

# Zhonghua Wang

DEEP LEARNING · MEDICAL IMAGE ANALYSIS

1088 Xueyuan Blvd, Shenzhen, China

✉ (+86) 13528846999 | ✉ wzhjerry1112@gmail.com | ✉ WzhJerry

*"Be the change that you want to see in the world."*

## Summary

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Master's student at the Southern University of Science and Technology, specializing in medical image analysis using deep learning methodologies. With a prolific academic background, I have authored 7 peer-reviewed publications and contributed to advanced research in the analysis of fundus, ocular, and OCTA images. My current focus lies in leveraging cutting-edge deep learning techniques to solve challenges in dermoscopic images, aiming to improve diagnostic accuracy. Beyond academics, I have successfully led 2 student climbing plans, reinforcing my capabilities in team leadership and strategic planning. I hold 2 software copyrights and a patent, highlighting my innovation and expertise in the field.

## Honors & Awards

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2021	<b>Top 10 Students</b> , Graduate Students in College of Engineering	Shenzhen, China
2020	<b>3rd Prize</b> , Challenge of Optimization of Low-dose CT image quality	Shenyang, China
2020	<b>Outstanding student scholarship</b> , Shuren College Annual selection	Shenzhen, China
2018	<b>3 Place Award</b> , Computer Programming Competition, SUSTech	Shenzhen, China

## Education

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### Southern University of Science and Technology

M.S. IN ELECTRONIC INFORMATION AND TECHNOLOGY

Shenzhen, China

- Research Student in Artificial Intelligence Laboratory

Sep. 2021 - Present

### Southern University of Science and Technology

B.S. IN INFORMATION SYSTEM

Shenzhen, China

- Top ten graduates in College of Engineering

Sep. 2017 - Jun. 2021

## Published Paper

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### Conferences

- **Wang Z**, Huang Y, Lyu J, Cheng P, Tang X. Deep Learning Based Discrimination of Corneal Ulcer Patterns Using Fluorescein Staining Images[C]//The Fourth International Symposium on Image Computing and Digital Medicine. 2020: 126-129.
- **Wang Z**, Lin L, Wu J, Tang X. Multi-task Learning Based Ocular Disease Discrimination and FAZ Segmentation Utilizing OCTA Images[C]//2021 43rd Annual International Conference of the IEEE Engineering in Medicine & Biology Society (EMBC). IEEE, 2021: 2790-2793.
- Lin L, **Wang Z**, Wu J, Lyu J, Wu J, Tang X. Bsda-net: A boundary shape and distance aware joint learning framework for segmenting and classifying octa images[C]//Medical Image Computing and Computer Assisted Intervention–MICCAI 2021: 24th International Conference, Strasbourg, France, September 27–October 1, 2021, Proceedings, Part VIII 24. Springer International Publishing, 2021: 65-75.
- **Wang Z**, Lyu J, Luo W, Tang X. (2021) Adjacent Scale Fusion and Corneal Position Embedding for Corneal Ulcer Segmentation. In: Fu H., Garvin M.K., MacGillivray T., Xu Y., Zheng Y. (eds) Ophthalmic Medical Image Analysis. OMIA 2021. Lecture Notes in Computer Science, vol 12970. Springer, Cham.
- Lin L, Cheng P, **Wang Z**, Li M, Wang K, Tang X. Automated segmentation of corneal nerves in confocal microscopy via contrastive learning based synthesis and quality enhancement[C]//2021 IEEE 18th International Symposium on Biomedical Imaging (ISBI). IEEE, 2021: 1314-1318.
- **Wang Z**, Lyu J, Luo W, Tang X. Superpixel inpainting for self-supervised skin lesion segmentation from dermoscopic images[C]//2022 IEEE 19th International Symposium on Biomedical Imaging (ISBI). IEEE, 2022: 1-4.

### Journals

- **Wang Z**, Lyu J, Tang X. autoSMIM: Automatic Superpixel-based Masked Image Modeling for Skin Lesion Segmentation[J]. IEEE Transactions on Medical Imaging, 2023.

## Research Experience

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2020	<b>Student's Climbing Program</b> , Research and development of intelligent diagnosis system for corneal ulcer
2021	<b>Guangdong Postgraduate Academic Forum</b> , Image Processing and Pattern Recognition
2022	<b>Student's Climbing Program</b> , Automatic enhancement of low-quality fundus image and DR diagnosis
2022	<b>Jiaxing Research Institute Program</b> , AlforEye Artificial Intelligence Diagnosis System
2022	<b>Shenzhen Emergency Prevention and Control Project</b> , Research and development of key technologies for fully automatic intelligent nucleic acid sampling robot system