# XT32H05x

# XT32 microcontroller UART Application notes

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# **Revision History**

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### **Contents**

1	INTR	ODUCE	. 1
-			
	1.1	REQUIRED PERIPHERALS	. 1
	1.2	COMPATIBLE DEVICES	. 2
2	DESIG	GN DESCRIPTION	. 2
	2.1	FEATURE OVERVIEW	
	2.2	DESIGN STEP	. 2
	2.3	Design considerations	. 4
	2.4	SOFTWARE FLOWCHART	. 4
	2.5	REFERENCE CODE	
	2.6	Additional resources	. 7

# **List of Figures**

Figure 1.	IO function selection	
Figure 2.	Application flow—Polling mode	4

# **List of Tables**

Table 1.	Modules in example	. 1
Table 2.	Device list	. 2

#### 1 Introduce

This application note serves as a comprehensive guide for software developers, offering essential information on Universal Asynchronous Receiver/Transmitter (UART). It covers fundamental concepts and provides guidelines to ensure proper utilization of UARTs in software development projects. Whether you're a beginner or an experienced developer, this document will equip you with the necessary knowledge and best practices to effectively configure and utilize UARTs in your applications.

#### 1.1 Required peripherals

This application involves modules as table 1.

Table 1. Modules in example

Sub-module	Peripheral use	Note
PADI	2 ports as UART transmitter port and	Call HAL_PADI_Init() in code
	receiver port	
UART	pin2 as UART1TX,	
	pin6 as UART1RX	
GPIO	2 LED pins and 1 button pin	**only for result indication
		purposes.

#### 1.2 Compatible devices

This example is compatible with the devices in Table 2.

Table 2. Device list

Product	EVB
XT32H050	XB002823

#### 2 Design description

#### 2.1 Feature overview

XT32H0xxx provides 4 UART peripherals: UART1, UART2, UART3, UART4.

The UART software provides the following features:

- Half-duplex operation
- Asynchronous operation
- Flexible data formats (5~ 8 data bits, 1 or 2 stop bits)
- Baud rate: 2400 to 1500000 baud

#### 2.2 Design steps

- 1. Enable UART1 Baudrate source clock and set clock divider.
- 2. Configure pin alternate function as UART from Peripheral PADI

through PADI\_InitTypeDef structure. This example uses UART1 as serial communication.

- > PADI\_IDX\_IO1\_UART1\_TX, means select and enable the IO1(pin 2).
- ➤ PADI\_CFG\_IO1\_UART1\_TX, means select UART0TX function for IO1.



Figure 1. IO function selection

Note: please refer to XT32H0xxB—reference manual document to find the assignment relationship between pin 2 with IO1, pin6 with IO5.

- 3. Configure parameters for UART1 module.
- 4. Process to transfer serial data with external devices.

# 2.3 Design considerations 2.4 Software flowchart

Figure 2. Application flow—Polling mode

#### 2.5 Reference code

Configure Peripheral PADI through PADI\_InitTypeDef structure to select alternate function as UART1 interface as bellowing code:

#### Configure Peripheral UART1:

```
/* -3- Configure uart module */
huart1.Instance = UART1;
huart1.Init.BaudRate = 9600;
huart1.Init.WordLength = UART_WORDLENGTH_8;
huart1.Init.StopBits = UART_STOPBITS_1;
huart1.Init.Parity = UART_PARITY_NONE;
huart1.Init.HwFlowCtl = UART_HWCONTROL_NONE;

if (HAL_UART_Init(&huart1) != HAL_OK)
{
    /* Error_Handler */
    Error_Handle();
}
```

#### XT\_Uart\_Task handles the basic transfer process.

```
void XT Uart Task(void)
 /* USER CODE */
 if(EVB_Button1_State_Get()==PRESSED)
   if (HAL_UART_Transmit(&huart1, (uint8_t *)aTxBuffer,
sizeof(aTxBuffer), 5000) != HAL_OK)
      if(HAL_UART_GetError(&huart1)!=HAL_UART_ERROR_NONE)
        Error_Handle();
   /*receive data from slave device */
   if (HAL_UART_Receive(&huart1, (uint8_t *)aRxBuffer,
sizeof(aTxBuffer)-2, 5000) != HAL OK)
      if(HAL_UART_GetError(&huart1)!=HAL_UART_ERROR_NONE)
        Error_Handle();
    /*receive data until the bus idle state*/
sizeof(aTxBuffer), &received count,0x1000) != HAL OK)
        if(HAL_UART_GetError(&uart_huart)!=HAL_UART_ERROR_NONE)
        Error_Handler();
   if(Buffercmp(aRxBuffer,aTxBuffer,(sizeof(aTxBuffer))-2)==0){
      EVB_Led_Toggle(LED_GREEN);
   }else
      EVB_Led_Off(LED_GREEN);
```

#### 2.6 Additional resources

- XT32H0xxB--reference manual
- XT32H0xxB--gpio-AN2302
- XT32H0xxB--dma-AN2308