

# Federated Knowledge Graphs Embedding

Hao Peng<sup>\*1</sup>, Haoran Li<sup>\*2</sup>, Yangqiu Song<sup>2</sup>, Vincent Zheng<sup>3</sup>, Jianxin Li<sup>1</sup>

<sup>1</sup>Beijing Advanced Innovation Center for Big Data and Brain Computing, Beihang University;

<sup>2</sup>Department of Computer Science and Engineering, HKUST; <sup>3</sup>AI Group, Webank Co., Ltd.

{penghao, lijx}@act.buaa.edu.cn, hlibt@connect.ust.hk, yqsong@cse.ust.hk, vincentz@webank.com

## ABSTRACT

In this paper, we propose a novel decentralized scalable learning framework, *Federated Knowledge Graphs Embedding* (FKGE), where embeddings from different knowledge graphs can be learnt in an asynchronous and peer-to-peer manner while being privacy-preserving. FKGE exploits adversarial generation between pairs of knowledge graphs to translate identical entities and relations of different domains into near embedding spaces. In order to protect the privacy of the training data, FKGE further implements a privacy-preserving neural network structure to guarantee no raw data leakage. We conduct extensive experiments to evaluate FKGE on 11 knowledge graphs, demonstrating a significant and consistent improvement in model quality with at most 17.85% and 7.90% increases in performance on triple classification and link prediction tasks.

## 1 INTRODUCTION

Knowledge graphs (KGs) have been built to benefit many applications, e.g., semantic search, question answering, recommendation systems, etc. [14, 20]. There have been several big and general-purpose KGs such as Freebase [3] (or later Wikidata [40]) and Yago [34], and numerous domain-specific KGs of various sizes such as GeoNames [1] in geography and Lexvo [11] in linguistics. To our best knowledge, most companies build their own commercial KGs, which usually require laborious human annotation and high computational cost<sup>1</sup>. However, there are multiple reasons that companies would not want to share their KGs. First, each company has its private part of data, which cannot be disclosed to others. Second, even if privacy is not a concern, they would not expose their knowledge to other companies except they can also benefit from others. Third, integrating knowledge itself is not trivial or easy. On the other hand, in many cases, companies indeed have the motivation to exchange knowledge to improve their own data quality and service. For example, a drug discovery company may benefit from a patient social network and a gene bank, and so as the other two interested in a drug network and a disease network owned by the drug discovery company. Sometimes, the data cannot even be bought due to the privacy concern. For example, under EU’s GDPR<sup>2</sup>, companies cannot use or share a user’s data without his/her consent. Therefore, a more loosely coupled and principled way to share their KGs that can benefit multiple parties should be considered.

Traditionally, federated database systems [33] were proposed to support unified query language over heterogeneous databases

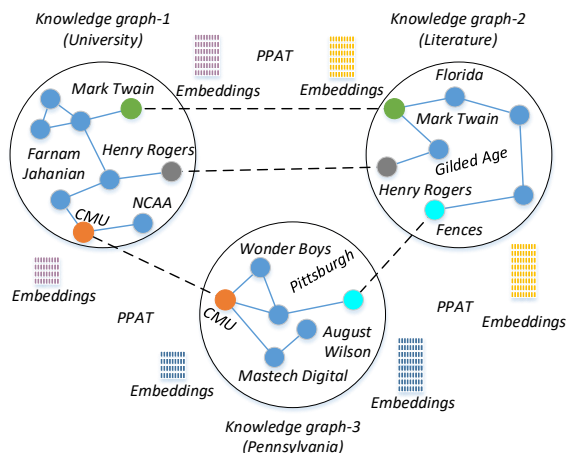


Figure 1: Overview of FKGE framework. Different Knowledge graphs may use different embedding models.

without doing actual data integration. Such systems do not help improve individual KG’s quality or service with private data preserved. Recently, machine learning, in particular KG representation learning or KG embedding, has been shown to be powerful for knowledge representation, reasoning, and many downstream applications [20, 28, 41]. When representing entities and their relations in a vector space, different KGs may share information if their embedding spaces are (partially) aligned [8, 37, 46, 51]. However, revealing vector representations to other parties can also leak private information [6]. Currently, for multiple cross-domain KGs, especially for the ones shared by different companies, state-of-the-art KG embedding models cannot make full use of the data from different domains while preserving the privacy. More recently, *federated machine learning* [48] has been widely considered when heterogeneous devices or multiple parties contribute non-IID data where privacy of different sources should be preserved. However, the natures of distributed federated learning [21, 22] (which requires centralized averaging platform) and vertical or horizontal federated learning (which do not consider graph structures) make them non-trivial to be adapted to KG embeddings. There are some existing federated learning mechanisms for graphs [23] but they treat each node to be a computing cell and cannot collaboratively train multiple KGs together.

To improve the quality of individual KGs for multiple cross-domain KGs, we propose a new framework called *Federated Knowledge Graphs Embedding* (FKGE), where embeddings from different KGs can be learnt jointly in an asynchronous and pairwise manner

<sup>1</sup>See <https://www.maana.io/> for a general pipeline of components.

<sup>2</sup><https://gdpr-info.eu>

\* Equal contribution.

while being privacy-preserving. In FKGE, we design a privacy-preserving adversarial translation (PPAT) network to mutually enhance embeddings of each pair of KGs based on aligned entities and relations. PPAT network’s mechanism guarantees the differential privacy for the paired embeddings of aligned entities and relations not leaked to each other. For example, in Fig. 1, *Mark Twain* and *Henry Rogers* are two of aligned entities that belong to both *University* and *Literature* KGs, they have different representations in two embedding spaces of two KGs. We use PPAT network to separate their embeddings from both sides while we are still able to exploit their embeddings to improve the embedding quality for both *University* and *Literature* KGs.

In summary, we highlight the following characteristics of our FKGE<sup>3</sup> framework. 1) FKGE framework is asynchronous and decentralized. Different from centralized client-based models, FKGE pairs up KGs from different domains with an adversarial network. 2) FKGE is scalable and compatible with many base embedding models. The asynchronous and decentralized setting leads to parallel computation between pairs of collaborators. Moreover, FKGE can serve as a meta-algorithm for existing KG embedding methods through a handshake protocol. 3) FKGE is privacy-preserving and guarantees no raw data leakage. FKGE’s design requires no raw data transmission between collaborators, and transmitted generated embeddings are differentially private.

## 2 RELATED WORK

As our work is closely related to federated learning and knowledge graph embedding, the related works are two-fold.

### 2.1 Federated Learning

Federated learning allows multiple data owners to collaborate on building models without compromising on data privacy. Google first proposed a federated learning framework between the cloud server and edge devices to train on edges and update global model on the cloud [21, 22, 26]. Yang et al. [48] further extended the definition from edge devices to general data owners, so that the collaborations between separate databases were taken into scenarios of federated learning. For graph structured data, Lalitha et al. [23] considered using federated learning in a peer to peer manner. FedE [9] exploited federated learning over a KG through centralized aggregation for the link prediction task. However, both of them handled one single graph by either treating each node to be a computing cell or distributing triplets in a KG into different servers and performed the Federated Averaging algorithm introduced by Google [26], and thus cannot collaboratively train multiple KGs together.

In terms of privacy preserving mechanisms, most works used homomorphic encryption (HE) [30], secure multi-party computation (MPC) [27], and differential privacy (DP) [12, 15, 17] to improve security. There are also several extensions which combine or improve the above frameworks. For example, Lyu et al. [25] used DP, HE, and Blockchain technologies to build a decentralized fair and privacy-preserving deep learning framework. Xu et al. [45] designed a verifiable federated learning framework based on the homomorphic hash function and pseudorandom. Our proposed FKGE framework is targeted for multiple KGs with millions of entities and

HE is inefficient for our task. DP addresses individuals’ privacy concerns while aggregating different databases so that specific users’ information can not be inferred through federation. Therefore, DP algorithm is implemented for our FKGE.

### 2.2 Knowledge Graph Embedding

KG embedding plays an important role in knowledge base inferences and downstream applications [2, 28, 41]. Popular models are mostly based on a translational model, where a head is translated to a tail through a relational embedding [4], or a bilinear model, where a bilinear matrix is used to combine the head and tail to form a loss function [29]. Recently, there have been many extensions based on these two models [19, 24, 42, 44]. More recently, these models are extended to the complex space instead of using the Euclidean space [35, 39], which can model many important properties of relations such as symmetry, inversion, and composition.

When there are multiple KGs, embedding based entity alignment can be performed. Such entity alignment task usually assumes that different KGs are partially aligned and tries to predict more aligned entities. For example, the entity alignment can be based on cross-lingual KGs [8, 32, 43, 52], KGs with multi-view entity-related information [5, 7, 50], and KGs in similar domains with significant entity overlaps [36, 38, 47, 51]. After joint learning, embeddings for entity alignment are usually aligned in a unified space so the vectors can be used to find nearest entities in other KGs. Note that our FKGE framework is different from above KG alignment problems. Instead of predicting the potential aligned entities using given ones, we aim to improve individual KG embeddings based on provided aligned entities. In FKGE, after joint training, each KG still does not know other KG’s embedding space, but embeddings in each KG are all improved for better downstream tasks such as node classification or link prediction. This is guaranteed by the differential privacy mechanism that we introduced in our PPAT network: when training each pair of embedding sets for the aligned entities, they cannot leak a single embedding since inclusion and exclusion of a particular embedding will not affect the out-come distribution very much. This also allows us to use different base KG embedding models for different KGs.

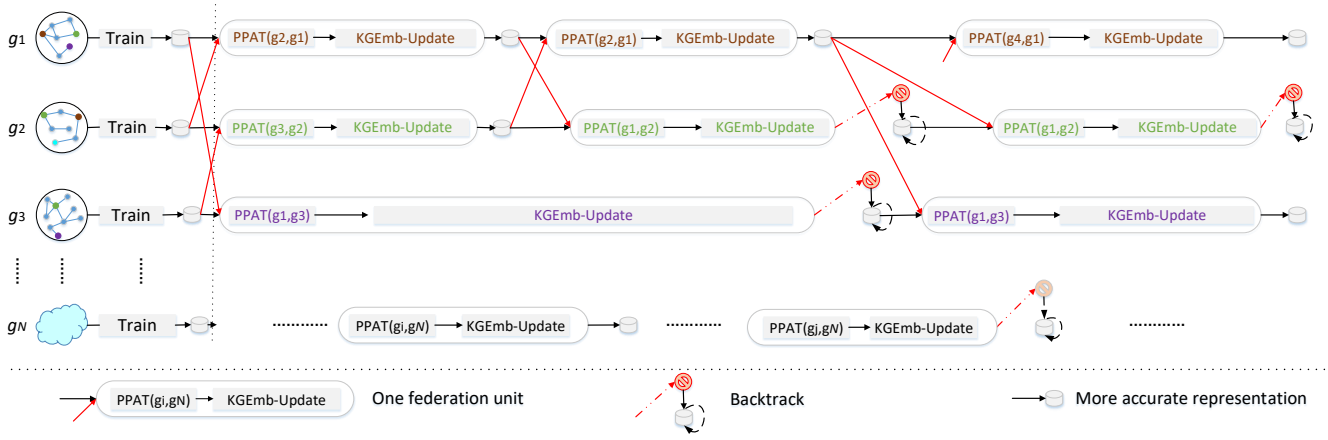
## 3 FEDERATED KNOWLEDGE GRAPHS REPRESENTATION LEARNING

In this section, we present detailed descriptions of FKGE. We first give the problem definition and sketch intuitive solution in Section 3.1. Then we introduce more details of our privacy-preserving model in Section 3.2. Finally, we give a comprehensive explanation of our federated training mechanism in Section 3.3.

### 3.1 Problem Formulation and Proposed Solution

We define the set of knowledge graphs (KGs) from separate owners as  $\mathcal{KG} = \{g_1, g_2, g_3, \dots, g_N\}$ , where  $N$  is the total number of KGs. Every element in  $\mathcal{KG}$  locates in different databases and cannot access other KGs’ databases. Let  $g_k = \{\mathcal{E}_k, \mathcal{R}_k, \mathcal{T}_k\} (1 \leq k \leq N)$  denote the  $k$ -th KG in  $\mathcal{KG}$ . Each triple  $(h, r, t) \in \mathcal{T}_k$  (the set of triples of  $g_k$ ) is composed of a head entity  $h \in \mathcal{E}_k$  (the set of entities of  $g_k$ ), a tail entity  $t \in \mathcal{E}_k$  and a relation  $r \in \mathcal{R}_k$  (the set of relations

<sup>3</sup>Code is available at <https://github.com/HKUST-KnowComp/FKGE>.



**Figure 2: An example of whole training procedure.** The order of training is not fixed and depends on individual knowledge graph owner’s computation power and willingness to cooperate. “Train” indicates training KGE model locally. “PPAT( $g_i, g_j$ )” denotes the PPAT embeddings between  $g_i$  and  $g_j$  where the generator locates in client  $g_i$  and the discriminator lies in host  $g_j$ . “KGEEmb-Update” updates aligned embeddings with generated output of PPAT network and retrain all the embeddings as “Train”. “Backtrack” happens if evaluation result after “KGEEmb-Update” is not improved, then newly trained embeddings are abandoned and previous embeddings are kept. If result of host  $g_j$  or client  $g_i$  has more accurate representation than previous embedding, the result is stored and then it broadcasts signal to other knowledge graphs for further federation. Otherwise the result is backtracked.

of  $g_k$ ). For any pair of KGs ( $g_i, g_j$ ) in  $\mathcal{KG}$ , we assume that both aligned entities  $\mathcal{E}_i \cap \mathcal{E}_j$  and relations  $\mathcal{R}_i \cap \mathcal{R}_j$  are given which can be done by a secure hash<sup>4</sup>. Our goal is to exploit aligned entities and relations to further improve all embeddings of any individual KG. To aid discussion, Tab. 1 depicts the notations used throughout the paper. Each KG owner  $g_i$  trains its own embeddings of entities  $\mathcal{E}_i$  and relations  $\mathcal{R}_i$  locally. Based on the trained embeddings, FKGE aggregates the embeddings of both aligned entities and relations from paired KGs, and then updates embeddings in a federated manner. For aligned entities and relations from any pair of KGs, e.g., ( $g_i, g_j$ ), FKGE includes a secure pipeline that can refine the embeddings of  $\mathcal{E}_i \cap \mathcal{E}_j$  and  $\mathcal{R}_i \cap \mathcal{R}_j$  and further improve embeddings of  $\mathcal{E}_i \cup \mathcal{R}_i$  and  $\mathcal{E}_j \cup \mathcal{R}_j$  individually. Moreover, FKGE proposes a federated training mechanism to improve all the parties jointly via broadcasting. If  $g_i$  or  $g_j$  gains improvement from the refined embeddings, it will broadcast signals to other KGs to further improve overall results. Otherwise, it will backtrack to original embeddings before federation. As an example shown in Fig. 2, in the beginning,  $g_1, g_2, g_3$  train their embedding locally. During first federation, they form 3 pairs of KGs: ( $g_1, g_3$ ), ( $g_2, g_1$ ) and ( $g_3, g_2$ ). After first federation,  $g_1$  and  $g_2$  gain improvement for overall embeddings.  $g_3$ ’s training takes longer time and fails to improve its embedding, therefore  $g_3$  backtracks to initial embedding. During second federation,  $g_1$  and  $g_2$  pair up as ( $g_2, g_1$ ) and ( $g_1, g_2$ ) and only  $g_1$  gains improvements.  $g_2$  backtracks to previous embedding. Since  $g_3$  is still on the training process, it will not join second federation and will go to sleep state if no available KG exists. For third federation,  $g_1$  finishes its training and broadcasts  $g_3$  to wake up. Then they form ( $g_1, g_3$ ), ( $g_1, g_2$ ) and ( $g_4, g_1$ ) pairs for federation. The whole training procedure continues until no more improvement for all the KGs.

**Table 1: Glossary of Notations.**

Symbol	Definition
$\mathcal{KG}$	Knowledge graph set
$g_k$	$k$ -th knowledge graph
$\mathcal{E}_k$	The set of entities of $g_k$
$\mathcal{R}_k$	The set of relations of $g_k$
$\mathcal{T}_k$	The set of triples of $g_k$
$N$	Total number of knowledge graphs
$T_i$	$i$ -th teacher discriminator
$\theta_i^T$	Parameters of $i$ -th teacher discriminator
$S$	Student discriminator
$\theta_S$	Parameters of student discriminator
$G$	Generator
$\theta_G$	Parameters of generator $G$ that includes the mapping matrix $W$
$X$	Embedding of aligned entities and relations of the client
$Y$	Embedding of aligned entities and relations of the host
$N(X)$	Raw embeddings of neighbor entities and joining relations of $X$
$n$	Total number of training samples
$ T $	Total number of teacher discriminators
$\lambda$	Noise (scale) of Laplace random variable
$n_0$	Total vote number for 0 of teacher discriminators
$n_1$	Total vote number for 1 of teacher discriminators
$l$	A chosen positive integer for moment
$d$	Embedding dimension of entity and relation

### 3.2 Privacy-Preserving Adversarial Model

Given two KGs ( $g_i, g_j$ ) with aligned entities  $\mathcal{E}_i \cap \mathcal{E}_j$  and relations  $\mathcal{R}_i \cap \mathcal{R}_j$ , FKGE exploits a GAN [16] structure to unify the embeddings of aligned entities and relations, where we borrow the idea of MUSE [10] which used a translational mapping matrix  $W$  in the generator to align two manifolds in the GAN’s intermediate vector space. The generator and the discriminator can locate in different sides for a pair of KGs. More specifically, we may put the generator in  $g_i$  and the discriminator in  $g_j$ . The generator translates aligned entities’ embeddings from  $g_i$  to  $g_j$  and the discriminator distinguishes between synthesized embeddings of the generator

<sup>4</sup><https://csrc.nist.gov/publications/detail/fips/180/4/final>





database. The student loss function is formulated as:

$$L_S(\theta_S; T, G) = \frac{1}{n} \sum_{i=1}^n [\gamma_i \log S(G(x_i); \theta_S) + (1 - \gamma_i) \log (1 - S(G(x_i); \theta_S))], \quad (7)$$

where  $\gamma_i = \text{PATE}_\lambda(x_i)$ , the noisily aggregated label voted by teacher discriminators.

Besides the generated embedding  $G(X)$ , after the training process of PPAT network is stable, the client generates embeddings for the adjacent entities of the aligned entities in  $g_i$  and the joining relations as types of virtual entities and relations that are added into the host. We use  $\mathcal{N}(X)$  to denote the raw embeddings of adjacent entities and joining relations, and the generated embeddings of virtual entities and relations can be denoted as  $G(\mathcal{N}(X))$ . These virtual entities and relations are only used for KGE, and will be removed before responding to other hosts.

### 3.2.2 Privacy Analysis and Parameter Estimation

For the PPAT network, our dataset  $X$  to feed the generator is embedding of  $\mathcal{E}_i \cap \mathcal{E}_j$  and  $\mathcal{R}_i \cap \mathcal{R}_j$  in  $g_i$ , the neighboring dataset is defined by excluding a particular embedding from  $X$ . We use  $X'$  to denote the neighboring dataset such that there is an embedding  $x_i \in X$  and  $X - \{x_i\} = X'$ . The algorithm to perform parameter estimation is shown in Algorithm 2 in Appendix A. The raw embeddings of aligned entities and relations in  $X$  are fed to the generator to generate adversarial samples  $G(X)$  which are later on transmitted to all teacher discriminators  $T$  of the host. By adding Laplace noise to voted results of teacher discriminators, differential privacy requirement is satisfied [31]. The student discriminator  $S$  is then trained by the synthesized embeddings with aggregated labels that contains 0 or 1 voted by teacher discriminators. The Post-Processing Theorem [13] which states the composition of a data-independent mapping  $f$  with an  $(\epsilon, \delta)$  - differentially private algorithm  $M$  is also  $(\epsilon, \delta)$  - differentially private. By Post-Processing Theorem, the student discriminator  $S$  is also differentially private since it is trained by differentially private labels. Moreover, the generator  $G$  is differentially private since  $G$  is trained by student discriminator  $S$ . Hence, the transmitted embeddings are synthesized and differentially private since they are outputs of the generator  $G$ .

During the training process, the host calculates the generator's and all discriminators' loss functions locally: gradients of student discriminator loss and teacher discriminator losses are used to update discriminators' parameters locally, while gradients of generator loss are sent back to the generator to update its parameters. Thus, neither of  $g_i$  and  $g_j$  is able to access the embeddings or raw data of the other's. Therefore the raw data's privacy are protected for any participant of knowledge graph owners.

As we incorporate the differential privacy mechanism in our PPAT network, following PATE-GAN's proof, we can also estimate  $\epsilon$  in Def. 3.2 for PPAT. We formulate the upper bound of  $\hat{\epsilon}$  in PPAT in Eq. (8):

$$\hat{\epsilon} = \min_l \frac{\alpha(l) + \log(\frac{1}{\delta})}{l}, \quad (8)$$

where  $\alpha(l)$  is the moments accountant for  $l$ -th moment. Its upper bound is derived by Theorem 2 and Theorem 3 in PATE mechanism [31] as shown in Eq. (9):

### Algorithm 1: KGProcessor

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**Input** : The Host KG  $g_j$   
**Output** : Best embedding  $E_b$

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1 // Start self iterative training to get the best knowledge
  graph embedding and the best score  $S_b$ 
2  $E_b \leftarrow g_j.\text{train}()$ ;
3  $S_b \leftarrow g_j.\text{test}(E_b)$ ;
4  $g_j.\text{state} \leftarrow \text{Ready}$ ;
5 // Start federated learning, and  $Q$  is handshake signal Queue
6  $Q.\text{receive\_signal}()$ ; // Receiving signal as Host
7 while  $g_j.\text{state} = \text{Ready}$  do
8    $U_p \leftarrow \text{False}$ ; // Set the improvement identifier  $U_p$  to false
9   while  $Q$  is not empty do
10     $g_j.\text{state} = \text{Busy}$ ; // Start PPAT, and set the state to busy
11     $E_t \leftarrow \text{ActiveHandshake}(g_j, Q.\text{poll}())$ ;
12     $g_j.\text{aggregation}(E_t)$ ;
13    // Start  $g_j$  KGE-Update, after aggregating embedding
14     $T_e \leftarrow g_j.\text{train}()$ ;
15     $T_s \leftarrow g_j.\text{test}(T_e)$ ;
16    // Backtrack function is the embodiment of our
      backtrack mechanism
17     $U_p, S_b, E_b \leftarrow g_j.\text{backtrack}(T_s, S_b, T_e, E_b)$ ;
18     $g_j.\text{state} = \text{Ready}$ ;
19   if  $U_p = \text{False}$  and  $Q$  is empty then
20     // Both following states are configured by KG owner or
      activated by handshake signal
21     if  $g_j.\text{state} = \text{Sleep}$  then
22        $g_j.\text{sleep}()$ ;
23     if  $g_j.\text{state} = \text{Ready}$  then
24       //  $g_j$  begins self iterative training
25        $T_e \leftarrow g_j.\text{train}()$ ;
26        $T_s \leftarrow g_j.\text{test}(T_e)$ ;
27        $U_p, S_b, E_b \leftarrow g_j.\text{backtrack}(T_s, S_b, T_e, E_b)$ ;
28   if  $U_p = \text{True}$  and  $Q$  is empty then
29     // Broadcast handshake signal to other KGs having
      aligned entities and relations
30      $g_j.\text{send\_handshake\_signal}()$ ;
31 return Best embedding  $E_b$ ;

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$$\alpha(l) = \alpha(l) + \min \left\{ 2\lambda^2 l(l+1), \log \left( (1-q) \left( \frac{1-q}{1-e^{2\lambda q}} \right)^l + qe^{2\lambda l} \right) \right\}, \quad (9)$$

where  $q$  is an intermediary value which is formulated in Eq.(10):

$$q = \frac{2 + \lambda |n_0 - n_1|}{4 \exp(\lambda |n_0 - n_1|)}, \quad (10)$$

where  $n_0, n_1$  denote the number of teachers' votes for 0 or 1 separately. More details about updating  $\alpha$  and  $\hat{\epsilon}$  are shown in Algorithm 2 in Appendix A. By choosing  $\delta$  and  $\lambda$ , the  $\hat{\epsilon}$  can be calculated.

### 3.3 Federated Training

For multiple KGs, we construct PPAT networks between any pair of  $(g_i, g_j) \in \mathcal{KG}$  where  $\mathcal{E}_j \cap \mathcal{E}_i \neq \emptyset$  or  $\mathcal{R}_j \cap \mathcal{R}_i \neq \emptyset$ , and produce  $2 \times \binom{N}{2}$  PPAT networks at most at the same time. For any pair of  $(g_i, g_j)$ , at least one client and one host are required separately. Our asynchronous and decentralized setting allows individual KG owner to decide whether it should collaborate with other KGs. More specifically, the collaboration process can be described as a handshake protocol. Any  $g_i$  has three states: *Ready*, *Busy*, and *Sleep*. *Ready* state indicates  $g_i$  having available computational resources

and being active to pair up with other KGs. *Busy* state indicates that  $g_i$  does not have enough resources and will not respond to any collaboration request at the moment. Instead, collaborators will be put in a queue till  $g_i$  finishes its work and is ready for collaborations. *Sleep* state indicates that though  $g_i$  has the computational resources, it has not received any collaboration request yet. That is, If *Ready* state can not find a partner, it will switch to *Sleep* state and wake up to *Ready* state after a certain time period or being notified by a collaboration request. Algorithm 1 describes how a KG refines its embeddings. A successful handshake process between  $g_i$  and  $g_j$  implies  $state(g_i) \neq Busy, state(g_j) \neq Busy$ , and at least one of them has *Ready* state. The whole handshake mechanism is explained in Appendix A. Fig. 2 illustrates an example of the federated training process.

## 4 EXPERIMENTS

In this section, we present extensive experiments to evaluate the performance of the proposed FKGE framework. In Section 4.1, we will introduce basic experimental setup and metrics. Then we will use FKGE to conduct both triple classification and link prediction experiments in Section 4.2. Moreover, we will conduct ablation study to show the effectiveness of FKGE in Section 4.3. Finally, we will analyze time cost for our experiment in Section 4.4.

### 4.1 Experimental Settings

**Dataset.** We select 11 knowledge graphs (KGs) at different scales from the Linked Data community<sup>5</sup>. For knowledge graph embedding (KGE), OpenKE framework [18] is used so that FKGE is compatible with various KGE models. For each KG, we count the numbers of relation, entity and triple, and divide the triples into train, valid, and test sets with ratio 90 : 5 : 5 according to the default setting in the OpenKE. Note that in order to reduce computational time of training and testing in KGE, we cut out some sparse entities and triples that are not relevant to aligned entities and triples from the original KGs. A summary statistics of these KGs is shown in Tab. 2. The Linked Data community provides aligned entities (AE) between different KGs in RDF files, statistics as recorded in Tab. 3. We use the above KGs to fully evaluate the advantages of the proposed FKGE framework.

#### 4.1.1 Hyperparameter Setting

To simulate real-world asynchronous training without data leakage, we set each KG to one process and implement all comparative experiments on 11 independent processes using the same type of GPU devices with the same configurations. During a handshake process, we use pipeline communication between processes to transmit generated adversarial samples from client to host and gradients from host to client. In consideration of computational time and testing results, we set default dimension  $d$  of the embedding vector to  $d = 100$ , and step of testing to 1,000 epochs. For other essential parameters of KGE, we set the learning rate to 0.5 and batch size to 100 following the default setting of the OpenKE [18]. Negative samples are generated by corrupting either head or tail entities and ratios of negative samples and positive samples are 1:1. For the essential parameters of the PPAT network, we set batch size,

KGs	#Relation	#Entity	#Triple
Dbpedia	14,085	49,1078	1,373,644
Geonames	6	300,000	1,163,878
Yago	37	286,389	1,824,322
Geospecies	38	41,943	782,120
Poképédia	28	238,008	548,883
Sandrart	20	14,765	18,243
Hellenic	4	11,145	33,296
Lexvo	6	9,810	147,211
Tharawat	12	4,693	31,130
Whisky	11	642	1,339
World lift	10	357	1,192
Summation	14,257	1,398,830	5,915,596

Table 2: Statistics of the Knowledge Graphs.

KGs	# AEs	KGs	# AEs	KGs
Geonames	118,939	Dbpedia	27	Poképédia
Yago	123,853	Dbpedia	133	Geospecies
Yago	53,553	Geonames	89	Geospecies
Sandrart	379	Dbpedia	41	Hellenic
Dbpedia	507	Lexvo	245	Geonames
Dbpedia	403	Tharawat	90	Geonames
Dbpedia	70	Whisky	39	Geonames
Dbpedia	25	World lift	18	Yago
Lexvo	77	Yago	266	Tharawat
Whisky	49	Yago	-	-

Table 3: Statistics of Aligned Entities (AEs).

teacher number, learning rate, momentum to 32, 4, 0.02, 0.9. We train for 1,000 epochs for each KG to get the initial best score and embeddings, and then activate the federal unit.

#### 4.1.2 Privacy Setting

For differential privacy setting, we set  $\lambda$  to 0.05 and  $\delta$  to  $10^{-5}$ . For each pair of KGs in federated training, there is an PPAT network with varied  $\epsilon$  according to the input dataset  $X$  since total the number of queries of paired embeddings may change according to number of aligned entities. We estimate the largest upper bound  $\hat{\epsilon}$  for all the  $\epsilon$  and the bound is  $\hat{\epsilon} = 2.73$ . Since for each round of federated training, the max  $\alpha(l)$  is 0.29 for all the ActiveHandshake in Algorithm 2, putting  $\ln \frac{1}{\delta} = 11.5$  and  $l = 9$  together, we obtain upper bound 2.73 for all  $\epsilon$  following Eqs. (8 - 10).

#### 4.1.3 Evaluation Metrics

The proposed FKGE framework is compatible with different KGE methods. We choose popular and simple translation-based models including TransE [4], TransH [42], TransR [24], and TransD [19] from the OpenKE [18] to evaluate the quality of the embeddings trained by different methods under two classical testing tasks of KGE: triple classification and link prediction. For triple classification, we apply the **Accuracy** as evaluation metric. For link prediction, we apply the widely used proportion of correct entities in top-1, 3 and 10 ranked entities (**Hit@1, 3 and 10**) as evaluation metrics. Next, we verify the effectiveness and scalability of the FKGE framework in detail.

<sup>5</sup><https://lod-cloud.net/>

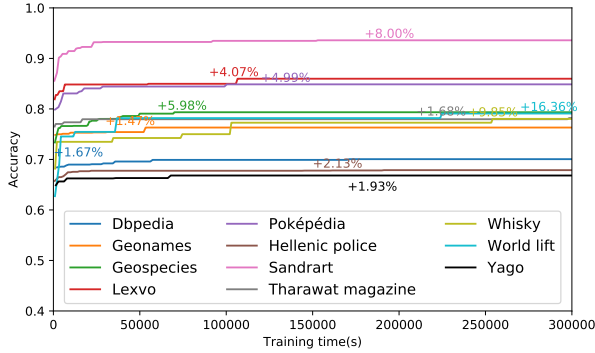


Figure 4: Performance of FKGE with TransE on the triple classification task.

## 4.2 Evaluation

Here, we demonstrate the advantages of the FKGE based on experimental results on triple classification and link prediction tasks.

### 4.2.1 Triple Classification

We give the baseline accuracies and analysis of triple classification of the 11 knowledge graphs using TransE in Appendix B. Besides, to make fair comparison, we also give the triple classification accuracies of unifying 11 KGs together in Appendix B. Based on the same random initialization, we apply the FKGE framework to the 11 knowledge graphs with TransE. The results of triple classification are shown in Fig. 4, where the marked improvements are compared with the results before training (at time 0). After the same 300,000 seconds of training, it can be observed that the accuracy of each knowledge graph increases. Specifically, compared with the baseline method, the accuracy results (KG ordered as in Tab. 2) have been improved by 16.49%, 2.98%, 2.06%, 17.85%, 2.11%, 0.60%, 0.48%, 0.77%, 1.82%, 12.88% and 14.55% on triple classification task, respectively. The improvements in accuracy of the above 11 knowledge graphs benefit from the cross-knowledge embedding integration in the FKGE. Moreover, the continuous and steady improvements also show the effectiveness of the backtrack mechanism in the FKGE. Therefore, based on the FKGE framework and TransE, the 11 knowledge graphs have achieved consistent improvements in terms of accuracy in triple classification.

Not only TransE benefits from the PPAT network, but also other mainstream KGE models can be improved through the FKGE framework. We also randomly select KGE method from the 4 popular translation family models for each knowledge graph. We give the results and analysis of the baseline using different translation family models in Appendix B. After 300,000 seconds of training, the accuracy of the FKGE in the triple classification for the 11 KGs is shown in Fig. 5, where the marked improvements are also compared with the results before training (at time 0). Specifically, compared with their respective base methods, the 11 KGs have been improved by 7.08% (TransR), 2.23% (TransD), 1.33% (TransE), 1.32% (TransR), 1.77% (TransE), 0.38% (TransD), 0.57% (TransD), 1.92% (TransD), 2.42% (TransD), 13.64% (TransH), and 7.27% (TransR) on the triple classification, respectively. It confirms that the FKGE framework has the advantage of being compatible with different KGE methods.

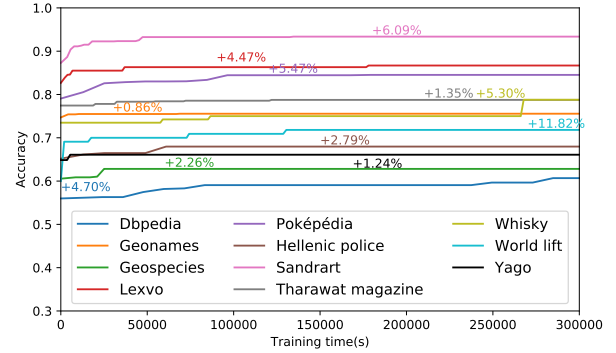


Figure 5: Performance of FKGE using different KGE models on the triple classification.

Overall, the above two triple classification experiments demonstrate the effectiveness and adaptability of the proposed FKGE framework.

### 4.2.2 Link Prediction

We compare the performance of link prediction with type constraint following the OpenKE in multiple scenarios. As shown in Tab. 4, we present the evaluation results of Hit@1, 3, and 10 in the Filter setting. The Filter means that those corrupted triples in test set and validation set are removed for the link prediction. The Independent-TransE means using the traditional TransE based KGE individually. The FKGE means using TransE and federated training to improve every KG collaboratively. Besides TransE, we also use other KGE methods for link prediction. The Random-Independent-KGE means that each KG is applied with a KGE randomly from translation-based models and is training independently. The Multi-FKGE means that each KG randomly chooses a KGE from the translation-based models and also employs the FKGE for further training. Here, we keep the same base KGE methods selected in Fig. 5. Compared with the baseline methods, the TransE based FKGE has increased at most by 7.44%, 6.44%, and 5.59% in terms of Hit@10, 3, and 1, and Multi-FKGE has increased at most by 7.90%, 7.01%, and 5.87% in terms of Hit@10, 3, and 1. For example, benefited from the TransE based FKGE, the *World lift* gains 5.93%, 4.31%, and 3.55% improvements in terms of Hit@10, 3, and 1 under the Filter. The above experiments under link prediction also demonstrate the effectiveness and adaptability of the proposed FKGE framework.

## 4.3 Ablation Study

Here we first consider whether the inclusion of aligned entities and relations is beneficial to FKGE’s performance. Because the existing KGs provide no aligned relations, we manually divide *Geonames* into two subsets named *SubgeonamesA* and *SubgeonamesB* of the same size to verify the contribution of aligned entities and relations. We treat relations similarly as entities and simply put them together for model training. Note that the size of divided KGs shrinks on both entity and relation, and are tested on different sets of triples. The accuracies may differ from baselines (Shown in Appendix C). As shown in Fig. 6, the blue and orange lines represent the accuracy of the two subsets with TransE only, namely *TransE: subgeonamesA* and *TransE: subgeonamesB*, in the triple classification; the green and red lines represent the accuracy by using only the aligned

Methods	Independent-TransE			FKGE			Random-Independent-KGE			Multi-FKGE		
Metric	Hit@10	Hit@3	Hit@1	Hit@10	Hit@3	Hit@1	Hit@10	Hit@3	Hit@1	Hit@10	Hit@3	Hit@1
Dbpedia	23.29	12.88	5.12	<b>25.07</b>	<b>14.41</b>	<b>6.37</b>	5.46	2.51	1.10	<b>6.67</b>	<b>3.20</b>	<b>1.24</b>
Geonames	8.82	3.69	1.93	<b>9.65</b>	<b>4.88</b>	<b>2.12</b>	8.45	4.53	1.90	<b>8.85</b>	<b>4.97</b>	<b>2.14</b>
Yago	2.05	0.76	0.25	<b>2.59</b>	<b>0.88</b>	<b>0.29</b>	2.03	<b>0.75</b>	<b>0.24</b>	<b>2.36</b>	<b>0.75</b>	<b>0.24</b>
Geospecies	58.49	45.81	34.01	<b>60.97</b>	<b>46.95</b>	<b>35.03</b>	38.68	26.43	13.12	<b>40.92</b>	<b>28.04</b>	<b>14.38</b>
Poképédia	38.14	29.04	19.31	<b>45.58</b>	<b>35.48</b>	<b>24.90</b>	34.22	25.13	16.43	<b>42.12</b>	<b>32.14</b>	<b>22.65</b>
Sandrart	87.39	83.16	67.18	<b>88.65</b>	<b>84.97</b>	<b>72.14</b>	87.71	83.71	68.91	<b>87.99</b>	<b>84.22</b>	<b>69.69</b>
Hellenic	32.18	21.87	18.96	<b>33.00</b>	<b>22.87</b>	<b>19.35</b>	32.21	22.23	18.59	<b>32.82</b>	<b>22.59</b>	<b>19.44</b>
Lexvo	85.67	76.07	58.29	<b>87.35</b>	<b>77.74</b>	<b>62.90</b>	84.21	75.82	58.09	<b>85.72</b>	<b>76.99</b>	<b>59.76</b>
Tharawat	12.48	4.56	1.67	<b>13.45</b>	<b>5.26</b>	<b>2.19</b>	12.30	4.38	1.39	<b>12.55</b>	<b>5.21</b>	<b>1.77</b>
Whisky	28.78	15.15	9.84	<b>35.60</b>	<b>18.93</b>	<b>10.60</b>	28.78	18.93	12.87	<b>30.12</b>	<b>19.45</b>	<b>12.92</b>
World lift	45.76	24.57	7.62	<b>51.69</b>	<b>28.88</b>	<b>11.17</b>	18.64	8.47	1.69	<b>18.85</b>	<b>9.32</b>	<b>2.54</b>

Table 4: Evaluation results on link prediction (%). We show the best results with boldface.

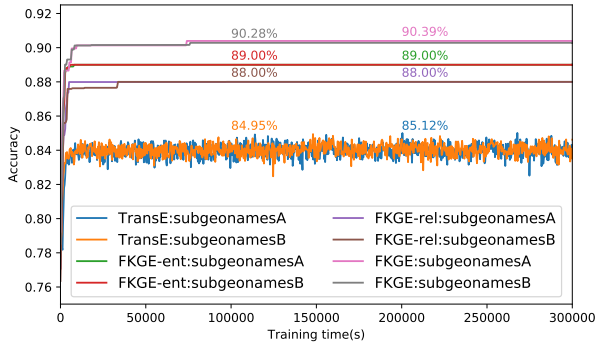


Figure 6: Experiment on manually divided *Geonames*.

entities based on FKGE with TransE, namely *FKGE-ent: subgeonamesA* and *FKGE-ent: subgeonamesB*; the purple and brown lines represent the accuracy by using only the aligned relations based on FKGE with TransE, namely *FKGE-rel: subgeonamesA* and *FKGE-rel: subgeonamesB*; the pink and grey lines represent the accuracy by using both aligned entities and relations based on FKGE with TransE, namely *FKGE: subgeonamesA* and *FKGE: subgeonamesB*, respectively. Obviously, compared with the *TransE: subgeonamesA* and *TransE: subgeonamesB*, *FKGE: subgeonamesA* and *FKGE: subgeonamesB* achieve significant improvements of 5.33% and 5.27% in triple classification, respectively. Besides that, both *FKGE-ent: subgeonamesA* and *FKGE-ent: subgeonamesB* achieve 1.00% improvement over the relation alignment based *FKGE-rel: subgeonamesA* and *FKGE-rel: subgeonamesB*. In general, for the proposed FKGE framework, aligned entities and relations both contribute to the improvement of knowledge graph representations, and the refined embeddings show that PPAT network is also effective.

Besides aligned entities and relations, we also conduct experiments to show the impact of introduced noise  $\lambda$  with different scales. We evaluate triple classification accuracies between *Geonames* and *Dbpedia* with various  $\lambda$  since they share more than 100,000 entities and have similar KG size. The result is shown in Tab. 5. It can be observed that all accuracies are similar with no difference greater than 0.6%. A plausible explanation is that the PPAT network tends to be robust by introducing acceptable randomness.

Noise $\lambda$	No noise	0.05	1	2	5
Dbpedia	68.51%	67.94%	68.29%	68.54%	68.11%
Geonames	74.29%	74.21%	74.28%	74.34%	74.02%

Table 5: Triple classification accuracy with different noise scales for FKGE between *Dbpedia* and *Geonames*.

Lastly, we also do experiments on the scales of aligned entities, dimensions of embeddings, and types of aggregation functions for ablation study. We put these 3 results in Appendix C.

#### 4.4 Time Consumption

To analyze the time cost for individual KG and demonstrate scalability of FKGE. During federation, we evaluate the time cost for different ratios of aligned entities between *Geonames* and *Dbpedia*. We keep the exact experimental setup as Section 4.1 except that only *Geonames* and *Dbpedia* are used for the experiment. It's easy to verify that KGEmb-Update and PPAT training pairwise constitute major time costs for individual KGs. Both of the KGs share similar results, and we show time consumption of *Geonames* in Fig. 7. For each ratio, we run the experiments for 10 times and average the corresponding time consumption. It can be observed that KGEmb-Update usually costs much more time than PPAT network and its cost remains around 4,000s as number of aligned entities increases. For PPAT training, the cost increases roughly linearly from 350s to 1,000s as number of aligned entities increases, which constitutes around 8% ~ 20% among overall training time. In general, for each KG in FKGE, overall time cost is acceptable compared with gained improvements. The linear time cost of the PPAT network indicates FKGE is scalable for aligned entities. Moreover, for transmission between client and host, the client sends translated embeddings of size (batch size,  $d$ ) and host transmits gradients for client of size ( $d$ ,  $d$ ). Using our experimental settings batch size = 32,  $d$  = 100 and 64 bit for double precision, total communication cost for a batch training of the PPAT network is at most 0.845 Mb. Therefore, it is practical for FKGE to train PPAT networks online like a peer-to-peer network.



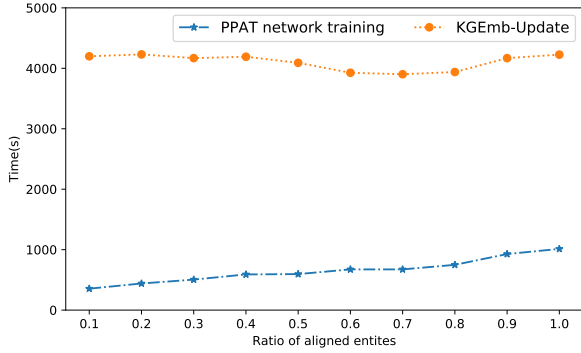


Figure 7: Time cost experiment on *Geonames* (in seconds).

## 5 CONCLUSION

In this paper, we present a well-performed and decentralized federated knowledge graph embedding framework. First, we exploit a privacy-preserving adversarial model between pairs of knowledge graphs to merge identical entities or relations of different domains, and guarantee no raw data leakage. Then, we implement an asynchronous and pairwise federated representation learning framework on knowledge graphs. We conduct extensive experiments to evaluate FKGE on 11 knowledge graphs, demonstrating significant and consistent improvements in model quality through performance on triple classification and link prediction tasks. The ablation study also indicates that merging both aligned entities and relations are beneficial for overall improvement. Besides, the time consumption demonstrates the scalability of FKGE. In the future, we plan to integrate more advanced knowledge graph representation learning models and extend our federated learning framework to other complex knowledge data exchanging scenarios.

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## A ALGORITHM EXPLANATION

In order to better understand the training procedure of the PPAT network, we explain handshake mechanism between client and host KGs in Algorithm 2.

### Algorithm 2: ActiveHandshake

---

**Input** : The caller or Host KG  $g_j$ , Client KG  $g_i$ , Parameter  $\delta$ , Noise  $\lambda$   
**Output** : Translated embedding  $E_t$

---

```

1 // Initialization
2 PPAT.initialize( $g_j, g_i$ );  $\alpha = 0$ ;
3 repeat
4    $AdvS \leftarrow g_i.generate(X)$ ; // Generate adversarial samples
5    $g_j.receive(g_i.send(AdvS))$ ; // Communication between processes
6   // Train all teacher discriminators with partitioned  $AdvS$ 
7    $Probs \leftarrow g_j.teacher\_Ds(Y, AdvS)$ ;
8    $vote \leftarrow PATE_\lambda(Probs)$ ;
9   // Train student discriminator with noisily voted labels
10   $Proba \leftarrow g_j.student\_D(vote, AdvS)$ ;
11   $L_G, L_S \leftarrow g_j.loss\_calculation(Proba)$ ;
12   $L_T \leftarrow g_j.loss\_calculation(Probs)$ ;
13   $grad\_G, grad\_T\_Ds, grad\_S\_D \leftarrow backpropagation(L_G, L_T, L_S)$ ;
14   $g_i.receive(g_j.send(grad\_G))$ ;
15   $g_j.update\_parameters(\Theta_T, grad\_T\_Ds)$ ;
16   $g_j.update\_parameters(\Theta_S, grad\_S\_D)$ ;
17   $g_i.update\_parameters(\Theta_G, grad\_G)$ ;
18  // Update moments
19   $q \leftarrow \frac{2+\lambda|n_0-n_1|}{4 \exp(\lambda|n_0-n_1|)}$ ;
20   $\alpha(l) \leftarrow \alpha(l) + \min \left( 2\lambda^2 l(l+1), \log \left( (1-q) \left( \frac{1-q}{1-e^{2\lambda q}} \right)^l + qe^{2\lambda l} \right) \right)$ ;
21 until PPAT training converged;
22  $\hat{\epsilon} \leftarrow \min_l \frac{\alpha(l) + \log(\frac{1}{\delta})}{l}$ ;
23  $E_t \leftarrow g_j.receive(g_i.generate(X), g_i.generate(N(X)))$ ;
24 return Translated embedding  $E_t$ ;

```

---

## B BASELINE RESULTS

We present the baseline accuracies of triple classification of the 11 knowledge graphs using TransE in Fig. 8. We can see that after adequate rounds of iterative training, the performances are difficult to be further improved though fluctuations and uncertainty exist. The performances of baseline are unstable: accuracies of *Yago* and *Dbpedia* are even reduced. Fig. 9 shows the baseline performance of FKGE using different knowledge graph embedding models as base models. To verify the effectiveness of the proposed FKGE over unified structure of the knowledge graphs, we integrate 11 knowledge graphs into one united knowledge graph by merging aligned entities, and then test the performance of TransE on each KG independently. The accuracy of triple classification of a unified knowledge graph is shown in Fig. 10. As shown in the Fig. 10, compared with the FKGE based on TransE in Fig. 4, the accuracy of triple classification in the unified knowledge embedding space has generally decreased by 8.78% - 21.43%. Moreover, compared with the independent knowledge graph embedding in Fig. 8, the unified knowledge graph embedding even has generally decreased by 6.82% - 17.63%. The above comparative experiments show that, despite the aligned entities, integrating the embeddings of multiple knowledge graphs into one unified vector space does not help to obtain effective representation of the knowledge graphs for the triple classification.

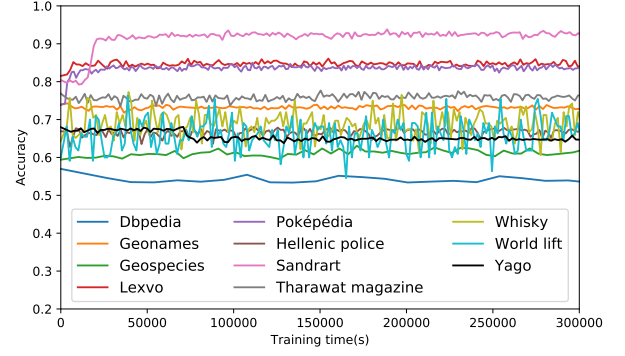


Figure 8: Performance of baseline method using TransE on the triple classification task.

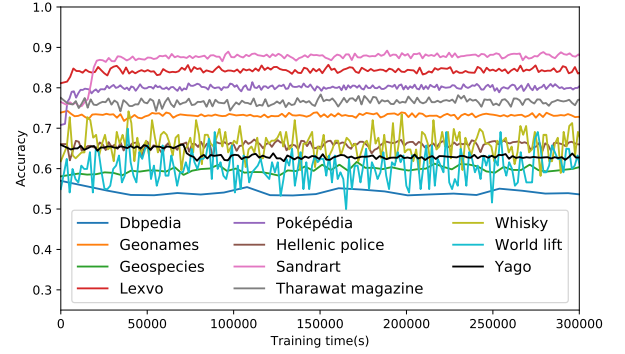


Figure 9: Performance of different KGE models from translation family on the triple classification task.

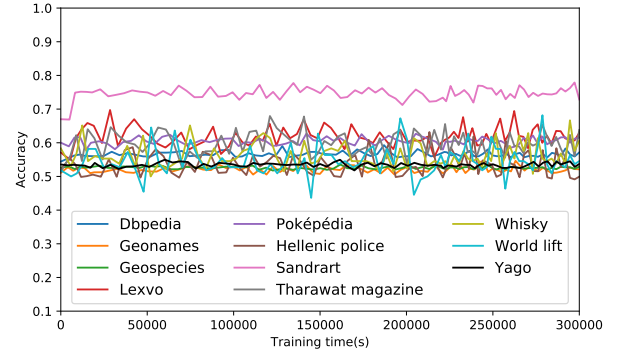


Figure 10: Performance of unified KGE using TransE on the triple classification task.

## C SCALE EXPERIMENTS

In order to measure the impact of the scale of aligned entities involved in the FKGE, we compare the performance of different numbers of the aligned entities and different numbers of knowledge graphs under triple classification. We randomly sample 20%, 40%, 60% and 80% of the aligned entities for fusing them through the PPAT network, respectively. The results on triple classification with different sampling rates are shown in Fig. 11. Intuitively, the more entities' embeddings that can be fused, the more obvious the improvements are. For example, by sampling 20%, 40%, 60% and 80% and 100% sampling rates, the *World lift* gains 3.52%, 4.05%, 5.19%, 6.44% and 7.16% improvements on the triple classification

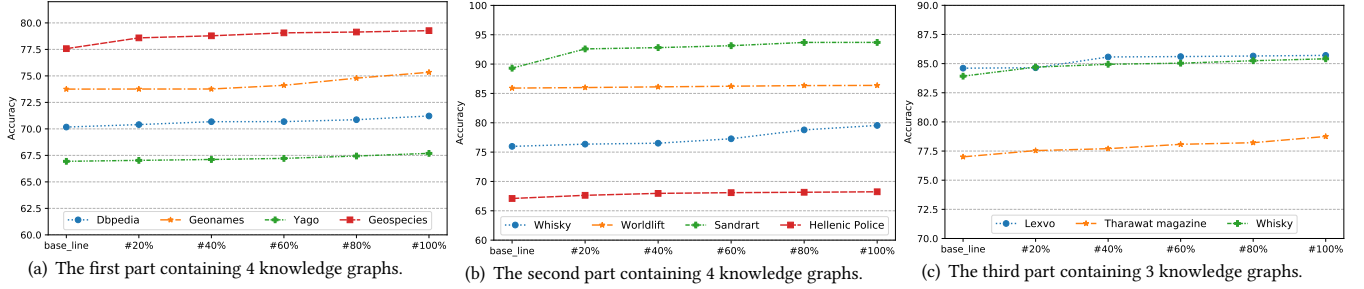


Figure 11: Evaluation results on triple classification with different sampling rates.

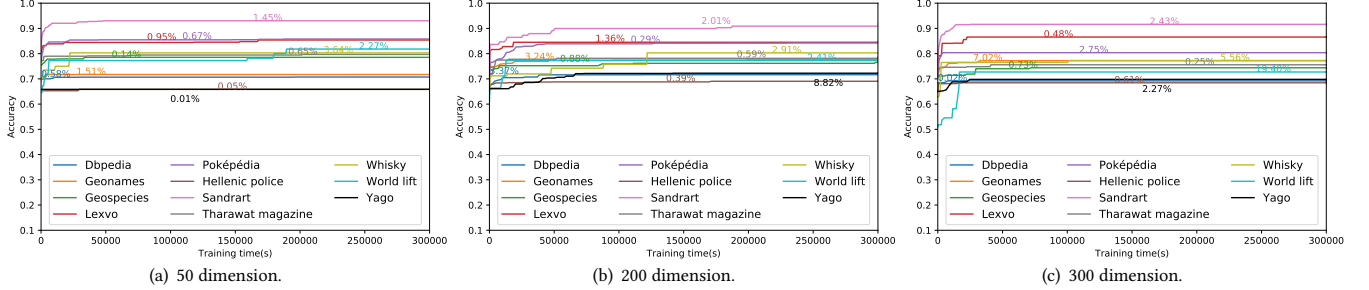


Figure 12: Performance of FKGE using transE on triple classification with different dimensions of embedding vectors.

Sampling	#20%				#40%				#60%				#80%			
Metric	Mean Rank	Hit@10	Hit@3	Hit@1	Mean Rank	Hit@10	Hit@3	Hit@1	Mean Rank	Hit@10	Hit@3	Hit@1	Mean Rank	Hit@10	Hit@3	Hit@1
Geonames	63,080.34	8.93	3.86	1.93	62,421.95	9.17	4.47	1.99	61,276.67	9.35	4.49	2.04	59,786.04	9.65	4.57	2.04
Yago	30,638.51	2.05	0.76	0.25	28,838.64	2.235	0.79	0.26	26,563.40	2.35	0.81	0.26	26,421.51	2.55	0.82	0.27
Geospecies	415.47	59.31	45.97	34.81	409.06	59.70	45.99	35.08	400.73	60.17	46.38	35.12	397.69	60.28	46.72	35.30
Poképédia	7,463.42	38.37	30.01	20.01	7,450.85	43.25	30.50	21.61	7,445.54	44.09	33.08	23.39	7,434.55	45.49	33.43	24.19
Sandrart	56.23	87.61	83.38	67.96	52.39	88.38	83.43	69.51	51.71	88.65	84.34	70.38	47.39	88.98	84.37	72.10
Hellenic Police	1,886.24	32.29	22.06	19.03	1,853.55	32.47	22.41	19.08	1,823.84	32.63	22.78	19.11	1,751.37	32.98	22.86	19.27
Lexvo	43.64	86.01	76.59	58.43	44.96	86.14	76.86	59.68	43.43	86.70	77.11	60.47	41.57	86.77	77.62	61.30
Tharawat magazine	232.63	12.50	4.58	1.76	232.62	12.92	4.81	1.96	228.65	13.13	5.09	1.99	226.67	13.19	5.15	2.10
Whisky	49.47	29.39	15.98	9.91	49.85	31.14	16.24	10.15	44.47	31.85	17.06	10.25	43.12	33.35	17.64	10.58
World lift	22.98	46.80	25.47	7.85	22.82	49.71	25.60	7.99	22.74	50.06	28.62	8.02	22.11	50.15	28.87	10.30

Table 6: Evaluation results on link prediction tasks in Filter with different sampling ratio(%) of aligned entities.

KGs	Dbpedia	Geonames	Yago	Geospecies	Poképédia	Sandrart	Hellenic	Lexvo	Tharawat	Whisky	World lift
FKGE-simple	70.28	73.94	67.29	78.53	85.81	92.19	67.38	85.24	78.34	77.27	86.36
FKGE	71.22	75.34	67.69	79.27	86.41	93.70	68.24	85.71	78.75	79.55	89.09

Table 7: Evaluation results of FKGE on triple classification with two different aggregation setting (%).

task, respectively. Similarly, Fig. 12 presents performances of FKGE by setting 3 different dimensions of embedding vectors. Overall, we can find that the larger the dimension of the embedding vector in the whole, the more obvious the effect that FKGE improves. The reason may be that under a certain dimension ranges, the larger the dimension of the embedded vectors, the more hidden information FKGE can federate.

Tab. 6 presents the results of link prediction by using TransE based FKGE, in terms of Mean Rank, Hit@10, Hit@3 and Hit@1, with different sampling ratio in the PPAT network. Intuitively, the more entities' embeddings that can be integrated, the more obvious the improvements are. For example, in the Filter metric, by using the federated knowledge graph representation learning of 20%, 40%, 60%, 80% and 100% (Presented in Tab. 4) sampling rates, the *Poképédia* gains up to 0.23%, 5.11%, 5.95%, 7.35% and 7.44% improvements

in terms of Hit@10 on the link prediction task, respectively. In addition to the metric of Hit@10, most of other knowledge graphs have achieved similar performance improvements in Mean Rank, Hit@3 and Hit@1. The above experimental results have once again proved the scalability and effectiveness of the proposed FKGE framework.

In order to measure whether the inclusion of virtual entities and relations contributes to the improvement of KGE, we compare the results of two types of aggregation methods on the triple classification task. We name the FKGE without additional virtual entities and relations in the generated embedding of PPAT network as FKGE-simple. By using TransE as base KGE method, Tab. 7 presents the result of triple classification between FKGE and FKGE-simple for all 11 knowledge graphs. We observe the consistent increases from 0.40% (Yago) to 2.73% (World lift) by including virtual entities and relations in the FKGE.