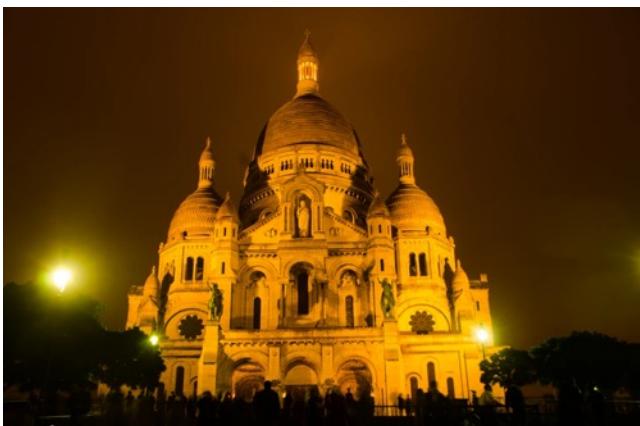
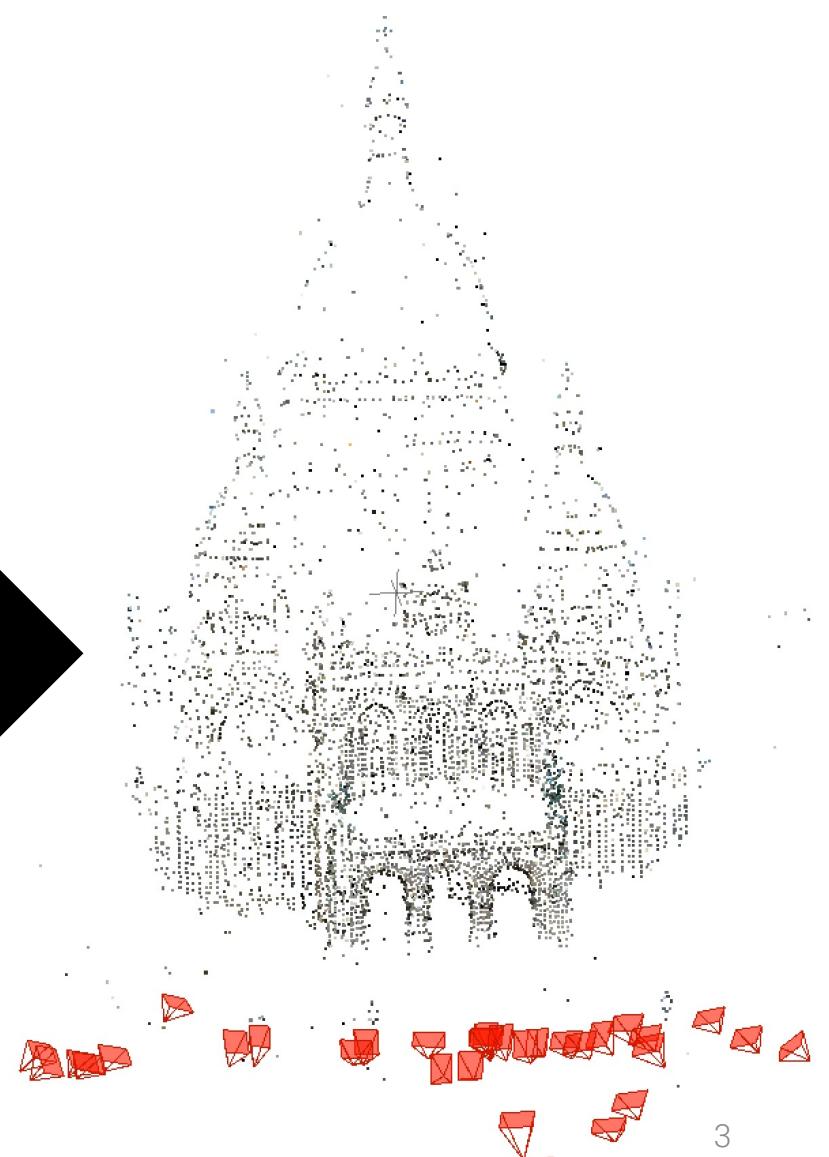


Structure-from-Motion



SfM →



1. Feature Detection and Description



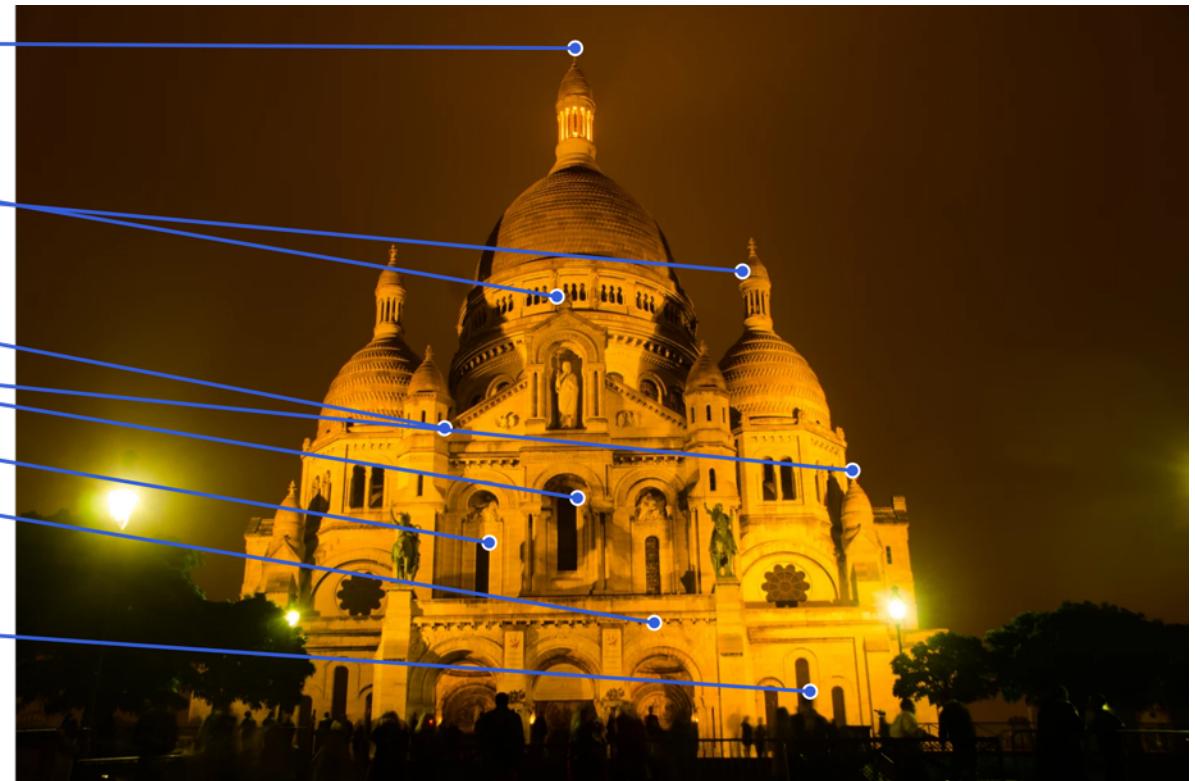
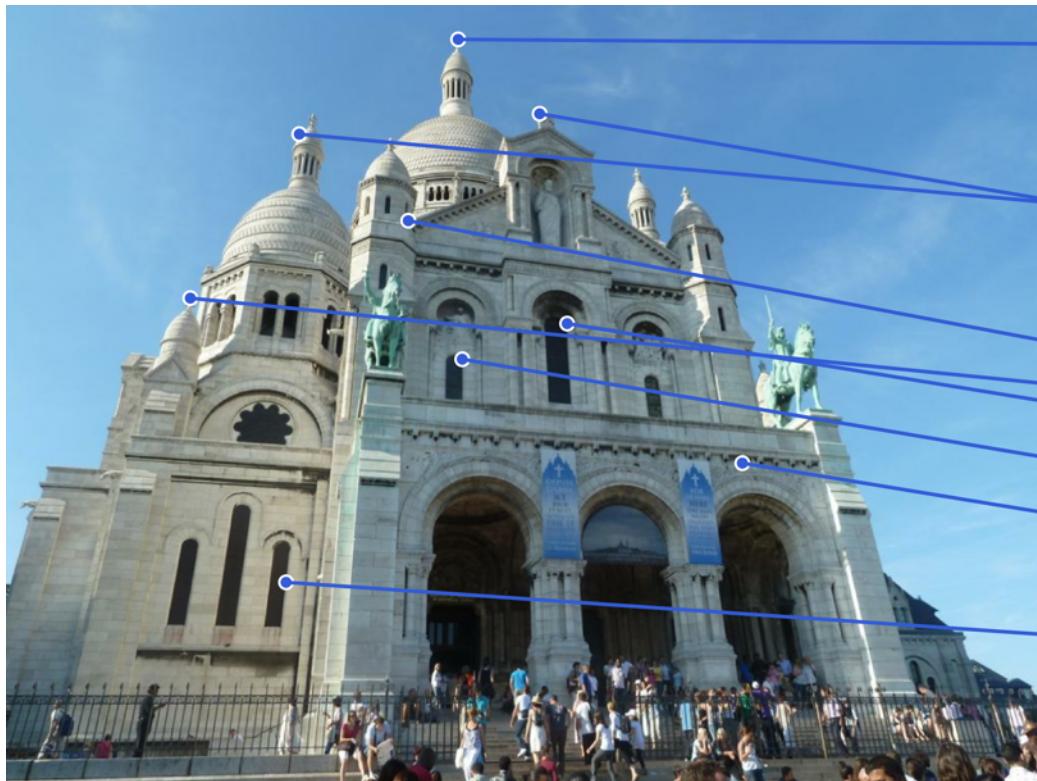
1. Feature Detection and Description



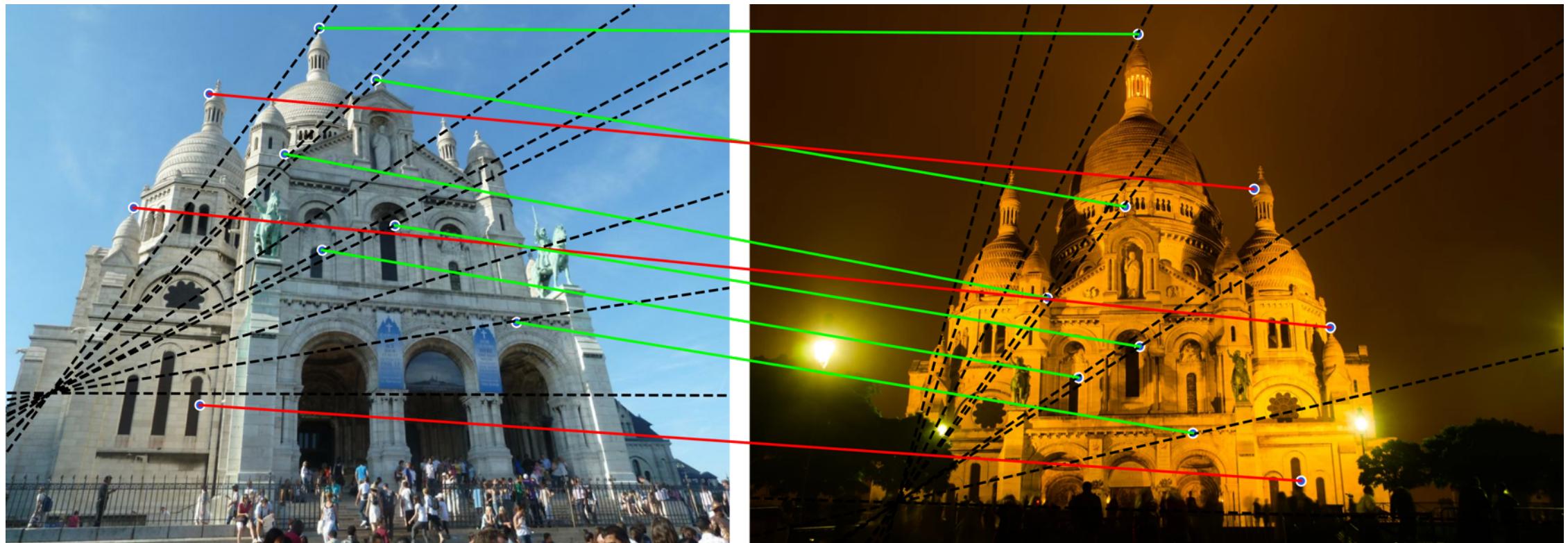
1. Feature Detection and Description



2. Feature Matching

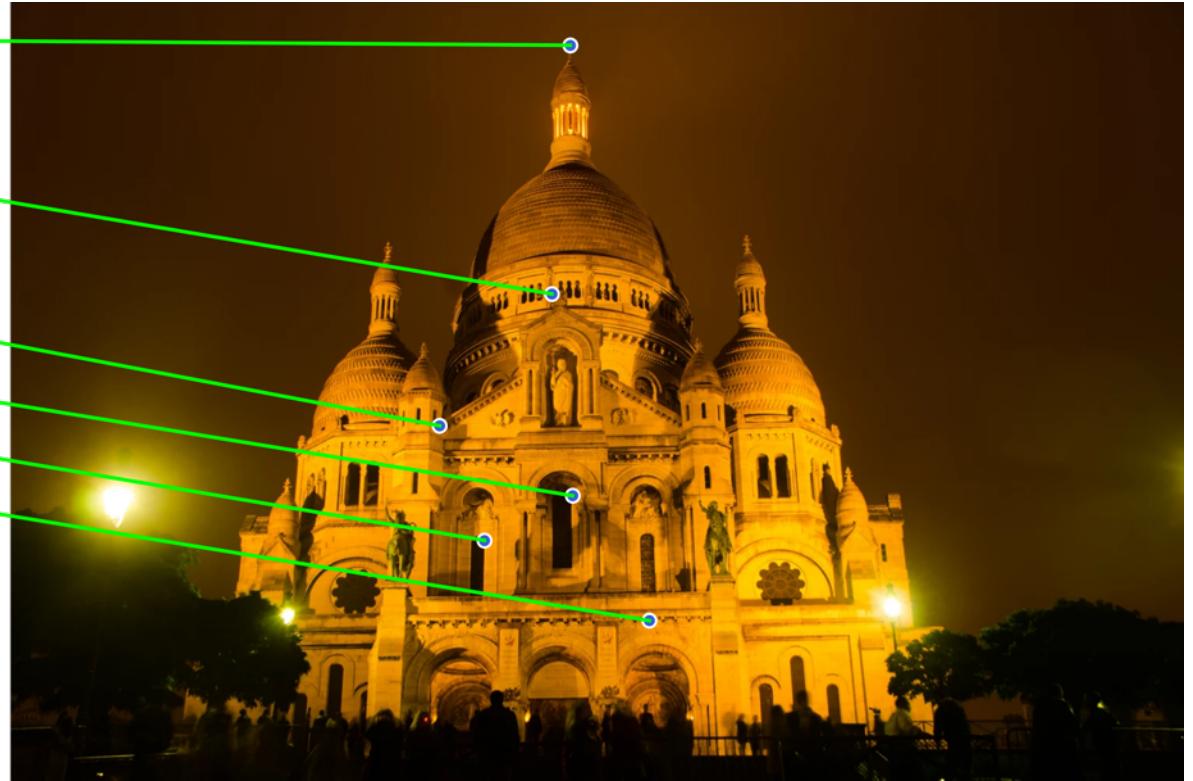
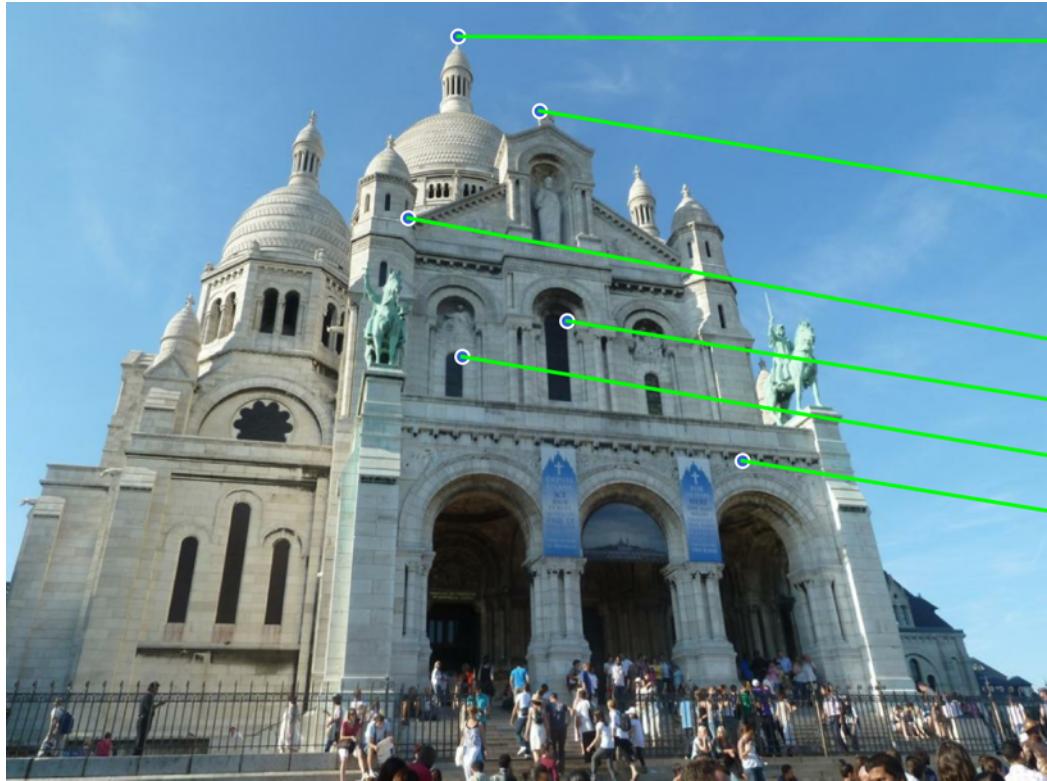


3. Geometric Verification

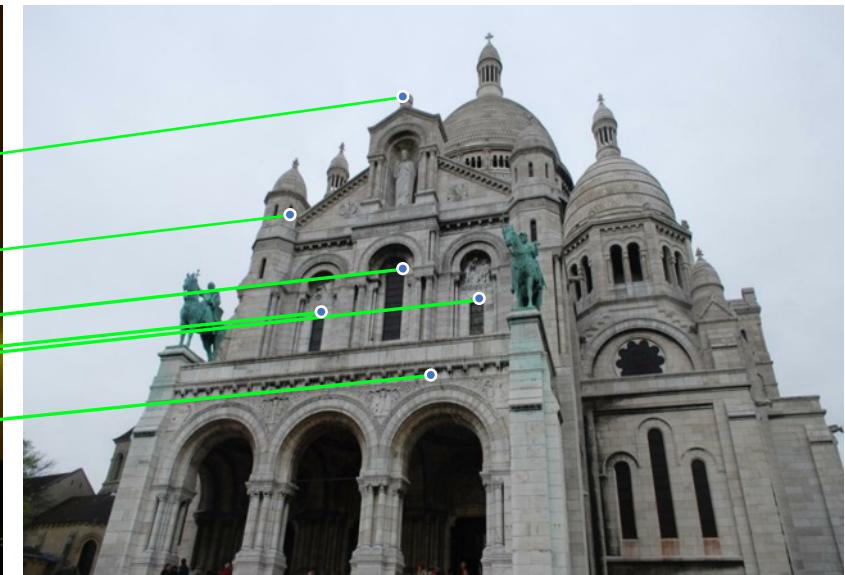
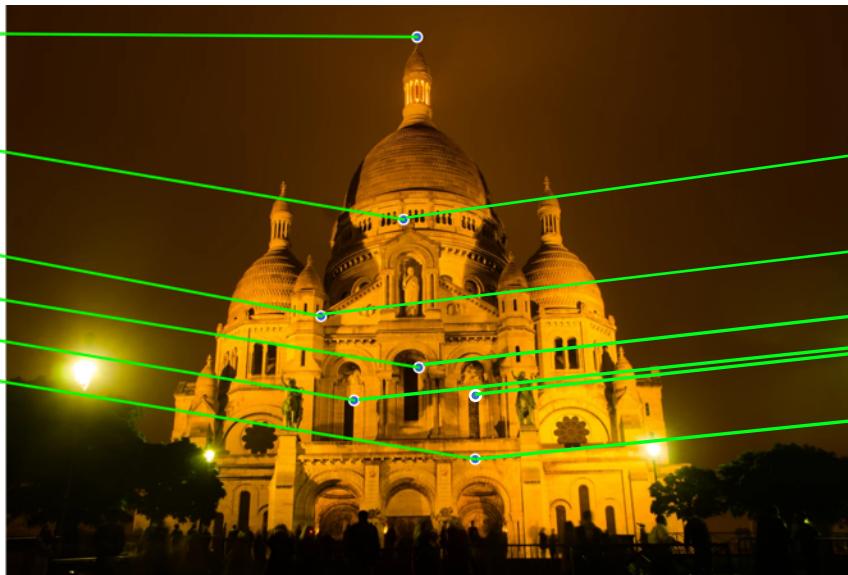
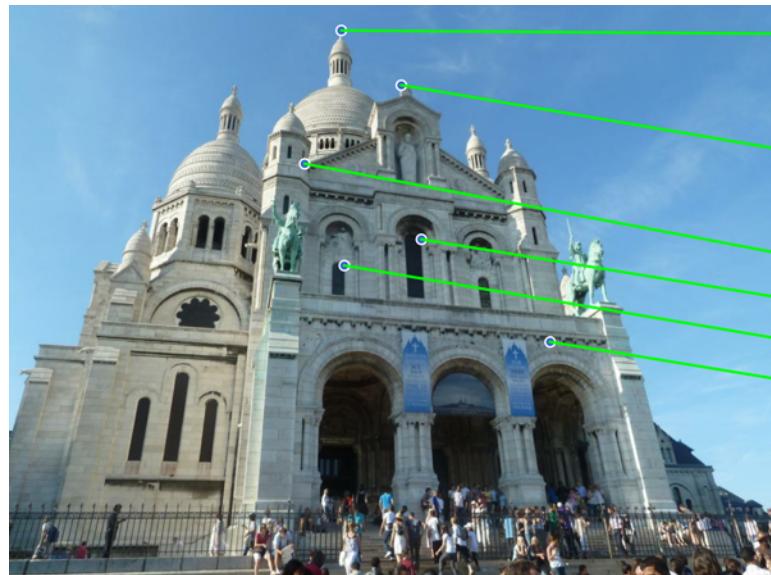


Use epipolar constraints to remove incorrect matches

3. Geometric Verification



4. Triangulation



4. Triangulation



4. Triangulation

