

# Further Mathematics Notes - Core Pure

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2024

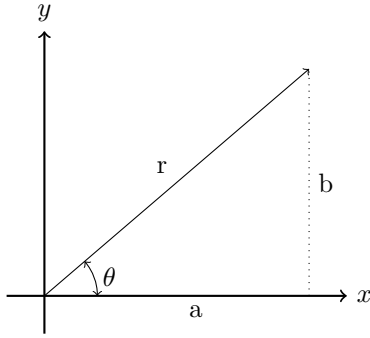
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# 1 Proof

## 2 Complex numbers

### 2.1 Forms expressing complex number



#### 2.1.1 Cartesian form

$$z = a + bi$$

$$\operatorname{Re}(z) = a, \operatorname{Im}(z) = b$$

$$|z| = \sqrt{a^2 + b^2}$$

#### 2.1.2 Polar form

$$z = (r, \theta)$$

$$r = \sqrt{a^2 + b^2}, \theta = \arg(z)$$

$$a = r \cos \theta, b = r \sin \theta, \tan \theta = \frac{b}{a}$$

$$z = r \cos \theta + r \sin \theta i = r(\cos \theta + \sin \theta i) = r \operatorname{cis} \theta$$

#### 2.1.3 Exponential / Euler form

$$z = re^{i\theta}$$

### 2.2 Calculations

$$\bullet z_1 z_2 = r_1 r_2 \operatorname{cis}(\theta_1 + \theta_2) = r_1 r_2 e^{i(\theta_1 + \theta_2)}$$

$$\bullet \frac{z_1}{z_2} = \frac{r_1}{r_2} \operatorname{cis}(\theta_1 - \theta_2) = \frac{r_1}{r_2} e^{i(\theta_1 - \theta_2)}$$

$$\bullet z^n = r^n \operatorname{cis}(n\theta) = r^n e^{i n \theta}$$

$$\bullet \sqrt[n]{z} = \sqrt[n]{r} \operatorname{cis}\left(\frac{\theta + 2k\pi}{n}\right) = \sqrt[n]{r} e^{i \frac{\theta + 2k\pi}{n}} \quad (k = 0, 1, 2, \dots, n-2, n-1)$$

$$\bullet \sqrt{a + ib} = \pm \left( \sqrt{\frac{|z| + a}{2}} + i \frac{b}{|b|} \sqrt{\frac{|z| - a}{2}} \right)$$

$$\bullet \arg(z_1 z_2) = \arg(z_1) + \arg(z_2)$$

$$\bullet \arg\left(\frac{z_1}{z_2}\right) = \arg(z_1) - \arg(z_2)$$

## 3 Matrices

### 3.1 Finding determinants

### 3.2 Finding inverse matrices

$2 \times 2$  matrices:

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$3 \times 3$  matrices:

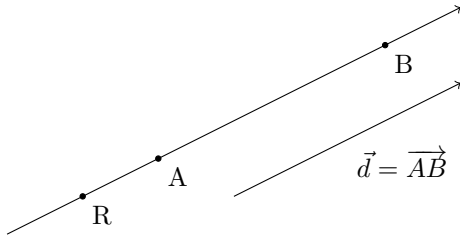
## 4 Further algebra and functions

### 4.1 Vieta's Law

## 5 Further calculus

## 6 Further vectors

### 6.1 Expressing linear equations



#### 6.1.1 Vector form

$$\vec{r} = \vec{a} + t\vec{d} \text{ or } (\vec{r} - \vec{a}) \times \vec{d} = 0 \text{ / } (\vec{r} - \vec{a}) \times \vec{b} = 0$$

#### 6.1.2 Parametric form

$$\begin{cases} x = x_0 + tu \\ y = y_0 + tv \\ z = z_0 + tw \end{cases}$$

#### 6.1.3 Cartesian form

$$\frac{x - x_0}{u} = \frac{y - y_0}{v} = \frac{z - z_0}{w} (= t)$$

### 6.2 Expressing planes

#### 6.2.1 Vector form

$$\vec{r} \cdot \vec{n} = \vec{r} \cdot \vec{a} \text{ } (\vec{n} = \text{normal}, \vec{a} = \text{a point on plane})$$

#### 6.2.2 Parametric form

$$\vec{r} = \vec{a} + \lambda\vec{b} + \mu\vec{c}$$

#### 6.2.3 Cartesian form

$$\text{When } \vec{n} = \begin{pmatrix} a \\ b \\ c \end{pmatrix}: ax + by + cz = d$$

### 6.3 Formulae

#### 6.3.1 Dot and cross product

$$\bullet \vec{a} \cdot \vec{b} = |\vec{a}||\vec{b}| \cos \theta = x_1x_2 + y_1y_2 + z_1z_2$$

$$\vec{a} \perp \vec{b}: \vec{a} \cdot \vec{b} = 0$$

$$\cos \theta = \frac{\vec{a} \cdot \vec{b}}{|\vec{a}||\vec{b}|}$$

$$\bullet \vec{a} \times \vec{b} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \times \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{pmatrix} x_2y_3 - x_3y_2 \\ x_3y_1 - x_1y_3 \\ x_1y_2 - x_2y_1 \end{pmatrix}$$

$$\text{Calculating cross product using matrix: } \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \end{vmatrix}$$

$$\vec{a} \times \vec{b} \perp \vec{a} \text{ and } \vec{a} \times \vec{b} \perp \vec{b}, \text{ so } \vec{a} \times \vec{b} = \vec{n}$$

$$|\vec{a} \times \vec{b}| = |\vec{a}||\vec{b}| \sin \theta$$

$$\vec{a} \parallel \vec{b}: \vec{a} = \lambda\vec{b}; \vec{a} \times \vec{b} = \vec{0}$$

## 6.4 Questions

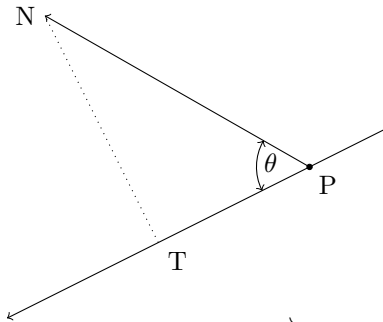
### 6.4.1 Angle between planes

1. Find the normal of the two planes
2. Use  $\theta = \cos^{-1} \frac{\vec{n}_1 \cdot \vec{n}_2}{|\vec{n}_1||\vec{n}_2|}$  to find the angle between planes
3. If  $\theta > 90$  then the angle is  $180 - \theta$

### 6.4.2 Angle between plane and line

$$\phi = 90 - \cos^{-1} \frac{\vec{n} \cdot \vec{d}}{|\vec{n}||\vec{d}|} \text{ or } \phi = \sin^{-1} \frac{\vec{n} \cdot \vec{d}}{|\vec{n}||\vec{d}|}$$

### 6.4.3 Finding distances between point and line



$$|\vec{PT}| = |\vec{PN}| \cos \theta = \frac{\vec{PN} \cdot \vec{d}}{|\vec{d}|}$$
$$|\vec{NT}| = \sqrt{|\vec{PN}|^2 - |\vec{PT}|^2}$$

### 6.4.4 Finding distances from point to plane

When  $P = (x_0, y_0, z_0)$  and the plane has equation  $ax + by + cz - d = 0$ : distance =  $\frac{|ax_0 + by_0 + cz_0 + d|}{\sqrt{a^2 + b^2 + c^2}}$

### 6.4.5 Finding distances between lines

$$\text{distance} = \frac{|\vec{AB} \cdot \vec{n}|}{|\vec{n}|} \quad (\vec{AB} = \text{any line that connects 2 lines together})$$

### 6.4.6 Finding intersections between line and plane

Write line in parametric form, substitute  $x$ ,  $y$  and  $z$  into the equation for plane (Cartesian form)



# 7 Polar coordinates

## 8 Hyperbolic functions

## 9 Differential equations