

# Shixun Xu

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## RESEARCH INTERESTS

My research primarily focuses on developing AI algorithms for the management, optimization, and resource allocation of wired and wireless networks. Additionally, I am passionate about constructing AI systems and enabling device-edge-cloud collaboration for AI model deployment.

## EDUCATIONAL BACKGROUND

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|---|---|--|
| <b>Master's Degree</b>                                      | <b>Beijing University of Posts and Telecommunications</b> | 09.2022-06.2025                                      |
| <i>Information and Communication Engineering</i>            | <b>GPA: 3.57/4.00</b>                                     | <b>Weighted Average: 87.89/100</b>                   |
| <b>Bachelor's Degree</b>                                    | <b>Shanxi University</b>                                  | 09.2018-07.2022                                      |
| <i>Science and Technology of Electronic and Information</i> | <b>GPA: 4.07/4.50</b>                                     | <b>Weighted Average: 91.38/100</b> <b>Rank: 1/70</b> |

## PUBLICATIONS

- [1] Bing Shen, **Shixun Xu (equal contribution as co-first author)**, Xiaofeng Lu, et al., “**Research on Resource Allocation and Trajectory Optimization Based on C-DON in UAV**,” *Journal of Test and Measurement Technology*, vol. 36, no.2, pp. 141-146, 2022. (Published in Chinese)
- [2] **Shixun Xu**, Ao Zhang, Wenxuan Song, et al., “**Challenges and Crucial Technologies of Industrial Computing-First Network**,” *Automation Panorama*, vol. 10, no. 2, pp. 50-54, 2023. (Published in Chinese)
- [3] **Shixun Xu**, Fangmin Xu, Chenglin Zhao, et al., “**Routing Optimization and Wireless Resource Allocation in a Smart Production Network Enabled by Computing Power Network and Digital Twin**,” *IEEE Transactions on Network and Service Management*. (Under Review)

## Research Experience

### Secure Communication Between a UAV and a Vehicle through a Physical Layer Method:

- Constructed a combinational optimization problem based on the safe rate of the UAV-to-Vehicle communication.
- Designed a curiosity-driven deep Q-learning algorithm to jointly plan the flying trajectory of the UAV and the ratio of the communication power to the interference power of the UAV.

### An End-to-end Self-driving Strategy:

- Created a labeled manned-driving dataset through the CARLA platform and separated it uniformly into several parts to simulate distributed data.
- Trained an end-to-end self-driving model through a conditional imitation learning algorithm in a federated learning framework and tested the performance of the trained model in the CARLA platform.

### A Node Detection Algorithm to Maintain the Member List in a Computer Network:

- Designed a node detection algorithm based on the process of rumor spreading.

## Professional Tools or Skills

**Language:** CET4: 651, CET6: 585. (IELTS is under preparation)

**IDE:** Pycharm, MATLAB, Keil.

**Programming Language:** Python, C, Verilog, LaTeX.

**Framework:** TensorFlow 1.x, TensorFlow 2.x, PyTorch, Numpy, Pandas.

**Mathematic Tools:** Deep reinforcement learning, deep learning, heuristic algorithms, KKT condition, Kalman filter estimation, etc.