```
p1
```

$$d = -\frac{b}{\|b\|_2}$$

p2

(a) Hessian =
$$\begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix}$$

(b)yes

prove:

assume that
$$H = \begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\begin{split} &\text{let } z = \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} \\ &\text{then } z^T H z = 2z^2 \geq 0 \end{split}$$

so that matrix H is positive semi-definite, thus the function is convex

р3

import numpy as np import pandas as pd import matplotlib.pyplot as plt from sklearn.linear_model import LinearRegression from sklearn.metrics import mean_squared_error

#(1)

```
d = [100,100,100,127,127,127,152,152,152,178,178,178]
t_squre = [0.36,0.38,0.46,0.46,0.49,0.51,0.50,0.53,0.56,0.55,0.58,0.61]

plt.scatter(d, t_squre, color='blue', label='Data Points')
plt.xlabel('distance/cm')
plt.ylabel('time^2/s^2')
plt.title('Distance vs Time^2')
plt.legend()
plt.show()
```

#(2)

my_linear_model = LinearRegression()

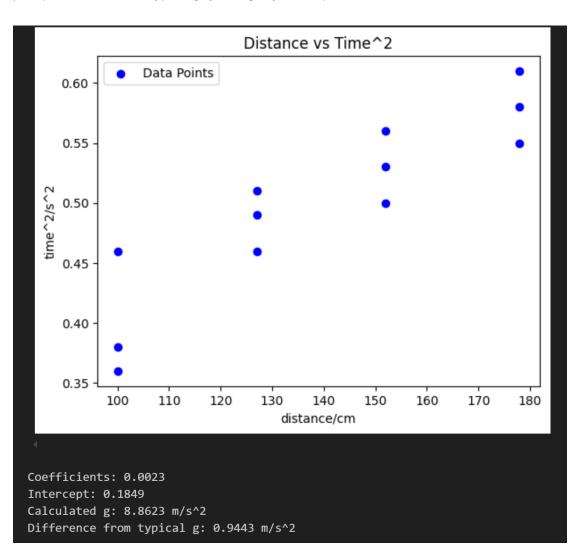
my_linear_model.fit(np.array(d).reshape(-1, 1), np.array(t_squre).reshape(-1, 1)) # training model

 $print(f'Coefficients: \{my_linear_model.coef_[0][0]:.4f\}') \ \# \ priting \ trained/optimal \ coeffs \ of polynomial \ terms$

print(f'Intercept: {my_linear_model.intercept_[0]:.4f}') # trained/optimal worker bias

#(3)

g_cal = 2/(my_linear_model.coef_[0][0]*100) # calculating g from coeffs g_typical= 9.80665 # typical value of g delta_g = abs(g_cal - g_typical) # calculating delta_g print(f'Calculated g: {g_cal:.4f} m/s^2') print(f'Difference from typical g: {delta_g:.4f} m/s^2')



(1)

```
import numpy as np
import pandas as pd
from sklearn.metrics import mean_squared_error
from sklearn.linear_model import LinearRegression
from sklearn.preprocessing import PolynomialFeatures
def model_D(x,D):
   poly = PolynomialFeatures(degree=D, include_bias=True)
   X_poly = poly.fit_transform(x)
   if D == 2:
       w = np.array([[5,1.5,0.03]])
   elif D == 3:
       w = np.array([[2,0.5,0.01,-0.001]])
   return X_poly @ w.T
x_validation = np.array([[4], [8], [9],[14]])
y_validation = np.array([[10], [20], [25], [35]])
y_pred_2 = model_D(x_validation, 2)
y_pred_3 = model_D(x_validation, 3)
mse_2 = mean_squared_error(y_validation, y_pred_2)
mse_3 = mean_squared_error(y_validation, y_pred_3)
print(f'MSE for D=2: {mse_2:.4f}')
print(f'MSE for D=3: {mse_3:.4f}')
```

output:

```
MSE for D=2: 7.4140
MSE for D=3: 320.9830
```

(2)MSE for D=2 is much smaller than MSE for D=3,thus D=2 is more approperiate

(1)

```
import numpy as np
import matplotlib.pyplot as plt

#function and its derivative
f = lambda v: v**4-5*v**2-3*v
f_derivative = lambda w: 4*w**3 - 10*w - 3

max_no_iterations = 3
alpha = 0.1
w = np.zeros(max_no_iterations)
w0 = -2.0
w[0] = w0

#gradient descent
for i in range(1,max_no_iterations):
    w[i] = w[i-1] - alpha * f_derivative(w[i-1])
    print(f'Iteration {i}: w = {w[i]:.4f}, f(w) = {f(w[i]):.4f}')
```

output:

```
Iteration 1: w = -0.5000, f(w) = 0.3125
Iteration 2: w = -0.6500, f(w) = 0.0160
```

(2.a)

```
import numpy as np
import matplotlib.pyplot as plt

#function and its derivative
f = lambda v: v**4-5*v**2-3*v
f_derivative = lambda w: 4*w**3 - 10*w - 3

max_no_iterations = 10000
alphas = [0.2,0.1,0.01,0.001]
epsilon = 0.001
w = np.zeros(max_no_iterations)
w0 = -2.0
w[0] = w0
```

```
#gradient descent
for alpha in alphas:
    print(f'Using alpha = {alpha}')
    w[0] = w0  # Reset w[0] for each alpha
    #gradient descent
    for i in range(1,max_no_iterations):
        w[i] = w[i-1] - alpha * f_derivative(w[i-1])
        if abs(f_derivative(w[i])) < epsilon:
            print(f'Convergence after {i} iterations ')
            print(f'the value of w at convergence is approximately {w[i]:.4f}')
            print(f'Optimal value of f(w) is {f(w[i]):.4f}')
            break</pre>
```

output:

```
Using alpha = 0.2

Using alpha = 0.1

Convergence after 10 iterations

the value of w at convergence is approximately -1.4017

Optimal value of f(w) is -1.7584

Using alpha = 0.01

Convergence after 58 iterations

the value of w at convergence is approximately -1.4018

Optimal value of f(w) is -1.7584

Using alpha = 0.001

Convergence after 616 iterations

the value of w at convergence is approximately -1.4018

Optimal value of f(w) is -1.7584

Using alpha = 0.001

Convergence after 616 iterations

the value of w at convergence is approximately -1.4018

Optimal value of f(w) is -1.7584

/var/folders/8f/s8cd84vs6ln67ggwr23649m80000gn/T/ipykernel_13280/4274278412.py:6: RuntimeWarning: overflow encountered in double_scalars

f_derivative = lambda w: 4*w**3 - 10*w - 3

/var/folders/8f/s8cd84vs6ln67ggwr23649m80000gn/T/ipykernel_13280/4274278412.py:6: RuntimeWarning: invalid value encountered in double_scalars

f_derivative = lambda w: 4*w**3 - 10*w - 3
```

When alpha = 0.2,no optimal value is obtained

(2.b)

```
import numpy as np
import matplotlib.pyplot as plt

#function and its derivative
f = lambda v: v**4-5*v**2-3*v
f_derivative = lambda w: 4*w**3 - 10*w - 3

max_no_iterations = 10000
alpha = 0.01
epsilon = 0.001
w = np.zeros(max_no_iterations)
w0 = 0.5

#gradient descent
for i in range(1,max_no_iterations):
```

```
\begin{split} w[i] &= w[i-1] - alpha * f\_derivative(w[i-1]) \\ & \text{if abs}(f\_derivative(w[i])) < epsilon: \\ & \text{print}(f'Convergence after \{i\} iterations ') \\ & \text{print}(f'the value of w at convergence is approximately $\{w[i]:.4f\}'$) \\ & \text{break} \\ & \text{print}(f'Iteration $\{i\}$, $w = $\{w[i]:.4f\}$, $f(w) = $\{f(w[i]):.4f\}'$) \\ \end{split}
```

output:

```
Convergence after 54 iterations
the value of w at convergence is approximately 1.7139
Iteration 54, w = 1.7139, f(w) = -11.2003
```

For my answer in a,l didn't get the global optimal value of w_0 . But if we choose the alpha = 0.01 and w_0 = 0.5,we'll get the global optimal value of w_0 .