

Feature Matching

Once keypoints have been found in all images, they need to be matched across each other. To this end, we try to match keypoints in the following way:

- From each pair of images:
 - Match keypoints using the descriptor based on the shortest hamming distance.
 - From all of the matched keypoints, use RANSAC to compute the Fundamental Matrix (F) and use it to filter out as many outliers as possible.

