# Xiaorui Gu

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#### Education

## University of Illinois Urbana-Champaign

August 2021 - May 2025

Bachelor of Science, Mechanical Engineering | GPA 3.72/4.00

## **Northwestern University**

Incoming, August 2025

Master of Science, Electrical Engineering

## **Experience**

## **Mobility and Fall Prevention Research Laboratory**

June 2024 - February 2025

Carle Illinois College of Medicine, Research Intern (Hardware)

- Advisor: Dr. Manuel E. Hernandez, Carle Illinois College of Medicine
- Developed a piezoresistive pressure sensor array, achieving high sensitivity and durability for walking pattern analysis.
- Designed an interactive LED-based visual aid synchronized with a mobile device UI.
- Tested firmware for precise data acquisition, ensuring reliable sensor integration into the system.

# **Bahl Research Group**

August 2023 – January 2025

University of Illinois Urbana-Champaign, Undergraduate Lab Assistant

- Advisor: Dr. Gaurav Bahl, Department of Mechanical Science & Engineering
- Designed and constructed experimental setups for a fully levitated 6-DOF system, enabling advanced wireless signal generation.
- Provided manufacturing support across semesters, including CAD, 3D printing, laser cutting, water jet cutting, and PCB soldering.

Garg Group May 2023 – March 2025

University of Illinois Urbana-Champaign, Undergraduate Research Assistant

- Advisor: Dr. Nishant Garg, Department of Civil & Environmental Engineering
- Investigated a 3D reconstruction pipeline using OpenCV and Open3D for measuring concrete flow motion.
- Prototyped a micrometer-scale displacement sensor based on capacitance-to-digital converters and analyzed failure reasons.
- Implemented a sensor array for temperature and humidity monitoring (through I2C), integrating data collection with Firebase.

## **Project**

## Autonomous Driving with Static & Dynamic Obstacle Avoidance

January 2025 – Present

Project Team: SafeTaxi, ECE484: Principles of Safe Autonomy, University of Illinois Urbana-Champaign

• Developed vision-LiDAR fusion algorithms for lane following and various obstacle avoidance scenarios, using the International F1TENTH Autonomous Racing Competition platform powered by NVIDIA Jetson NX.

#### Skills

**Programming** - Python, C++, Java, MATLAB **Frameworks & Libraries** - PyTorch, OpenCV, ROS, Gazebo, Rviz **CAD & Simulation** - KiCAD, Fusion 360, SolidWorks, SiemensNX

## **Publication**

Gu, X., Gupta, P., Liu, J., Zhou, H., Cisto, B., Khan, M.A., Mason, S., Motl, R., Sebastiao, E., & Hernandez, M. E. (2025). Intelligent square stepping exercise system for cognitive-motor rehabilitation in older adults with multiple sclerosis. Proceedings of the 2025 Design of Medical Devices Conference; (In press).

## **Honors**

James Scholar, University of Illinois Urbana-Champaign Division of General Studies (2022), Grainger College of Engineering (2023–2025)