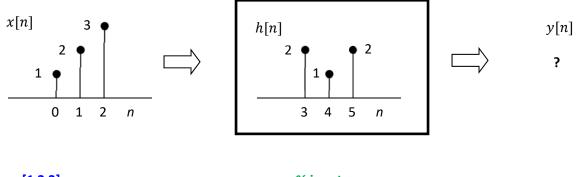
ELEC2100 Prelab #2

Objective

- To be familiar with impulse response and convolution

Ex.1 Convolution



```
x=[1 2 3];
                                                   % input x
                                                   % n index of x
nx=0:2;
                                                   % impulse response h
h=[2 1 2];
nh=3:5;
                                                   % n index of h
y=conv(x,h)
                                                   % obtain the output y using convolution
                                                   % n index of y
ny=3:7;
% \min(ny) = \min(nx) + \min(nh)
                                          \rightarrow
                                                   3 = 0 + 3
                                          \rightarrow
% \max(ny) = \max(nx) + \max(nh)
                                                   7 = 2 + 5
% Each time-shifted impulse of the impulse response can be regarded as a delay unit.
figure(1);
subplot(311); stem(nx,x); ylabel('x[n]'); grid; axis([-1 8 0 4]);
subplot(312); stem(nh,h); ylabel('h[n]'); grid; axis([-1 8 0 4]);
subplot(313); stem(ny,y); ylabel('y[n]'); grid; axis([-1 8 0 11]);
xlabel('n');
```

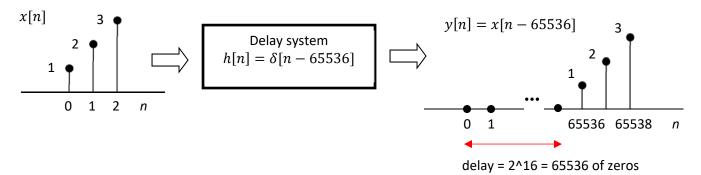
Self-check:

- Write down the mathematical expression of x[n] as the sum of impulses.
- Write down the mathematical expression of h[n] as the sum of impulses.
- Obtain the output sequence y by hand calculation.
- Check your answer with the Matlab result.

Ex.2 Impulse Response (Audio)

Read the audio file (song2.wav) using "audioread". Use "zeros" to introduce delay to the audio file.

e.g.



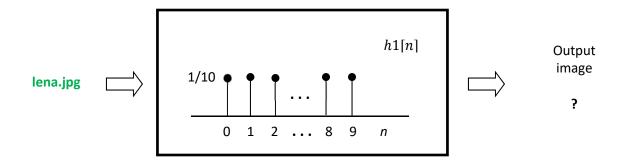
```
[x,fs] = audioread('song2.wav');
                                                % read audio file and sample rate
x=x';
                                                % transpose of x
delay=2^16;
                                                % delay (in terms of points with zero magnitude)
y=[zeros(1,delay) x];
                                                % delayed version by adding zeros in front of x
                                                % time index of x
tx=[0:length(x)-1]/fs;
                                                % time index of v
ty=[0:length(y)-1]/fs;
figure(2);
plot(tx,x); grid;
                                                % plot x
hold on;
plot(ty,y,'r');
                                                % plot y in the same figure(2)
xlabel('time (sec)');
legend('Original','Delayed');
hold off;
z=[x zeros(1,delay)] + y;
                                                % original and delayed are added together
% Two matrices must have the same length before adding them together.
% Certain number of zeros are added to original x so as to make it have the same length as y.
sound(x, fs);
                                                % hear the original
sound(y, fs);
                                                % hear the delayed
                                                % hear the sum of x and y
sound(z, fs);
```

Self-check:

- Is x a row matrix or column matrix?
- Why is it necessary to obtain the transpose of x?
- Can you modify the given Matlab code so that it is not necessary to do transpose of x?
- What is the time interval between two consecutive sample points?
- What is the actual delay time (in seconds)?
- Can you hear any difference between the original and the delayed version?
- What is the mathematical expression of the impulse response h[n] to generate z[n]?
- Can you define the impulse response h and use "conv" to generate z?

Ex.3 Impulse Response (Image)

Display the image file (lena.jpg) using "imread". Apply the image file to system h1[n] using "conv2" (i.e. perform 2-D convolution).



i2=imread('lena.jpg'); % read the file figure(3); imshow(i2); % display the image h1=ones(1,10)/10 % impulse response (1-by-10, 1-D filter) % perform 2-D convolution using 1-D filter y1=conv2(h1, h1, i2, 'same'); figure(4); imshow(uint8(y1)); % map values into [0:255] before showing the figure h2=ones(10,10)/100 % impulse response (10-by-10, 2-D filter) y2=conv2(i2, h2, 'same'); % perform 2-D convolution using 2-D filter % map values into [0:255] before showing the figure figure(5); imshow(uint8(y2));

For color image, use the Matlab command "convn" to perform N-dimensional convolution.

Self-check:

- Compare i2 and y1.
- What is the difference on y2 between with 'same' and without 'same'?
- Why is it necessary to use the command "uint8" for showing the image after convolution?
- Any difference on the convolution between using 1-D filter and 2-D filter in this example?
- What do the above systems (h1 and h2) do?