

**system/segmentation**



```
graph LR; A((system/segmentation)) --> B((/managed_subsystem/camera)); B --> C((/managed_subsystem/depth)); C --> D((/managed_subsystem/sensor_fusion))
```

**/managed\_subsystem/sensor\_fusion**  
**/managed\_subsystem/depth**

**/managed\_subsystem/camera**

**/managed\_subsystem/image**