libraries into Code::Blocks by opening the global linker settings in **Settings** → **Compiler** → **Linker Settings** and adding the library **/usr/lib/libwiringPi.so** to the **Link libraries** field (see figure 8).
7. Additionally add **-pthread** in the **Other linker options** field. Close the linker settings again.



All necessary libraries are also linked in the projects linker settings to not run into trouble in case they have not been linked in the global linker settings.

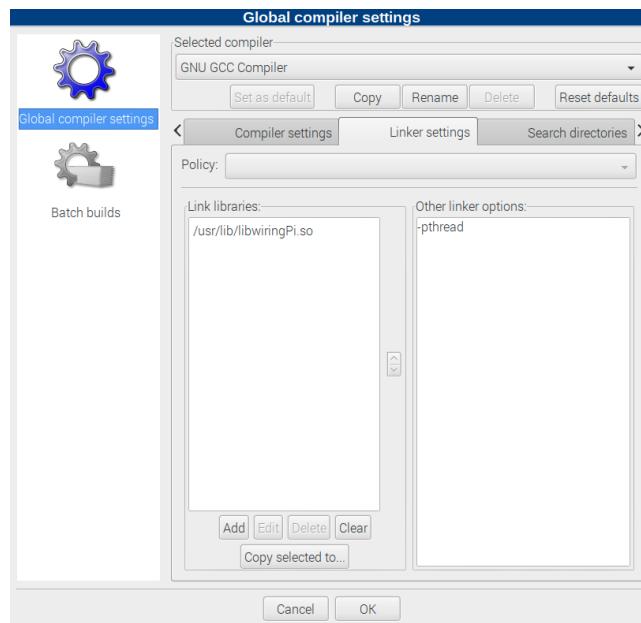


Figure 8: Code::Blocks linker settings

8. Then press **Build → Rebuild** to build the project (see figure 9).

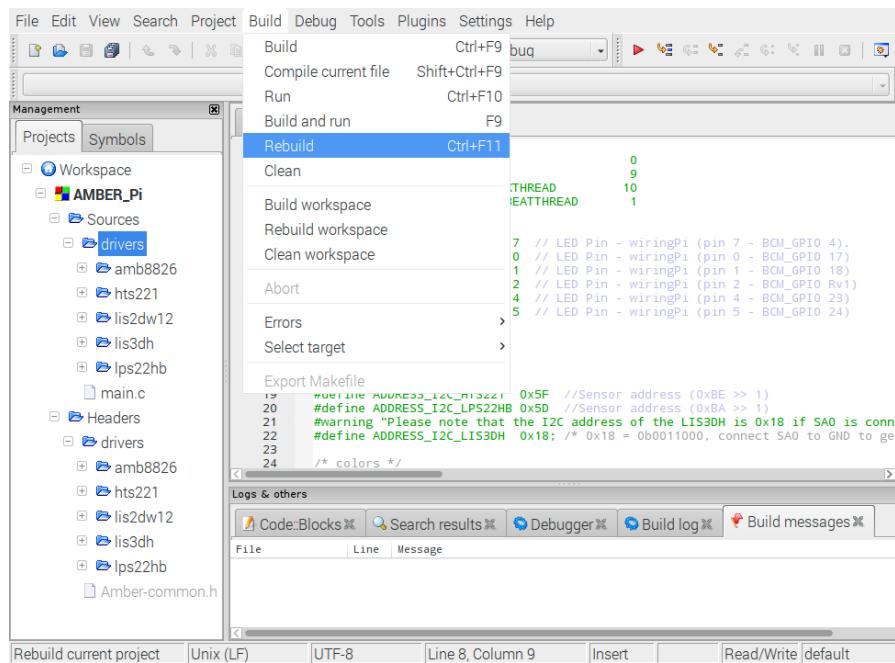


Figure 9: Rebuild the application

9. If it builds without errors the Raspberry Pi, WiringPi and Sensors SDK setup succeeded.
10. In case of further question, please contact our technical support at <https://we-online.com/wireless-connectivity/support>

5 Software history

Version 1.0.0 "Release"

- First released version of the SDK.
- PADS driver and example.

Version 1.1.0 "Release"

- Added driver support for ITDS and PDUS sensors.
- Added example for ITDS.

Version 1.2.0 "Release"

- Added driver support for TIDS sensor.
- Added temperature readout functions to ITDS drivers.
- Updated the quick start example of the PADS sensor.

Version 1.3.0 "Release"

- Added driver support for HIDS sensor.
- Added quick start example for HIDS sensor.
- Updated the Raspberry Pi specific platform files to support the SPI interface.

Version 1.4.0 "Internal"

Version 1.5.0 "Release"

- Added SPI support for PADS and ITDS sensor.

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