

# 实验过程

- **First Fit (FF)**

## 算法思想

在 First Fit 算法中，分配器会扫描空闲块列表，找到第一个足够大的空闲块，并将其分配出去。如果该空闲块大于请求的内存，则会分割该块。

## 优缺点

- **优点:** 查找速度相对较快，因为一旦找到合适的空闲块，立即停止搜索。
- **缺点:** 容易导致内存碎片，特别是外部碎片。

## 提高查找性能

在本次实验中好像并无。

- **Best Fit (BF)**

## 算法思想

Best Fit 算法在所有的空闲块中找到与请求最匹配（即最接近）的空闲块。这通常需要扫描整个空闲块列表。

## 优缺点

- **优点:** 最小化了每次分配后的剩余空间，从而减少了浪费。

- **缺点:** 查找性能较差，因为通常需要扫描整个列表；可能导致更多小的空闲块，进而增加碎片。

提高查找性能

维护一个按照大小排序的空闲块列表来提高查找性能。

- **Worst Fit (WF)**

算法思想

Worst Fit 算法选择最大的可用空闲块进行分配，假设剩下的空间可能更有用。

优缺点

- **优点:** 理论上，选择最大的空闲块应该能减少碎片。
- **缺点:** 在实践中，通常并不比其他算法好，查找性能也通常是最差的。

提高查找性能

维护一个按大小排序的空闲块列表来提高查找性能。

对于FF的空闲块排序（事实上是不需要排序的，因为无论如何排列，只要找到第一个可用的就行），对于BF、WF我采用了相同的排序算法——归并排序，这是一种稳定的且速度极快的排序算法，对于提升内存分配速率有很大作用。

- 内碎片

由于我们对于最小碎片长度有要求，一个空闲块的大小enough但是并不sufficient。比如在我们的实验中最小的碎片长度为10，一个空闲块大小为28，现在要给他分配一个20大小的proc，只能剩下8，如果被切出，不符合要求，因此28要一次性分配给proc。（此时proc的size是否应该保持为request\_size（20）而不是28？我个人认为要记录为28，无论这8个空间是否被proc使用，但是其所“占用”的就是这么大，对于其他proc的影响也是这么大）

- 外碎片

由于我们的多次申请空间释放空间导致的长度小于最小值的碎片。例如经过一系列行为，导致701—705的空间为free的，但是显然这部分空间永远无法被使用到。

内存紧缩解决的就是这种碎片。

- 回收内存时。空闲块合并主要是通过insertion sort实现，根据空闲块的地址排序，如果空闲块的内存是连续的，那就将其合并为一个块。

代码实现：

```
#include <stdio.h>
#include <stdlib.h>

#define PROCESS_NAME_LEN 32
#define MIN_SLICE 10
```

```
#define DEFAULT_MEM_SIZE 1024
#define DEFAULT_MEM_START 0

#define MA_FF 1
#define MA_BF 2
#define MA_WF 3

#include "2.3.h"

struct free_block_type {
    int size;
    int start_addr;
    struct free_block_type *next;
};
struct free_block_type *free_block = NULL;

struct allocated_block {
    int pid;
    int size;
    int start_addr;
    char process_name[PROCESS_NAME_LEN];
    struct allocated_block *next;
};
struct allocated_block
*allocated_block_head = NULL;

int allocate_mem(struct allocated_block
*ab);
void kill_process();
```

```

struct allocated_block *find_process(int
pid);
void free_mem(struct allocated_block *ab);
void dispose(struct allocated_block
*free_ab);
void kill_block(struct allocated_block
*ab);
void display_mem_usage();
void set_mem_size();
void set_algorithm();
void display_menu();
void new_process();
void rearrange(int algorithm);
void sort_free_blocks();
void compact();
void memory_compaction();
void do_exit();
int mem_size = DEFAULT_MEM_SIZE;
int ma_algorithm = MA_FF;
static int pid = 0;
int flag = 0;

struct free_block_type *init_free_block(int
mem_size) {
    struct free_block_type *fb;
    fb = (struct free_block_type
*)malloc(sizeof(struct free_block_type));
    if (fb == NULL) {
        printf("No mem\n");
        return NULL;
    }
}

```

```
    }  
    fb->size = mem_size;  
    fb->start_addr = DEFAULT_MEM_START;  
    fb->next = NULL;  
    return fb;  
}
```

```
void set_mem_size() {  
    int size;  
    if (flag != 0) {  
        printf("Cannot set memory size  
again\n");  
        return;  
    }  
    printf("set memory_size to: ");  
    scanf("%d", &size);  
    if (size > 0) {  
        mem_size = size;  
        free_block->size = mem_size;  
    }  
    flag = 1;  
}
```

```
void set_algorithm() {  
    int algorithm;  
    printf("\t1 - First Fit\n");  
    printf("\t2 - Best Fit \n");  
    printf("\t3 - Worst Fit \n");  
    scanf("%d", &algorithm);
```

```

    if (algorithm >= MA_FF && algorithm <=
MA_WF) {
        ma_algorithm = algorithm;
    }
    rearrange(ma_algorithm);
}

```

```

struct free_block_type *merge(struct
free_block_type *a,
                                struct
free_block_type *b, int criterion) {
    struct free_block_type dummy;
    struct free_block_type *current = &dummy;
    if (criterion == MA_BF) {
        while (a && b) {
            if (a->size < b->size) {
                current->next = a;
                a = a->next;
            } else {
                current->next = b;
                b = b->next;
            }
            current = current->next;
        }
        current->next = a ? a : b;
    } else if (criterion == MA_WF) {
        while (a && b) {
            if (a->size > b->size) {
                current->next = a;
                a = a->next;
            }
        }
    }
}

```

```

        } else {
            current->next = b;
            b = b->next;
        }
        current = current->next;
    }
    current->next = a ? a : b;
}
return dummy.next;
}

struct free_block_type *mergeSort(struct
free_block_type *head, int criterion) {
    if (!head || !head->next) return head;

    struct free_block_type *a = head, *b =
head->next;
    while (b && b->next) {
        head = head->next;
        b = b->next->next;
    }
    b = head->next;
    head->next = NULL;

    return merge(mergeSort(a, criterion),
mergeSort(b, criterion), criterion);
}

void rearrange_FF() { return; }
void rearrange_BF() { free_block =
mergeSort(free_block, MA_BF); }

```



```

void rearrange_WF() { free_block =
mergeSort(free_block, MA_WF); }
void rearrange(int algorithm) {
    switch (algorithm) {
        case MA_FF:
            rearrange_FF();
            break;
        case MA_BF:
            rearrange_BF();
            break;
        case MA_WF:
            rearrange_WF();
            break;
        default:
            printf("Invalid algorithm.\n");
    }
}

void sort_free_blocks() {
    // insertion sort
    struct free_block_type *current, *next,
    *tmp, *pre;

    if (!free_block || !free_block->next)
return;

    current = free_block->next;
    free_block->next = NULL;

    while (current) {

```

```

    pre = NULL;
    next = current->next;

    tmp = free_block;
    while (tmp->next && tmp->next-
>start_addr < current->start_addr) {
        pre = tmp;
        tmp = tmp->next;
    }
    if (!pre) {
        current->next = free_block;
        free_block = current;
    } else {
        current->next = pre->next;
        pre->next = current;
    }
    current = next;
}
}

```

```

int allocate_mem(struct allocated_block
*ab) {

```

```

    struct free_block_type *fb, *pre;

```

```

    int request_size = ab->size;

```

```

    fb = pre = free_block;

```

```

    int total_free_size = 0;

```

// 根据当前算法在空闲分区链表中搜索合适空闲分区进行分配，分配时注意以下情况：

```

    while (fb) {

```

```

    if (fb->size - request_size >=
MIN_SLICE) {
        // 1. 找到可满足空闲分区且分配后剩余空间足
        够大，则分割
        ab->start_addr = fb->start_addr;
        ab->size = request_size;
        fb->start_addr += request_size;
        fb->size -= request_size;
        goto success;
    } else if (fb->size >= request_size) {
        // 2. 找到可满足空闲分区且但分配后剩余空间
        比较小，则一起分配
        ab->start_addr = fb->start_addr;
        ab->size = fb->size;
        pre->next = fb->next;
        free(fb);
        goto success;
    } else {
        total_free_size += fb->size;
        pre = fb;
        fb = fb->next;
    }
}

if (total_free_size >= request_size) {
    memory_compaction();
    // 3.
    // 找不可满足需要的空闲分区但空闲分区之和能满
    足需要，则采用内存紧缩技术，进行空闲分区的合并，然后
    再分配
    fb = pre = free_block;

```

```

    while (fb) {
        if (fb->size - request_size >=
MIN_SLICE) {
            ab->start_addr = fb->start_addr;
            ab->size = request_size;
            fb->start_addr += request_size;
            fb->size -= request_size;
            goto success;
        } else if (fb->size >= request_size)
        {
            ab->start_addr = fb->start_addr;
            ab->size = fb->size;
            pre->next = fb->next;
            free(fb);
            goto success;
        } else {
            pre = fb;
            fb = fb->next;
        }
    }
    return -1;

```

success:

```

    rearrange(ma_algorithm);
    return 1;

```

// 4. 在成功分配内存后，应保持空闲分区按照相应算法有序

```

    // 5. 分配成功则返回1，否则返回-1

```

```

}

```

```

void memory_compaction() {
    // Step 1: 将所有已分配的块移动到内存的起始地址
    int new_start_addr = 0;
    struct allocated_block *cur =
allocated_block_head;
    while (cur) {
        cur->start_addr = new_start_addr;
        new_start_addr += cur->size;
        cur = cur->next;
    }
    // Step 2: 释放所有旧的空闲块
    struct free_block_type *fb = free_block;
    while (fb) {
        struct free_block_type *tmp = fb;
        fb = fb->next;
        free(tmp);
    }

    // Step 3: 创建一个新的空闲块，其起始地址为最后
    一个已分配块的结束地址
    free_block = (struct free_block_type
*)malloc(sizeof(struct free_block_type));
    free_block->start_addr = new_start_addr;
    free_block->size = mem_size -
new_start_addr;
    free_block->next = NULL;
}

void new_process() {
    struct allocated_block *ab;

```

```

    int size;
    int ret;
    ab = (struct allocated_block
*)malloc(sizeof(struct allocated_block));
    if (!ab) exit(-5);
    ab->next = NULL;
    pid++;
    sprintf(ab->process_name, "PROCESS-%02d",
pid);
    ab->pid = pid;
    printf("Memory for %s: ", ab-
>process_name);
    scanf("%d", &size);
    if (size > 0) ab->size = size;
    ret = allocate_mem(ab);
    if ((ret == 1) && (allocated_block_head
== NULL)) {
        allocated_block_head = ab;
    } else if (ret == 1) {
        ab->next = allocated_block_head;
        allocated_block_head = ab;
    } else if (ret == -1) {
        printf("Allocation fail\n");
        free(ab);
    }
}

void kill_process() {
    struct allocated_block *ab;
    int pid;

```

```

printf("kill Process, pid=");
scanf("%d", &pid);
ab = find_process(pid);
if (ab != NULL) {
    free_mem(ab); /*释放ab所表示的分配区*/
    dispose(ab); /*释放ab数据结构节点*/
}
}

void free_mem(struct allocated_block *ab) {
    int algorithm = ma_algorithm;
    struct free_block_type *fb;
    fb = (struct free_block_type
*)malloc(sizeof(struct free_block_type));
    if (!fb) {
        printf("malloc fail in free_mem\n");
        return;
    }
    fb->size = ab->size;
    fb->start_addr = ab->start_addr;
    fb->next = free_block;
    free_block = fb;
    sort_free_blocks();
    compact();
    rearrange(ma_algorithm);
    // 进行可能的合并，基本策略如下
    // 1. 将新释放的结点插入到空闲分区队列末尾 I
choose the head not end.
    // 2. 对空闲链表按照地址有序排列
    // 3. 检查并合并相邻的空闲分区
    // 4. 将空闲链表重新按照当前算法排序

```

```

}
void dispose(struct allocated_block
*free_ab) {
    struct allocated_block *pre, *ab;
    if (free_ab == allocated_block_head) { /*
如果要释放第一个节点*/
        allocated_block_head =
allocated_block_head->next;
        free(free_ab);
        return;
    }
    pre = allocated_block_head;
    ab = allocated_block_head->next;
    while (ab != free_ab) {
        pre = ab;
        ab = ab->next;
    }
    pre->next = ab->next;
    free(ab);
}

void compact() {
    struct free_block_type *fb = free_block;
    struct free_block_type *next = NULL;

    while (fb && fb->next) {
        next = fb->next;
        if (fb->start_addr + fb->size == next-
>start_addr) {
            fb->size += next->size;

```



```

        fb->next = next->next;
        free(next);
    } else {
        fb = fb->next;
    }
}
}

```

```

struct allocated_block *find_process(int
pid) {
    struct allocated_block *ab =
allocated_block_head;
    while (ab != NULL) {
        if (ab->pid == pid) {
            return ab;
        }
        ab = ab->next;
    }
    return NULL;
}

```

```

void kill_block(struct allocated_block *ab)
{
    struct allocated_block *pre_ab =
allocated_block_head;
    if (ab == allocated_block_head) {
        allocated_block_head = ab->next;
        free(ab);
        return;
    }
}

```

```

while (pre_ab) {
    if (pre_ab->next == ab) {
        pre_ab->next = ab->next;
        free(ab);
        return;
    }
    pre_ab = pre_ab->next;
}

void display_mem_usage() {
    struct free_block_type *fbt = free_block;
    struct allocated_block *ab =
allocated_block_head;

    if (fbt == NULL) {
        printf("No free memory blocks\n");
        return;
    }

    printf("-----
-----\n");
    printf("Free Memory:\n");
    printf("%20s %20s\n", "start_addr",
"size");
    while (fbt != NULL) {
        printf("%20d %20d\n", fbt->start_addr,
fbt->size);
        fbt = fbt->next;
    }
}

```

```

printf("\nUsed Memory:\n");
printf("%10s %20s %10s %10s\n", "PID",
"ProcessName", "start_addr", "size");
while (ab != NULL) {
    printf("%10d %20s %10d %10d\n", ab-
>pid, ab->process_name, ab->start_addr,
        ab->size);
    ab = ab->next;
}

printf("-----
-----\n");
}

```

```

int main() {
    char choice;
    pid = 0;
    free_block = init_free_block(mem_size);
    // 初始化空闲区
    while (1) {
        display_menu();
        fflush(stdin);
        choice = getchar();
        switch (choice) {
            case '1':
                set_mem_size();
                break;
            case '2':
                set_algorithm();
                flag = 1;

```

```

        break;
    case '3':
        new_process();
        flag = 1;
        break;
    case '4':
        kill_process();
        flag = 1;
        break;
    case '5':
        display_mem_usage();
        flag = 1;
        break;
    case '0':
        do_exit();
        exit(0);
    default:
        break;
    }
}
}

void display_menu() {
    printf("\n");
    printf("1 - Set memory size\n");
    printf("2 - select memory allocation\n");
    printf("3 - New process\n");
    printf("4 - Terminate a process\n");
}

```

```
printf("5 - Display memory usage \n");
printf("0 - Exit\n");
}

void do_exit() {
    struct allocated_block *ab =
allocated_block_head;
    while (ab) {
        allocated_block_head = ab->next;
        free(ab);
        ab = allocated_block_head;
    }
    struct free_block_type *fb = free_block;
    while (fb) {
        free_block = fb->next;
        free(fb);
        fb = free_block;
    }
}
```