Evaluation:

Efficiency: timing (use cozmo to evaluate this). Call function a every step we need.

1. how long it takes to give instructions for robot
2. how long overall takes it to reach the goal

Surveys (monkey servers): qualitative questions? (how they enjoyed the interactions + feedback about how to improve).

CODING.

1. Movements. Define function for each of this movements (define the distance movement, coordiates, etc).
2. Map creation (environment: position of cubes and cozmo, and keep track of all over time).
3. Human robot interaction. Detect human, over time,etc.

State machine: listening to instructions, follow instructions, update the human. – wait, follow instructions, update.

Use while loops.