# **Example ACSE-2 Autumn 2019**

## **Imperial College London 2019**

## Please answer all questions

### Total time for the exam: 90 minutes

## Calculators will be provided

#### Total marks= 80

- (1) Give a mathematical definition of the Taylor series. Using an expansion about the point x=0 use Taylor series to estimate the value of exp(x) when x=0.1 accurate to 6 significant figures. [6 marks]
- (2) (a) Consider the ordinary differential equation system

$$\frac{dx}{dt} = Ax$$
, where  $A = \begin{pmatrix} -1 & 3 \\ 3 & -1 \end{pmatrix}$ 

The solution takes the form: x(t) = Cexp(tA), where C is a constant (vector) of integration. Using matrix diagonalization to compute this matrix exponential, show that the solution can be written as

$$x(t) = \frac{1}{2}(C_1 + C_2) {1 \choose 1} exp(2t) + \frac{1}{2}(C_2 - C_1) {-1 \choose 1} exp(-4t)$$
[10 marks]

- (b) What choice of initial condition for this problem yields a solution that tends to zero as t tends to infinity? [4 marks]
- (3) Define the vector one, two and max norms mathematically. Consider a vector with two components, plot the shapes mapped out in 2D by all vectors with unit norm, i.e. the "unit circle", using each of these three norms. [6 marks]
- (4) Consider a plane of reflection that passes through the origin. Let  $\hat{\mathbf{n}}$  be the unit normal vector to the plane and let  $\mathbf{r}$  be the position vector for a point in space.
  - (a) Show that the reflected vector for  $\mathbf{r}$  is given by  $\mathbf{T} \cdot \mathbf{r} = \mathbf{r} 2(\mathbf{r} \cdot \hat{\mathbf{n}})\hat{\mathbf{n}}$ , where  $\mathbf{T}$  is the transformation that corresponds to the reflection. [6 marks]

(b) Let 
$$\hat{\mathbf{n}} = \frac{1}{\sqrt{3}} (\hat{\mathbf{e}}_1 + \hat{\mathbf{e}}_2 + \hat{\mathbf{e}}_3)$$
. Find the matrix of T. [5 marks]

(5) Given a vector field  $\mathbf{v} = x_1^2 \hat{\mathbf{e}}_1 + x_3^2 \hat{\mathbf{e}}_2 + x_2^2 \hat{\mathbf{e}}_3$ . For the point  $\mathbf{x} = (1,1,0)$ , find the following: [7 marks]

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i.  $\nabla \mathbf{v}$ 

ii.  $\nabla \cdot \mathbf{v}$ 

iii.  $\nabla \times \mathbf{v}$ 

The differential dv for  $d\mathbf{x} = ds(\hat{\mathbf{e}}_1 + \hat{\mathbf{e}}_2 + \hat{\mathbf{e}}_3)/\sqrt{3}$ iv.

(6)

(a) Given the following strain tensor  $\mathbf{\varepsilon} = \begin{bmatrix} 5 & 4 & 0 \\ 4 & -1 & 0 \\ 0 & 0 & 3 \end{bmatrix} \times 10^{-5}$  in a point

Sketch and describe how two lines originally in  $\hat{\mathbf{e}}_1$  and  $\hat{\mathbf{e}}_2$  direction, respectively, would be deformed by this strain field. [*5 marks*]

Find the principal strains [6 marks]

Find the principal strain directions and use these to sketch how a sphere would deform in this strain field [*9 marks*]

(7)

Consider a case with material flowing in a channel of a width 2b, driven by a pressure drop along the channel of  $\Delta P$  over every distance L. Take  $x_1$  to be the direction of flow and  $x_2$  the direction across the width of the channel, i.e. ranging from -b on the bottom to b on the top. The channel can be considered infinite in  $x_3$  direction.

For this case, the Navier-Stokes equation simplifies to:

$$\nabla \cdot \boldsymbol{\tau} = \nabla p$$

where  $\tau$  is the deviatoric stress tensor and p is pressure. Assume that there is linear relation between deviatoric stress  $\tau$  tensor and strain rate **D**:  $\tau = 2\eta \mathbf{D}$ , where  $\eta$  is viscosity.

(a) Write out the relevant components of the force balance for this case, i.e. for the non-zero components of the stress divergence and pressure gradient.

[4 marks]

(b) Show that the following is the velocity profile: 
$$v_1(y)=\frac{1}{2\eta}\frac{\Delta P}{L}(b^2-x_2^2)$$

[5 marks]

(c) Derive equations to describe the pathlines of the flow, i.e. relating position of a fluid particle  $\mathbf{x}(t)$  to its initial position  $\boldsymbol{\xi}$  and time t. Sketch the pathlines of 3 particles with positions chosen to illustrate the character of the flow.

[7 marks]