

Feature Detection

- The first thing that must be done is finding image points, or keypoints, that are likely to be seen across multiple images.
- While *SIFT* is the most well known keypoint detector, it has some limitations and is also a patented algorithm, meaning it cannot be used commercially without paying licensing fees.
- To this end, we opted to use the *ORB* feature points; which is claims to be both better and faster than *SIFT*.

