Traffic congestion avoidance through a cross simulation between ns-3 and SUMO



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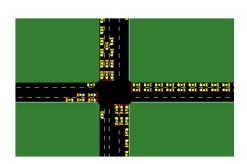
Introduction [1/2]





The Problem:

Network and Road congestion



Why network congestion?

Now self-driving cars, the need to have good communication between vehicles. Exchange of a lot of information and a lot of nodes in the same place.

Introduction [2/2]

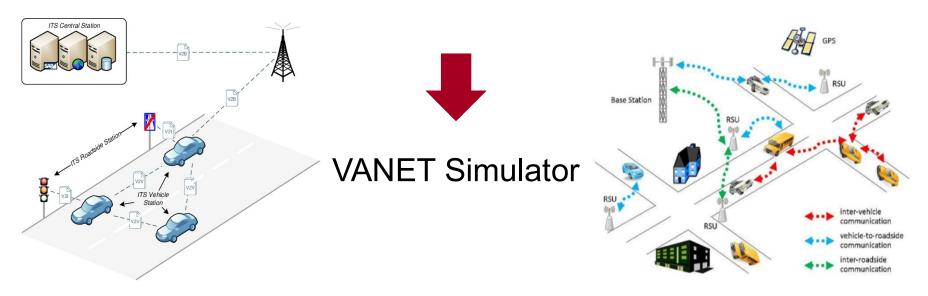


Solution?

Good management of the channel to maintain good performance

How?

By simulation, because it's too expansive to recreate a complete scenario like that.



Simulators



How simulate a VANET environment?

Using more existing simulators:

• NS-3



• SUMO



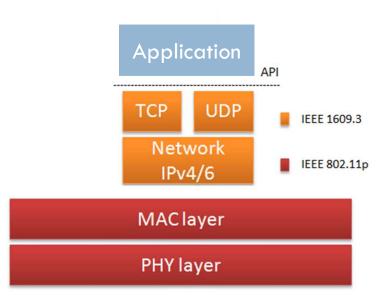


NS-3: Network simulator



- Implementation of the communication stack:
 - Log-distance path loss model
 - Nakagami-m fading
 - Random loss for the shadowing
- A UDP application to implement V2V communication





SUMO

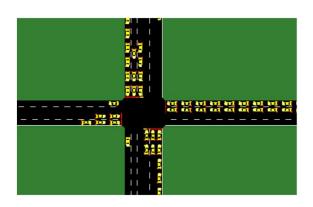


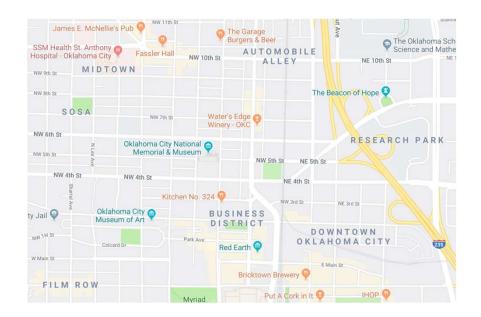
SUMO: Simulation of Urban Mobility



Realistic environment

Correct mobility pattern





NS3-SUMO-COUPLING



Coupling:



TU Dresden module that implements a TCP client for the communication

NS-3 SUMO

A TCP server that answers to the requests of the client

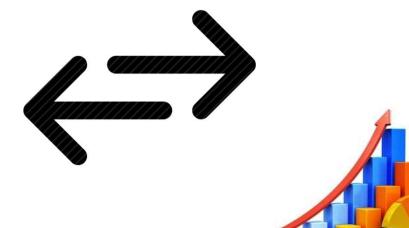
SW Implementation



After the creation of the environment, we start to speak about our UDP application, that can be seen as the conjunction of three main methods:

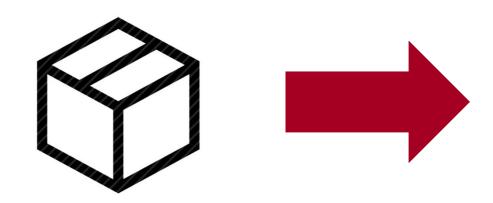
Send

Receive



Stats computation and decision



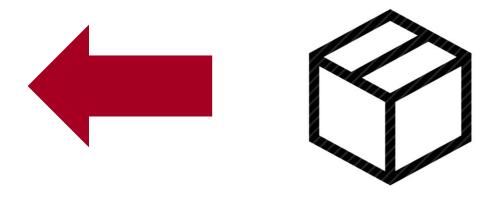


The UDP packet contains the following information:

- ID
- Road ID
- Timestamp
- Number of packets/s
- If is congested or not

Receive





When a UDP packet arrives at a node the process is the following:

- Extraction of the information
- Gather some metrics
- Data organization

Stats calculation





Computation and aggregation of some statistics that will be then used to make a decision:

- Throughput
- Delay
- Packet loss

Decision part



Now that we have all the data, we can make a decision.



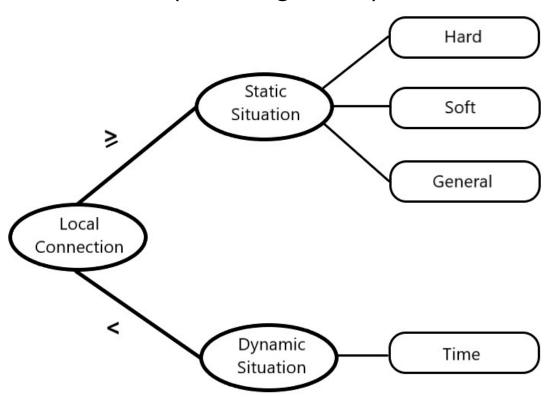
The decision process is subdivided in this way:

- Status identification and Rerouting
- Interval change
- Combination of the two

Status Identification [1/2]



The status (as congested) is identified by a decision tree:



HARD: high "local" throughput AND high "local" delay both compared to a minimum value.

SOFT: high "local" throughput OR high "local" delay AND the speed of the car.

General: we have a very high general throughput OR a very high general delay

Time: we consider the evolution of the "local" delay and "local" throughput by using two sub-windows if the values in the newest window are bigger than the old one it means that the vehicle is congested.

Status Identification [2/2]





Another way to decide the status of the vehicle is a voting system that works in this way:

 If the half + 1 (including myself) of the vehicles in the road tell that the road is congested, then we are congested.

Rerouting



The rerouting phases are:

 Identification of the congested road

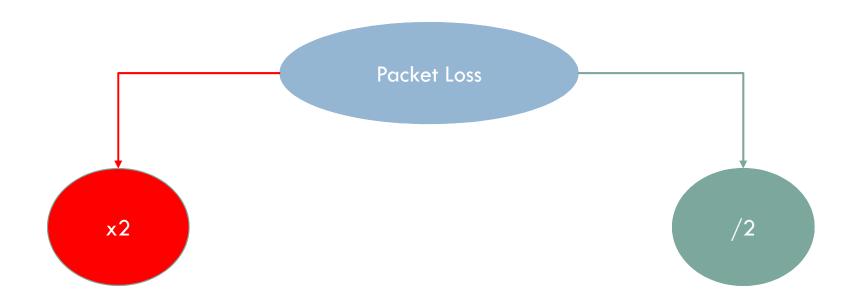


- Setting a new cost for the congested road
- Rerouting callback of TraCl (SUMO)
- Reset the cost of the roads

Change Interval



Another approach that we used to reduce the network congestion is to reduce the interval on which the packet is sent from a node.



Combination







Change Interval

The rerouting procedure affects the change of the interval because we have set that, if the vehicle is stacked the interval must decrease.

Rerouting



Change Interval

The change interval procedure affects the rerouting because in this way we obtain a different number of packets, and this changes the overall state.

Results



Variables considered:

- The aggressiveness of the thresholds
- Size of the dynamic window
- Number of vehicles in the scene
- Type of strategy adopted

90 seconds of simulation

standard, weak, aggressive

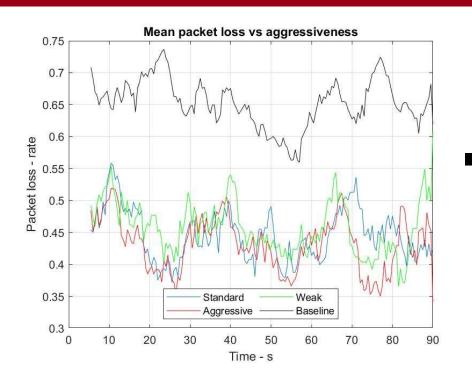
1, 2, 3, 4, 8 instants

50, 75, 100, 125, 150, 175, 200

- Rerouting ———— yes/no
- Interval change → yes/no

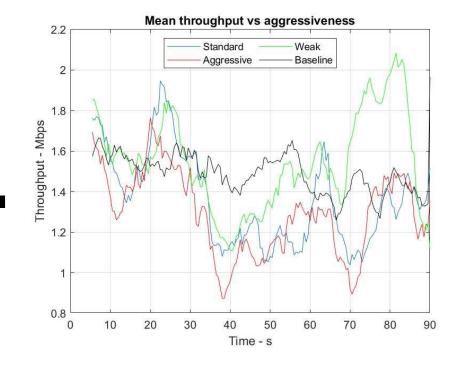
Threshold aggressiveness





Throughput: baseline more stable, situations where weak thresholds give better results

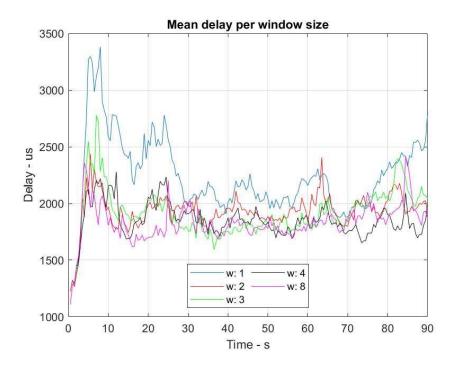
Packet loss: baseline way higher than any threshold choice on the project

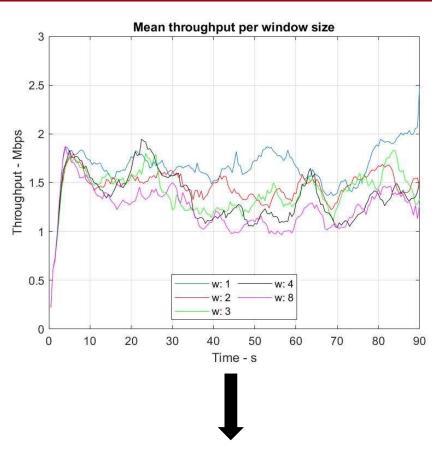


Dynamic window size



Higher delay with the static case. In general, bigger window size means lower delay.





Throughput very similar, but lower as the window gets bigger.

Half way recap



Best choice

Threshold aggressiveness:

The packet loss is always better than the baseline, where the mean value is almost doubled. Throughput similar, but more stable in the baseline; weak thresholds give best values

WEAK

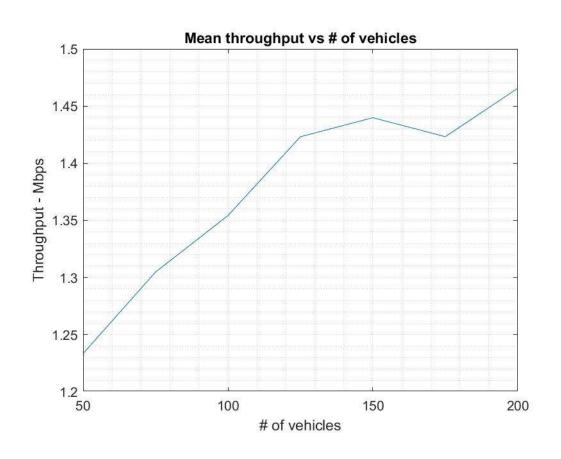
Dynamic window size:

A mid-small value has a better packet loss and doesn't penalize the throughput too much

2-3

Number of vehicles [1/2]



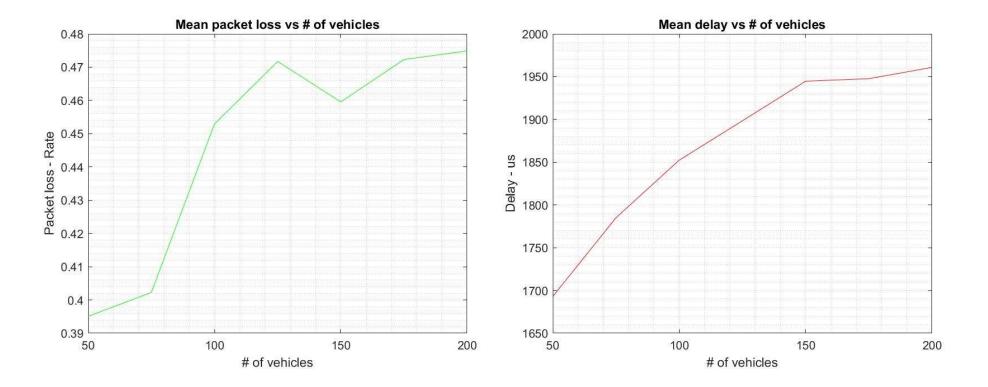


In general, as expected, if the number of vehicles rises in the scene, the throughput goes up

BUT

Number of vehicles [2/2]





Delay and packet loss rise with the number of vehicles, so a trade-off is needed

Strategy combinations [1/2]



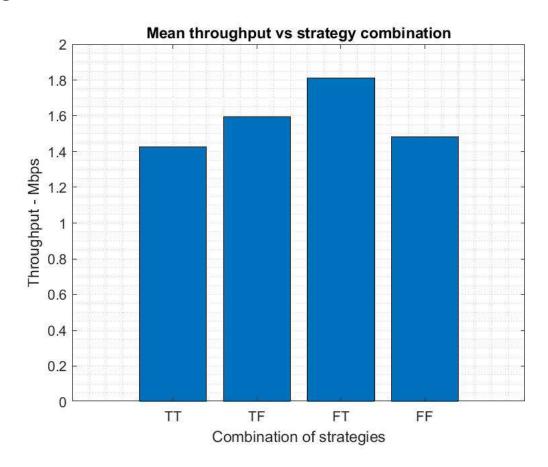
TT: both rerouting and interval change

TF: only rerouting

FT: only interval change

FF: baseline

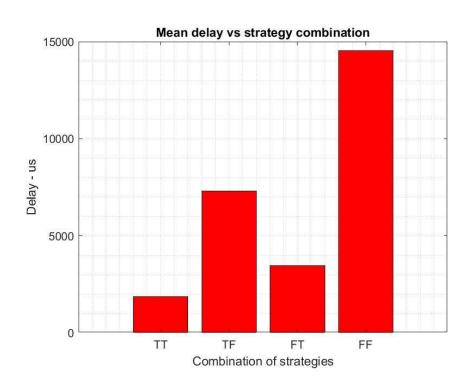
TT has a mean throughput lower than the baseline, but the other solutions are better.

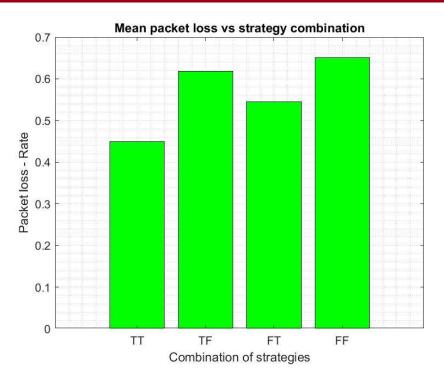


Strategy combinations [2/2]



In both delay and packet loss, if the strategy includes the interval change,



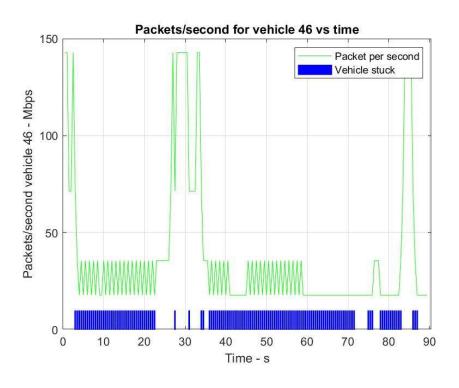


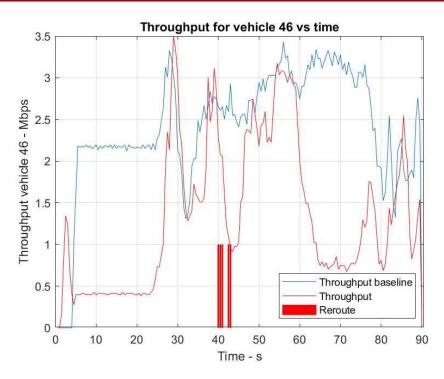
the metrics are better than the solutions with the rerouting.

Example of single vehicle



If the baseline throughput is high, the throughput of the project is low because the vehicle is in congestion.





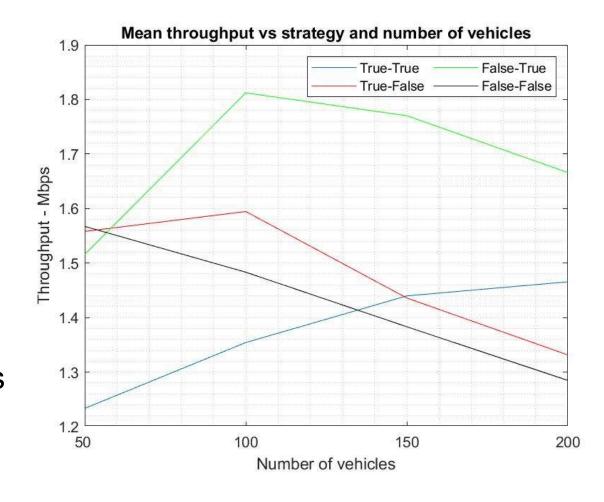
Applying rerouting strategy brings more throughput to the device.

Complete analysis [1/4]



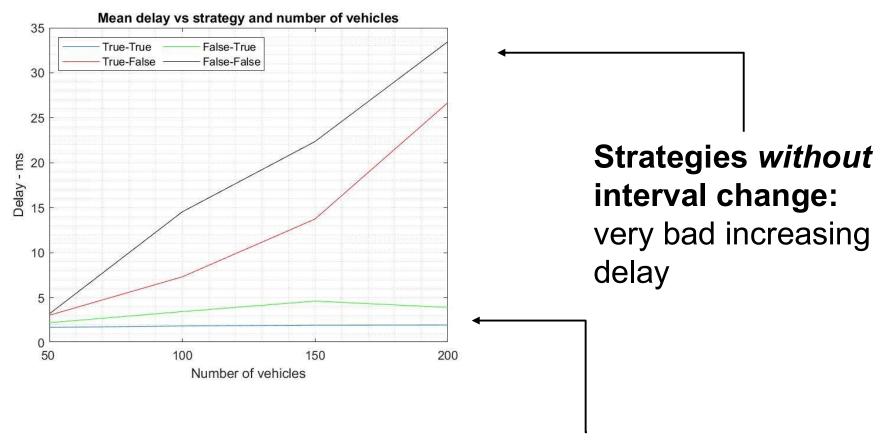
Combination of number of vehicles and strategy adopted:

The throughput is the best in the solution with only the interval change, but the complete strategy rises with the number of vehicles



Complete analysis [2/4]



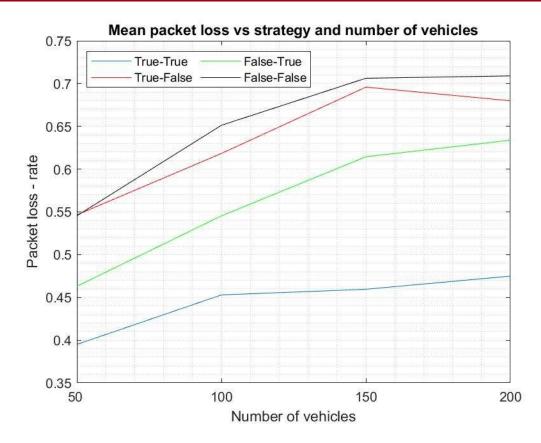


Strategies *with* **interval change**: low and stable delay

Complete analysis [3/4]



The complete strategy (TT), has the lowest packet loss; on average it's 20% better than the other strategies.



Between the other strategies, the best is the one with interval change only.

Complete analysis [4/4]



- The interval change strategy is a MUST
- Rerouting is an ok solution but lowers the throughput

RESULTS

- If the throughput is important, the best is the interval change-only strategy
- If the throughput can be sacrificed, the best choice is the complete strategy

Conclusions



- The number of vehicles affects every considered metric
- Changing the interval is a good strategy to improve the traffic and the reliability in the network
- This same strategy, when coupled with the rerouting, has the potential to improve the traffic in an urban scenario

For the future:

- Considering more variables and their combinations
- Considering different maps
- Gather more data with many runs



Thanks for your attention

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