

Experiment 2. “Wave-induced velocities and particle trajectories”

1. Background theory

The velocity components under progressive or standing waves can be estimated from the velocity potential ϕ from the solution of the Laplace equation which is given in terms of the wave height, H , water depth, h , the wave number, $k = 2\pi/L$, and the angular frequency, $\sigma = 2\pi/T$,

$$\phi(x, y, z) = -\frac{H g}{2 \sigma} \frac{\cosh k(h+z)}{\cosh kh} \sin(kx - \sigma t) \quad (1a)$$

$$\phi(x, y, z) = \frac{H g}{2 \sigma} \frac{\cosh k(h+z)}{\cosh kh} \cos kx \sin \sigma t \quad (1b)$$

where t is the time, g is the gravity acceleration, and x and z represent the horizontal and vertical position of the water particle, respectively. Therefore, velocity components u and w can be estimated for a progressive (eqn. 2a) and standing (eqn. 2b) wave as,

$$\begin{aligned} u &= -\frac{\partial \phi}{\partial x} = \frac{H}{2} \sigma \frac{\cosh k(h+z)}{\sinh kh} \cos(kx - \sigma t) \\ w &= -\frac{\partial \phi}{\partial z} = \frac{H}{2} \sigma \frac{\sinh k(h+z)}{\sinh kh} \sin(kx - \sigma t) \end{aligned} \quad (2a)$$

$$\begin{aligned} u &= \frac{H}{2} \sigma \frac{\cosh k(h+z)}{\sinh kh} \sin kx \sin \sigma t \\ w &= -\frac{H}{2} \sigma \frac{\sinh k(h+z)}{\sinh kh} \cos kx \sin \sigma t \end{aligned} \quad (2b)$$

The velocity associated with either progressive or stationary waves decreases with distance from the free surface (Figure 1) due to dependence on the elevation z (eqn. 2a and 2b). For standing waves, the maximum values for u and w occur underneath the nodes and antinodes (Figure 1b), whereas u and w are zero below the antinodes and nodes, respectively.

The maximum particle displacement $|\zeta|$ and $|\xi|$, for x and z directions, can be expressed as a function of the wave height H , the mean particle position underneath the wave, the wave period (T), and the water depth (h) (Figure 2).

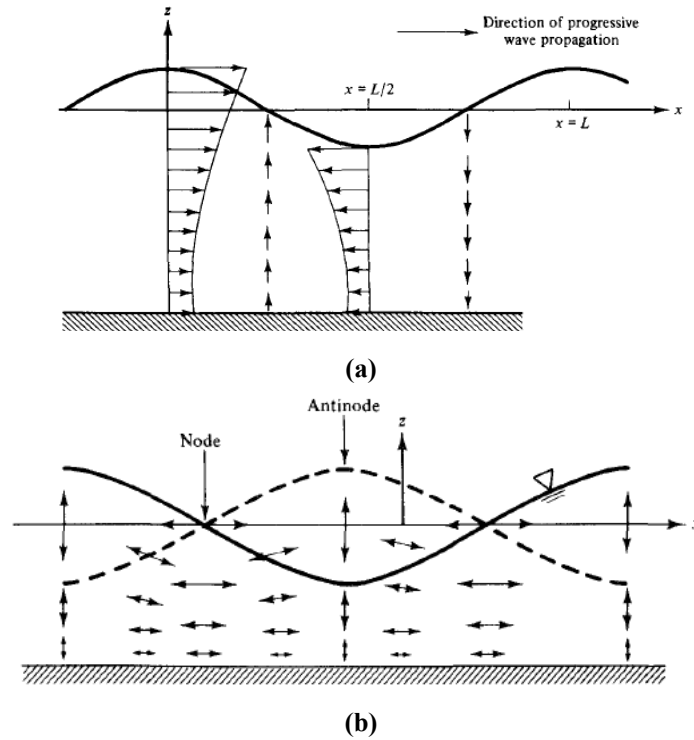


Figure 1. Wave-induced water particle velocities underneath a (a) progressive and (b) standing water wave. (Taken from Dean & Dalrymple, 1991).

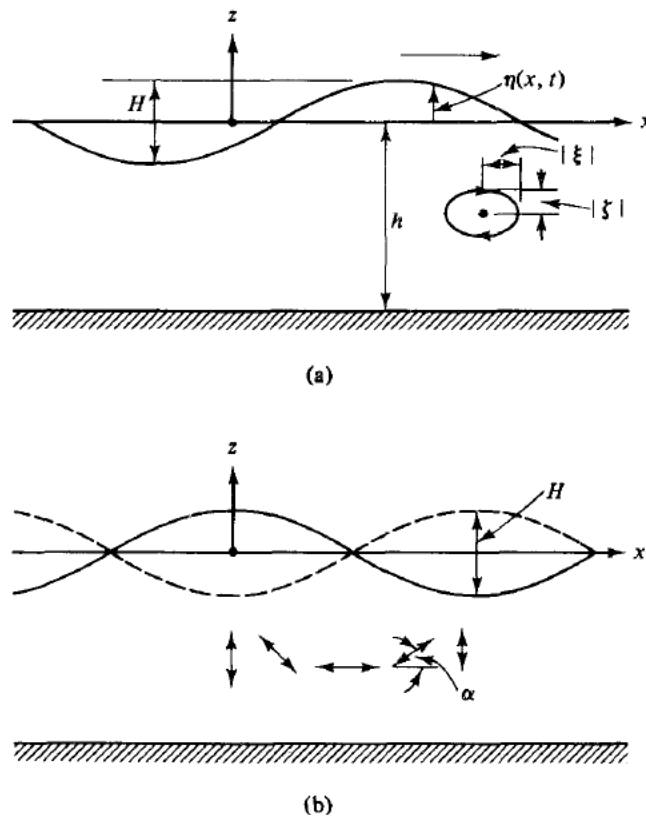


Figure 2. Water particles trajectories underneath a (a) progressive and (b) standing wave. (Taken from Dean & Dalrymple, 1991).

The maximum horizontal and vertical displacements of the water particles can be estimated theoretically, using linear wave theory, by integration of the velocity components (u and w) with respect to time. Hence, we obtain the following expression for progressive (eqn. 3a) and standing (eqn. 3b) waves:

$$\begin{aligned} |\zeta| &= \frac{H}{2} \frac{\cosh k(h+z)}{\sinh kh} \\ |\xi| &= \frac{H}{2} \frac{\sinh k(h+z)}{\sinh kh} \end{aligned} \quad (3a)$$

$$\begin{aligned} |\zeta| &= \frac{H}{2} \frac{\cosh k(h+z)}{\sinh kh} \sin kx \\ |\xi| &= \frac{H}{2} \frac{\sinh k(h+z)}{\sinh kh} \cos kx \end{aligned} \quad (3b)$$

2. Objectives

Measured the wave-induced velocities and particle trajectories under progressive and standing waves and compared to linear wave theory

3. Instructions

Progressive waves:

- Set the x - z location of the neutrally buoyant particle. The free-surface elevation sensor will correspond to the x location, whereas the velocity sensor to the z location.
- Start progressive wave generation and observe the free surface, wave-induced velocity, and particle movement at the original position of the neutrally buoyant particle.
- Export the measured variables to estimate the magnitudes of u and w and the particle maximum displacement $|\zeta|$ y $|\xi|$ as observed in the flume.
- Follow (i) to (iii) for two different water depths (suggestion: $z = -h/2$ and $z = -h$).

Standing waves:

- Select a standing wave and observe the location of the nodes and antinodes.
- Set the neutrally buoyant particle at the x location of the antinode and run the experiment for two different elevations (suggestion: $z = -h/2$ and $z = -h$).
- Start the standing wave generation and observe the free surface, wave-induced velocity, and particle movement at the original position of the neutrally buoyant particle.

- iv. Export the measured variables to estimate the magnitudes of u and w and the particle maximum displacement $|\zeta|$ y $|\xi|$ as observed in the flume.
- v. Repeat (ii-iv) at the x corresponding to a node.

4. Assignment

- Compute the wave-induced particle velocities and the particle trajectory displacement for both progressive and standing waves using wave theory (eqns. 2a, 2b, 3a, and 3b).
- Compare the measured velocities and trajectories with respect to linear wave theory results. Compute the relative error for each test.
- Discuss differences between theory and observations in terms of wave characteristics.

References:

Dean, R.G., and Dalrymple, R.A., 1991, Water wave mechanics for engineers and scientists. Advanced series on ocean engineering, Vol. 2. World Scientific.