

### Problem 1

(1).  $\alpha_1 = 2[1 - \Phi(k)] = 0.0027$

$\alpha_2 = 0.001$

(2)  $ARL_1 = \frac{1}{\alpha} = 370$

$ARL_2 = \frac{1}{\alpha} = 1000$

(3). mean change = 104 mm      1  $\sigma$  mean shift.

$\beta_1 = \Pr\{LCL \leq \bar{X} \leq UCL \mid \bar{X} \sim N(\mu_1, \sigma_0^2/n)\}$

$= \Pr\{LCL \leq \bar{X} \leq UCL \mid \bar{X} \sim N(\mu_0, \sigma_0^2/n)\} = \Pr\{\mu_0 - k\sigma_0/\sqrt{n} \leq \bar{X} \leq \mu_0 + k\sigma_0/\sqrt{n} \mid \bar{X} \sim N(\mu_0, \sigma_0^2/n)\}$

$= \Pr\left\{\frac{(\mu_0 - k\sigma_0/\sqrt{n}) - \mu_1}{\sigma_0/\sqrt{n}} \leq \frac{\bar{X} - \mu_1}{\sigma_0/\sqrt{n}} \leq \frac{(\mu_0 + k\sigma_0/\sqrt{n}) - \mu_1}{\sigma_0/\sqrt{n}}\right\}$

$= \Pr\left\{-k - \frac{\delta}{\sigma_0/\sqrt{n}} \leq Z \leq k - \frac{\delta}{\sigma_0/\sqrt{n}}\right\}$

$= \Phi\left(k - \frac{\delta}{\sigma_0/\sqrt{n}}\right) - \Phi\left(-k - \frac{\delta}{\sigma_0/\sqrt{n}}\right) = \Phi\left(3 - \frac{60}{2}\right) - \Phi\left(-3 - \frac{60}{2}\right)$

$= \Phi(-1) - \Phi(-7) = 0.1586$

$\beta_2 = \Phi\left(k - \frac{\delta}{\sigma_0/\sqrt{n}}\right) - \Phi\left(-k - \frac{\delta}{\sigma_0/\sqrt{n}}\right)$

$2[1 - \Phi(k)] = 0.001 \quad \Phi(k) = 0.9995 \quad k \approx 3.2$

$\therefore \beta_2 = \Phi(k - 5) - \Phi(-k - 5) = 0.04368$

(4)  $ARL_{out1} = \frac{1}{1 - \beta_1} = 1.18$

$ARL_{out2} = \frac{1}{1 - \beta_2} = 1.0456$

(5) option 1 :

Pros: With smaller sample sizes, the chart can quickly signal an out-of-control condition, allowing for rapid response.

Cons: 3-sigma limits are quite wide, leading to a higher risk of Type I errors when the process is actually in control.

Option 2 :

Pros: The probability limits allow for a more controlled Type I error rate, reducing the risk of false alarms compared to the 3-sigma limits.

Cons: The larger sample size may result in a slower response to change in the process.

Problem 2.

(1) Since  $n=1$ , So we can only use  $\bar{X}(I)$ -MR chart.

(2)

### Problem 3.

$$(1). k=3, n=6. \quad \sum_{i=1}^{30} \bar{X}_i = 6000 \quad \& \quad \sum_{i=1}^{30} R_i = 150 \Rightarrow \bar{\bar{X}} = 200; \bar{\bar{R}} = 50.$$

$$\text{For } \bar{X} \quad \left\{ \begin{array}{l} UCL = \bar{\bar{X}} + A_2 \bar{\bar{R}} = 200 + 0.483 \times 5 = 202.415 \\ CL = \bar{\bar{X}} = 200 \\ LCL = \bar{\bar{X}} - A_2 \bar{\bar{R}} = 200 - 0.483 \times 5 = 197.585 \end{array} \right.$$

$$\text{For } R: \quad \left\{ \begin{array}{l} UCL = D_4 \bar{\bar{R}} = 2.004 \times 5 = 10.02. \\ CL = \bar{\bar{R}} = 5 \\ LCL = D_3 \bar{\bar{R}} = 0. \end{array} \right.$$

$$(2) \quad \mu = 200 \quad \sigma = \frac{\bar{R}}{d_2} = \frac{5}{2.534} = 1.97$$

$$(3). \text{ shift } \sigma = \frac{200 - 199}{1.97} \approx 0.5068.$$

$$P = \Phi(k - 8\sqrt{n}) - \Phi(-k - 8\sqrt{n}) \approx 0.9606$$

### Problem 4

$$(1) \quad \mu = 10, \sigma = 2.5, n = 6.$$

$$\text{For } \bar{X} \text{ chart: } \left\{ \begin{array}{l} UCL = B_6 \sigma_0 = 2.088 \times 2.5 = 5.22 \\ CL = C_4 \sigma_0 = 0.9213 \times 2.5 = 2.30325 \\ LCL = B_1 \sigma_0 = 0. \end{array} \right.$$

$$(2) \text{ For } S \text{ chart: } \left\{ \begin{array}{l} UCL = C_{u6} \sigma_0 + 2.6 \sigma_0 \sqrt{1 - C_{u4}^2} = 0.9213 \times 2.5 + 3 \times 2.5 \sqrt{1 - (0.9213)^2} = 4.2475 \\ CL = C_6 \sigma_0 = 0.9213 \times 2.5 = 2.303 \\ LCL = C_{l6} \sigma_0 - 2.6 \sigma_0 \sqrt{1 - C_{l4}^2} = 0.9213 \times 2.5 + 3 \times 2.5 \sqrt{1 - (0.9213)^2} = 0.3595 \end{array} \right.$$

Problem 5:

$$(1) \quad \sigma \approx \frac{\bar{s}}{c_4} = \frac{0.322}{0.9400} = 0.3460$$

$$(2) \quad \text{For } \bar{x} \text{ chart: } \begin{cases} UCL = 1.9697 \\ CL = 1.5056 \\ LCL = 1.0415 \end{cases}$$

$$(3) \quad \text{For } s \text{ chart: } \begin{cases} UCL = 0.6794 \\ CL = 0.3252 \\ LCL = 0.0 \end{cases}$$

(4) There is one point out of control

(5) There is no point out of control.

(6)  $\bar{x}$  charts have a narrow limit while  $x-s$  charts have a wider limit.

So  $\bar{x}$  charts is more sensitive to changes in process variability.

Besides, mean values are consistent in both charts, indicate that process central tendency is stable. So  $\bar{x}$  chart is more accurate in reflecting changes.