



# FAL

Factorio Assembly Language

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**REFERENCE MANUAL**  
**v0.10.0**

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# 0. OVERVIEW

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The Factorio Assembly Language is the future of automated manufacture. Designed ground-up for use in large-scale factories. The Factorio Assembly Language has over op-codes and each MicroController can store 32 instructions.

*Notes like this will appear in black outlined rectangles. These notes indicate more information on a topic*

## 0.1 Registers

MicroControllers has 4 internal read-write registers:

**mem1**                      **mem2**                      **mem3**                      **mem4**

It also has 4 read-only registers:

**mem5** or **IPT**: Instruction pointer index.

**mem6** or **CNR**: Number of Signals on the Red Wire Input.

**mem7** or **CNG**: Number of Signals on the Green Wire Input

**mem8** or **CLK**: Monotonic clock.

## 0.1 Mapped Memory

The MicroController can be extended with RAM module. The MicroController has 4 external memory ports:

**North Port 01** is mapped to **MEM11-14**.

**South Port 01** is mapped to **MEM21-42**.

**North Port 02** is mapped to **MEM31-34**.

**South Port 02** is mapped to **MEM41-44**.

*You can also connect a MicroController to North and South Port 01.*

# 1. GLOSSARY

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## **1.1 Signal**

A Type and a signed integer value.

## **1.2 Type**

Each signal contains a Type. The type could either refer to an item your factory consumes or produces or could be a 'virtual' type.

## **1.3 Value**

The integer part of a Signal.

## **1.4 Move**

Copy a Signal from one register to another.

## **1.5 Set**

Set the Value of a Signal to another Value.

## **1.6 Register**

Register A unit of memory that can store one Signal.

## **1.7 Clear**

Reset a Register to NULL.

## **1.8 NULL**

A Virtual Black Signal with a Value of 0.

## **1.9 Label**

A text identifier used for the jumps.

# 2. BASIC INSTRUCTION SET

---

<:I> specifies a parameter that takes a literal integer.  
<:R> specifies a parameter that takes a register address.  
<:W> specifies a parameter that takes a wire Input address.  
<:L> specifies a parameter that takes a label.

*Each MicroController can only read one instruction per Nth tick.  
(customizable)*

## 2.1 Comments

**Syntax:** #<COMMENT>

All text after the comment

## 2.2 Labels

**Syntax:** :<LABEL>

Labels are used as identifiers for the jump instructions. A label is a colon followed by text. When using a label in a jump instruction you must also include the colon.

**Example:**

```
:LOOP
```

```
jmp :LOOP
```

## 2.3 NOP

**Syntax:** nop

NOP stands for no-operation. It has no effect on the state of the internal registers. It will still take 1 action for an MicroController to read a NOP instruction.

## 2.4 MOV

**Syntax:** mov <SRC:W/R> <DST:R>...

Takes the Signal at <SRC> and writes it to all <DST> Register(s).

## 2.5 SET

**Syntax:** set <SRC:I> <DST:R>

Takes the Value at <SRC> and write it to <DST>.

## 2.6 SWP

**Syntax:** swp <SRC:R> <DST:R>

Swaps the Signals in <SRC> and <DST>.

## 2.7 CLR

**Syntax:** clr < DST:R>...

Writes NULL to all <DST> Register(s).

## 2.8 Find In Green

**Syntax:** fig <SRC:R>

Looks for a Signal in the Green Wire Input where the Signal Type is equal to the type at <SRC>. If a signal is found it is written to memN.

**Example:**

```
fig mem21
mul mem1 2
mov mem1 out
```

## 2.9 Find In Red

**Syntax:** FIR <SRC:R>

Looks for a Signal in the Red Wire Input where the Signal Type is equal to the type at <SRC>. If a signal is found it is written to memN.

## 2.10 JMP

**Syntax:** jmp <SRC:I/R/L>

Jumps the instruction pointer to <SRC>. If <SRC> is a literal integer, the instruction pointer jumps to that line. If <SRC> is a Register, the instruction pointer jumps to line N where N is the value at the Register. If <SRC> is a Label, the instruction pointer jumps to the first declaration of that Label.

**Example:**

```
:LOOP
jmp :LOOP
```

## 2.11 HLT

**Syntax:** hlt <SRC:R>

Halts the program

# 3. ARITHMETIC INSTRUCTIONS

---

## 3.1 ADD

**Syntax:** add <SRC:I/R> <DST:I/R>

Adds the Value at <SRC> to the Value at <DST> and writes the result to memN.

## 3.2 SUB

**Syntax:** sub <SRC:I/R> <DST:I/R>

Subtracts the Value at <DST> from the Value at <SRC> and writes the result to memN.

## 3.3 MUL

**Syntax:** mul <SRC:I/R> <DST:I/R>

Multiplies the Value at <SRC> by the Value at <DST> and writes the result to memN.

## 3.4 DIV

**Syntax:** div <SRC:I/R> <DST:I/R>

Divides the Value at <SRC> by the Value at <DST> and writes the result to memN.

## 3.5 MOD

**Syntax:** mod <SRC:I/R> <DST:I/R>

Executes <SRC> modulo <DST> and writes the result to memN.

**Example:**

```
:60 second clock.
```

```
add mem1 1
```



mod mem1 60

jmp 1

### 3.6 POW

**Syntax:** pow <SRC:I/R> <DST:I/R>

Raises <SRC> to the power of <DST> and writes the result to memN.

*Arithmetic instructions ignore Signal Type.*

### 3.7 DIG

**Syntax:** dig <SRC:I/R>

Reads the digit at position <SRC> from mem1 and writes the result to memN.

### 3.8 DIS

**Syntax:** dis <SRC:I/R> <DST:I/R>

Writes <DST> to the digit at position <SRC> in mem1.

If <DST> is more than 1 digit long, it writes the 1<sup>st</sup> digit.

### 3.9 BITWISE AND

**Syntax:** bnd <SRC:I/R> <DST:I/R>

Executes <SRC> AND <DST> then writes the result to memN.

### 3.10 BITWISE OR

**Syntax:** bor <SRC:I/R> <DST:I/R>

Executes <SRC> OR <DST> then writes the result to memN.

### 3.11 BITWISE XOR

**Syntax:** bxe <SRC:I/R> <DST:I/R>

Executes <SRC> XOR <DST> then writes the result to memN.

### 3.12 BITWISE NOT

**Syntax:** bnd <SRC:I/R>

Executes NOT <SRC> then writes the result to memN.

### 3.13 BITWISE LEFT SHIFT

**Syntax:** bls <SRC:I/R> <DST:I/R>

Shifts bits in <SRC> by <DST> to the left, then writes the result to memN.

### 3.14 BITWISE RIGHT SHIFT

**Syntax:** brs <SRC:I/R> <DST:I/R>

Shifts bits in <SRC> by <DST> to the right, then writes the result to memN.

### 3.15 BITWISE LEFT ROTATE

**Syntax:** blr <SRC:I/R> <DST:I/R>

Rotate bits in <SRC> by <DST> to the left, then writes the result to memN.

### 3.16 BITWISE RIGHT ROTATE

**Syntax:** brr <SRC:I/R> <DST:I/R>

Rotate bits in <SRC> by <DST> to the right, then writes the result to memN.

# 4. TEST INSTRUCTIONS

---

Test instructions will skip the next instruction if the test is successful.

## 4.1 TEST GREATER THAN

**Syntax:** tgt <SRC:I/R> <DST:I/R>

Tests if <SRC> Value is greater than <DST> Value.

## 4.2 TEST LESS THAN

**Syntax:** tlt <SRC:I/R> <DST:I/R>

Tests if <SRC> Value is less than <DST> Value.

## 4.3 TEST EQUAL TO

**Syntax:** teq <SRC:I/R> <DST:I/R>

Tests if <SRC> Value is equal to <DST> Value.

## 4.4 TEST TYPES EQUAL

**Syntax:** tte <SRC:R> <DST:R>

Tests if <SRC> Type is equal to <DST> Type.

## 4.5 TEST TYPES NOT EQUAL

**Syntax:** ttn <SRC:R> <DST:R>

Tests if <SRC> Type is not equal to <DST> Type.

# 5. BLOCKING INSTRUCTIONS

---

Blocking instructions will pause the program until the operation is complete.

## 5.1 SLP

**Syntax:** slp <SRC:I/R>

Program will sleep for <SRC> ticks.

## 5.2 BKR

**Syntax:** bkr <SRC:I/R>

Pause the program until there is at least <SRC> Signals on the Red Wire Input.

## 5.3 BKG

**Syntax:** bkg <SRC:I/R>

Pause the program until there is at least <SRC> Signals on the Green Wire Input.

## 5.4 SYN

**Syntax:** syn

Pause the program until all other connected MicroControllers call SYN.

# 6. INTERRUPT SIGNALS

---

**There are 5 special signals that can be used to interrupt a program.** When a MicroController receives an interrupt signal on either it's Green or Red Wire Input will immediately execute the interrupt.

## **6.1 HLT**

Halts the program

## **6.2 RUN**

Runs the program

## **6.3 STP**

Steps the program (executes the current instruction then halts).

## **6.4 SLP**

Program will sleep for N ticks, where N is the Signal's Value.

## **6.5 JMP**

Jumps the Program Instruction Pointer to N, where N is the Signal's Value.

# 7. POINTERS

---

When specifying a memory address as a parameter to an instruction, you may also pass a memory pointer. A pointer is a special address where the literal address is evaluated at run-time.

Typically a memory address takes the form `mem1`. This instructs the MicroController to access the 1<sup>st</sup> Register. A pointer takes the form `mem@1`. This instructs the MicroController to read the Value at Register 1 and then read the Value at Register N, where N was the Value at Register 1.

## 7.1 `mem@n`

Access register X, where X is the Value at Register N.

## 7.2 `red@n`

Access Red Wire Input X, where X is the Value at Register N.

## 7.3 `green@n`

Access Green Wire Input X, where X is the Value at Register N.

# 8. EXAMPLE PROGRAMS

---

## 8.1 MULTIPLY INPUT

This program takes the 1<sup>st</sup> Red Wire Input, doubles it and outputs the result.

```
mov red1 mem1      # Write Red wire Input 1 to Register 1
mul mem1 2          # mem1 = mem1 * 2
mov mem1 out        # Write Register 1 to Output
```

## 8.2 ACCUMULATE INPUT

This program takes the first 4 Signals on the Red Wire Input and accumulates them over time. It requires a RAM module at North Port 01.

```
clr                # Clear all registers
set 11 mem2        # Set mem2 to 11
set 3 mem2         # Set mem2 to 3
:loop              # Create a label
mov red@3 mem1     # Write RED[mem3] to mem1
add mem1 mem@2     # mem1 = mem1 + mem[mem2]
mov mem1 mem@2     # Write mem1 to mem[mem2]
add mem2 1         # mem1 = mem2 + 1
tlr mem1 15        # Skip next line if mem1 < 15
set 11 mem1        # Set mem1 to 11
mov mem1 mem2      # Write mem1 to mem2
add mem3 1         # mem1 = mem3 + 1
tlr mem1 5         # Skip next line if mem1 < 5
set 1 mem1         # Set mem1 to 1
mov mem1 mem3      # Write mem1 to mem3
```