

# The 3D Wave Equation

## Elastic & Acoustic

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# Starting points

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- Particle position (displacement):  $\mathbf{u}(\mathbf{r}, t)$
- Equation of motion (i.e:  $\mathbf{F} = m\mathbf{a}$ )
- Hooke's Law:  $(\boldsymbol{\sigma} = \mathbf{C} : \mathbf{e})$

## Assumptions:

- isotropic (direction isn't important)
- small perturbations in  $\mathbf{u}$

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## Assumptions:

- form of  $\boldsymbol{\sigma}$ :  $\sigma_{ij} = e_{kk}\delta_{ij} + 2\mu e_{ij}$
- form of  $\mathbf{e}$ :  $e_{ij} = \frac{1}{2}(\nabla_i u_j + \nabla_j u_i)$



# 3d elastic isotropic wave equation

After some working, and use of identity:

$$\nabla^2 \mathbf{a} \equiv \nabla (\nabla \cdot \mathbf{a}) - \nabla \times \nabla \times \mathbf{a}$$

$$\rho \frac{\partial^2 \mathbf{u}}{\partial t^2} = (\nabla \cdot \mathbf{u}) (\nabla \lambda) + (\nabla \mathbf{u} + (\nabla \mathbf{u})^T) (\nabla \mu) + (\lambda + 2\mu) \nabla (\nabla \cdot \mathbf{u}) - \mu \nabla \times \nabla \times \mathbf{u}$$

Note: if Lamé parameters,  $\lambda$  and  $\mu$ , vary slowly in space then top two terms on RHS are small

Also: above supports both P-waves and S-waves

# 3d acoustic isotropic wave equation

In the acoustic case we have  $\lambda = \rho c^2$  and  $\mu = 0$   
Also, force is negative gradient of pressure,  $p$

Eliminating  $\mathbf{u}$  from 3d elastic equation gives:

$$\frac{1}{\rho c^2} \frac{\partial^2 p}{\partial t^2} = \nabla \cdot \left( \frac{1}{\rho} \nabla p \right)$$

Note: if density varies slowly enough in space then  $\rho$  cancels from both sides, and RHS is just  $\nabla^2 p$

