

ZIYI WU

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EDUCATION

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|--|-----------------------|
| University of Toronto , Toronto, ON, Canada | Sept. 2021 – Present |
| Ph.D. in Computer Science | |
| Advisor: Prof. Igor Gilitschenski | |
| Tsinghua University , Beijing, P.R.China | Aug. 2017 – Jun. 2021 |
| B.Eng. in Automation | |
| Advisor: Prof. Jiwen Lu | |

PUBLICATIONS & MANUSCRIPTS

* indicates equal contribution/supervision

Journal Papers

1. **Learning Efficient Binarized Object Detectors with Information Compression**
Ziwei Wang, Jiwen Lu, **Ziyi Wu**, Jie Zhou.
T-PAMI, 2021.

Conference Papers

1. **Breaking Bad: A Dataset for Geometric Fracture and Reassembly**
Silvia Sellán*, Yun-Chun Chen*, **Ziyi Wu***, Animesh Garg, Alec Jacobson.
NeurIPS Datasets and Benchmarks Track, 2022.
2. **Instance Similarity Learning for Unsupervised Feature Representation**
Ziwei Wang, Yunsong Wang, **Ziyi Wu**, Jiwen Lu, Jie Zhou.
ICCV, 2021.
3. **BiDet: An Efficient Binarized Object Detector**
Ziwei Wang, **Ziyi Wu**, Jiwen Lu, Jie Zhou.
CVPR, 2020.

Workshop Papers & Preprints

1. **SlotFormer: Unsupervised Visual Dynamics Simulation with Object-Centric Models**
Ziyi Wu, Nikita Dvornik, Klaus Greff, Thomas Kipf*, Animesh Garg*.
Preprint. Under review.
2. **SlotFormer: Long-Term Dynamic Modeling in Object-Centric Models**
Ziyi Wu, Nikita Dvornik, Klaus Greff, Jiaqi Xi, Thomas Kipf*, Animesh Garg*.
UAI@CRL workshop, 2022.
3. **Dynamics-aware Adversarial Attack of 3D Sparse Convolution Network**
An Tao, Yueqi Duan, He Wang, **Ziyi Wu**, Pengliang Ji, Haowen Sun, Jie Zhou, Jiwen Lu.
Preprint. Under review.
4. **IF-Defense: 3D Adversarial Point Cloud Defense via Implicit Function based Restoration**
Ziyi Wu*, Yueqi Duan*, He Wang, Qingnan Fan, Leonidas J. Guibas.
arXiv, 2020.

5. **A Cascade Regression Model for Anatomical Landmark Detection**
Zimeng Tan, Yongjie Duan, **Ziyi Wu**, Jianjiang Feng, Jie Zhou.
MICCAI@STACOM Workshop, 2019.
6. **CFUN: Combining Faster R-CNN and U-net Network for Efficient Whole Heart Segmentation**
Zhanwei Xu, **Ziyi Wu**, Jianjiang Feng.
arXiv, 2018.

EXPERIENCE

Toronto Intelligent Systems Lab, University of Toronto	Sept. 2022 – Present
Graduate Research Assistant	Supervisor: Prof. Igor Gilitschenski
3D vision, robotics	
Vector Institute	Sept. 2021 – Present
Student Researcher	
People, AI and Robotics Group, University of Toronto	Sept. 2021 – Aug. 2022
Graduate Research Assistant	Supervisor: Prof. Animesh Garg & Prof. Andrea Tagliasacchi
3D vision, robotics	
OpenMMLab, SenseTime Ltd.	Mar. 2021 – Aug. 2021
Research Intern	Manager: Dr. Kai Chen Mentor: Wenwei Zhang
Develop open source codebase for 3D scene understanding (MMDetection3D)	
Geometric Computation Group, Stanford University	Jun. 2020 – Dec. 2020
Research Intern	Supervisor: Prof. Leonidas J. Guibas
3D adversarial attack and defense in point cloud	
Intelligent Vision Group, Tsinghua University	Apr. 2019 – May. 2020
Undergraduate Researcher Assistant	Supervisor: Prof. Jiwen Lu
Efficient design for 2D object detectors	

INVITED TALK

Winner talk at ECCV 2022 MVCS Workshop CLEVRER Challenge	2022
SlotFormer: Unsupervised Visual Dynamics Simulation with Object-Centric Models	

HONORS & AWARDS

• 1st place in CLEVRER track at MVCS Challenge (ECCV 2022 Workshop)	2022
• Vector Institute Research Grant	2022
• Outstanding Graduates (Beijing, Tsinghua University & Dept. of Automation)	2021
• SenseTime Undergraduate Scholarship for AI Research	2020
• Xiaomi Scholarship, Tsinghua University	2020
• Fang Chongzhi Scholarship, Tsinghua University	2019
• Chinese National Scholarship	2018
• Spark Program Membership, Tsinghua University	
• Innovation Award of Science and Technology, Tsinghua University	2018-2020
• Champion of the 20th Electronic Design Competition, Tsinghua University	2018

ACADEMIC SERVICES

Conference Reviewer/PC Member

- IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR) 2022
- European Conference on Computer Vision (ECCV) 2022
- Conference on Neural Information Processing Systems (NeurIPS) 2022
- Association for the Advancement of Artificial Intelligence (AAAI) 2023
- IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) 2022
- IEEE International Conference on Robotics and Automation (ICRA) 2023

Journal Reviewer

- International Symposium of Robotic Research (ISRR)

Workshop Reviewer

- ICLR Workshop on the Elements of Reasoning: Objects, Structure and Causality 2022

Seminar Co-Organizer

- [Toronto AI in Robotics \(AIR\) Seminar](#) 2022-2023

MENTORING

Xudong Liu Oct. 2022 – Present

MScAC student, University of Toronto

Project: Event-based vision

Wuyue Lu Oct. 2022 – Present

B.S. student, University of Toronto

Project: Object-centric learning

Jingyu Hu Oct. 2022 – Present

B.S. student, University of Toronto

Project: Object-centric learning

Xinyu Kang May. 2022 – July. 2022

B.S. student, University of Toronto

Project: Fractured object reassembly

Jiaqi Xi Sept. 2021 – May. 2022

B.S. student, Peking University

Project: Object-centric dynamics model