

Week 1

Software testing: process of executing program/system with intent of finding errors

Fault: incorrect portions of code (can be missing as well as incorrect)

Failure: observable correct behaviour of program

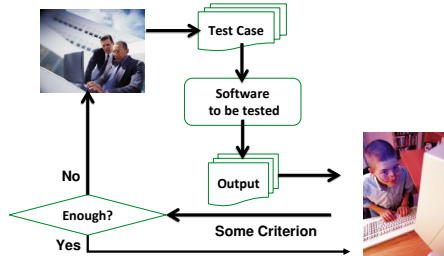
Error: cause of fault, something bad programmer did (conceptual, typo, etc)

Bug: informal term for fault

Test case: set of test inputs, execution conditions, expected results developed for particular objective, such as to exercise particular program path or verify compliance with specific requirement

A Typical Software Testing Process

Test case generation



Testing: find inputs that cause failure of software, failure unknown, performed by testers

Debugging: process of finding & fixing fault given failure, failure is known, performed by devs

Black-Box/Functional Testing: identify functions & design test cases to check whether functions are correctly performed by software (formal & informal specs)

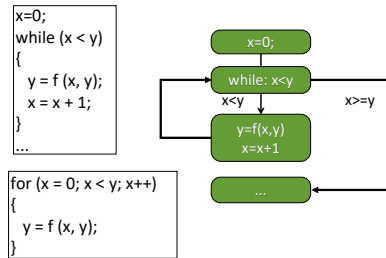
Equivalence partitioning: divide into partitions, select 1 test case from each partition, partitions must be disjointed (no input belongs to more than 1 partition) & all partitions must cover entire input domain

Equivalence partitioning examples: isEven then even & odd, password min 8 & max 12 characters then less than, valid, more than

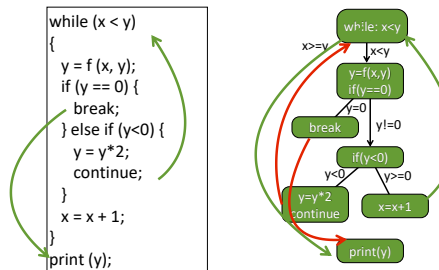
Boundary-Value analysis: partition input domain, identify boundaries, select test data (for range $[R_1, R_2]$ less than R_1 , equal to R_1 , between, equal to R_2 , greater than R_2 , for unordered sets select in & not in, for equality select equal & not equal, for sets, lists select empty & not empty)

White box/structural testing: generate test cases based on program structure, abstract program to control flow graph (node is sequence of statements, edge is transfers of control)

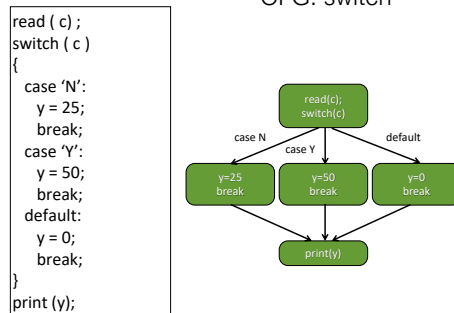
CFG : while and for loops



CFG: break and continue



CFG: switch



Coverage types: statement, branch, path (infinite if loop exists), strictly subsumes all beforehand

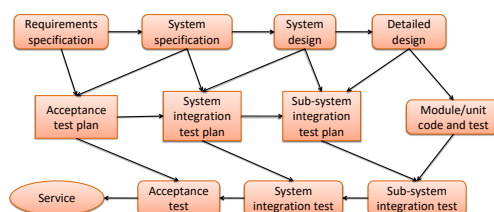
Week 2

Test oracle: expected output of software for given input, part of test case

Test driver: software framework that can load collection of test cases or test suite

Test suite: collection of test cases

The V-model of development



Testing types:

Unit/Module: test single module in isolated environment, use drivers & stubs for isolation

Integration: test parts of system by combining modules, integrated collection of modules tested as group or partial system

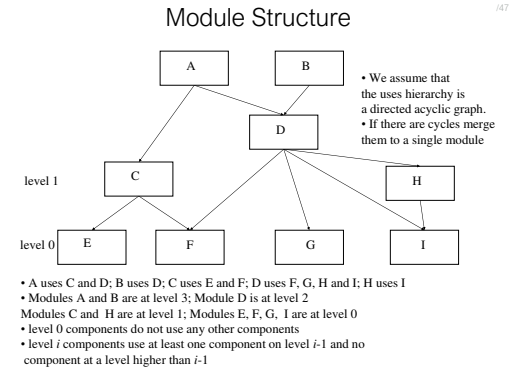
System: test system as a whole after integration phase

Acceptance: test system as a whole to find out if it satisfies requirements specifications

Driver: program that calls interface procedures of module being tested & reports results, simulates module that calls module currently being tested, also provides access to global variables for module under test

Stub: program that has same interface as module being used by module being tested but simpler, simulates module called by module being tested

Mock objects: create object that mimics behaviour needed for testing



Integration types:

Bottom-Up: only terminal modules tested in isolation, requires drivers but not stubs (since lower levels are tested already)

Top-down: modules tested in isolation are modules at highest level, requires stubs but not drivers

Sandwich: begin both bottom-up & top-down, meet at predetermined point in middle

Big bang: every module unit tested, then integrate all at once, no driver or stub needed but may be hard to isolate bugs

System/Acceptance testing: can construct test case based on requirements specifications, main purpose is to assure that system meets requirements, alpha testing performed within development organisation, beta testing performed by select group of friendly customers

Week 3

Basis Path Testing: between branch & path coverage, fulfills branch testing & tests all independent paths that could be used to construct any arbitrary path through computer program

Independent path: includes some vertices/edges not covered in other path

Cyclomatic complexity: $e - n + 2p$, e is edges, n is nodes, p is number of connected components, or $1 + d$, d is loops or decision points, upper bound on number of test cases to guarantee coverage of all statements

Decision Coverage: executing true/false of decision

Condition Coverage: executing true/false of each condition

Condition/Decision Coverage: DC & CC, better than either

Multiple Condition Coverage: whether every possible combination of boolean sub-expressions occurs, test cases are truth table, 2^n test cases for n conditions

Modified C/DC: for each basic condition C , 2 test cases, values of all evaluated conditions except C are the same, compound decision as a while evaluates to true for 1 & false for the other, subsumed by MCC & subsumes CC, DC, C/DC, stronger than statement & branch

MC/DC coverage: each entry & exit point invoked, each decision takes every possible outcome, each condition in a decision takes every possible outcome, each condition in decision is shown to independently affect outcome of decision, independence of condition is shown by proving that only one condition changes at a time

MC/DC: linear complexity

• $N+1$ test cases for N basic conditions

(((a || b) && c) || d) && e

Test Case	a	b	c	d	e	outcome
(1)	true	--	true	--	true	true
(2)	false	true	--	true	true	true
(3)	true	--	false	true	true	true
(4)	true	--	true	--	false	false
(5)	true	--	false	false	--	false
(6)	false	false	--	false	--	false

• Underlined values independently affect the output of the decision

Table 1. Types of Structural Coverage

Coverage Criteria	Statement Coverage	Decision Coverage	Condition Coverage	Condition/Decision Coverage	MC/DC	Multiple Condition Coverage
Every point of entry and exit in the program has been invoked at least once	*	*	*	*	*	*
Every statement in the program has been invoked at least once	*					
Every decision in the program has taken all possible outcomes at least once		*	*	*	*	*
Every condition in a decision in the program has taken all possible outcomes at least once			*	*	*	*
Every condition in a decision has been shown to independently affect that decision's outcome					*	†
Every combination of condition outcomes within a decision has been invoked at least once						*

Week 4

Dataflow Coverage: considers how data gets accessed & modified in system & how it can get corrupted

Common access-related bugs: using undeclared

defined/uninitialized variable, deallocating/reinitialising variable before constructed/initialised/used, deleting collection object leaving members inaccessible

Variable definition: defined whenever value modified (LHS of assignment, input statement, call-by-reference)

Variable use: used whenever value read (RHS of assignment, call-by-value, branch statement predicate)

p-use: use in predicate of branch statement

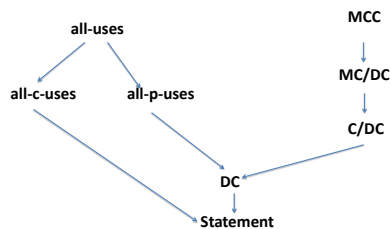
c-use: any other use

Use & redefine in single statement: both sides of assignment, call-by-reference

du-pair: with respect to variable v is a pair (d, u) such that d is a node defining v , u is a node/edge using v (if p-use u is outgoing edge of predicate), there is a def-clear path with respect to v from d to u

Definition clear: with respect to variable v if no variable re-definition of v on path

Relationships among some of the coverage criteria



Week 5

Program mutation: create artificial bugs by injecting changes to statements of programs, simulate subtle bugs in real programs

Mutation testing: software testing technique based on program mutation, can be used to evaluate test effectiveness & enhance test suite, can be stronger than control/data-flow coverage, extremely costly since need to run whole test suite against each mutant

Mutation testing steps: applies artificial changes based on mutation operators to generate mutants (each mutant with only one artificial bug), run test suite against each mutant (if any test fails mutant killed, else survives), compute mutation score

Symbolic execution/evaluation: analyse program to determine what inputs cause each part of program to execute, execute programs with symbols (track symbolic state rather than concrete input, when execute one path actually simulate many test inputs (since considering all inputs that can exercise same path))

Problems with symbolic execution:

Path explosion: 2^n paths for n branches, infinite paths for unbounded loops, calculate constraints for all paths is infeasible for real software

Constraint too complex: especially for large programs, also it is NP-complete

Input sub-domain: set of inputs satisfying path condition

Searching input to execute path: equivalent to solving associated path condition

Example

```

y = read();
p = 1;
while(y < 10){
    y = y + 1;
    if(y > 2)
        p = p + 1;
    else
        p = p + 2;
}
print(p);

```

$y=s$, s is a symbolic variable for input

```

p = 1, y = s
p = 1, y = s
s < 10, y = s + 1, p = 1
2 < s + 1 < 10, y = s + 1, p = 2
s + 1 <= 2, y = s + 1, p = 3

```

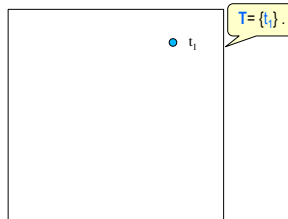
Week 6

Random testing: random number generator (monkeys) to generate test cases, also called fuzz testing, monkey testing, select tests from entire input domain (set of all possible inputs) randomly & independently, no guide towards failure-causing inputs

Adaptive Random Testing: achieve even spread of test cases

Fixed Size Candidate Set ART

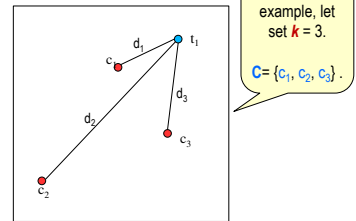
Step 1. Randomly select the first input, namely t_1 , and store it in a list (called T)



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Fixed Size Candidate Set ART (cont.)

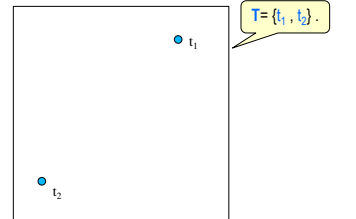
Step 2. Construct k random inputs to form a candidate set $C = \{c_1, c_2, \dots, c_k\}$, and measure their distance to t_1 .



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Fixed Size Candidate Set ART (cont.)

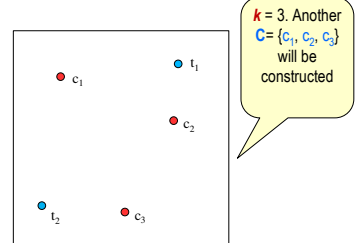
Step 3. Select the candidate which is the farthest away from t_1 to be the next test case. We name it t_2 and store it in T .



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Fixed Size Candidate Set ART (cont.)

Step 4. Re-construct another candidate set C with k random inputs.

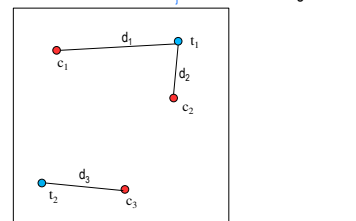


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Fixed Size Candidate Set ART (cont.)

Step 5. For each candidate c_i in C , do the following

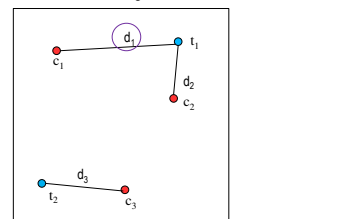
- find which test case in T is the nearest neighbour of c_i
- calculate the distance between c_i and its nearest neighbour.



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Fixed Size Candidate Set ART (cont.)

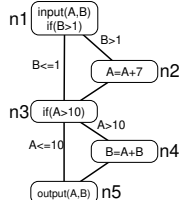
Step 6. Select the candidate with the longest distance to its nearest neighbour.



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Identifying du-pairs – variable A

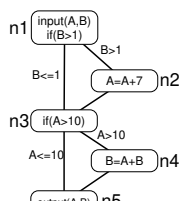
du-pair	path(s)
(1,2)	<1,2>
(1,4)	<1,3,4>
(1,5)	<1,3,4,5>
	<1,3,5>
(1,<3,4>)	<1,3,4>
(1,<3,5>)	<1,3,5>
(2,4)	<2,3,4>
(2,5)	<2,3,4,5>
	<2,3,5>
(2,<3,4>)	<2,3,4>
(2,<3,5>)	<2,3,5>



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Identifying du-pairs – variable B

du-pair	path(s)
(1,4)	<1,2,3,4>
	<1,3,4>
(1,5)	<1,2,3,5>
	<1,3,5>
(1,<1,2>)	<1,2>
(1,<1,3>)	<1,3>
(4,5)	<4,5>



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Dataflow test coverage criteria:

All-Defs: for every variable v , at least one def-clear path from every definition of v to at least one c-use or p-use of v must be covered

All-P/C-Uses: for every variable v , at least one def-clear path from every definition of v to every p/c-use of v must be covered

All-Uses: all du-pairs covered

Notations:

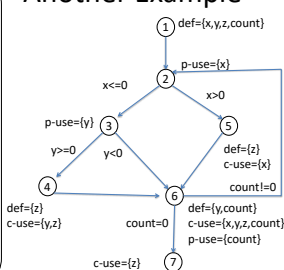
$d_1(x)$: definition of variable x in node i

$u_i(x)$: use of variable x in node i $dcu(d_i(x)) = dcu(x, i)$:

set of c-uses with respect to $d_1(x)$

$dpu(d_i(x)) = dpu(x, i)$: set of p-uses with respect to $d_1(x)$

Another Example



```

1 begin
2 float x,y,z=0.0;
3 int count;
4 input(x,y,count);
5 do{
6 if(x<0){
7 if(y>0){
8 z=y*z+1;
9 }
10 }
11 else{
12 z=1/x;
13 }
14 y=x*y+z;
15 count=count-1;
16 while(count>0)
17 output(z);
18 end

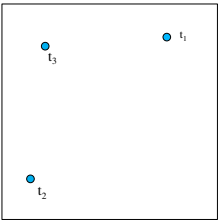
```

All-C-Uses for above: $dcu(x,1) + dcu(y,1) + dcu(y,6) + dcu(z,1) + dcu(z,4) + dcu(z,5) + dcu(count,1) + dcu(count,6) = 2 + 2 + 2 + 3 + 3 + 3 + 1 + 1 = 17$

All-P-Uses for above: $dpu(x,1) + dpu(y,1) + dpu(y,6) + dpu(z,1) + dpu(z,4) + dpu(z,5) + dpu(count,1) + dpu(count,6) = 2 + 2 + 2 + 0 + 0 + 0 + 2 + 2 = 10$ (note this includes using the initial count definition even though it will always be redefined (-1) before the comparison)

Fixed Size Candidate Set ART (cont.)

Step 7. Store the selected candidate in T



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Distance in ART: can use Euclidean distance, if $p = (p_1, p_2, \dots, P_n)$ & $q = (q_1, q_2, \dots, q_n)$ are 2 points in n -dimensional space, $d(p, q) = d(q, p) = \sqrt{(q_1 - p_1)^2 + (q_2 - p_2)^2 + \dots + (q_n - p_n)^2} = \sqrt{\sum_{i=1}^n (q_i - p_i)^2}$

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Algorithm 2:
initial_test_data := randomly generate a test data from the input domain;
selected_set := { initial_test_data };
counter := 1;
total_number_of_candidates := 10;
use initial_test_data to test the program;
if (program output is incorrect) then
 reveal_failure := true;
else
 reveal_failure := false;
end.if
while (not reveal_failure) do
 candidate_set := {};
 test_data := Select.The.Best.Test.Data(selected_set, candidate_set, total_number_of_candidates);
 use test_data to test the program;
 if (program output is incorrect) then
 reveal_failure := true;
 else
 selected_set := selected_set + { test_data };
 counter := counter + 1;
 end.if
end.while
output counter;

ART
Algorithm /2

T. Y. Chen, H. Leung, and I. K. Mak. Adaptive random testing. In Proceedings of the 9th Asian Computing Science Conference, pages 320–329, 2004

Random white-box testing: generate random method invocations & random parameters
Fuzz testing: random testing technique that involves

providing invalid, unexpected or random data as inputs to program, commonly used to discover coding errors & unknown vulnerabilities in software, OS or networks by inputting massive amounts of random data (fuzz) to system in attempt to make it crash, cost-effective alternative to more systematic testing techniques

Fuzz Testing Example /1

- Standard HTTP GET request
 - GET /index.html HTTP/1.1

Anomalous requests:

GET //////////index.html HTTP/1.1
GET %n%n%n%n%n%n%n.html HTTP/1.1
GET /AAAAAAAAAAAAA.html HTTP/1.1
GET /index.html HTTTTTTTTTTTTTP/1.1
GET /index.html HTTP/1.1.1.1.1.1.1.1

Ways to generate inputs:
Mutation based/dumb fuzzing: little/no knowledge of input sctructure assumed, anomalies added to existing valid inputs, may be completely random of follow heuristics (remove NL, shift char forward), get inputs, optionally mutate them, feed it to program, record if it crached & input causing it
Generation based smart fuzzing: test cases generated from some description fo format (RFC, docs, etc), anomalies added to each possible spot in inputs, knowledge of protocol should give better results than random fuzzing
Fuzzing rules of thumb: protocol specific knowledge very helpful (generational tends to beat mutation, better specs make better fuzzers), more fuzzers better (each implementation varies different fuzzers find different bugs), the longer it runs the more bugs found, best results come from guiding process (notice where get stuck, use profiling), code coverage useful for guiding process
Fuzz testing +/-: intuitively simple, but need to figure out how to check the output, corner faults might

escape detection, debugging with randomly generated input is challenging
Search-based testing: deem test case generation as search problem, based on random testing & focus on input domains, use code coverage as guidance (try to generate test case that covers certain code element such as method, statement, branch)
Metaheuristic search:
Hill climbing: start from random point, try all neighboring points, go to point with highest value until all neighboring points have value lower than current point, easy to find local optimal
Annealing simulation: adaptation of hill climbing, has probability to move after reached local peak, probability drops as time goes by
Genetic algorithm: simualte process of evolution, start with random points, select number of best points, combine & mutate points until no more improvements can be made
Transform testing to search: list of random test cases as start point, each test case is point in input domain, use various metaheuristic search algorithms to find test cases, measure how well we have solved the problem (use simeple fitness function, how fat is already covered elements from target code elements, try to make it 0)

An example with hill climbing

- Target is st2
- Start from 0, 0
- f(0, 0) = 10 value gap
- Try (0,1) (1,0), (0,-1), (-1,0)
- Go to (0,1)
- Until reach (0,10)
- f(0,10) = 7 value gap
- Increase x
- Until reach (7,10)
- Done!

