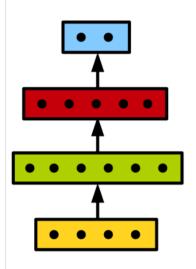
Más detalles, contenido del master haplap



Overfitting and regularization





The more layers / hidden units, the more capacity and risk of overfitting

- W can be very good for training, with enough layers and capacity the model can memorize the training data!
 Low train error
- Generalize very poorly to test data (i.e. the real world)

High test error

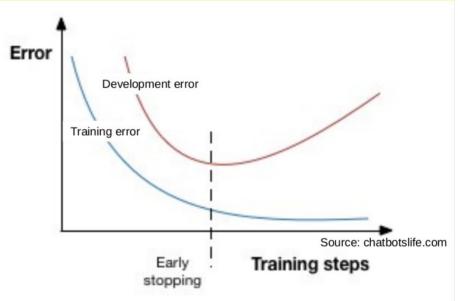




Overfitting, experimental design, Early stopping



 Overfitting can be seen in this graph







Overfitting, experimental design, Early stopping



- Overfitting can be seen in this graph
- Experimental setup: %80 train, %10 dev, %10 test (blind!!)
- Training steps Early stopping: Early finishes training as soon as development error starts to increase
- Model selection: best accuracy (lowest error) at development





Development error

Training error

Source: chatbotslife.com

Overfitting and regularization



Second solution: add a regularizer to the loss function that avoids the model to fit the training data

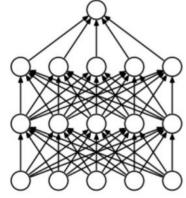
$$J_{i}(W) = -\log \left| \frac{\exp(W_{c_{i}}^{T} x)}{\sum_{c' \in C} \exp(W_{c'}^{T} x)} \right| + \lambda \sum_{k} W_{k}^{2} \quad \text{L2 norm}$$

Overfitting and regularization

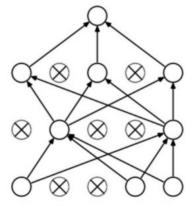


Third solution: Dropout

- At training time deactivate 50% of the activations at random (hyperparameter dropout rate)
- At test time use all activations



(a) Standard Neural Net



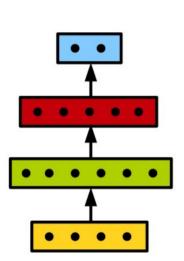
(b) After applying dropout.

Source: "Dropout: a simple way to prevent neural networks from overfitting", JMLR 2014

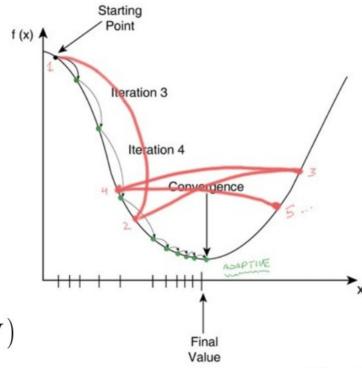


SGD convergence: learning rate





$$W = W - \eta \frac{1}{K} \sum_{i}^{K-1} \nabla J_{i}(W)$$



Source: cs231n.github.io

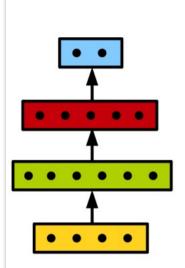




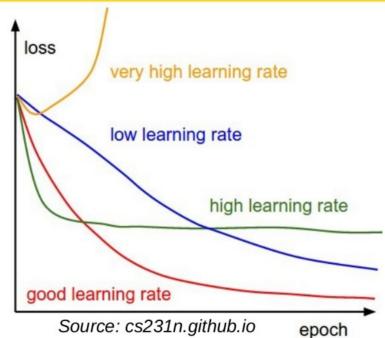


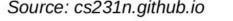
SGD convergence: learning rate





$$W = W - \eta \frac{1}{K} \sum_{i}^{K-1} \nabla J_{i}(W)$$







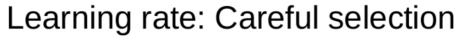


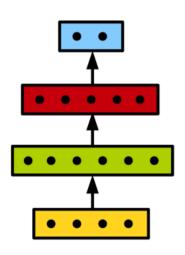




SGD convergence







• Optimizers (Adam, sgd, ...)

Don't expect convergence: use early stopping

Don't expect a unique solution: ensembling helps

$$W = W - \eta \frac{1}{K} \sum_{i}^{K-1} \nabla J_{i}(W)$$







MLP in Keras









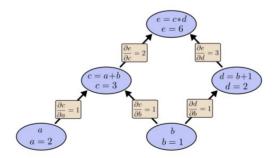
Introducing TensorFlow Keras

- High-level neural networks API, open source, Python
- High-level interface for Tensorflow 2
 - Works with on top of Pytorch too!
- Conceived as an interface for programmers
- Modular: model is a stack of layers
- Fast prototyping, hides details
 - Also its weakness: need to know lower level Tensorflow if layer/function is not available



Under the hood (back-end)

- Computational graphs
 - Numeric computation as data flow graphs
 - Nodes are operations, with inputs and outputs
 - Edges are tensors flowing between nodes
 - Forward computation
 - Backward (backpropagation) Autodiff: each node "knows" its derivative
 - Chain rule







- Define the model architecture (graph)
- Specify optimizer, loss, compile graph
- Train and test





- Prepare the input and specify dimensions
- Define the model architecture (graph)
- Specify optimizer, loss, compile graph
- Train and test

```
(x_train,y_train), (x_dev,y_dev) = load_my_data()
print(x_train.shape) # (6920, 1000)
print(y_train.shape) # (6920,)
print(x_dev.shape) # (872, 1000)
print(y_dev.shape) # (872,)
```





- Define the model architecture (graph)
- Specify optimizer, loss, compile graph
- Train and test

from tensorflow.keras import Sequential from tensorflow.keras.layers import Dense model = Sequential() model.add(Dense(units=1, activation='sigmoid', input_shape=(x_train.shape[1],)))

```
# input: (None, 1000)
# output: (None, 1)
```







- Define the model architecture (graph)
- Specify optimizer, loss, compile graph
- Train and test

model.summary()

```
Layer (type) Output Shape Param ======== dense (Dense) (None, 1) 1001
```





- Prepare the input and specify dimensions
- Define the model architecture (graph)
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