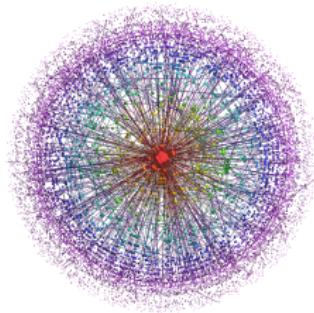




Algorithms and Data Structures

Lecture 10 Graphs: A Brief Recap

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"Graphs are among the most ubiquitous models of both natural and human-made structures. They can be used to model many types of relations and process dynamics in physical, biological and social systems. Many problems of practical interest can be represented by graphs.

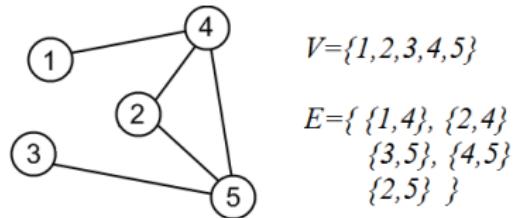
In computer science, graphs are used to represent networks of communication, data organization, computational devices, the flow of computation, etc. One practical example: The link structure of a website could be represented by a directed graph. The vertices are the web pages available at the website and a directed edge from page A to page B exists if and only if A contains a link to B. A similar approach can be taken to problems in travel, biology, computer chip design, and many other fields. The development of algorithms to handle graphs is therefore of major interest in computer science. "



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Definition [Graphs]

A **graph** is a pair $G = (V, E)$ where V is a finite set of **nodes** (or **vertices**) and E is a (possibly empty) set of unordered pairs of distinct vertices of G called **edges**.

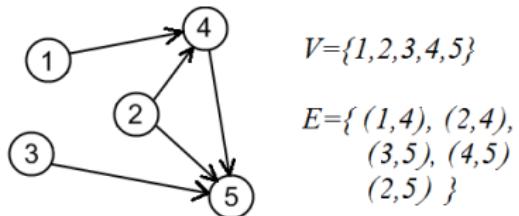


Note:

- Having multiple edges between two vertices is **not allowed**.
- Self-loops are **not allowed**, i.e., E is an **anti-reflexive** relation.
- Each edge is **bi-directional**, i.e., E is a **symmetric** relation.

Definition [Digraphs]

A **directed graph** (or simply called a **digraph**) is a pair $G = (V, E)$ where V is a finite set of **vertices** (or **nodes**) and $E \subseteq V^2 \setminus \{(v, v) \mid v \in V\}$; elements in E are called **directed edges** (or **arcs**, or **edges**). We denote an edge from u to v using (u, v) .



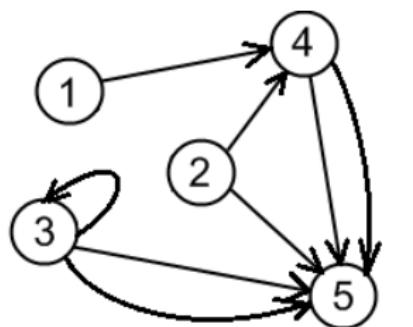
Note:

- Having multiple edges between two vertices is **not allowed**.
- Self-loops are **not allowed**, i.e., E is an **anti-reflexive** relation.
- Any graph is also a digraph, by considering every (undirected) edge as two arcs.

Variants of Graphs

We may enrich the notion of graphs in the following ways:

- **Multigraphs:** $G = (V, E)$ where $E \subseteq V^2$ is a **multiset**, i.e., a set where each element can appear more than once.
- **Weighted (di)graphs:** $G = (V, E, f, D)$ where (V, E) is a (di)graph and $f : E \rightarrow D$ is a weight function.



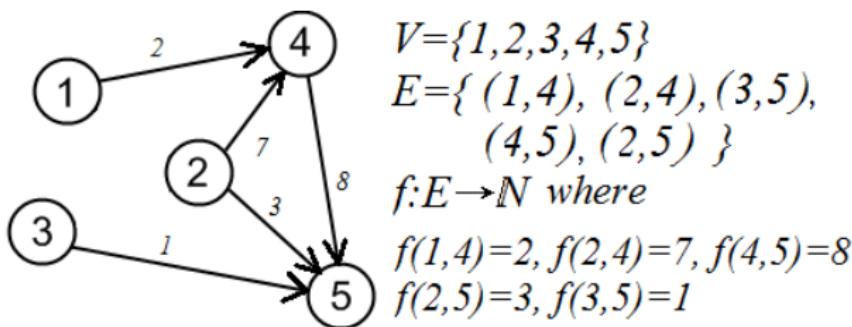
$$V = \{1, 2, 3, 4, 5\}$$

$$\begin{aligned}E = &\{(1, 4), (2, 4), (4, 5), \\&(4, 5), (2, 5), (3, 5), \\&(3, 5), (3, 3)\}\end{aligned}$$

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Let $G = (V, E)$ be a graph.

- The **order** of a graph G is the number of nodes in G , that is, $|V|$; it is customary to use the letter n to denote the order.
- it is customary to use the letter m to denote the number of edges, i.e $m = |E|$.
- We say that u is **adjacent** to v if $\{u, v\} \in E$; in this case, u, v are **neighbours**.
- If $\{u, v\}$ is an edge, we call u and v the **endpoints** of the edge.

Example:

	$V = \{1, 2, 3, 4, 5, 6, 7\}$ $E = \{\{1, 2\}, \{2, 3\}, \{1, 3\}, \{3, 4\}, \{5, 6\}\}$	<i>e.g.</i> 2 is adjacent to 3 3 is adjacent to 2 3 is adjacent to 4 2 is not adjacent to 4
--	---------------------------------------------------------------------------------------------	---------------------------------------------------------------------------------------------------------

Terminology

For (undirected) graph:

- The **degree** of a vertex is the number of its adjacent vertices.
- A **walk** is a sequence of vertices where each consecutive pair of vertices are joined by an edge.
- A **path** is a walk where no vertex is repeated.

For directed graph:

- The **in-degree** of a node is the number of incoming neighbours of the node.
- The **out-degree** of a node is the number of outgoing neighbours of the node.
- A **(directed) walk** is a sequence of nodes where each consecutive pair of nodes are connected by a directed edge.
- A **(directed) path** is a walk in which no node is repeated.

We define some common special types of graphs.

- (Complete graphs) A graph is **complete** if all pairs of distinct nodes are adjacent in G . A complete graph on n nodes is denoted by K_n .
- (Path graphs) A **path graph** is $G = (V, E)$ where $V = \{v_1, v_2, \dots, v_n\}$, and $E = \{\{v_1, v_2\}, \{v_2, v_3\}, \dots, \{v_{n-1}, v_n\}\}$. A path graph on n nodes is denoted by P_n .
- (Cycle graphs) A **cycle graph** is a graph $G = (V, E)$ where $V = \{v_1, v_2, \dots, v_n\}$, and $E = \{\{v_1, v_2\}, \{v_2, v_3\}, \dots, \{v_{n-1}, v_n\}, \{v_n, v_1\}\}$; this cycle graph is denoted by C_n .
- (Wheel graphs) A **wheel graph** is a graph $G = (V, E)$ where $V = \{u, v_1, v_2, \dots, v_n\}$, and

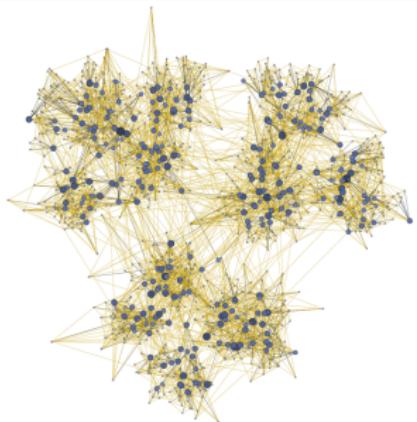
$$E = \{\{v_1, v_2\}, \{v_2, v_3\}, \dots, \{v_{n-1}, v_n\}, \{v_n, v_1\}\} \cup \{\{u, v_1\}, \{u, v_2\}, \dots, \{u, v_n\}\}.$$

This wheel graph is denoted by W_n .

Modeling with Graphs

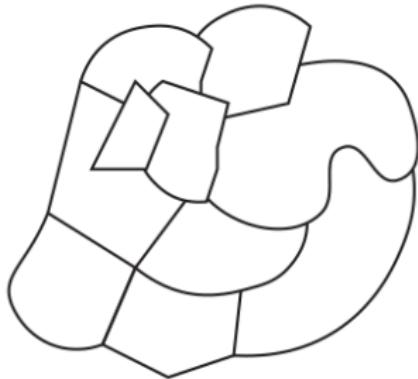
Many things interested by computer scientists are graphs:

- Network topology
- Binary relations
- Hyperlinks between webpages
- Transition diagram of systems
- Models of dependency between events



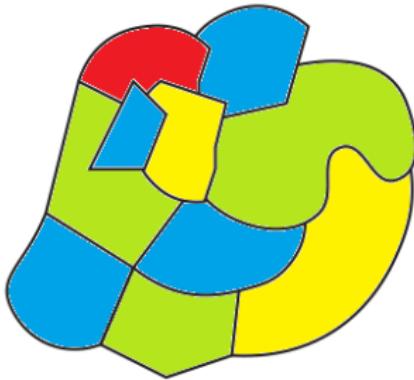
A Problem of Maps

Question 1 [Map Colouring] You are a cartographer charged with designing a map of a continent. You should fill regions using various colours, but want to use as few colours as possible, while giving different colours to neighbouring countries. How can you colour all the regions?



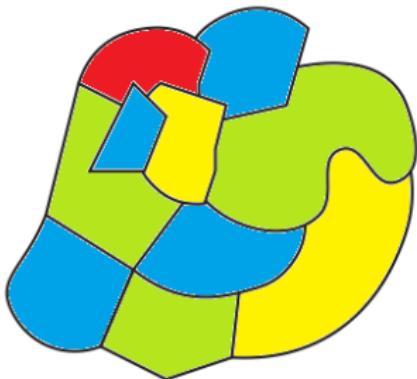
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- Can this map be coloured with fewer than four colours?
- Is there another map that requires more than four colours?

A Problem of Universities

Question 2 [Exam Scheduling]. A university needs to schedule exams at the end of the semester so that if a student is enrolled in two courses, these courses must get different examination periods. How can this be done?



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	1	ASE1251
Monday 26-Mar-2012	2	ASE2241
	2	ASE2251
Thursday 29-Mar-2012	3	ASE3241
	3	ASE3251
Monday 2-Apr-2012	3	ASE3009
	1	ASE1017
	3	ASE3025
	3	ASE3030
	2	ASE2041

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We would like to use a mathematical tool, called *graph*, to connect this problem with the map colouring problem

Exam Scheduling Problem: We turn the problem into a problem on graphs.

- **Nodes:** The nodes in V are exams.
- **Edges:** Two nodes are adjacent if they “share” a student.
- **Scheduling:** A **schedule** is a function $s : V \rightarrow T$ that maps nodes to a set T such that $\forall \{u, v\} \in E : s(u) \neq s(v)$

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Note: From an abstract point of view, the graph colouring problem and exam scheduling problem are the same problem!

Dining Mathematicians

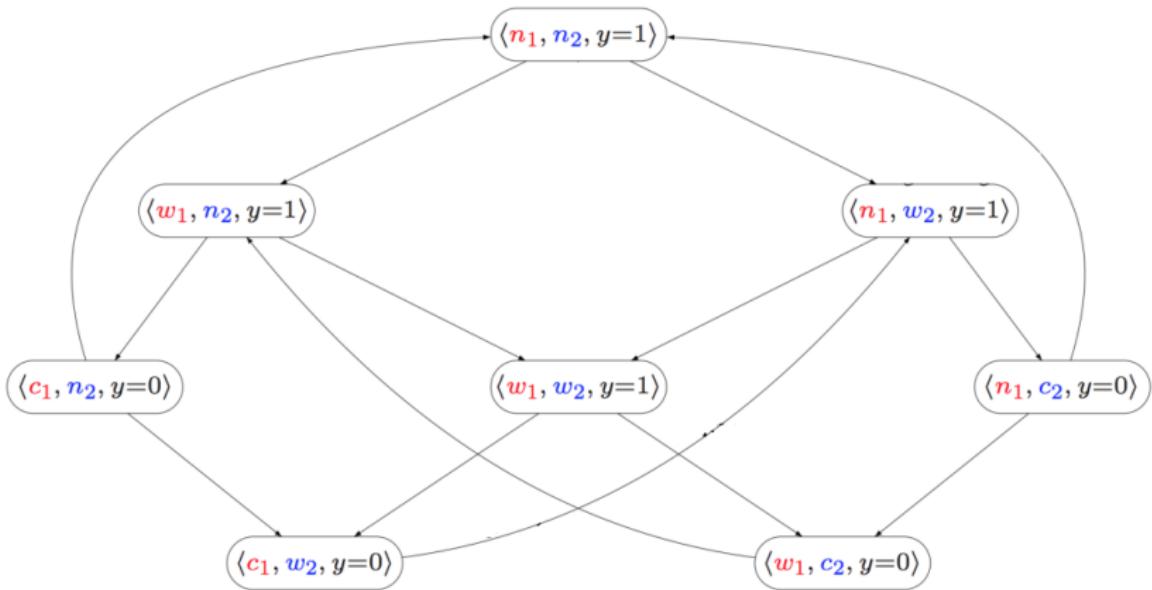
Question 3. Two mathematicians are working on different problems. Sometimes they get hungry and need to eat. However, there is only one (very large) bowl of noodles and only one person can eat at a time. They decide to share a **flag**. When the flag is raised, one person is eating, and the other has to wait. Each mathematician will repeat the following procedures:

```
Work on mathematics  
while flag is raised do  
    Wait to eat  
    Raise the flag  
    Eat!  
    Put down the flag
```

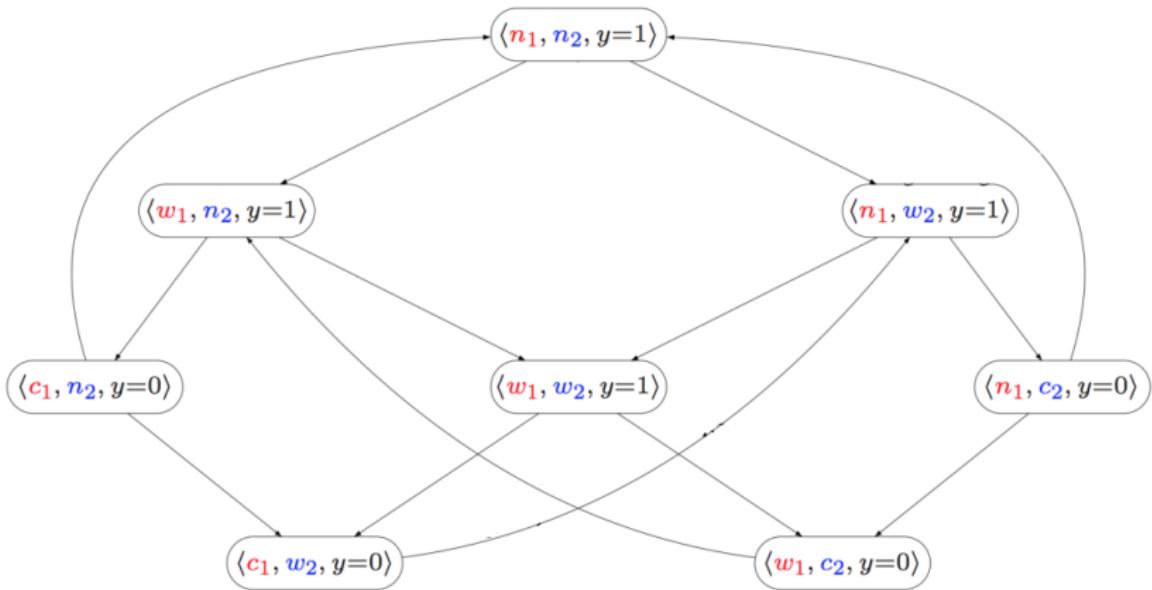


We can represent the situation by a graph:

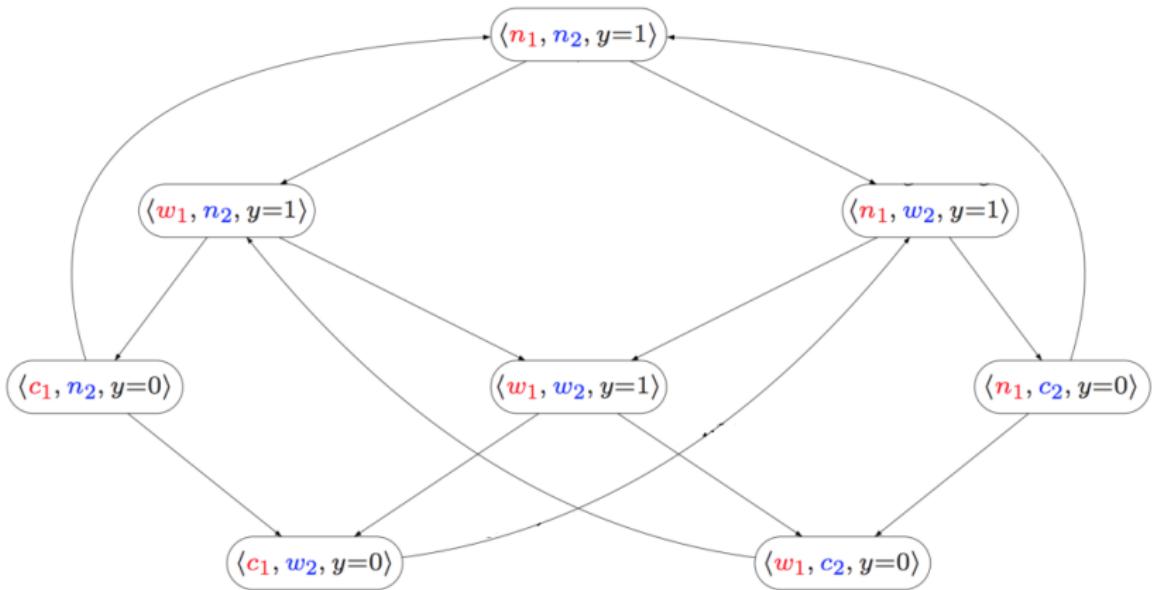
- **States:** A state is a tuple (x_1, x_2, y) where $x_i \in \{n_i, w_i, c_i\}$ denotes the current action of mathematician $i \in \{1, 2\}$, and $y \in \{0, 1\}$ denotes the current state of the flag.
 - n_i : M_i is working
 - w_i : M_i is waiting to eat
 - c_i : M_i is eating
 - $y = 0$: The flag is raised. $y = 1$: The flag is down.
- **Nodes:** The nodes are all states.
- **Edges:** Add a directed edge from one state s_1 to another state s_2 if it is possible to transit from s_1 to s_2 in one step.



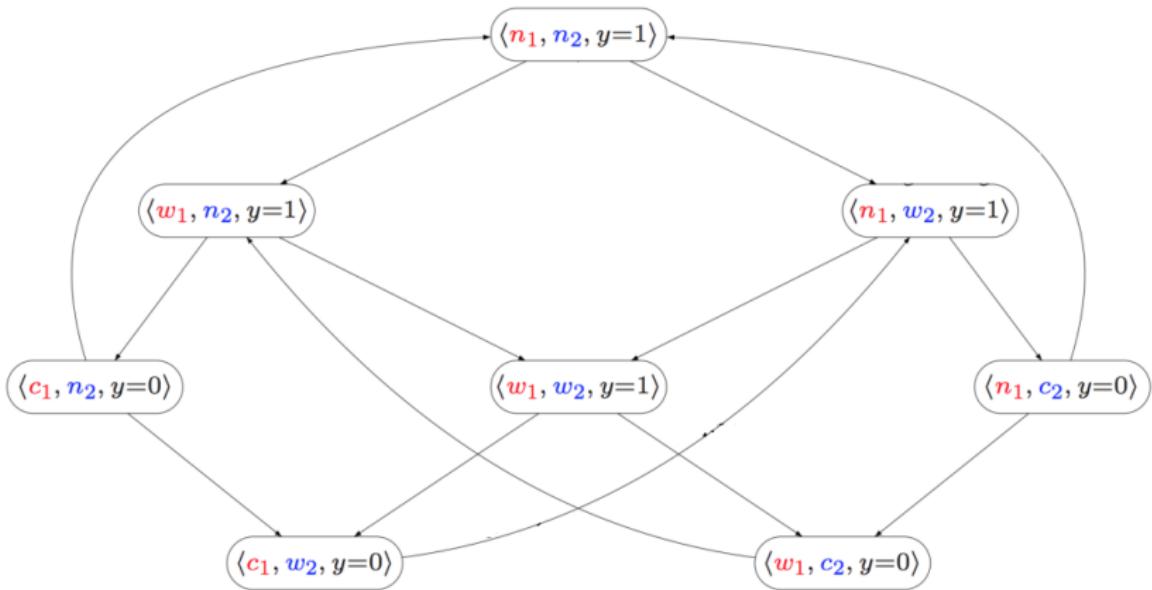
- Is it possible for two mathematicians to eat at the same time?



- Is it possible for two mathematicians to eat at the same time?
No, since there is no state that contains both c_1, c_2 .



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No, since there is no state that contains both c_1, c_2 .
- Is it possible for a mathematician to starve to death?



- Is it possible for two mathematicians to eat at the same time?
No, since there is no state that contains both c_1, c_2 .
- Is it possible for a mathematician to starve to death?
Yes, since there is a circuit in which one mathematician does not eat in any state.

Transition Diagrams

- A (software/hardware) system can be formally represented using a set of states. The operation of the system involve transitions between the states.
- A **transition diagram** is a digraph that represents states of a system and transitions between states.
- The goal is to verify that the system satisfies certain important properties:
 - Certain states will never be achieved.
 - Certain states will be visited repeatedly.
- The field of *formal verification* studies methods of verifying if such properties are met.

Graph as a Data Structure

Graph Representations

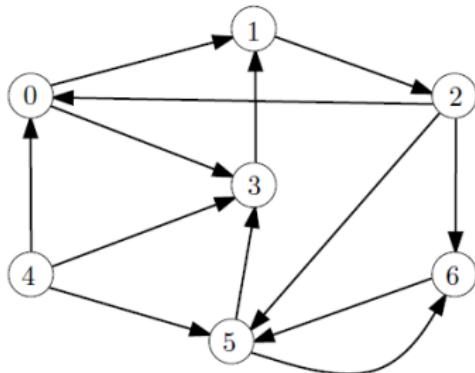
- There are **two** common ways of implementing a graph.
- These two implementations are based on two representations of graphs:
 - 1) **Adjacency matrix**
 - 2) **Adjacency list**
- The performance of the graph operations depends on the type of implementation we adopt.
- When we analyze graph operations, we measure the complexity in terms of the graphs' **order n** and **size m** .

Graph Representations

Suppose G is a digraph with nodes $\{0, 1, 2, \dots, n - 1\}$.

Definition [adjacency matrix]

The **adjacency matrix** of G is the $n \times n$ boolean matrix (encoded using 0,1) such that $(i, j) \in E$ if and only if the entry (i, j) is 1.

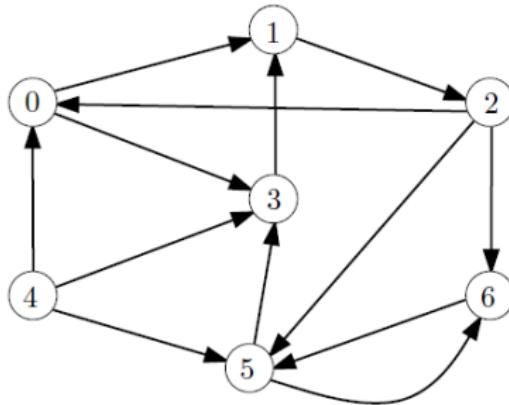


$$\begin{bmatrix} 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

Suppose G is a digraph with nodes $\{0, 1, 2, \dots, n - 1\}$.

Definition [adjacency list]

The **adjacency list** of a digraph G is a list of n lists, L_0, L_1, \dots, L_{n-1} , where the i th list L_i contains all the out-neighbors of node i .



7
1 3
2
0 5 6
1
0 3 5
3 6
5

Note: It is important to keep in mind the representations of graphs when implementing algorithm.

Size of representation

- Adjacency Matrix:
- Adjacency List:

Therefore adjacency list is suitable for **sparse graphs**, i.e., graphs that have must smaller number of edges than n^2 .

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Size of representation

- Adjacency Matrix: $O(n^2)$
- Adjacency List: $O(n + m)$

Therefore adjacency list is suitable for **sparse graphs**, i.e., graphs that have must smaller number of edges than n^2 .

- Basic definition: graph, digraph, multigraph, weighted graph
- Basic terminology: size, order, adjacency, neighbourhood, degree
- Basic graph types: complete graphs, cycles, etc.
- Graphs as models for: network topology, transitions, etc.
- Graph representations: adjacency matrix, adjacency list

