

XT32H05x

XT32 microcontroller UART Application notes

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Revision History

Release	Date	Author	Summary of Change
V0.0.0	12/09/2023	Shirling Liu	Initial

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1 Introduce

This application note serves as a comprehensive guide for software developers, offering essential information on Universal Asynchronous Receiver/Transmitter (UART). It covers fundamental concepts and provides guidelines to ensure proper utilization of UARTs in software development projects. Whether you're a beginner or an experienced developer, this document will equip you with the necessary knowledge and best practices to effectively configure and utilize UARTs in your applications.

1.1 Required peripherals

This application involves modules as table 1.

Table 1. Modules in example

Sub-module	Peripheral use	Note
PADI	2 ports as UART transmitter port and	Call HAL_PADI_Init() in code
	receiver port	
UART	pin2 as UART1TX,	
	pin6 as UART1RX	
GPIO	2 LED pins and 1 button pin	**only for result indication
		purposes.

1.2 Compatible devices

This example is compatible with the devices in Table 2.

Table 2. Device list

Product	EVB
XT32H050	XB002823

2 Design description

2.1 Feature overview

XT32H0xxx provides 4 UART peripherals: UART1, UART2, UART3, UART4.

The UART software provides the following features:

- Half-duplex operation
- Asynchronous operation
- Flexible data formats (5~ 8 data bits, 1 or 2 stop bits)
- Baud rate: 2400 to 1500000 baud

2.2 Design steps

- 1. Enable UART1 Baudrate source clock and set clock divider.
- 2. Configure pin alternate function as UART from Peripheral PADI

through PADI_InitTypeDef structure. This example uses UART1 as serial communication.

- ➤ PADI_IDX_IO1_UART1_TX, means select and enable the IO1(pin 2).
- ➤ PADI_CFG_IO1_UART1_TX, means select UART0TX function for IO1.

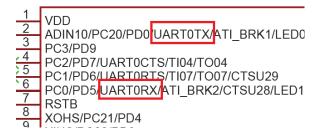


Figure 1. IO function selection

Note: please refer to XT32H0xxB—reference manual document to find the assignment relationship between pin 2 with IO1, pin6 with IO5.

- 3. Configure parameters for UART module.
- 4. Enable UART1_IRQn interrupt configuration if the example under IT mode, else ignore this step.
- 5. Process to transfer serial data with external devices.

2.3 Design considerations

2.4 Software flowchart

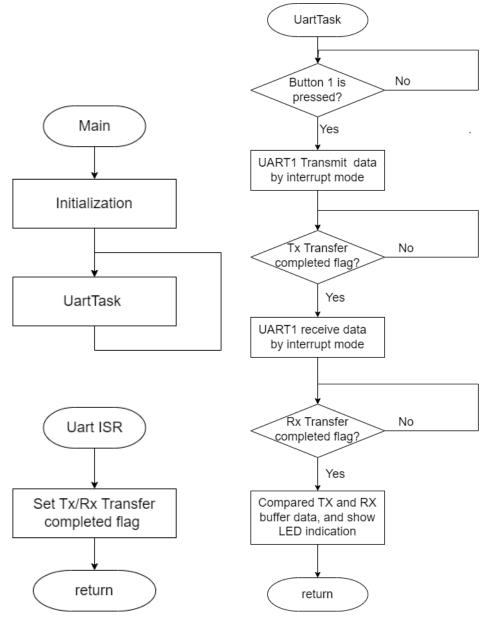


Figure 2. Application flow—Interrupt mode

2.5 Reference code

Configure Peripheral PADI through PADI_InitTypeDef structure to select alternate function as UART1 interface as bellowing code:

Configure Peripheral UART1:

```
/* -3- Configure uart module */
huart1.Instance = UART1;
huart1.Init.BaudRate = 9600;
huart1.Init.WordLength = UART_WORDLENGTH_8;
huart1.Init.StopBits = UART_STOPBITS_1;
huart1.Init.Parity = UART_PARITY_NONE;
huart1.Init.HwFlowCtl = UART_HWCONTROL_NONE;

if (HAL_UART_Init(&huart1) != HAL_OK)
{
    /* Error_Handler */
    Error_Handle();
}
```

XT_Uart_Task handles the basic transfer process.

```
void XT_Uart_Task(void)
/* USER CODE */
 if(EVB_Button1_State_Get()==PRESSED)
    if (HAL_UART_Transmit_IT(&huart1, (uint8_t *)aTxBuffer,
sizeof(aTxBuffer)) != HAL_OK)
      if(HAL_UART_GetError(&huart1)!=HAL_UART_ERROR_NONE)
        Error_Handle();
    while(!uTxFinished)
   uTxFinished = FALSE;
    /*receive data from slave device */
    if (HAL_UART_Receive_IT(&huart1, (uint8_t *)aRxBuffer,
sizeof(aTxBuffer)-2) != HAL_OK)
      if(HAL_UART_GetError(&huart1)!=HAL_UART_ERROR_NONE)
        Error_Handle();
    while(!uRxFinished)
    uRxFinished = FALSE;
    /*receive data until the bus idle state*/
    if(Buffercmp(aRxBuffer,aTxBuffer,(sizeof(aTxBuffer))-2)==0){
      EVB_Led_Toggle(LED_GREEN);
    }else
      EVB_Led_Off(LED_GREEN);
```

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2.6 Additional resources

- XT32H0xxB--reference manual
- XT32H0xxB--gpio-AN2302
- XT32H0xxB--dma-AN2308