

CS2040S

# Data Structures and Algorithms

DFS

# Housekeeping

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Midterms are still being graded.

We also still have a make-up to run before grading everyone entirely.

# Roadmap

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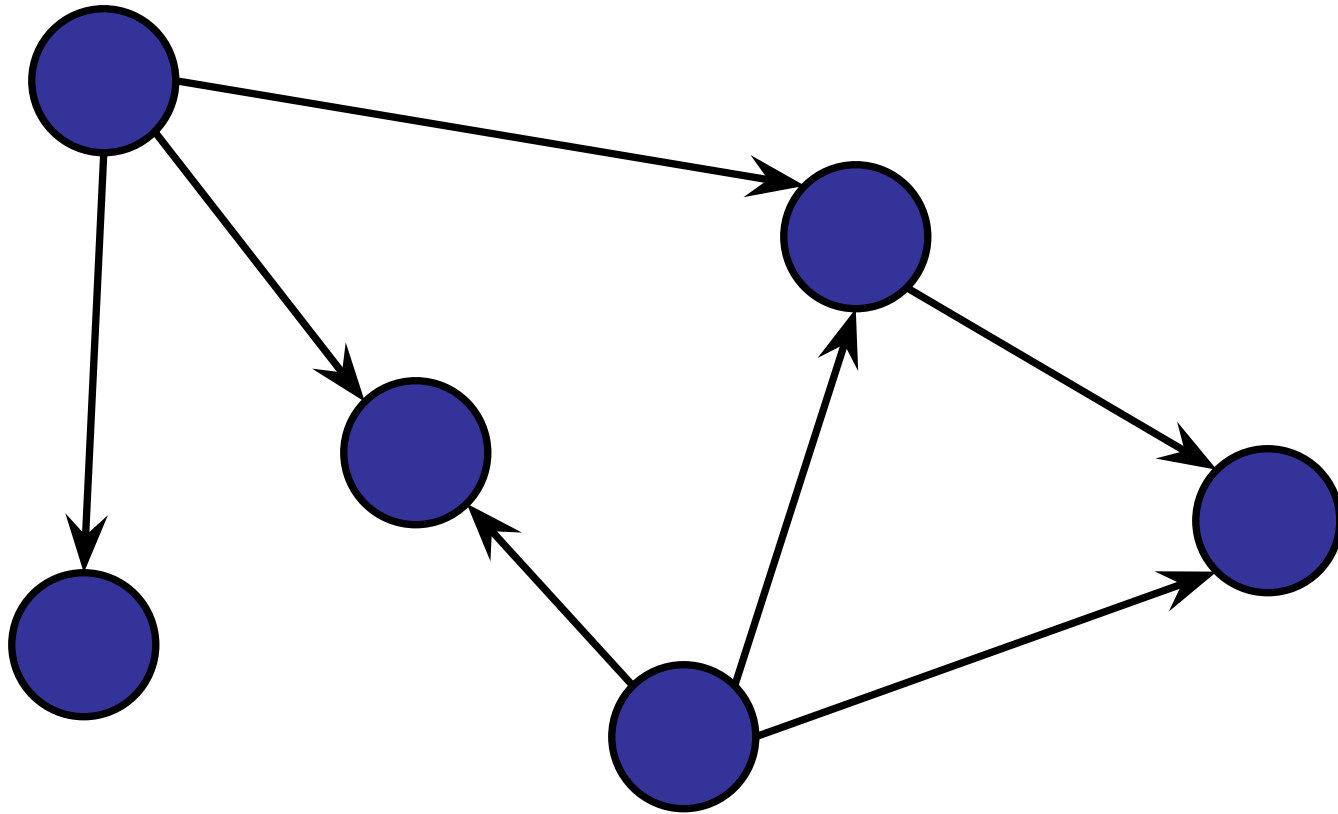
## Algorithms on Directed Graphs

- Searching directed graphs (DFS / BFS)
- Topological Sort
- Connected Components

## More Algorithms on Undirected Graphs

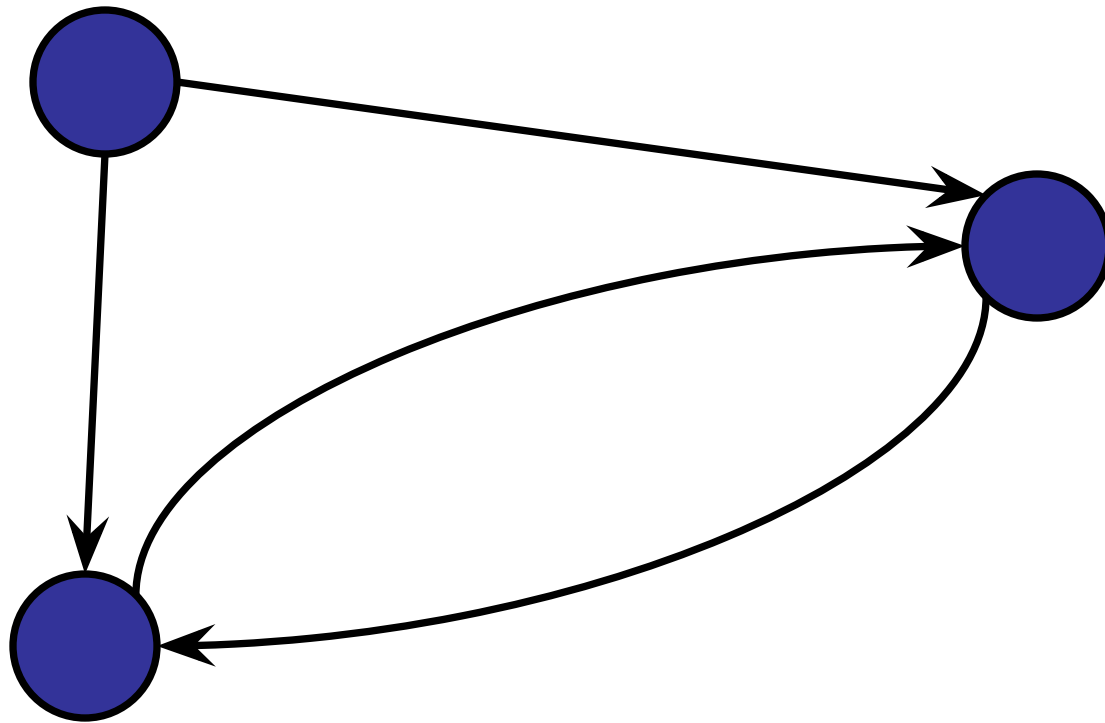
# Examples of Directed Graphs

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# Examples of Directed Graphs

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# Recall: Directed Graph

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Graph consists of two types of elements:

Nodes (or vertices)

- At least one.

Edges (or arcs)

- Each edge connects two nodes in the graph
- Each edge is unique.
- Each edge is **directed**.

# Directed Graphs Are Great For:

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- Modelling Dependencies
- Modelling one-way connections

# Directed Graphs Are Great For:

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- Modelling Dependencies
- Modelling one-way connections

C++ does not allow circular type definitions.

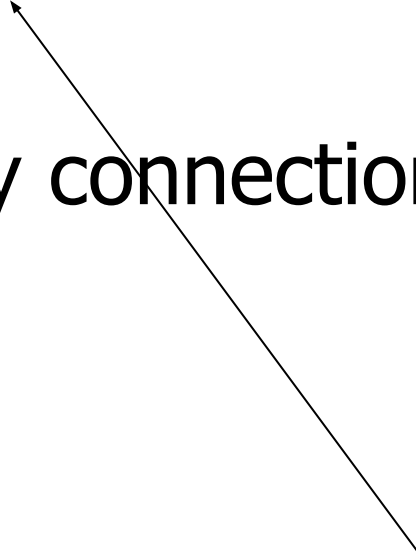




# Directed Graphs Are Great For:

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- Modelling Dependencies
- Modelling one-way connections



When you install packages/libraries  
how do we know which ones to  
install first?

# Example: Scheduling

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Set of tasks for baking cookies:

- Shop for groceries
- Put the cookies in the oven
- Clean the kitchen
- Beat the eggs in a bowl
- Measure the flour and sugar in a bowl
- Mix the eggs with the flour and sugar
- Turn on the oven
- Set the timer
- Take out the cookies

# Scheduling

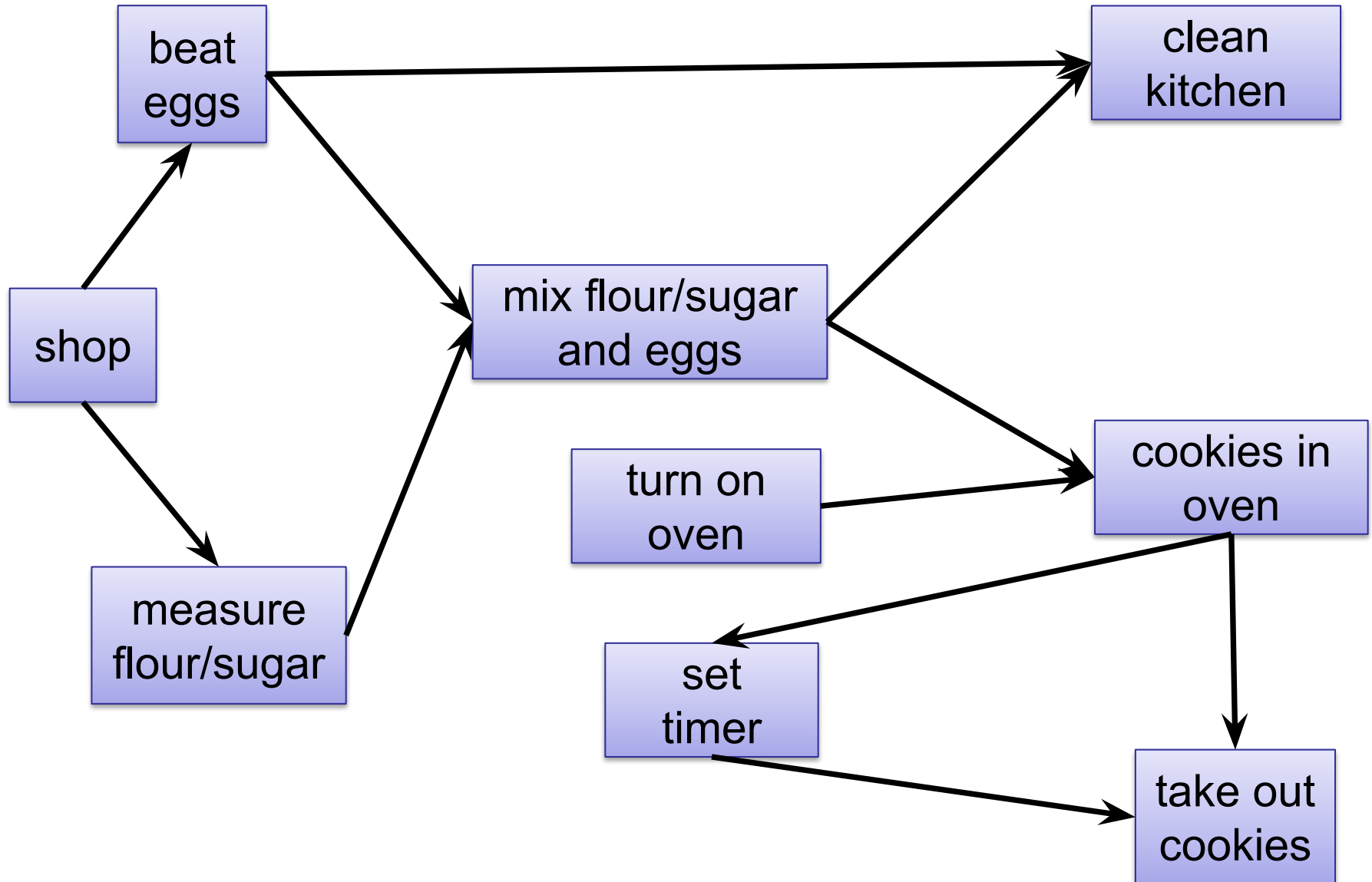
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## Ordering:

- Shop for groceries **before** beat the eggs
- Shop for groceries **before** measure the flour
- Turn on the oven **before** put the cookies in the oven
- Beat the eggs **before** mix the eggs with the flour
- Measure the flour **before** mix the eggs with the flour
- Put the cookies in the oven **before** set the timer
- Measure the flour **before** clean the kitchen
- Beat the eggs **before** clean the kitchen
- Mix the flour and the eggs **before** clean the kitchen

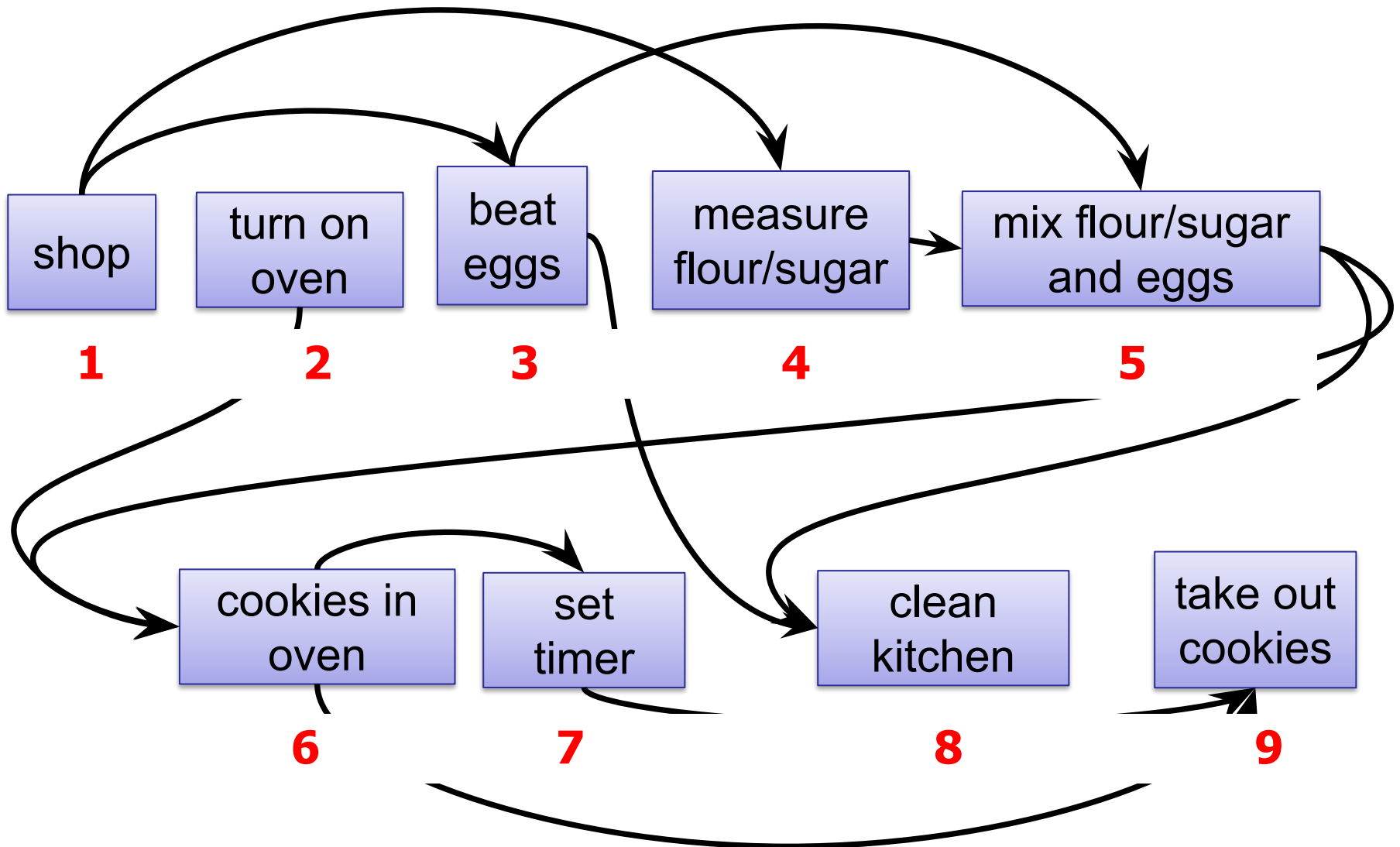
# Scheduling

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# Topological Ordering

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# Topological Order

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Properties:

1. Sequential total ordering of all nodes

1. shop

2. turn on oven

3. measure flour/sugar

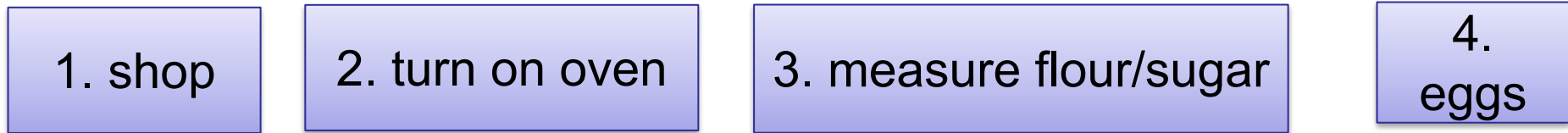
4.  
eggs

# Topological Order

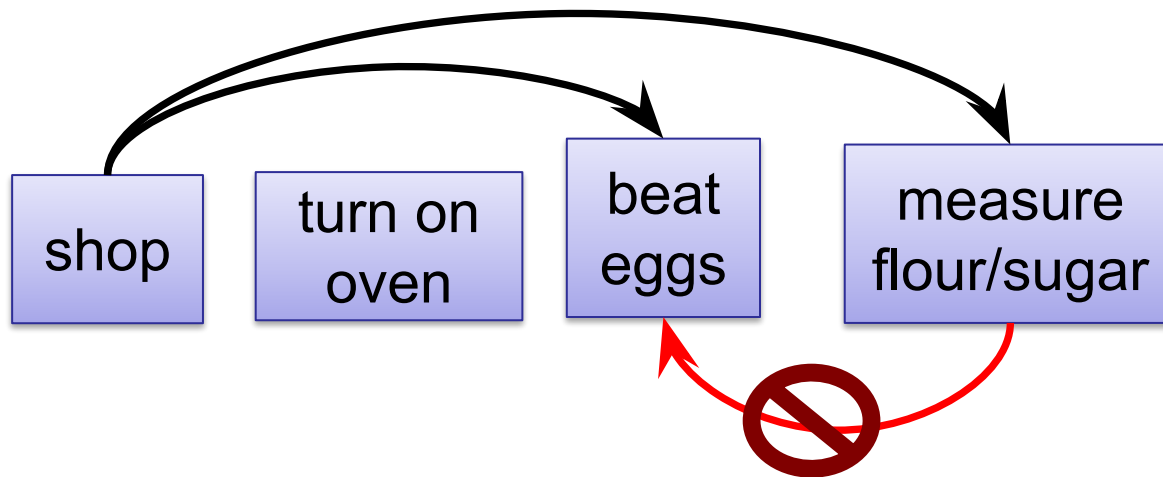
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## Properties:

1. Sequential total ordering of all nodes



2. Edges from original graph only point forward



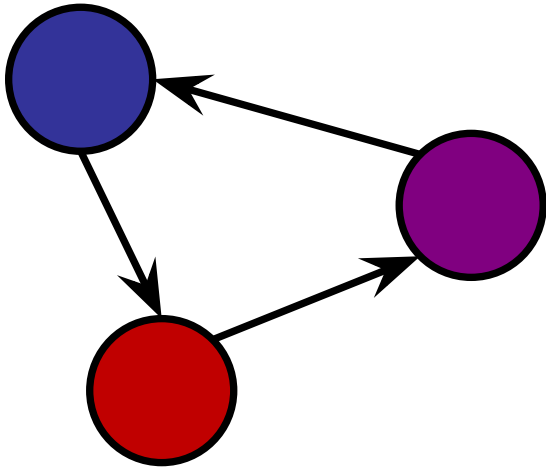
Does every directed graph have a topological ordering?

1. Yes
- ✓ 2. No
3. Only if the adjacency matrix has small second eigenvalue.

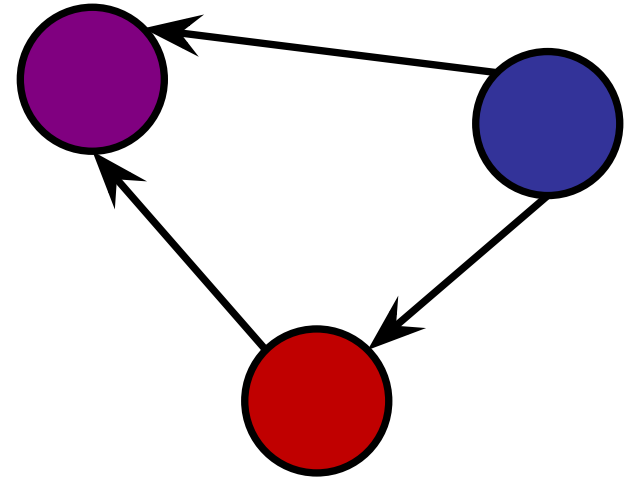


# Directed Acyclic Graphs

Cyclic

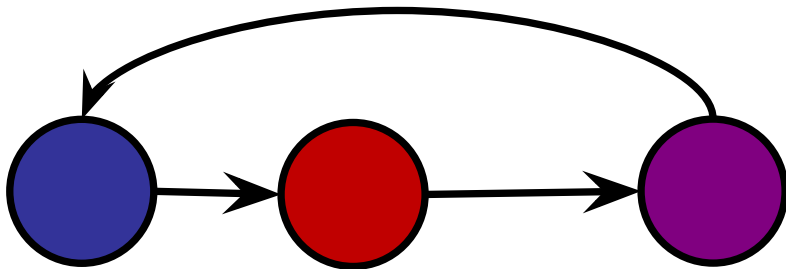
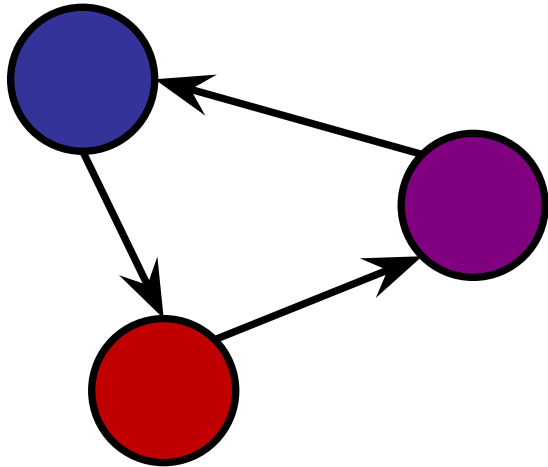


Acyclic

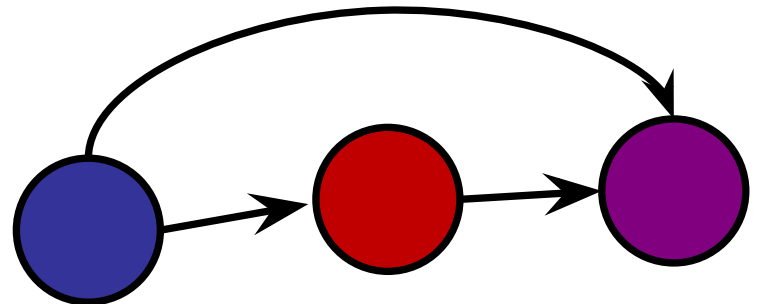
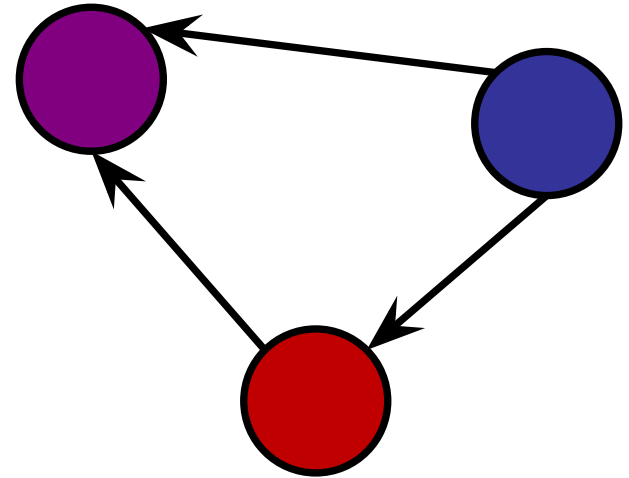


# Directed Acyclic Graphs

Cyclic



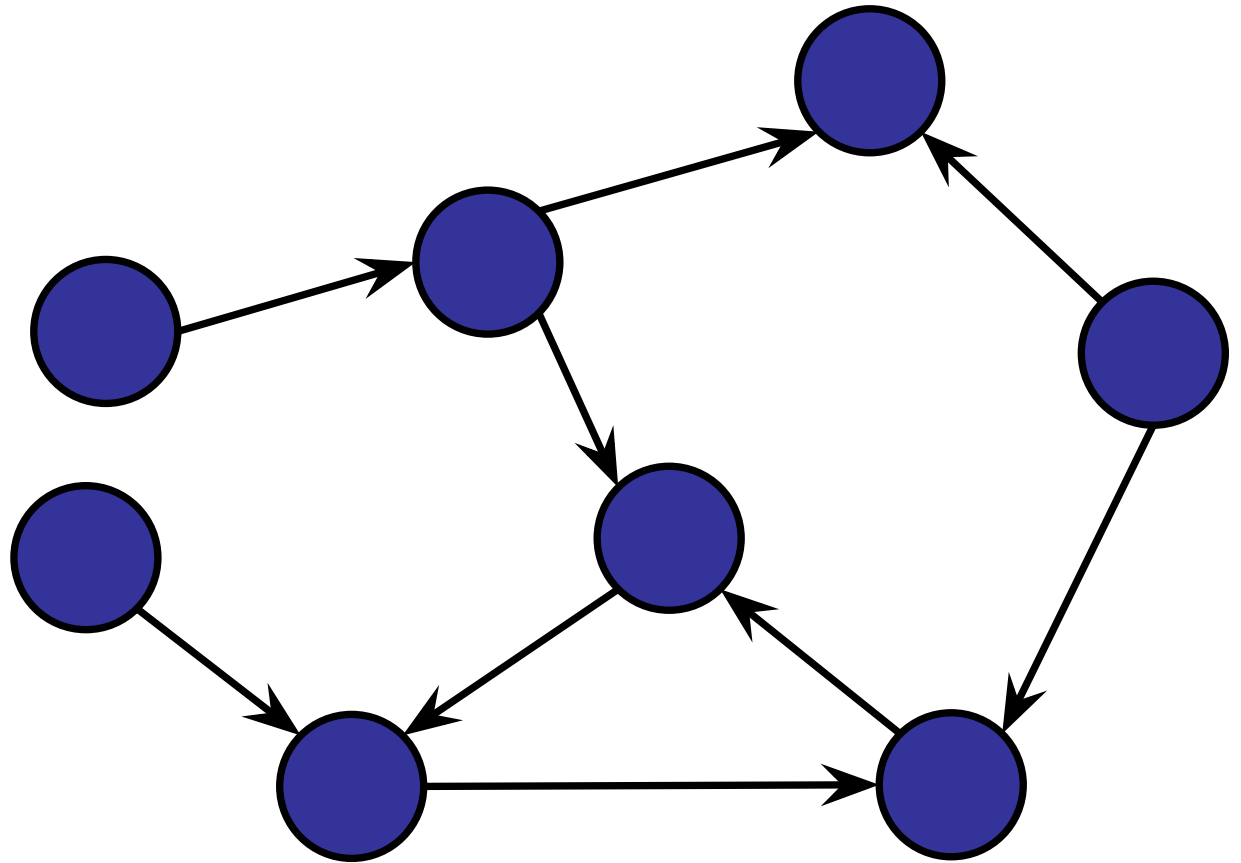
Acyclic



# Directed Acyclic Graphs

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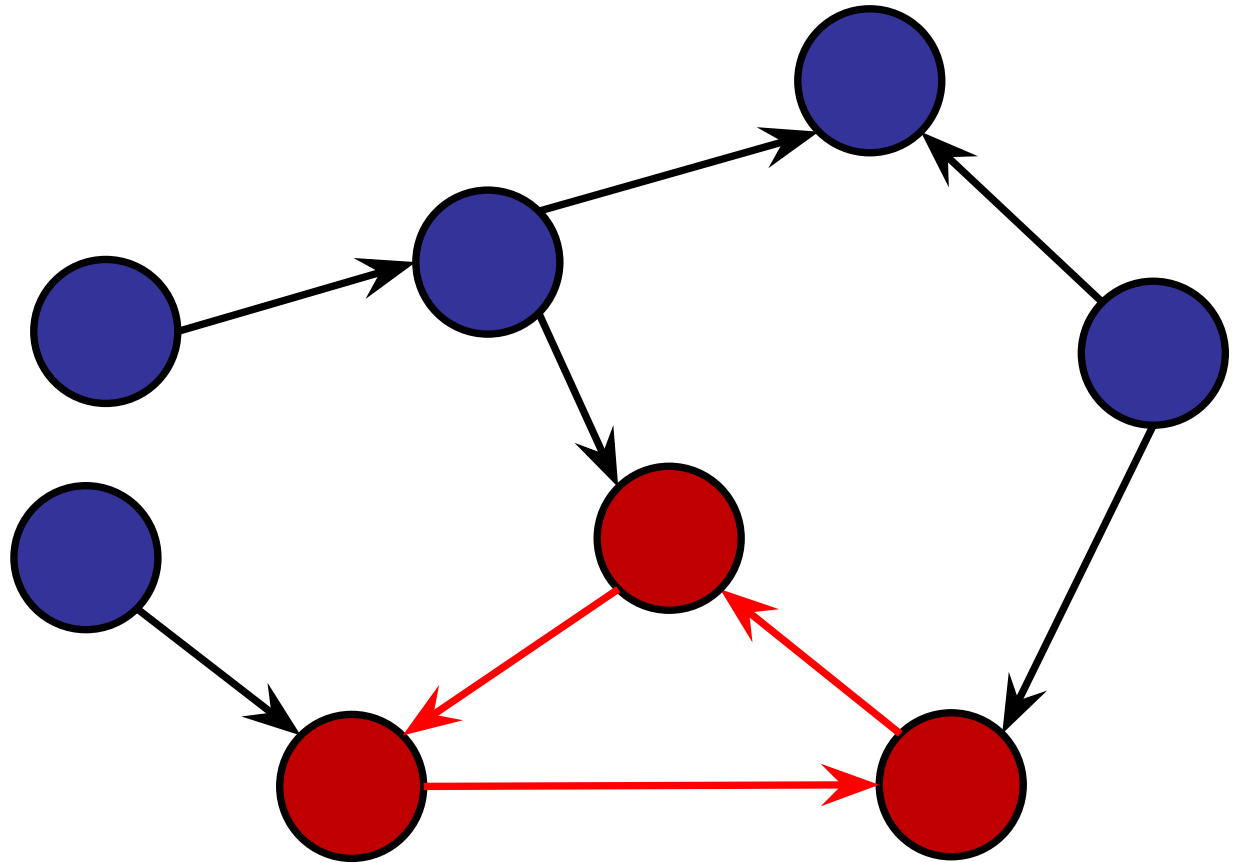
Does it have a topological ordering?



# Directed Acyclic Graphs

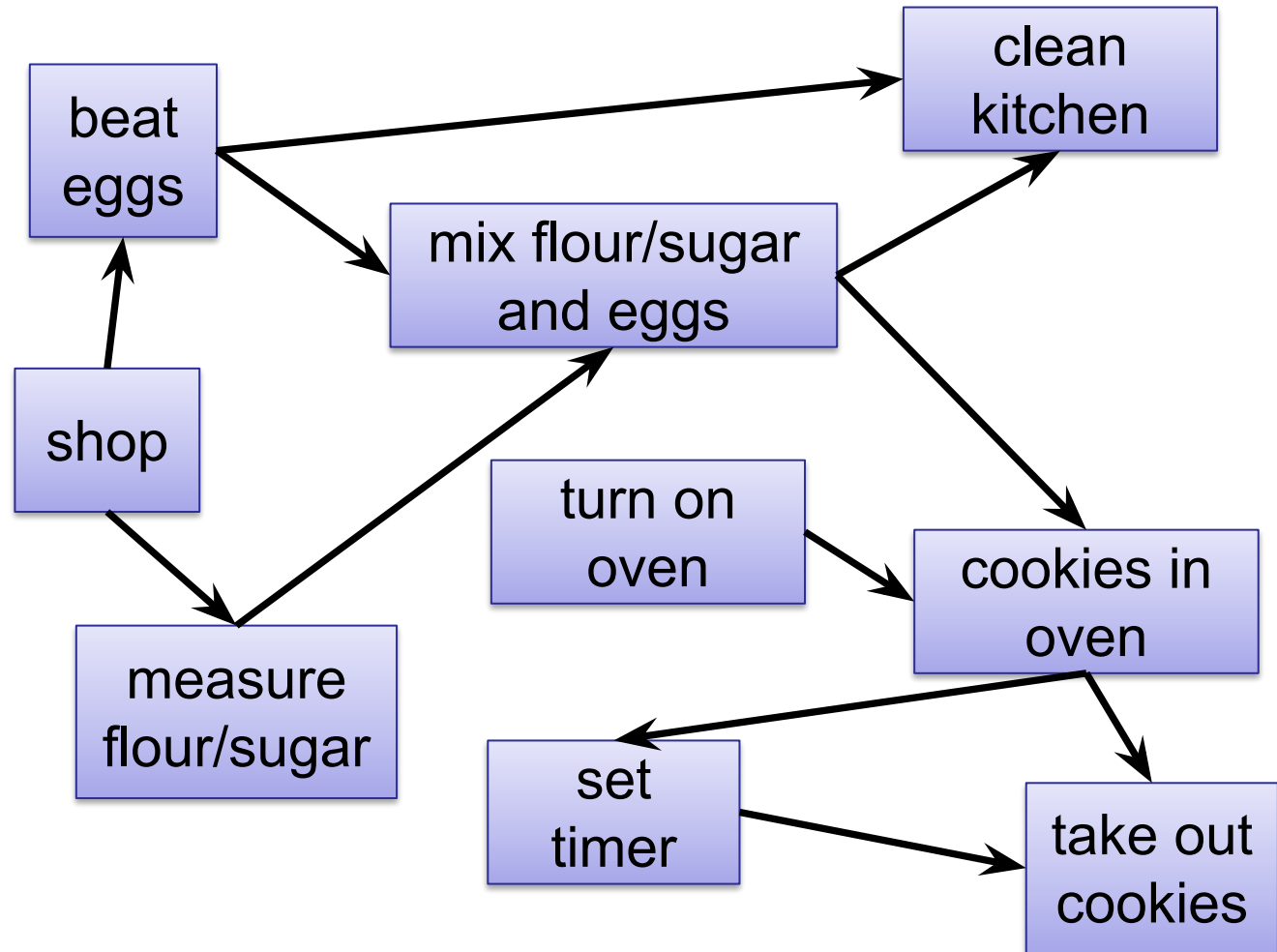
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Does it have a topological ordering?



# Directed Acyclic Graph

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# Topological Sorting

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Assuming a graph is acyclic:

A topological sort of the graph produces an ordering of the nodes.

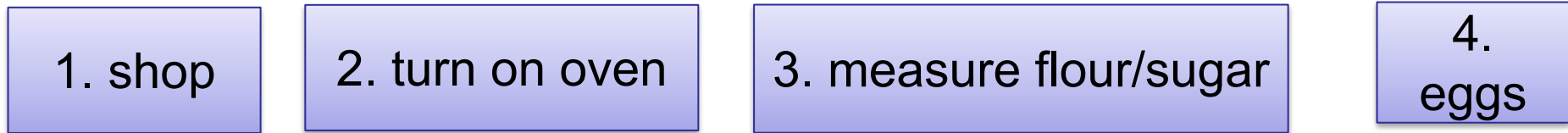
If edge  $(u, v)$  is in  $G$ , then  $u$  must appear before  $v$  in the toposort.

# Topological Order

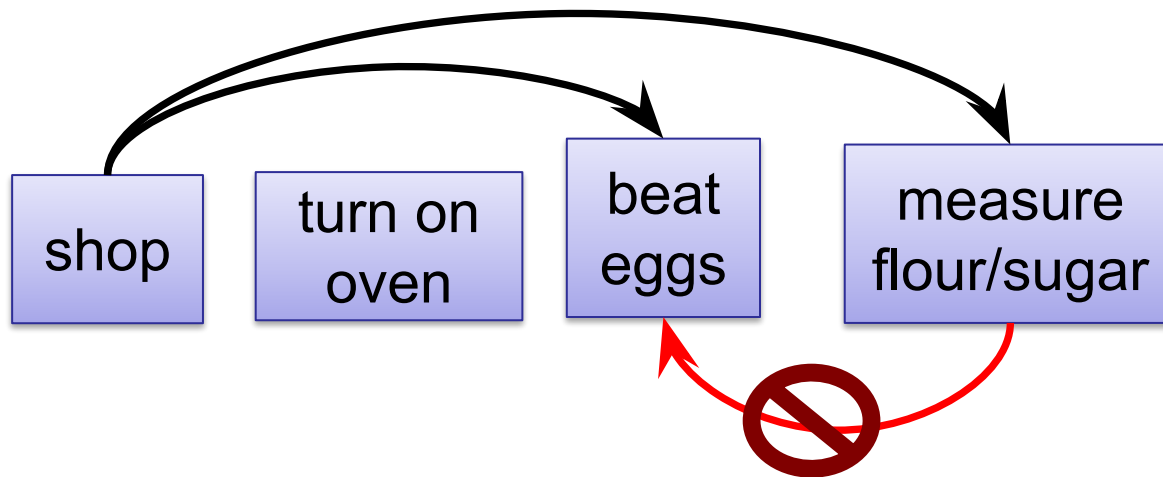
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## Properties:

1. Sequential total ordering of all nodes



2. Edges only point forward



# Topological Sorting

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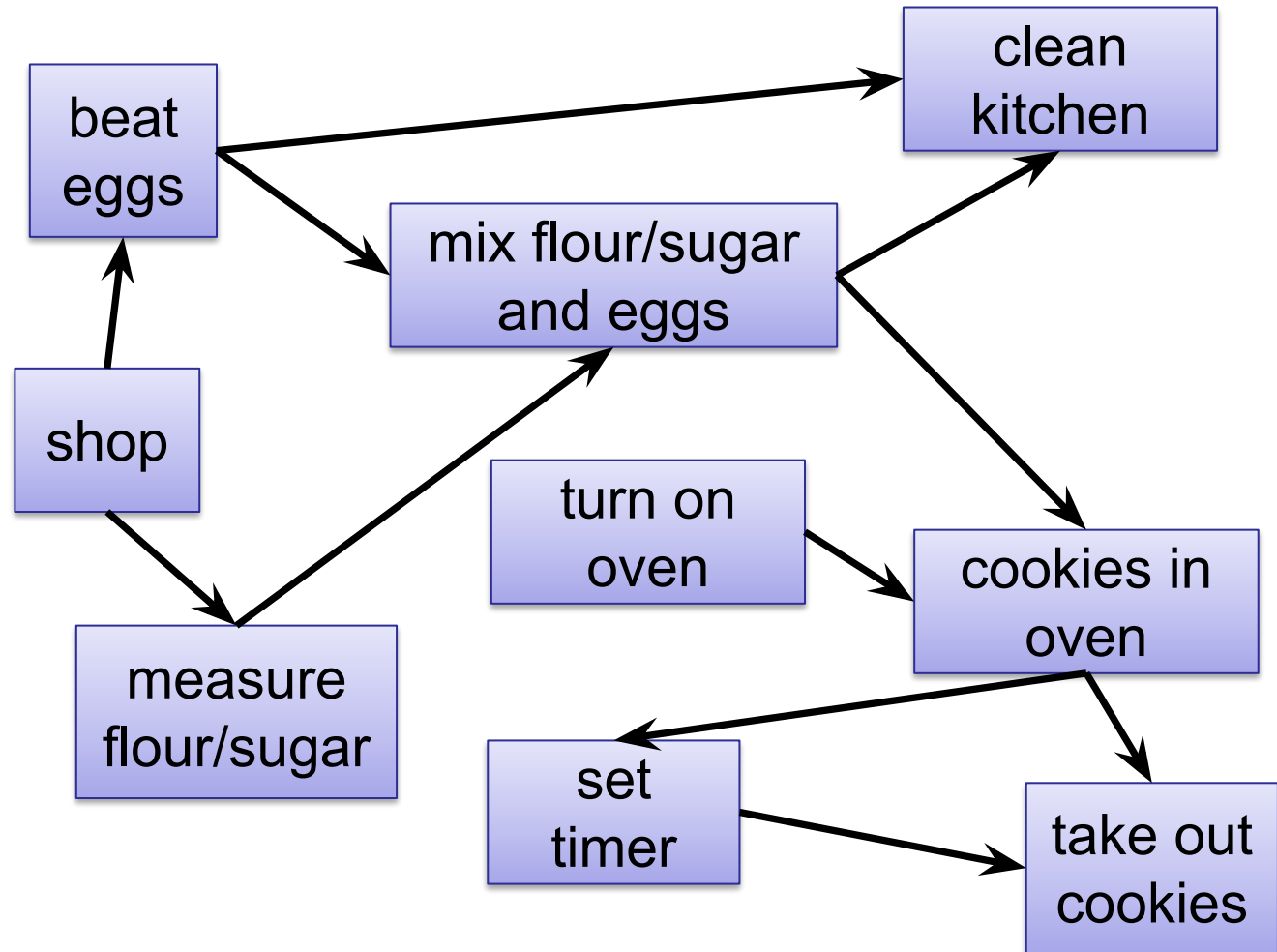
How do we produce the graph?

Can we just run DFS?



# Depth-First Search

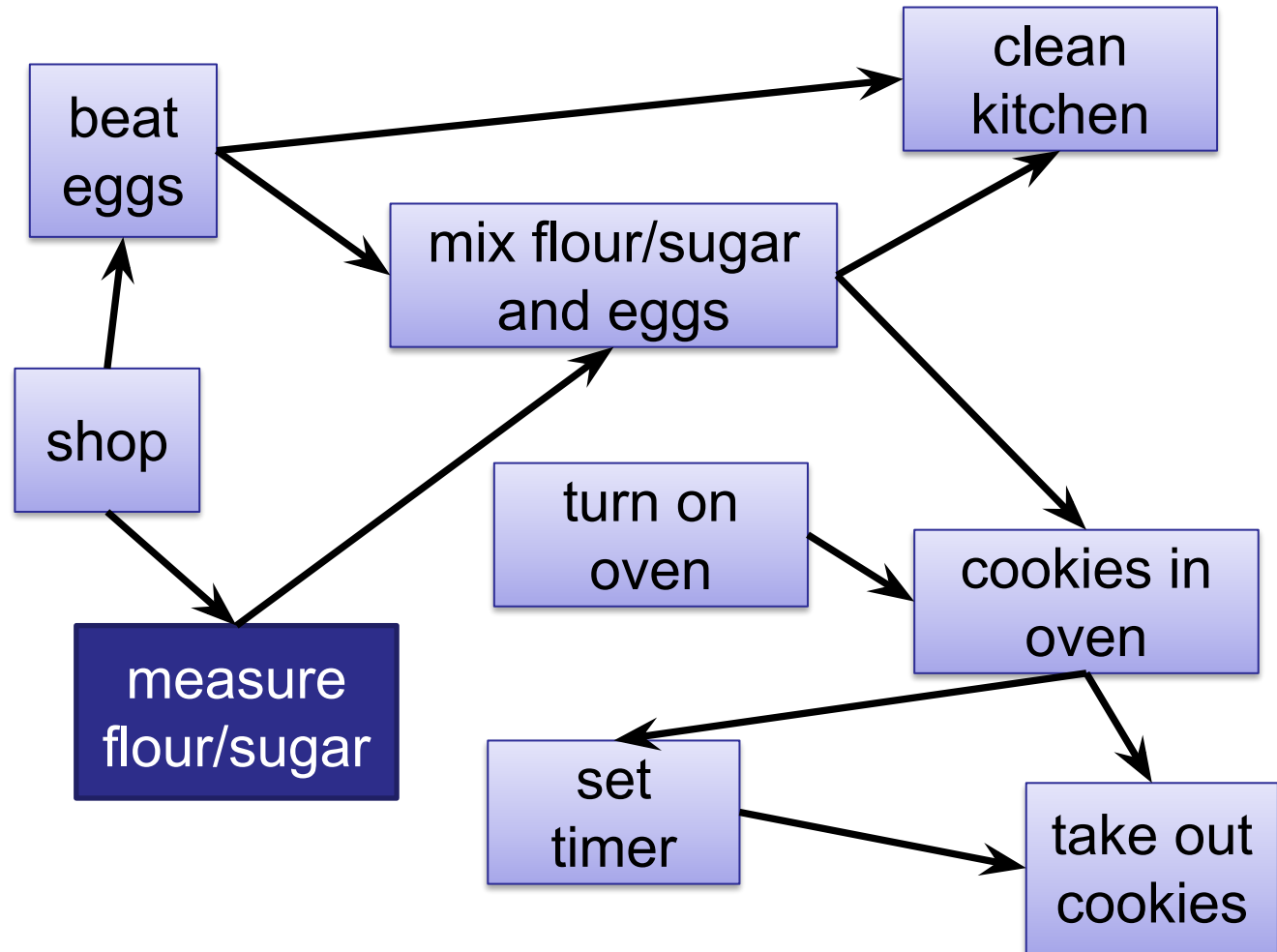
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# Depth-First Search

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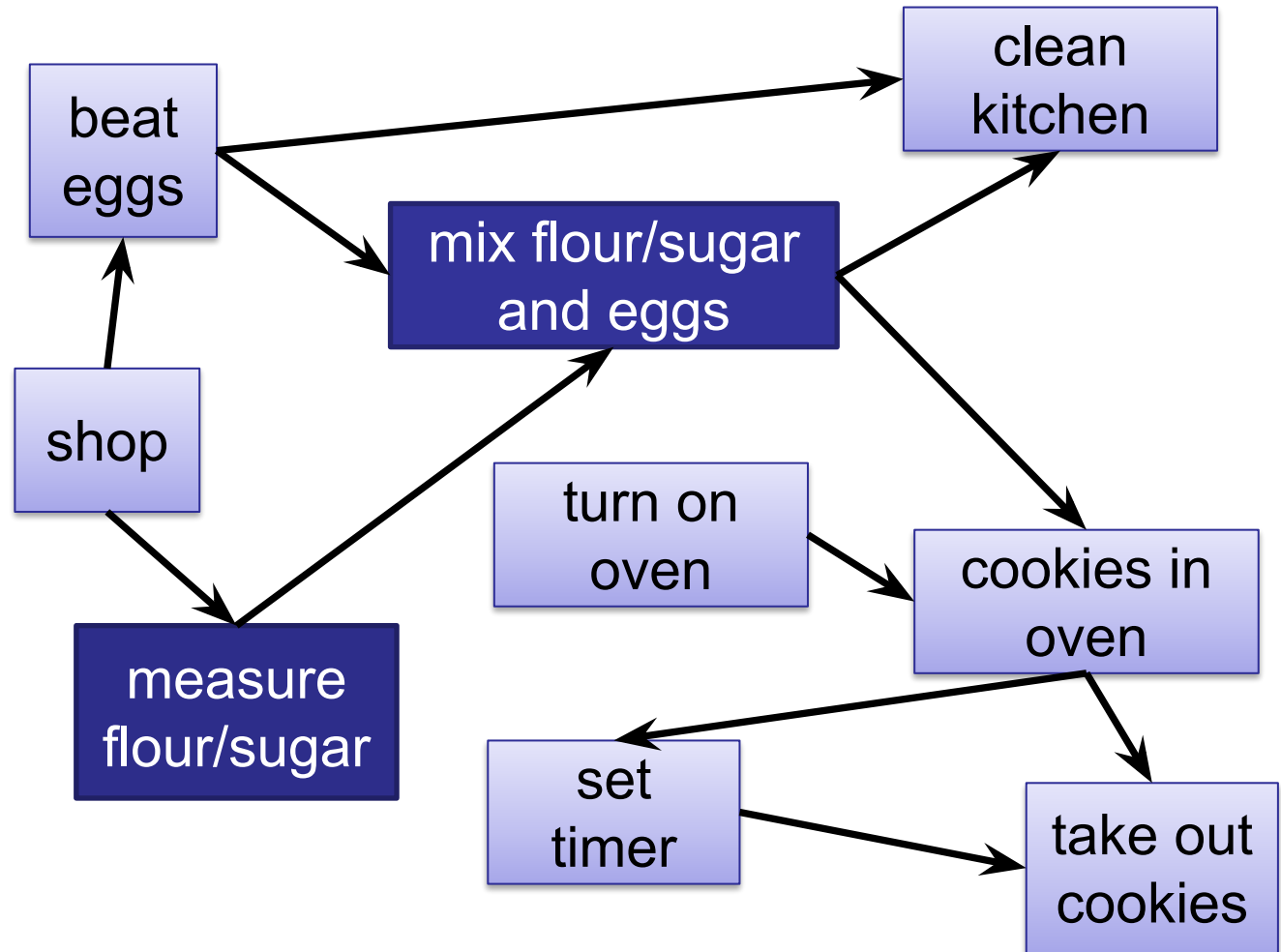
## 1. measure



# Depth-First Search

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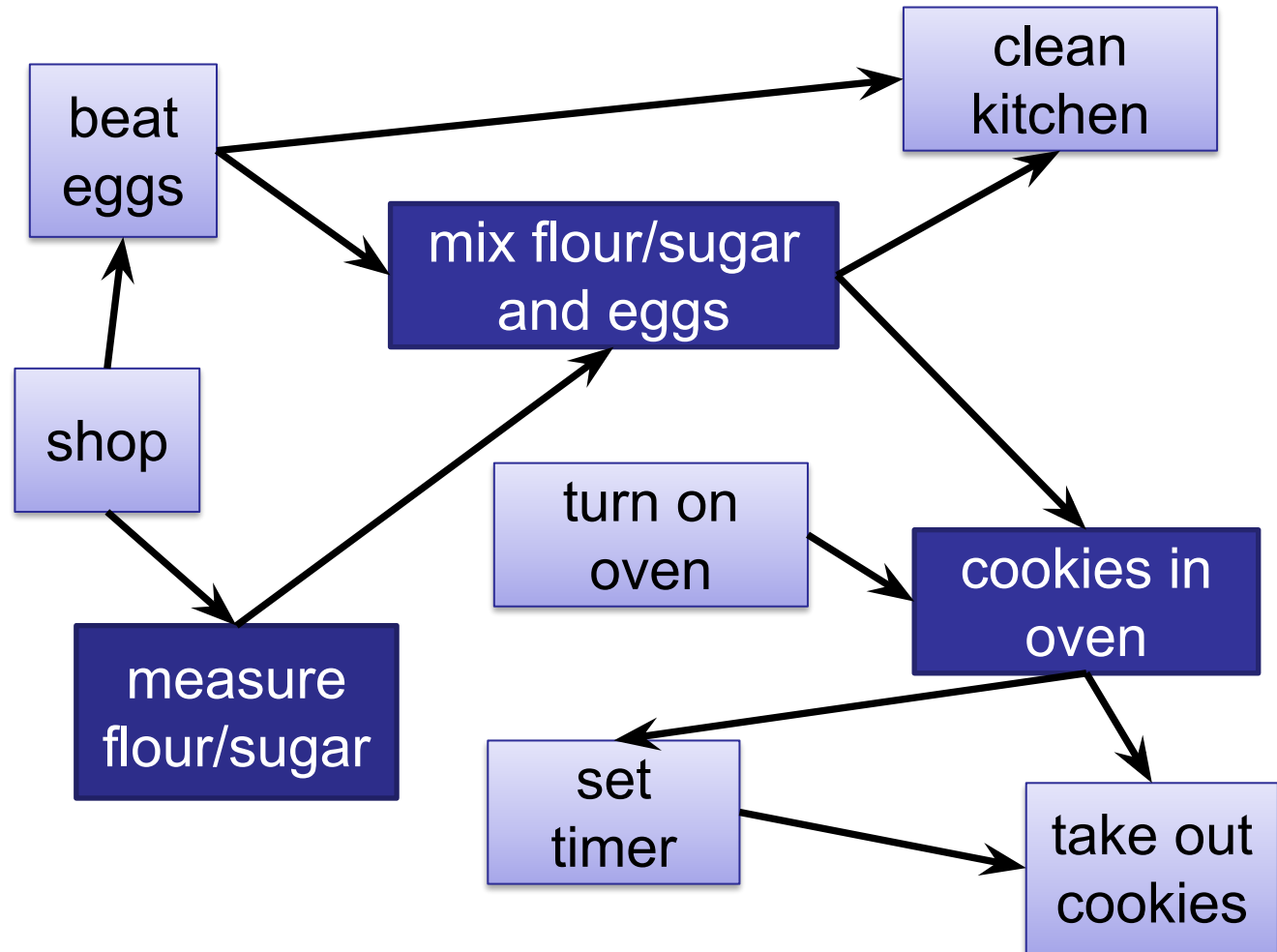
1. measure
2. mix



# Depth-First Search

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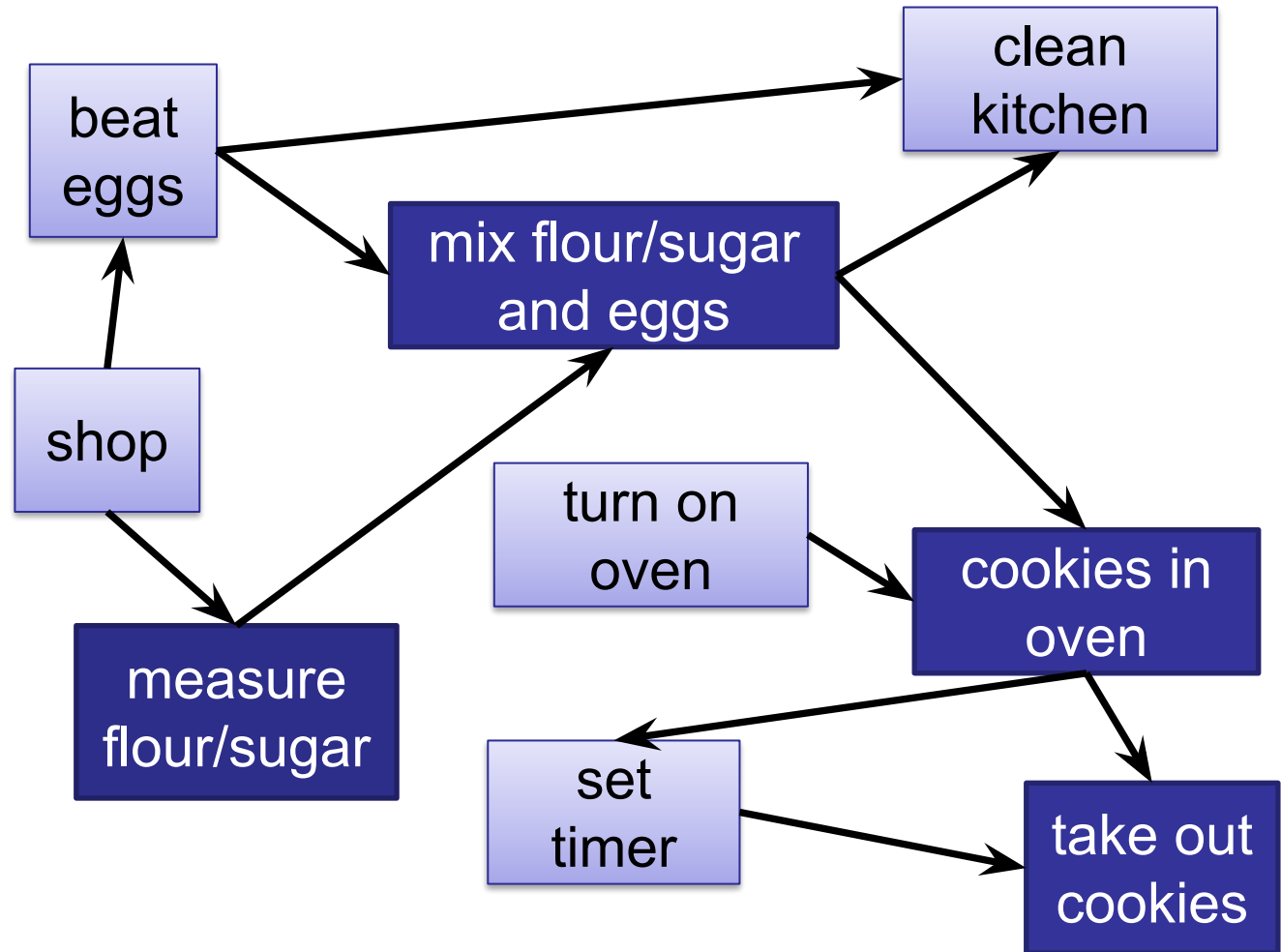
1. measure
2. mix
3. in oven



# Depth-First Search

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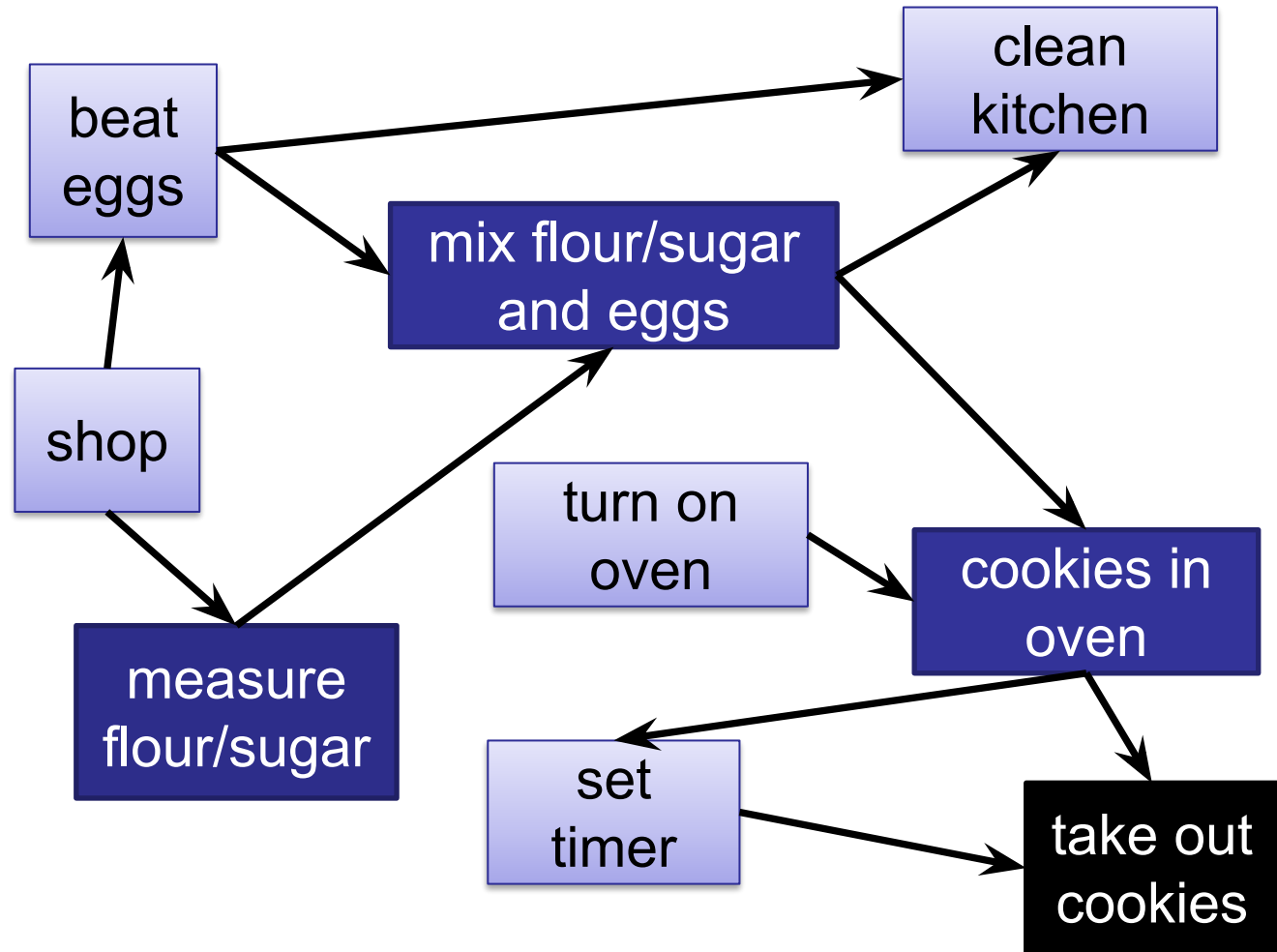
1. measure
2. mix
3. in oven
4. take out



# Depth-First Search

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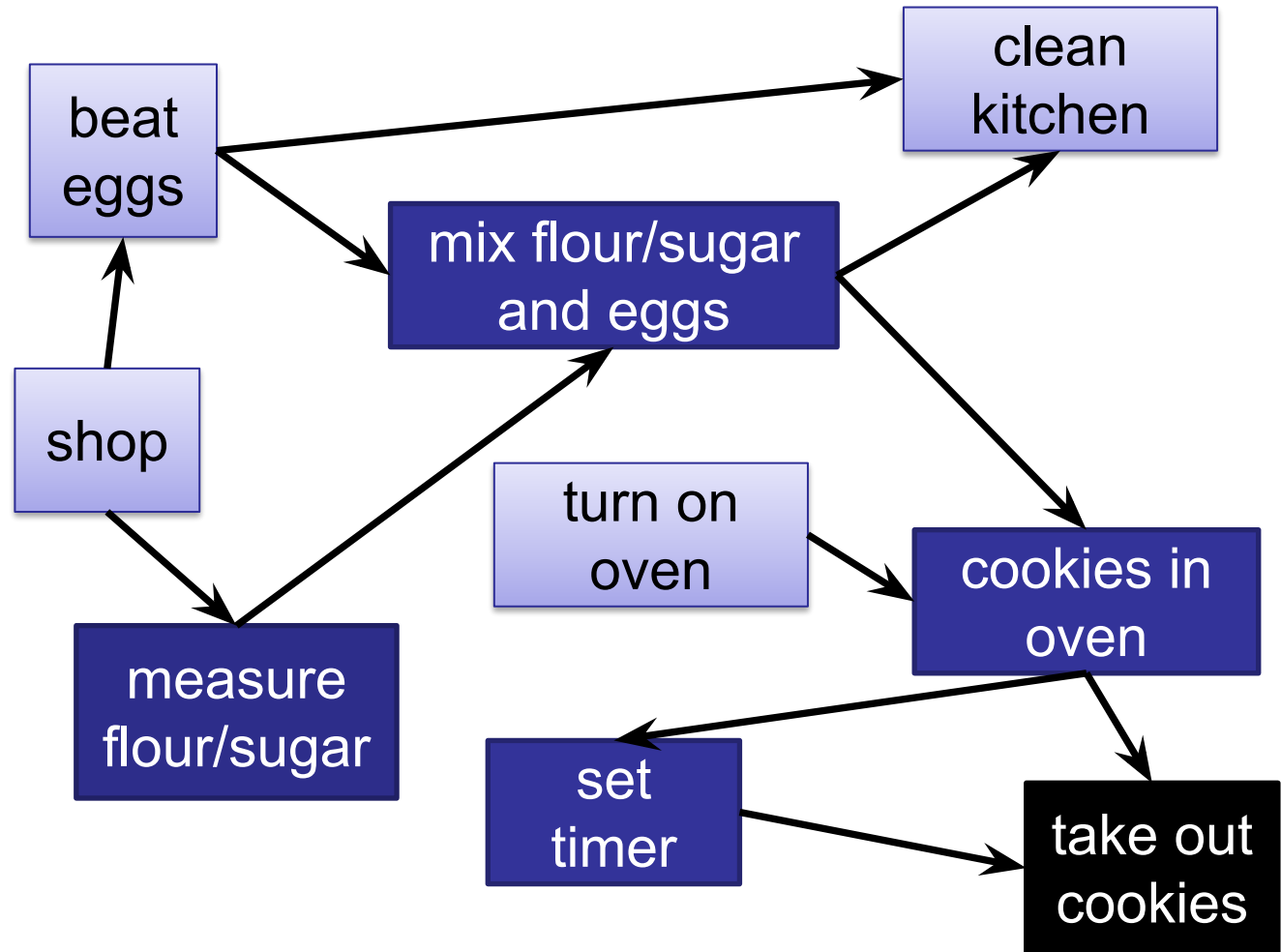
1. measure
2. mix
3. in oven
4. take out



# Depth-First Search

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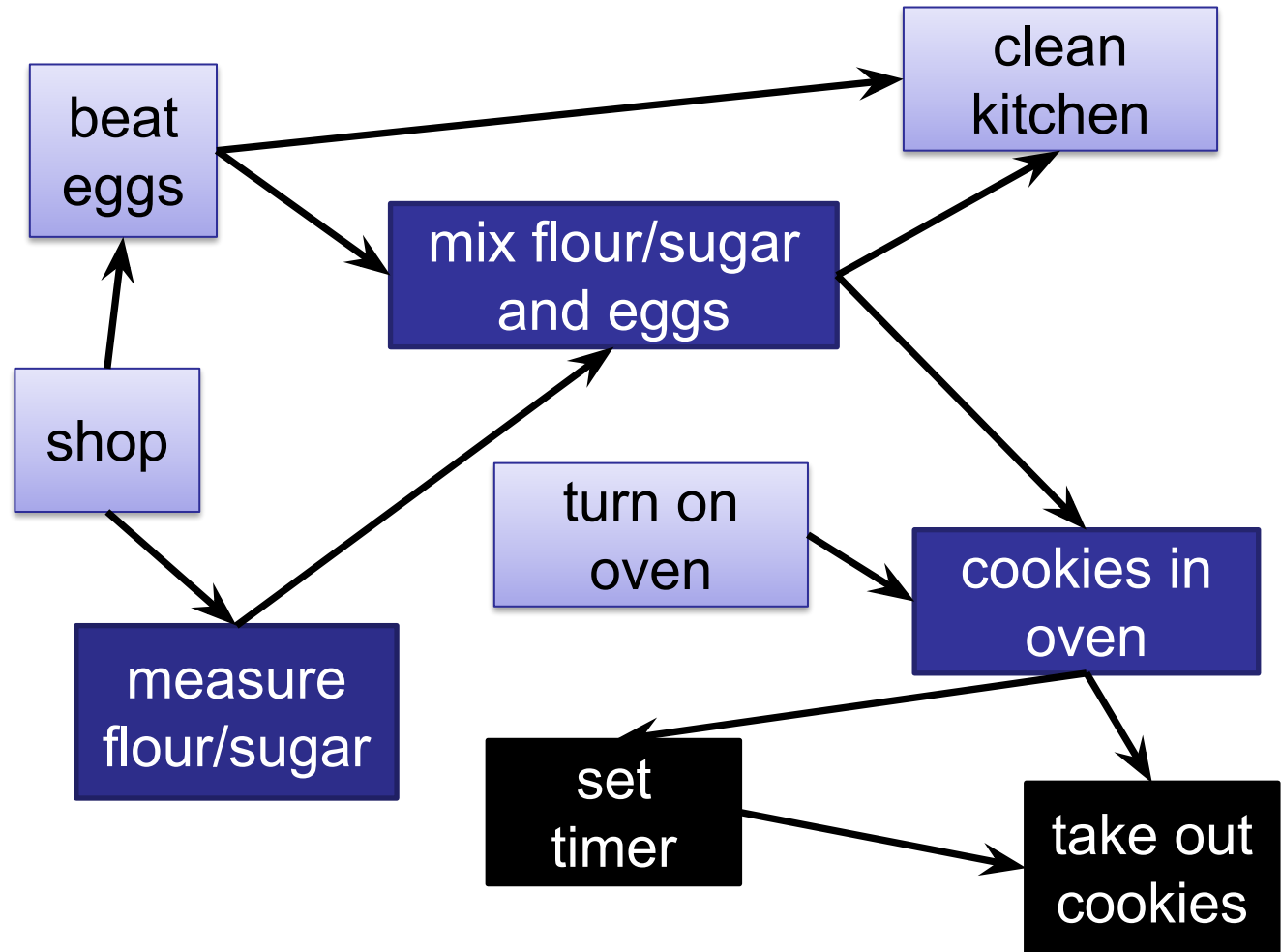
1. measure
2. mix
3. in oven
4. take out
5. set timer



# Depth-First Search

---

1. measure
2. mix
3. in oven
4. take out
5. set timer

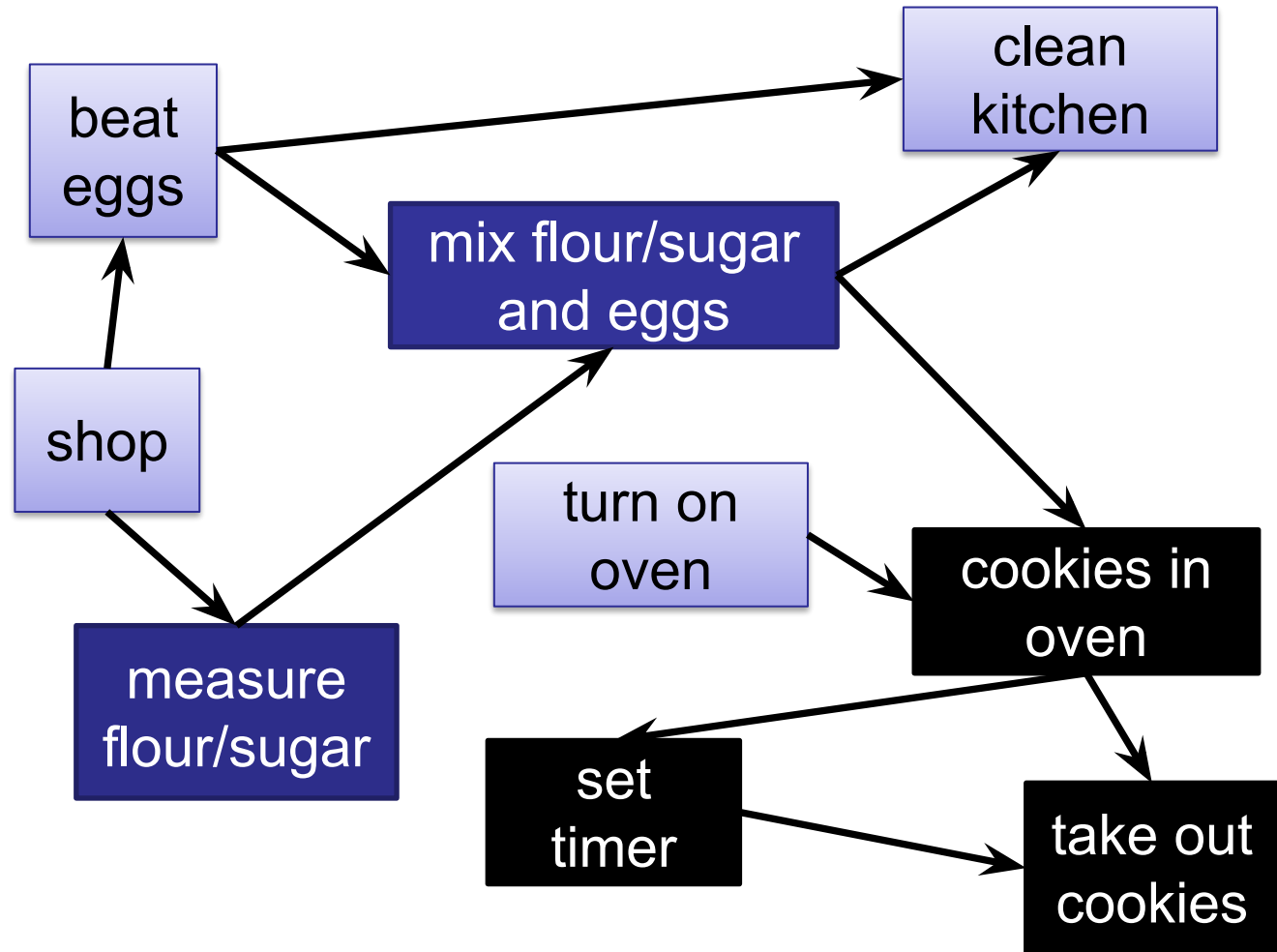




# Depth-First Search

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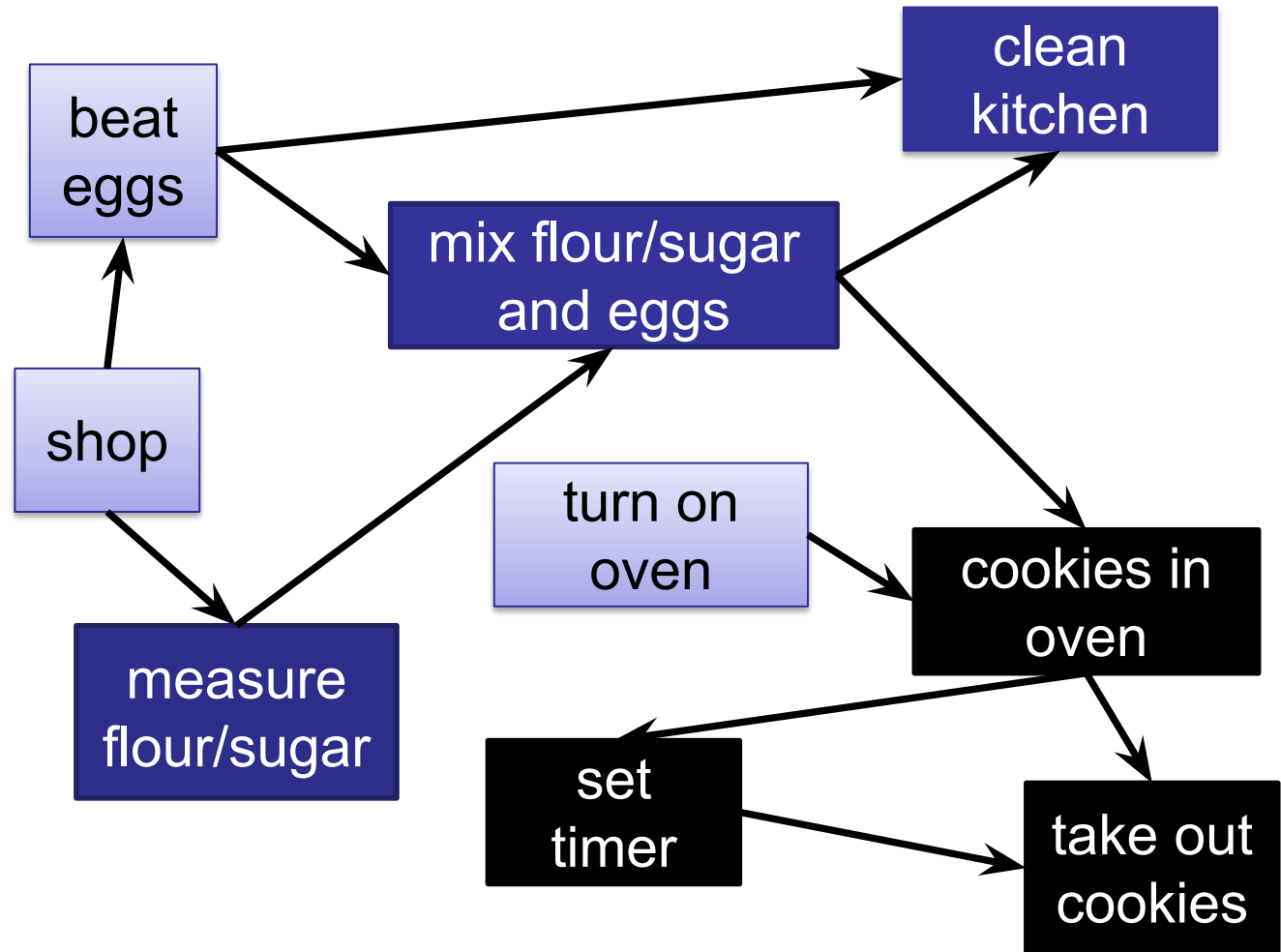
1. measure
2. mix
3. in oven
4. take out
5. set timer



# Depth-First Search

---

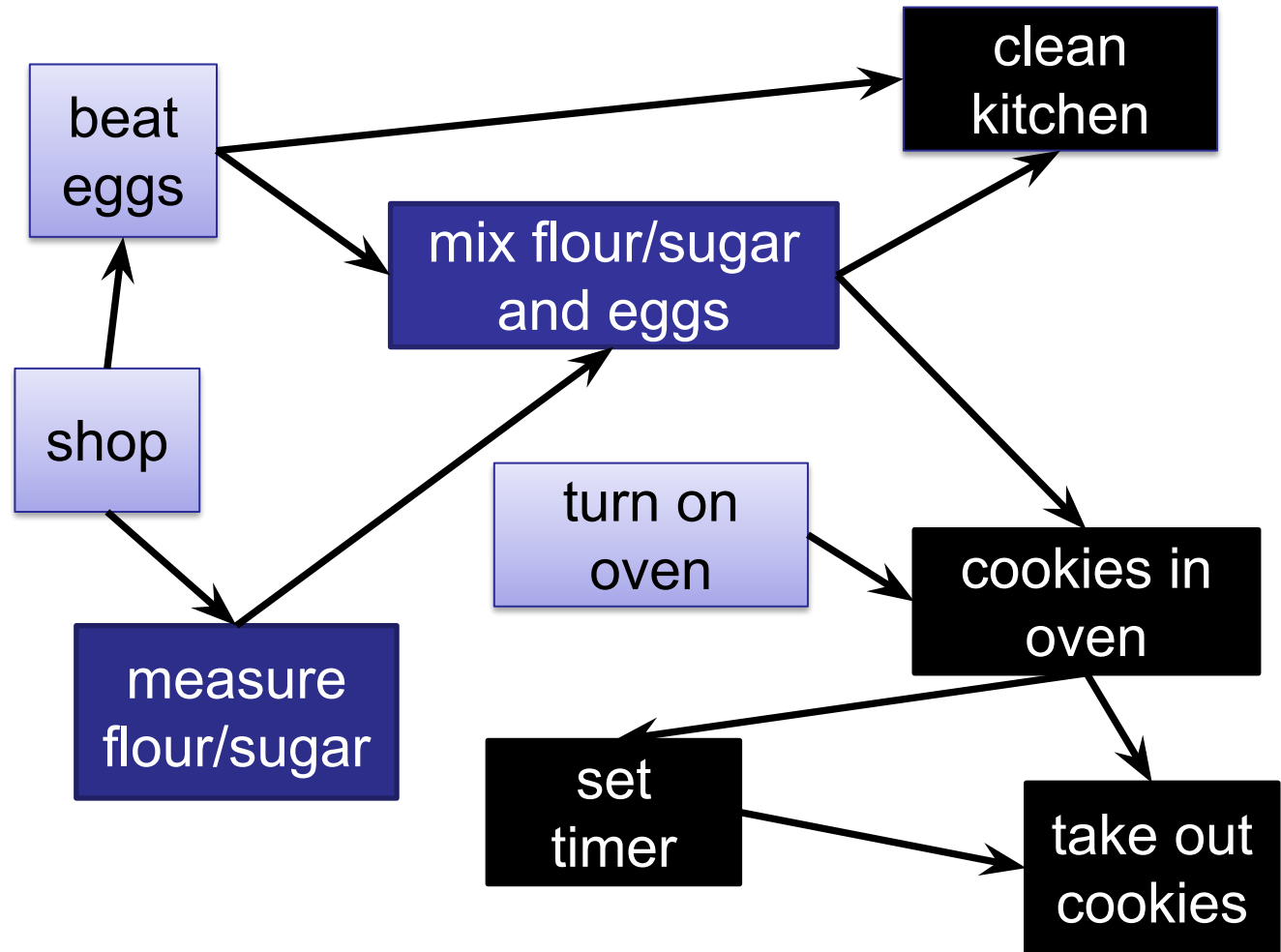
1. measure
2. mix
3. in oven
4. take out
5. set timer
6. clean



# Depth-First Search

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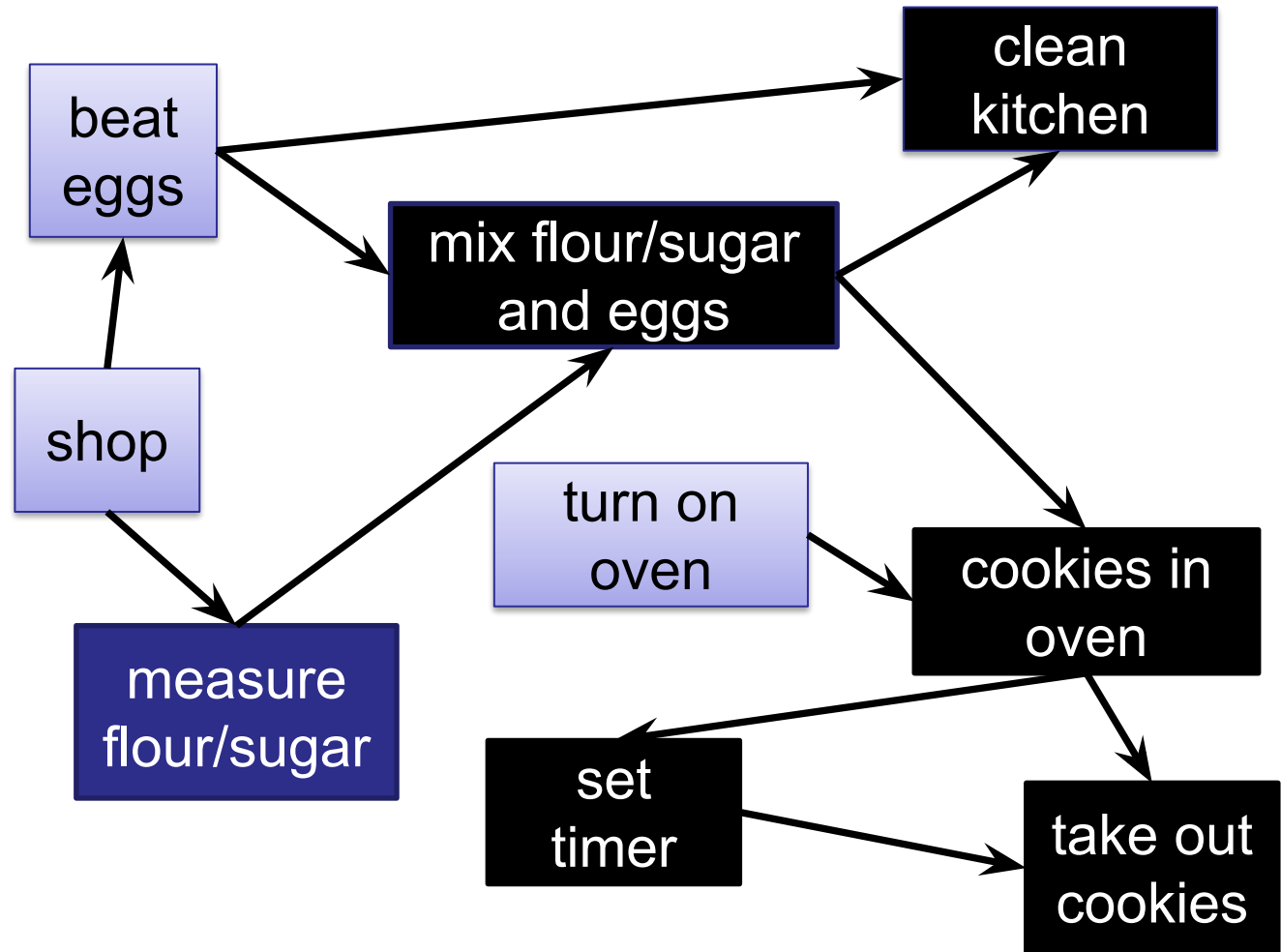
1. measure
2. mix
3. in oven
4. take out
5. set timer
6. clean



# Depth-First Search

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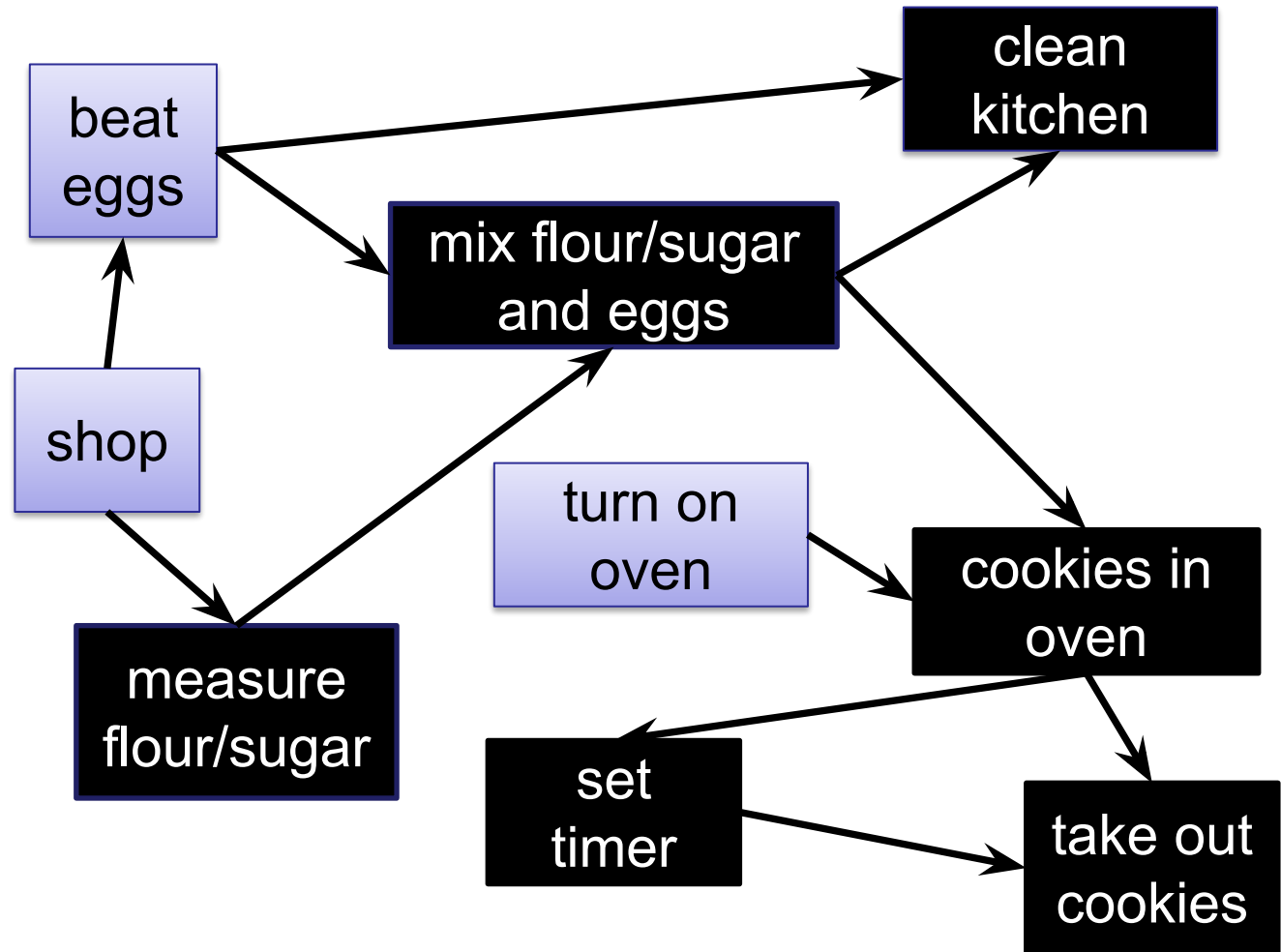
1. measure
2. mix
3. in oven
4. take out
5. set timer
6. clean



# Depth-First Search

---

1. measure
2. mix
3. in oven
4. take out
5. set timer
6. clean



# Searching a (Directed) Graph

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## **Pre-Order** Depth-First Search:

- Process each node when it is *first* visited.

# Searching a (Directed) Graph

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## **Pre-Order** Depth-First Search:

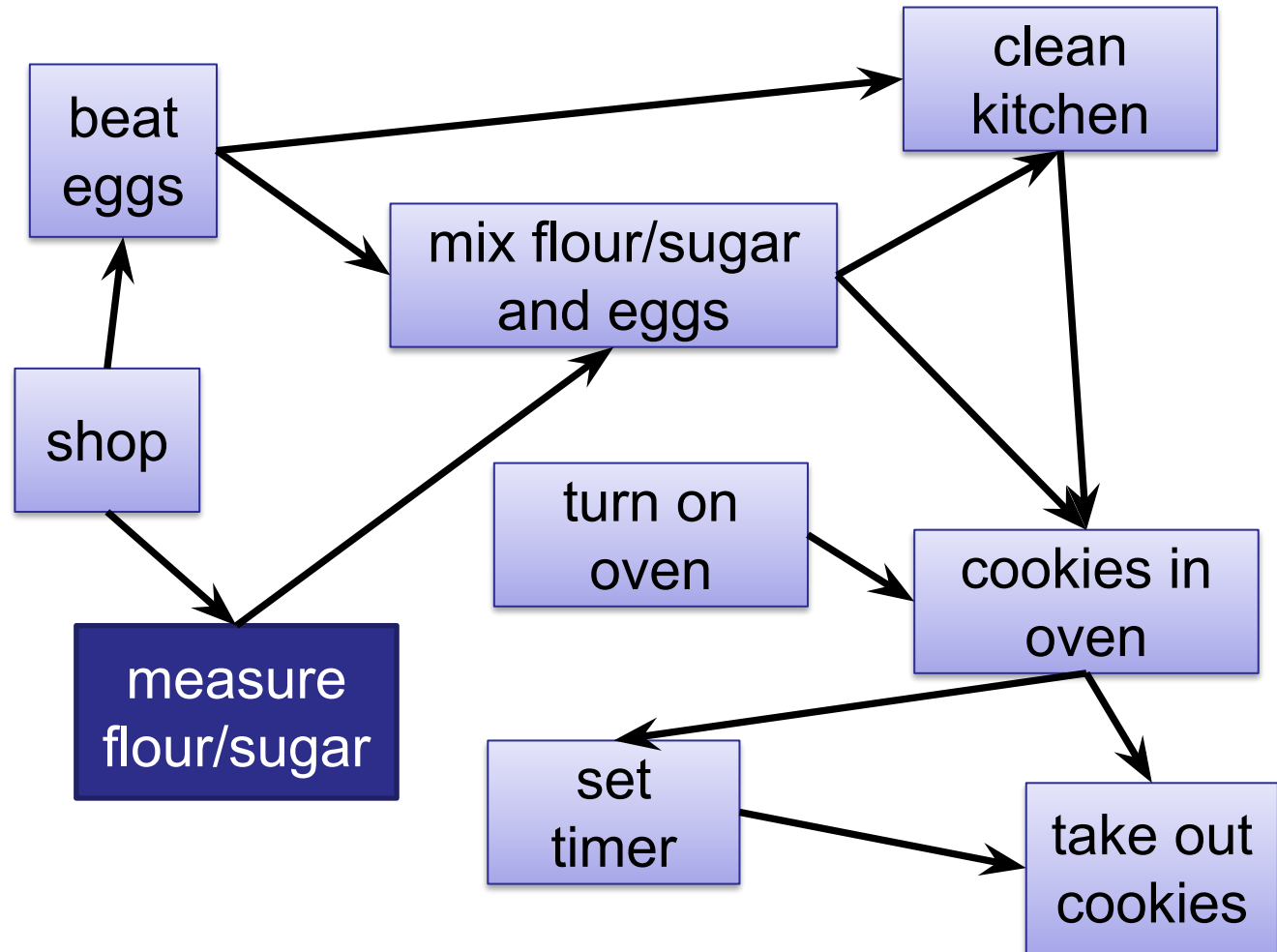
- Process each node when it is *first* visited.

## **Post-Order** Depth-First Search:

- Process each node when it is *last* visited.

# Post-Order Depth-First Search

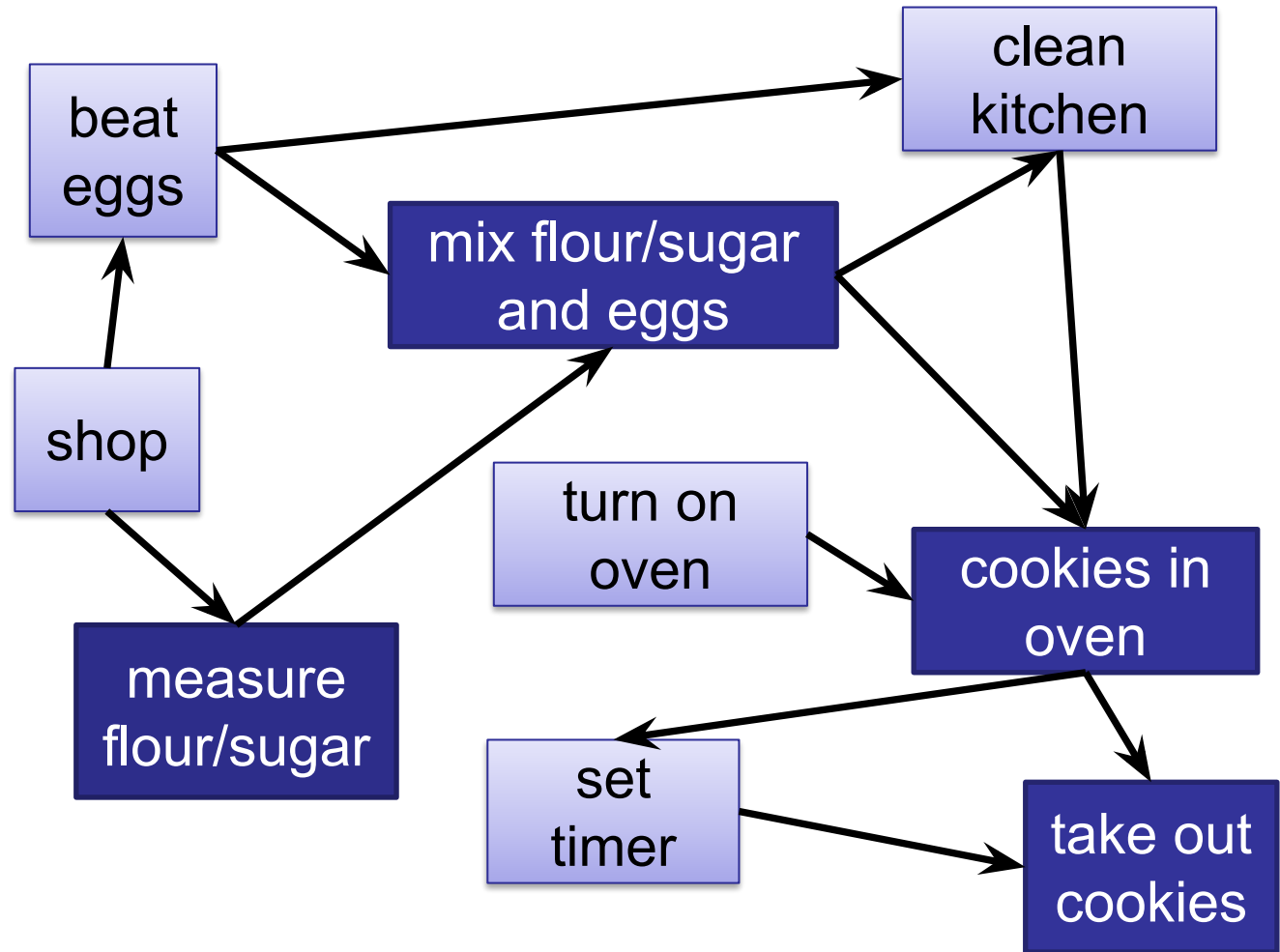
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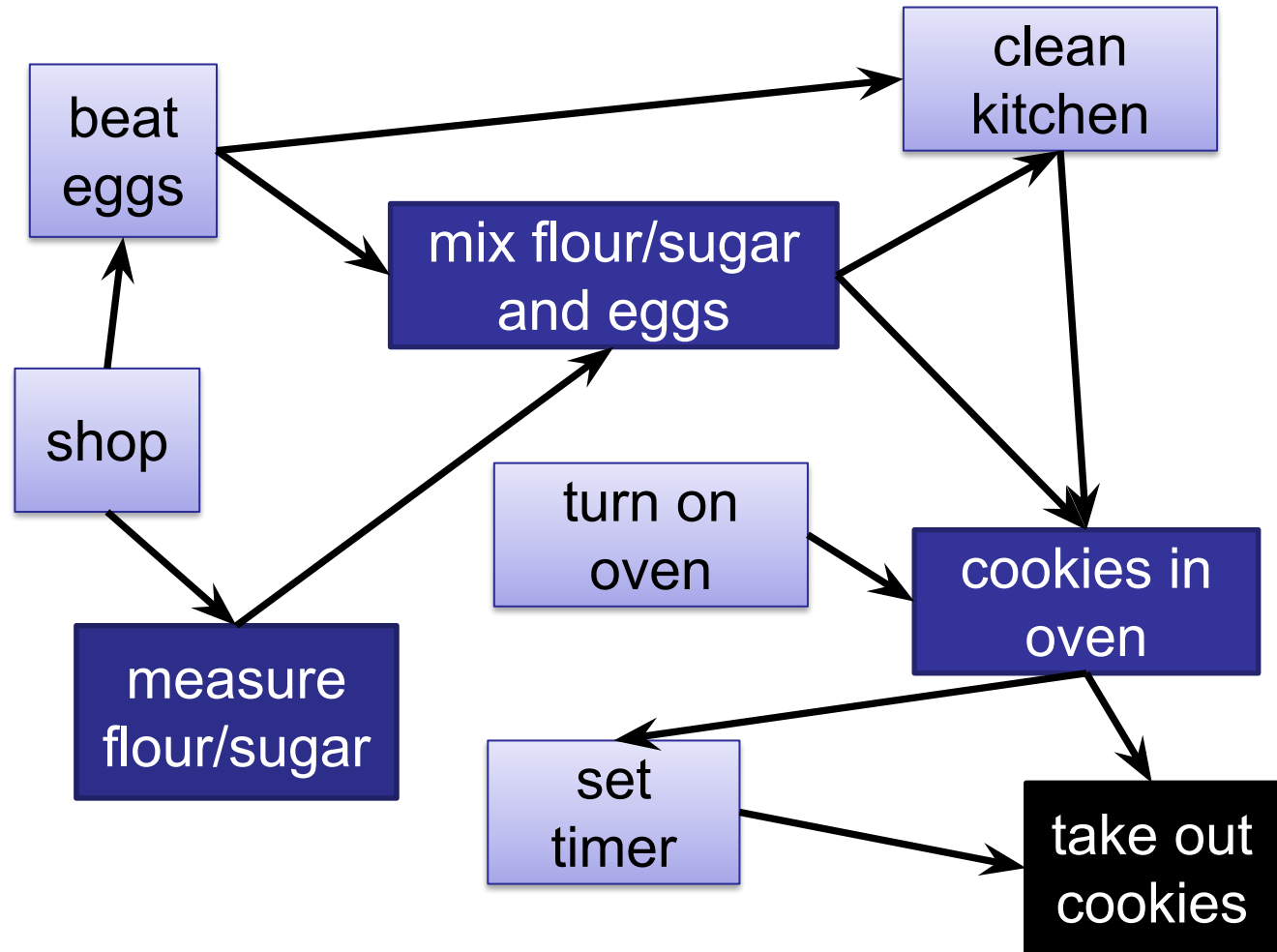
# Post-Order Depth-First Search

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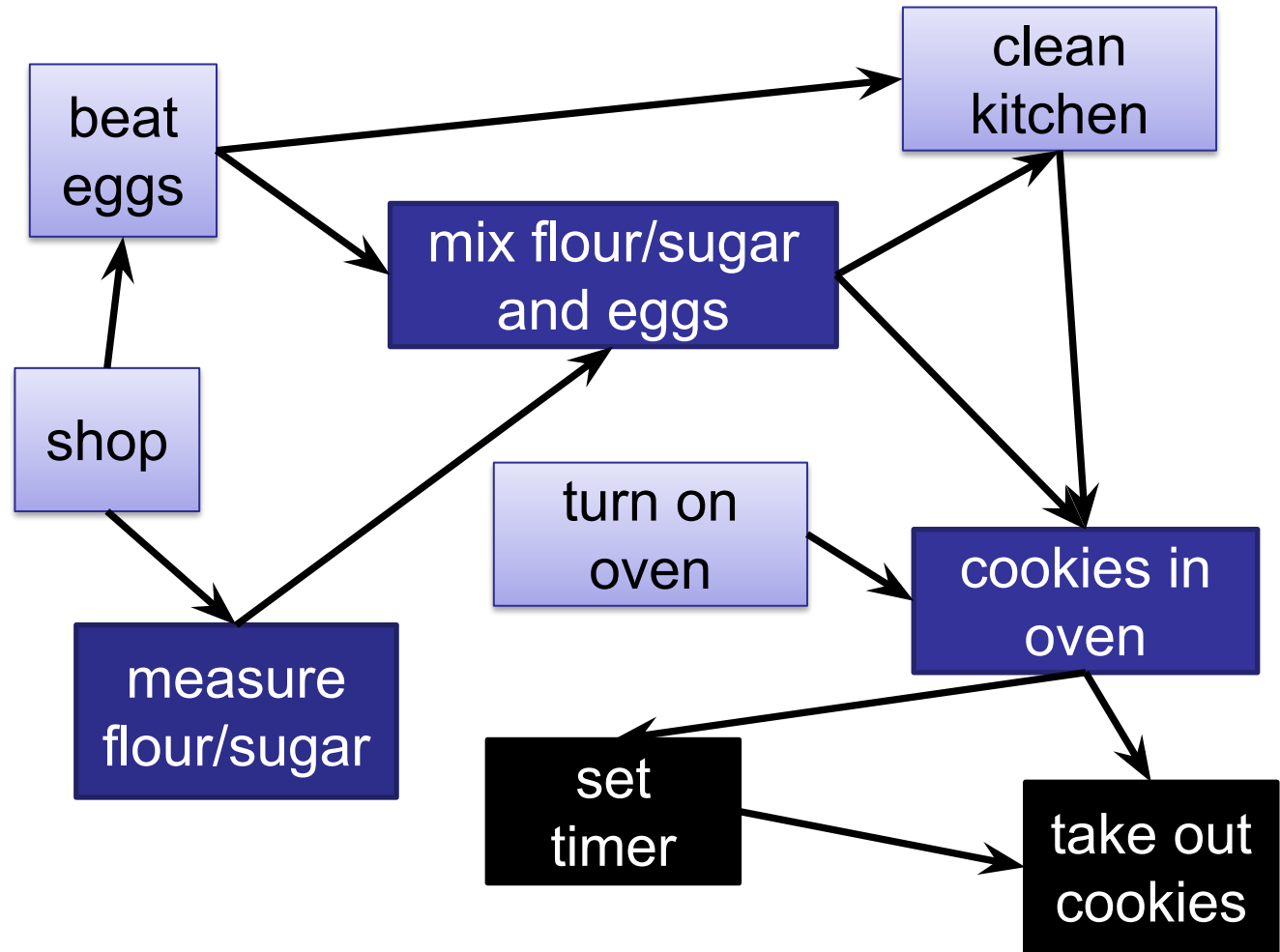
# Post-Order Depth-First Search

- 1.
- 2.
- 3.
- 4.
- 5.
- 6.
- 7.
- 8.
9. take out



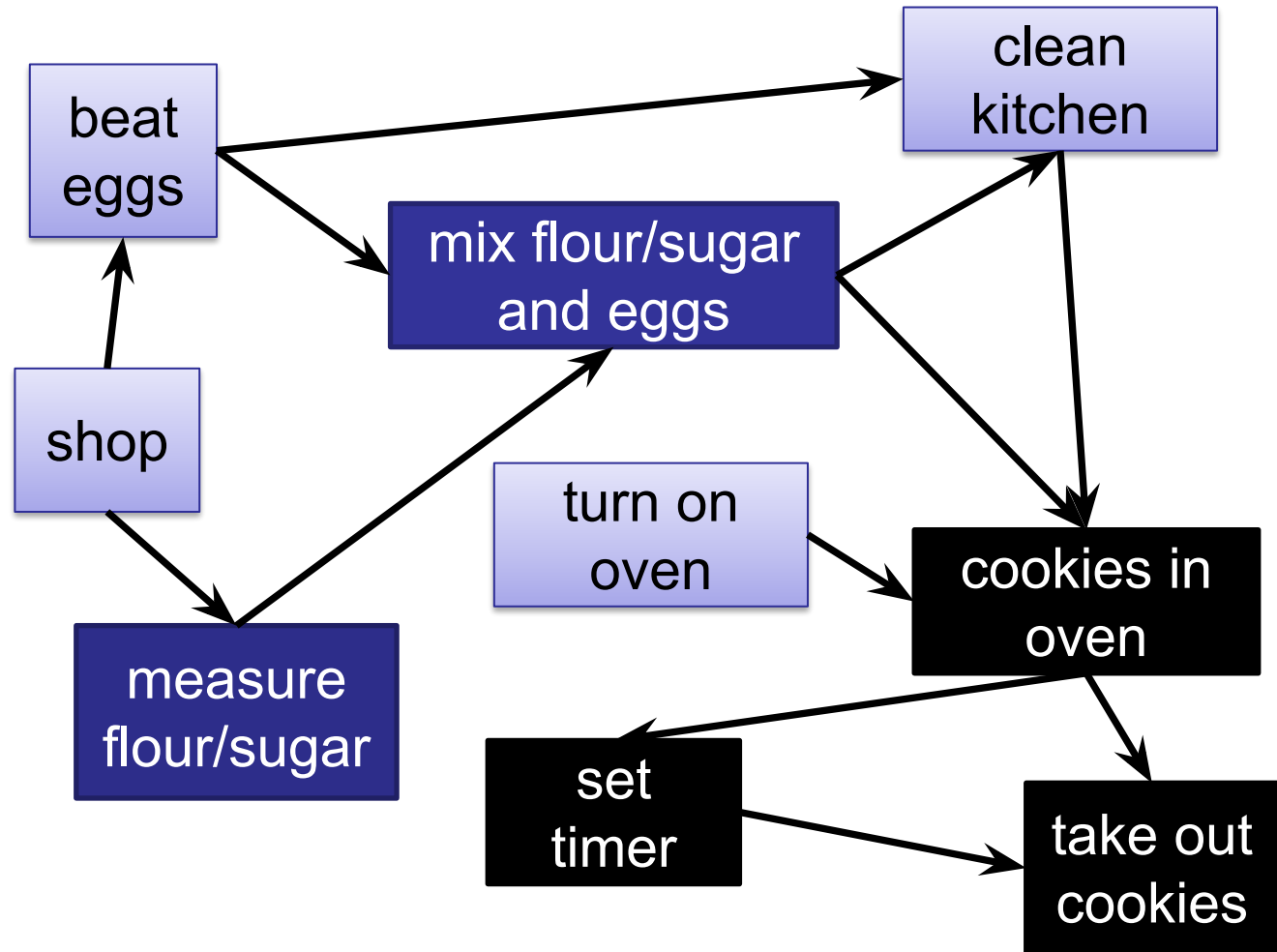
# Post-Order Depth-First Search

- 1.
- 2.
- 3.
- 4.
- 5.
- 6.
- 7.
8. set timer
9. take out



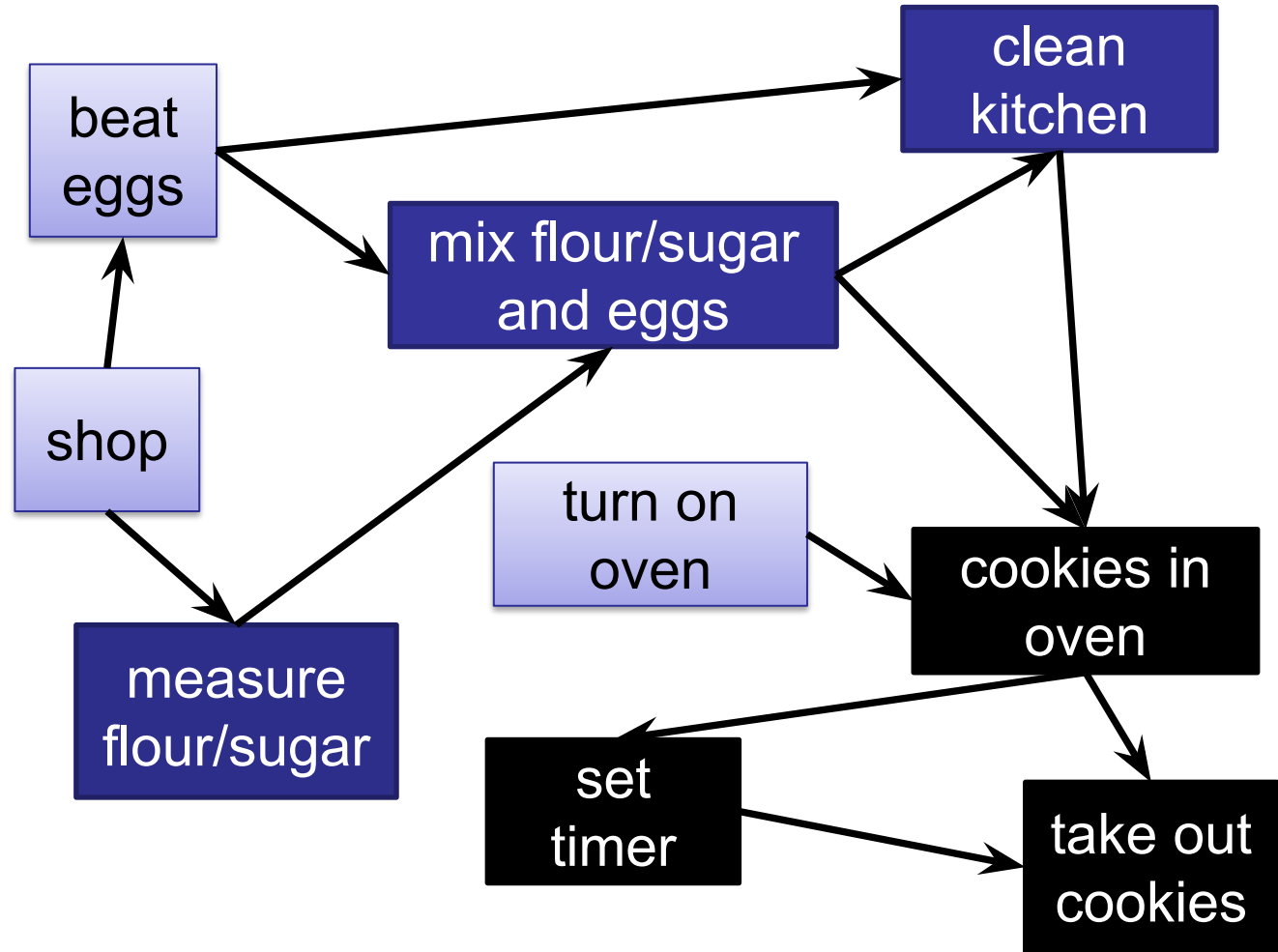
# Post-Order Depth-First Search

- 1.
- 2.
- 3.
- 4.
- 5.
- 6.
7. in oven
8. set timer
9. take out



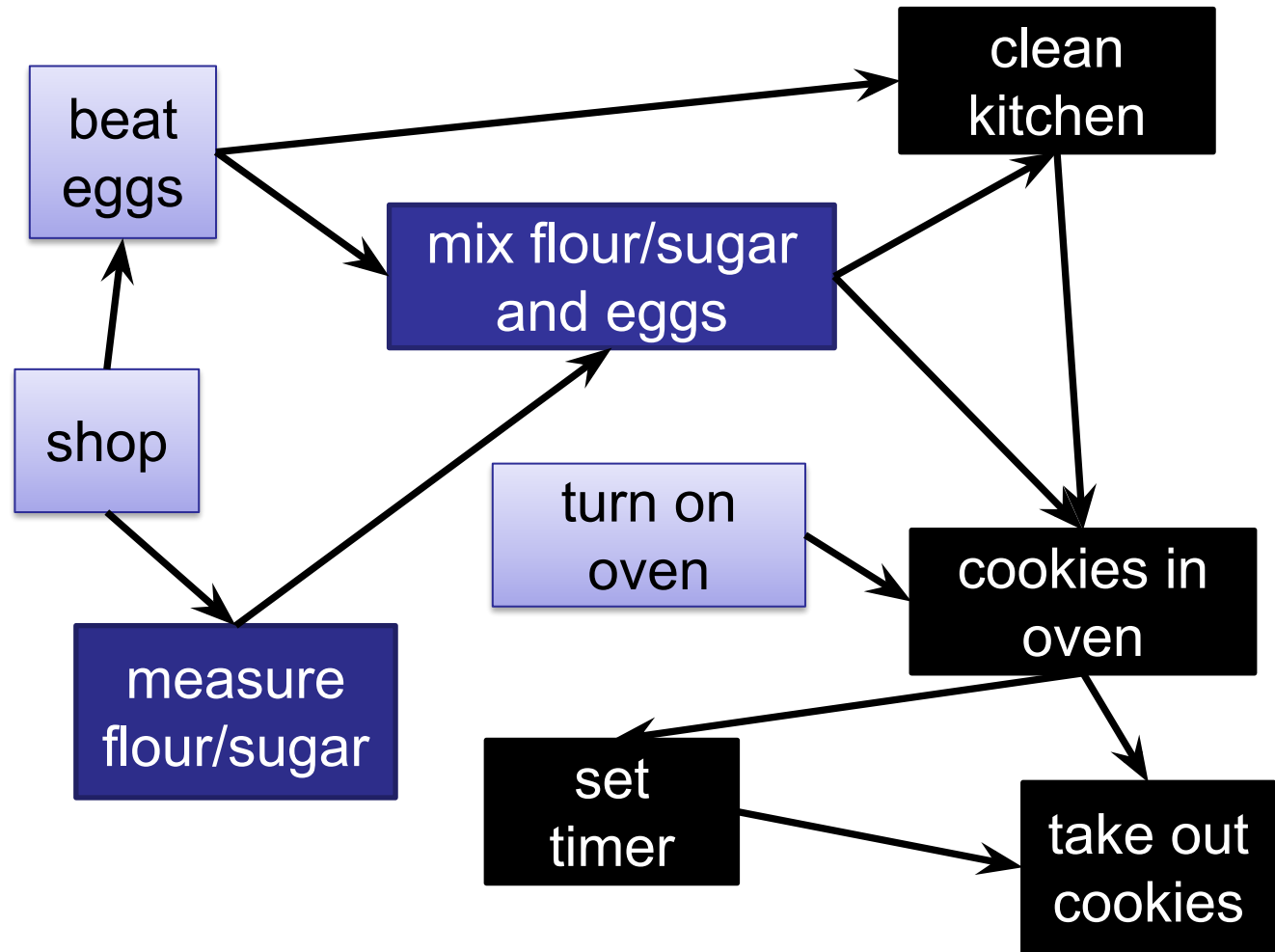
# Post-Order Depth-First Search

- 1.
- 2.
- 3.
- 4.
- 5.
- 6.
7. in oven
8. set timer
9. take out



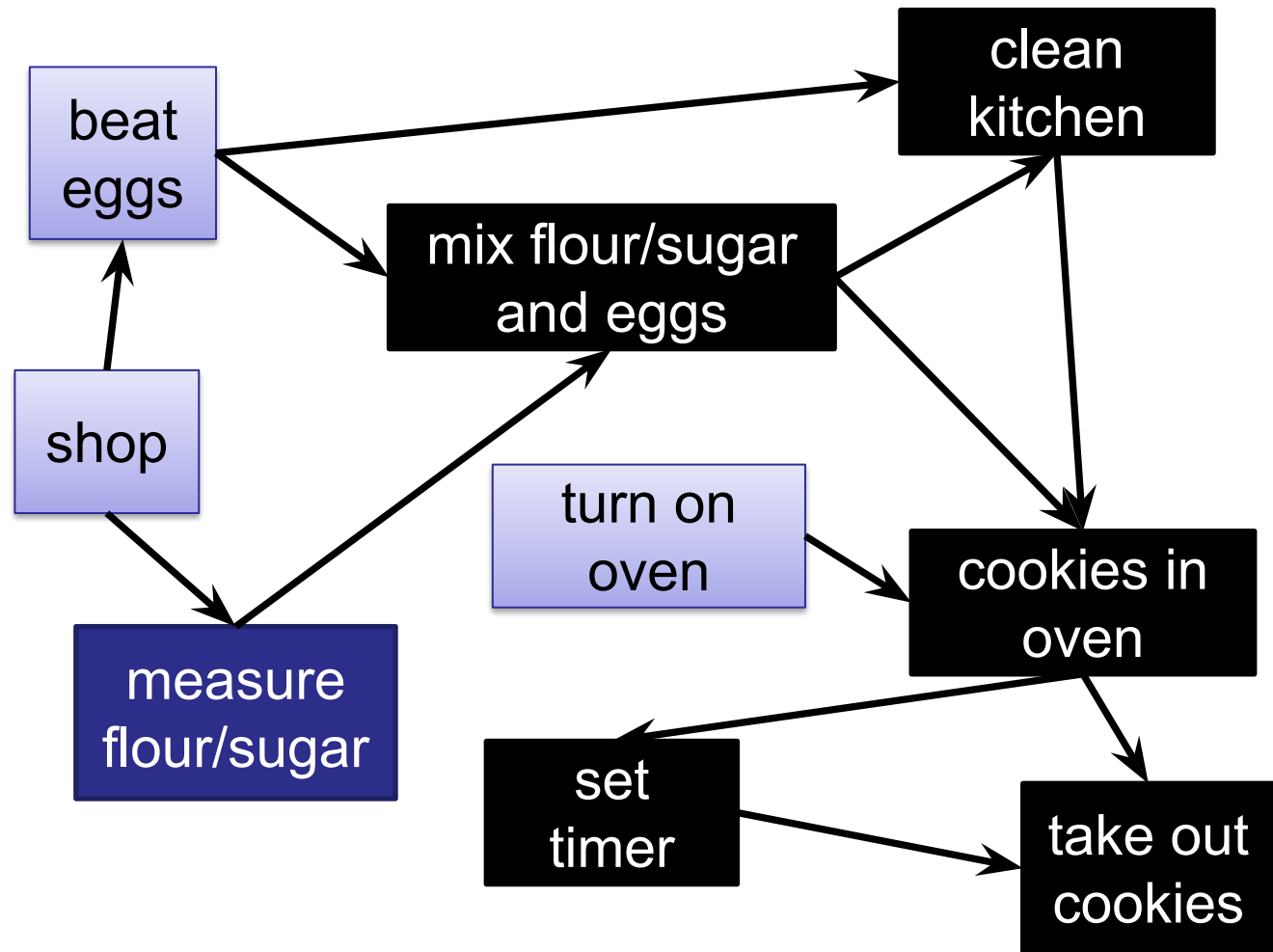
# Post-Order Depth-First Search

- 1.
- 2.
- 3.
- 4.
- 5.
6. clean
7. in oven
8. set timer
9. take out



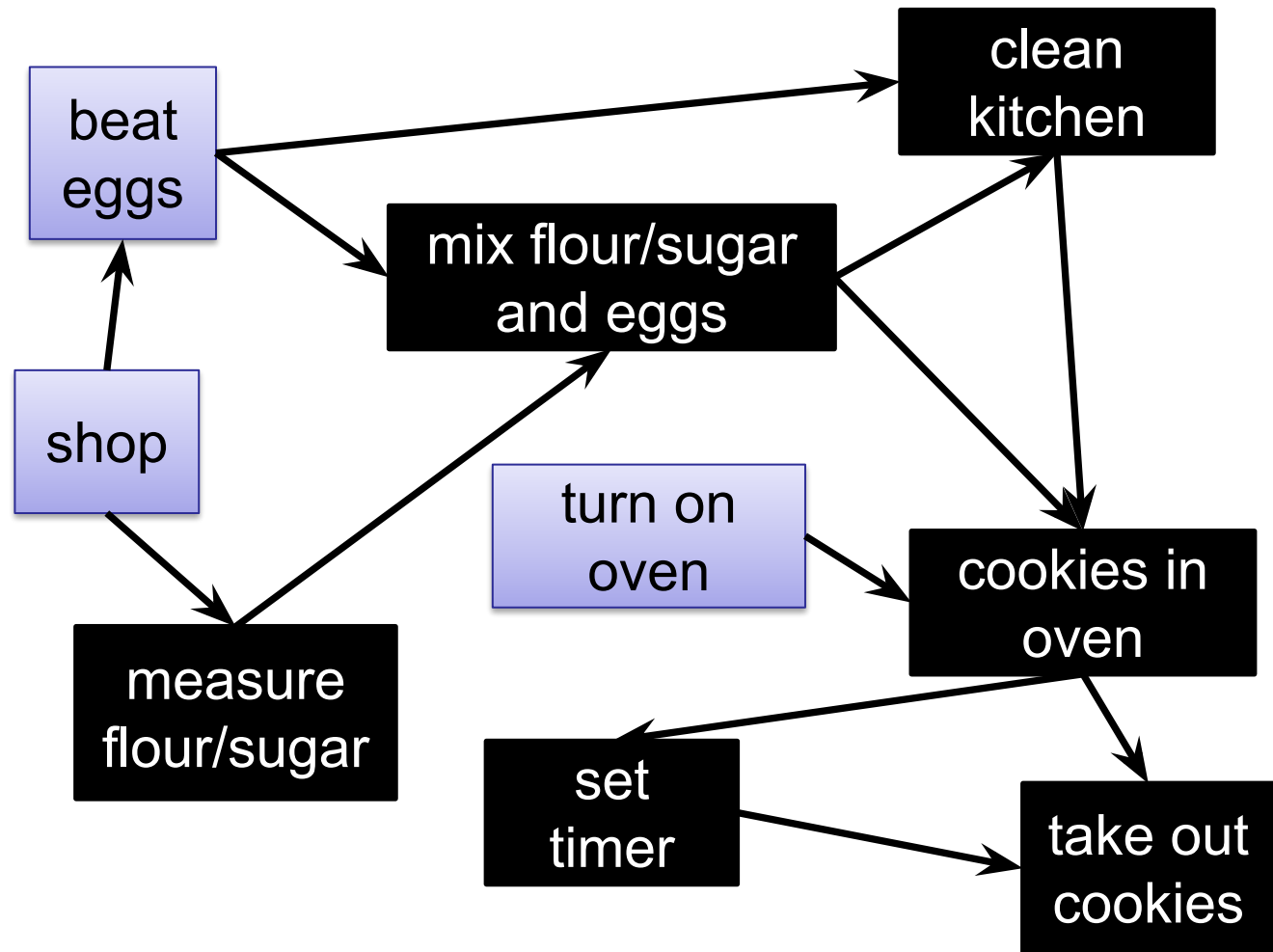
# Post-Order Depth-First Search

- 1.
- 2.
- 3.
- 4.
5. mix
6. clean
7. in oven
8. set timer
9. take out



# Post-Order Depth-First Search

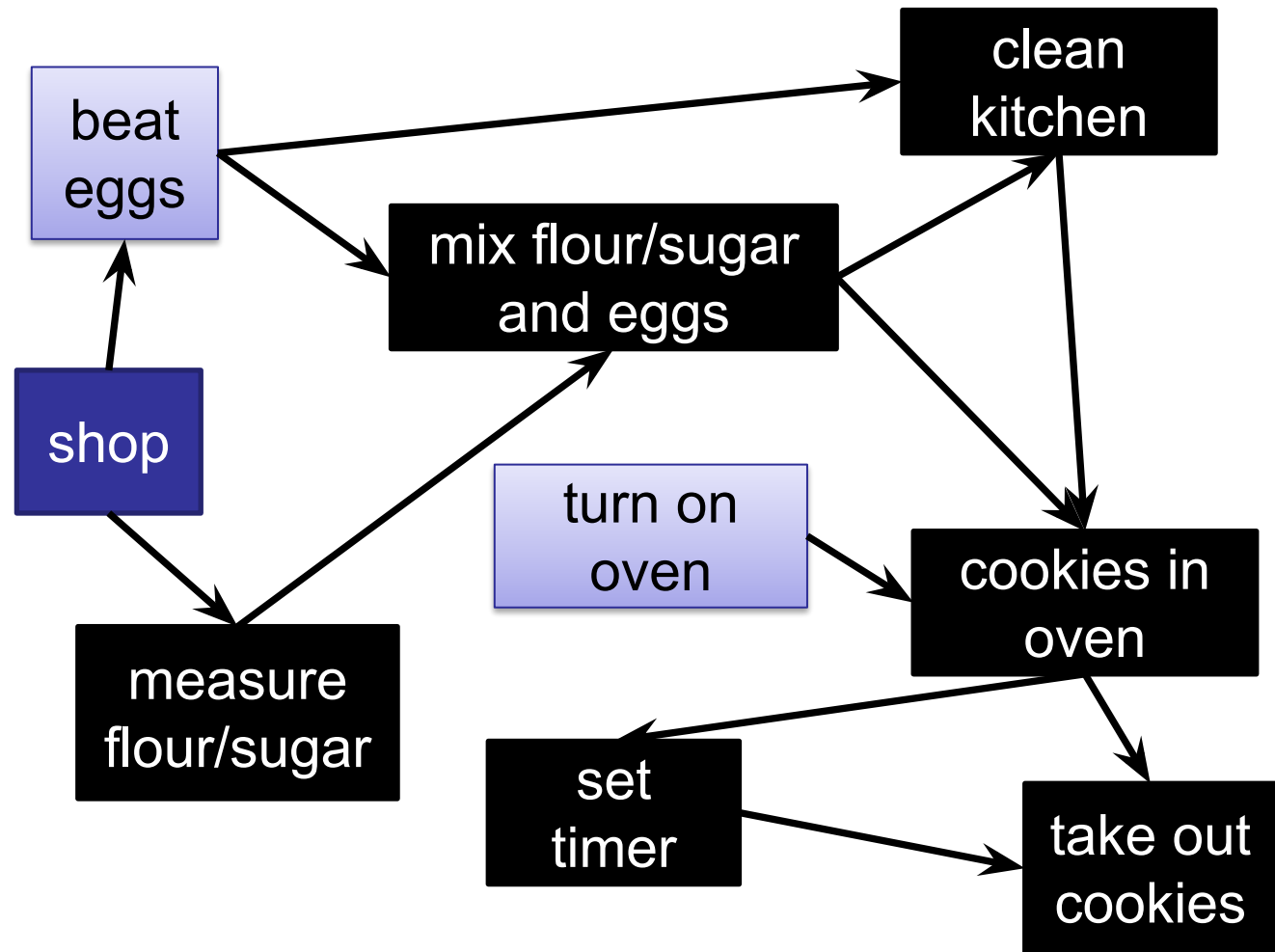
- 1.
- 2.
- 3.
4. measure
5. mix
6. clean
7. in oven
8. set timer
9. take out





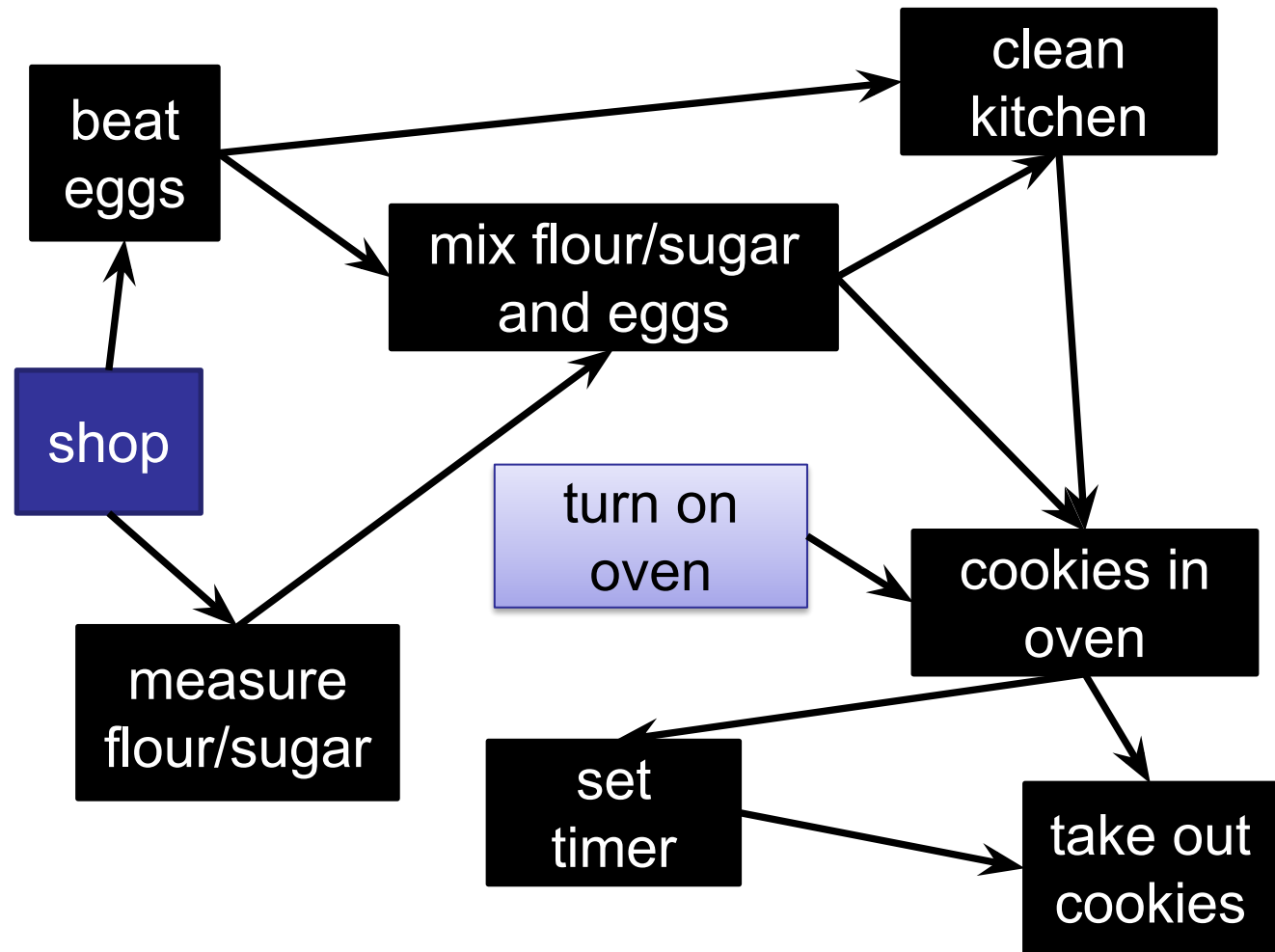
# Post-Order Depth-First Search

- 1.
- 2.
- 3.
4. measure
5. mix
6. clean
7. in oven
8. set timer
9. take out



# Post-Order Depth-First Search

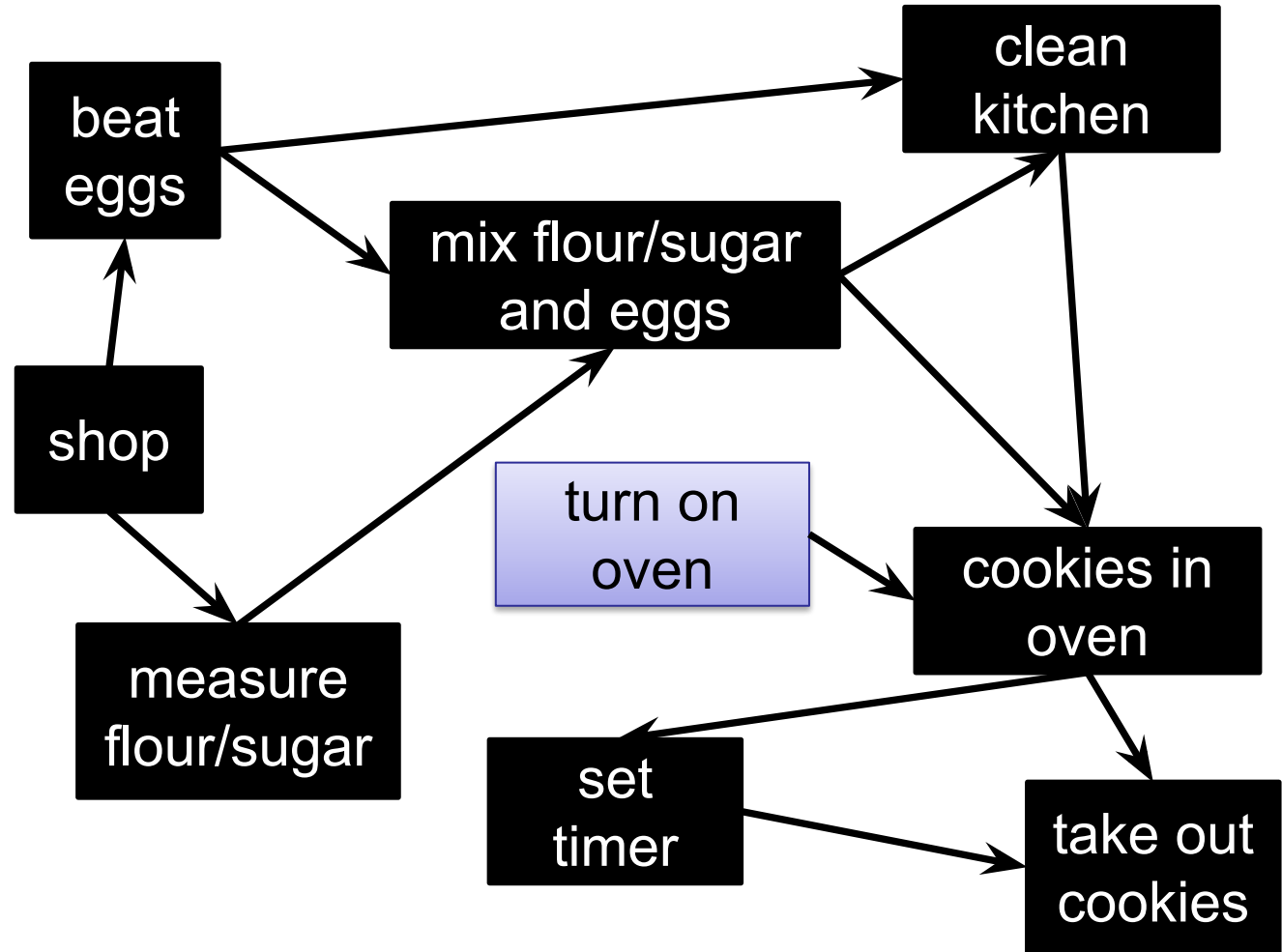
- 1.
- 2.
3. beat
4. measure
5. mix
6. clean
7. in oven
8. set timer
9. take out



# Post-Order Depth-First Search

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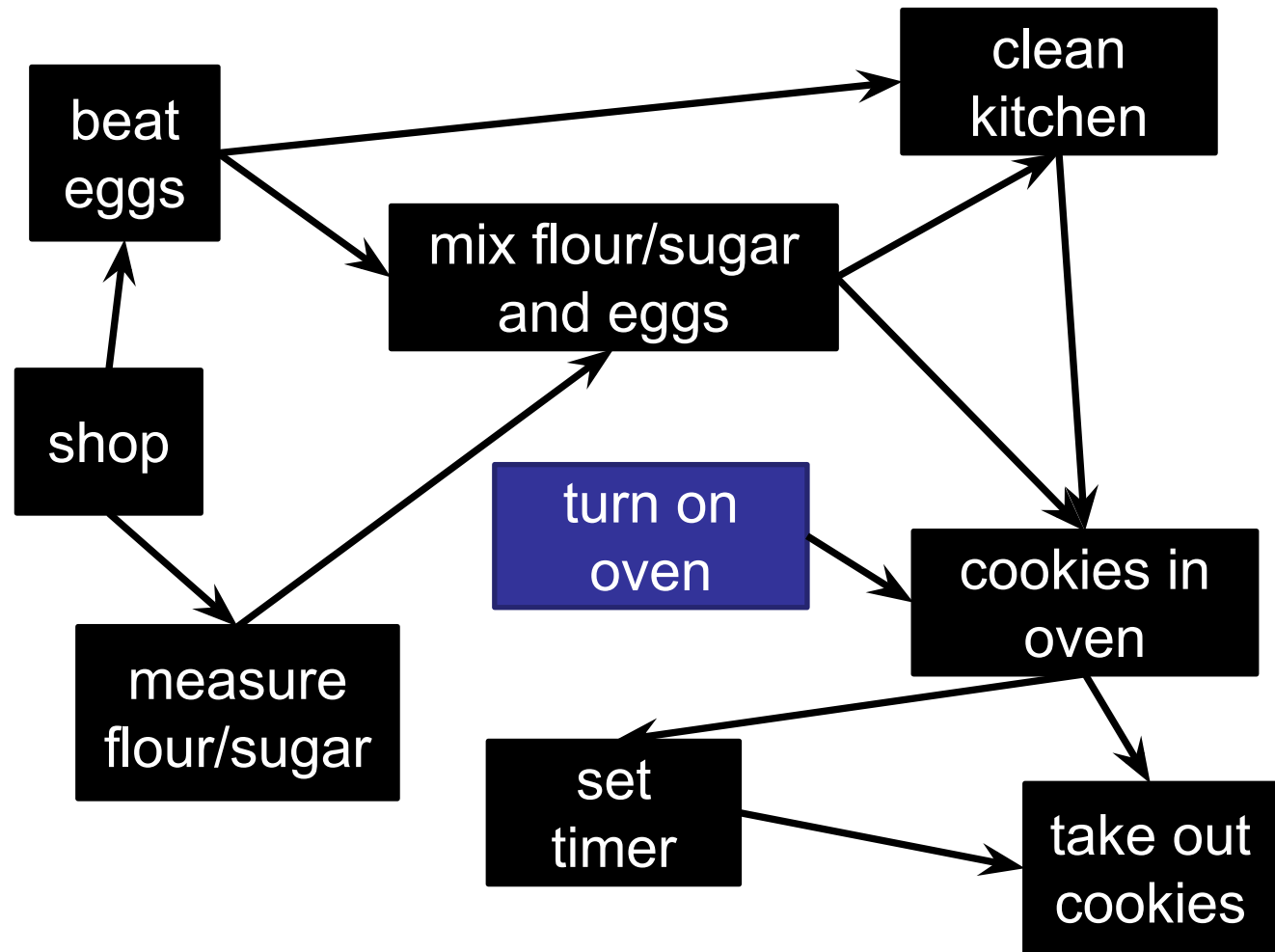
- 1.
2. shop
3. beat
4. measure
5. mix
6. clean
7. in oven
8. set timer
9. take out



# Post-Order Depth-First Search

---

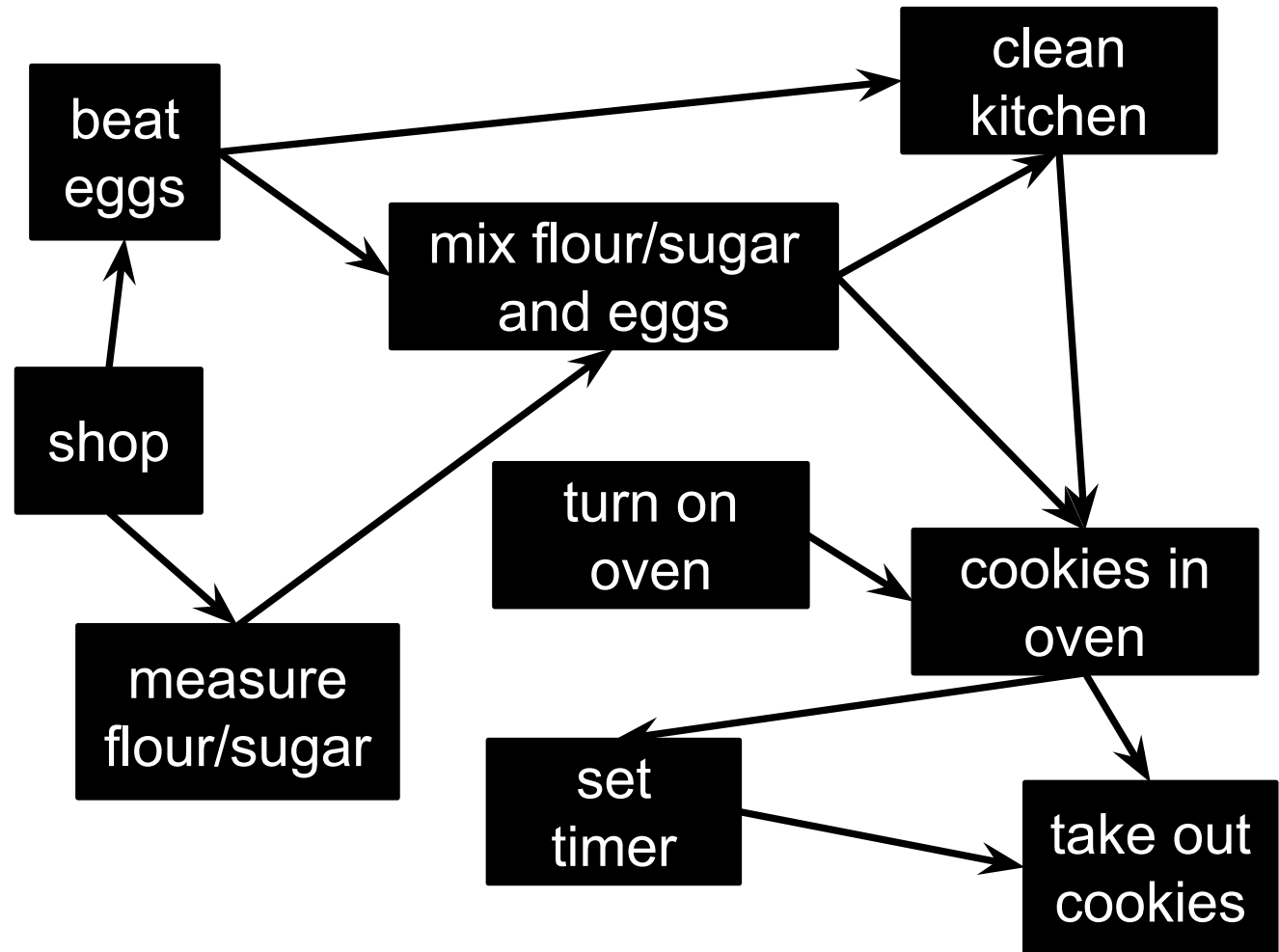
- 1.
2. shop
3. beat
4. measure
5. mix
6. clean
7. in oven
8. set timer
9. take out



# Post-Order Depth-First Search

---

1. on oven
2. shop
3. beat
4. measure
5. mix
6. clean
7. in oven
8. set timer
9. take out



# Depth-First Search

---

```
1 toposort(Node[] nodeList, boolean[] visited, int startId){
2     for (Integer v : nodeList[startId].nbrList) {
3         if (!visited[v]){
4             visited[v] = true;
5             toposort(nodeList, visited, v);
6             post operation here!
7         }
8     }
9 }
```

# Depth-First Search

---

```
1 toposort(Node[] nodeList, boolean[] visited, int startId){
2     for (Integer v : nodeList[startId].nbrList) {
3         if (!visited[v]){
4             visited[v] = true;
5             toposort(nodeList, visited, v);
6             schedule.prepend(startId) ;
7         }
8     }
9 }
```

# Depth-First Search

---

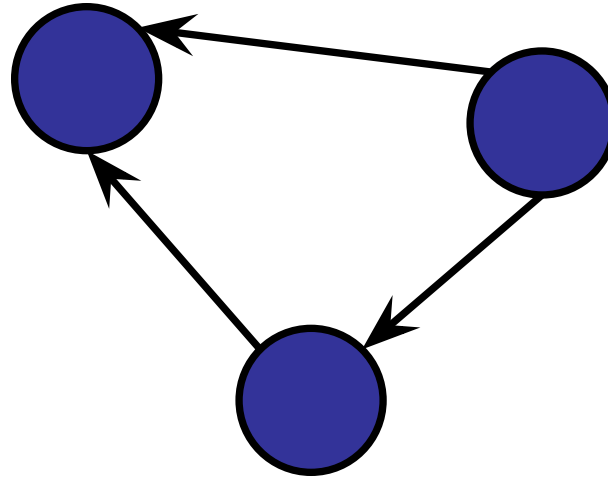
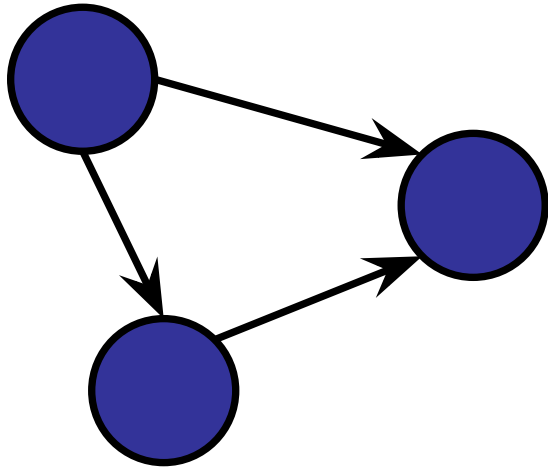
```
1 toposort(Node[] nodeList, boolean[] visited, int startId){
2     for (Integer v : nodeList[startId].nbrList) {
3         if (!visited[v]){
4             visited[v] = true;
5             toposort(nodeList, visited, v);
6             schedule.prepend(startId) ;
7         }
8     }
9 }
```

Does it toposort the graph?



# What about this graph?

---



# Depth-First Search

---

```
1 void toposort(  
2     Integer current_node,  
3     ArrayList<ArrayList<Integer>> adj_list,  
4     List<Integer> topo_list,  
5     boolean[] visited){  
6  
7     for(Integer neighbour : adj_list[current_node]){  
8         if(visited[neighbour]) { continue; }  
9         visited[neighbour] = true;  
10        toposort(neighbour, adj_list, topo_list, visited);  
11    }  
12  
13    topo_list.prepend(current_node);  
14 }  
15
```

# Depth-First Search

---

```
15
16 List<Integer> toposort_all(ArrayList<ArrayList<Integer>> adj_list){
17     // initially all false
18     boolean[] visited = new boolean[adj_list.size()]
19
20     // topo list
21     List<Integer> topo_list;
22
23     for(int start = 0; start < adj_list.size(); ++start){
24         if(visited[start]) { continue; }
25         toposort(start, adj_list, topo_list, visited);
26     }
27
28     return topo_list;
29
30 }
```

# Topological Sort

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What is the time complexity of topological sort?

# Topological Sort

---

What is the time complexity of topological sort?

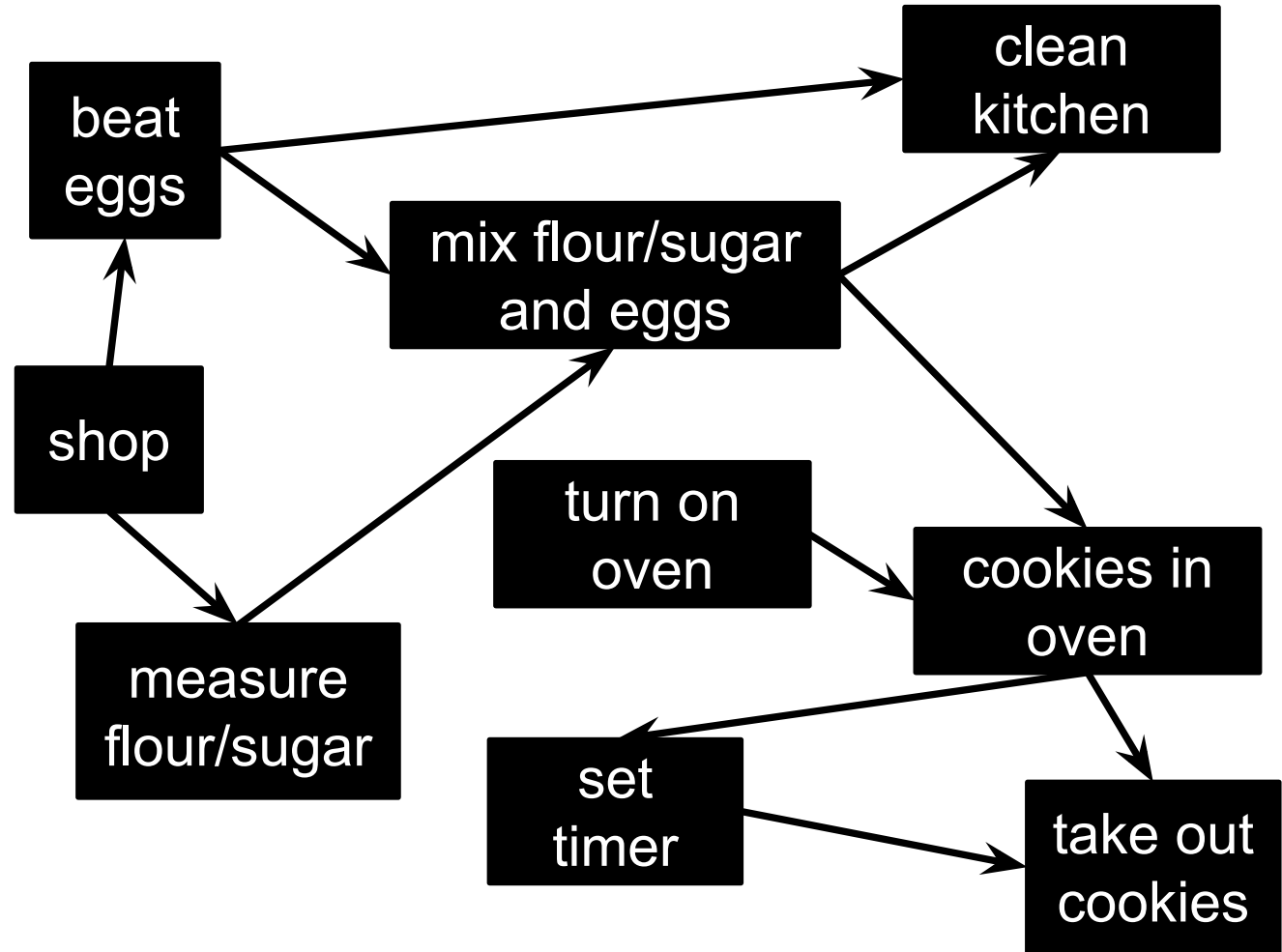
DFS:  $O(V+E)$

# Is a topological ordering unique?

1. Yes
- ✓ 2. No
3. Only on Thursdays.

# Post-Order Depth-First Search

1. **on oven**
2. **shop**
3. beat
4. measure
5. mix
6. **clean**
7. in oven
8. **set timer**
9. take out



# Topological Sort

---

Input:

- Directed Acyclic Graph (DAG)

Output:

- Total ordering of nodes, where all edges point forwards.

Algorithm:

- Post-order Depth-First Search
- $O(V + E)$  time complexity



# Topological Sort

---

Alternative algorithm:

Input: directed graph  $G$

Repeat:

- $S$  = all nodes in  $G$  that have *no* incoming edges.
- Add nodes in  $S$  to the topo-order
- Remove all edges adjacent to nodes in  $S$
- Remove nodes in  $S$  from the graph

Time:

- $O(V + E)$  time complexity

# Topological Sort

---

But how do we tell if the directed graph is cyclic or not?

# Some other DFS-able problems

---

1. How to tell if a graph is cyclic?

# Some other DFS-able problems

---

1. How to tell if a graph is cyclic?
2. How to find strongly connected components?

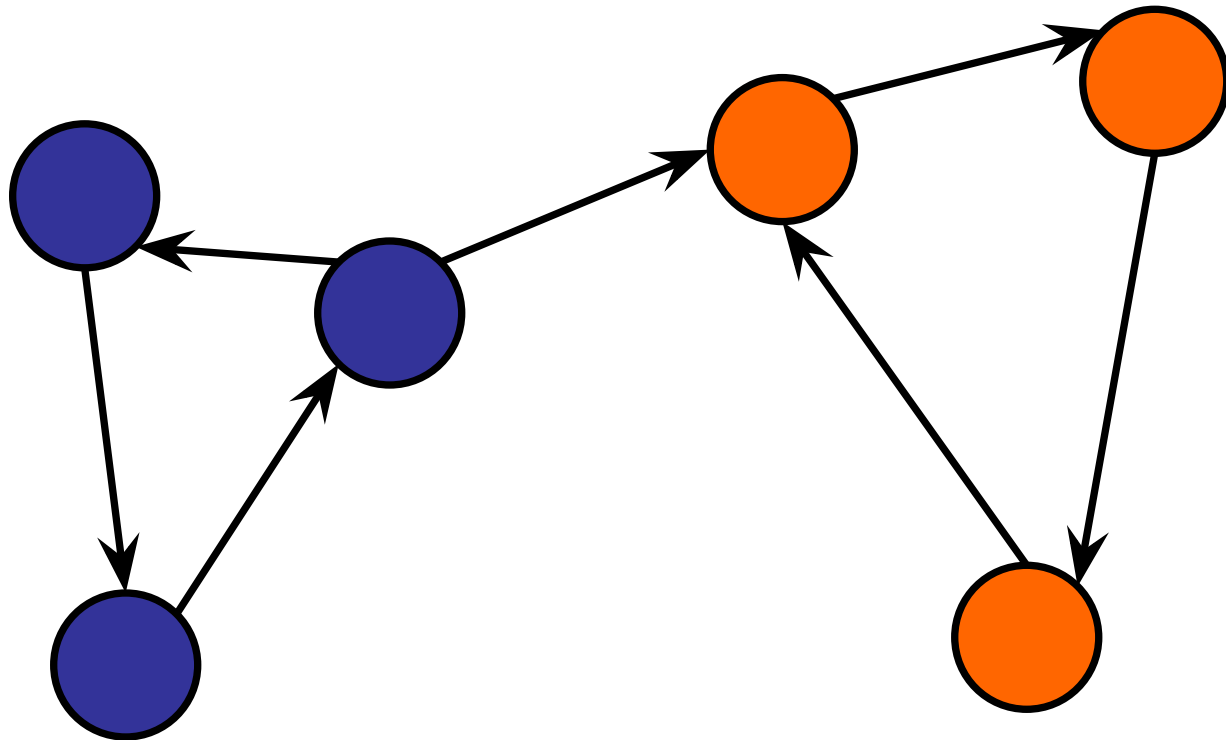
# Connected Components

---

## Strongly connected component

For every vertex  $v$  and  $w$ :

- There is a path from  $v$  to  $w$ .
- There is a path from  $w$  to  $v$ .

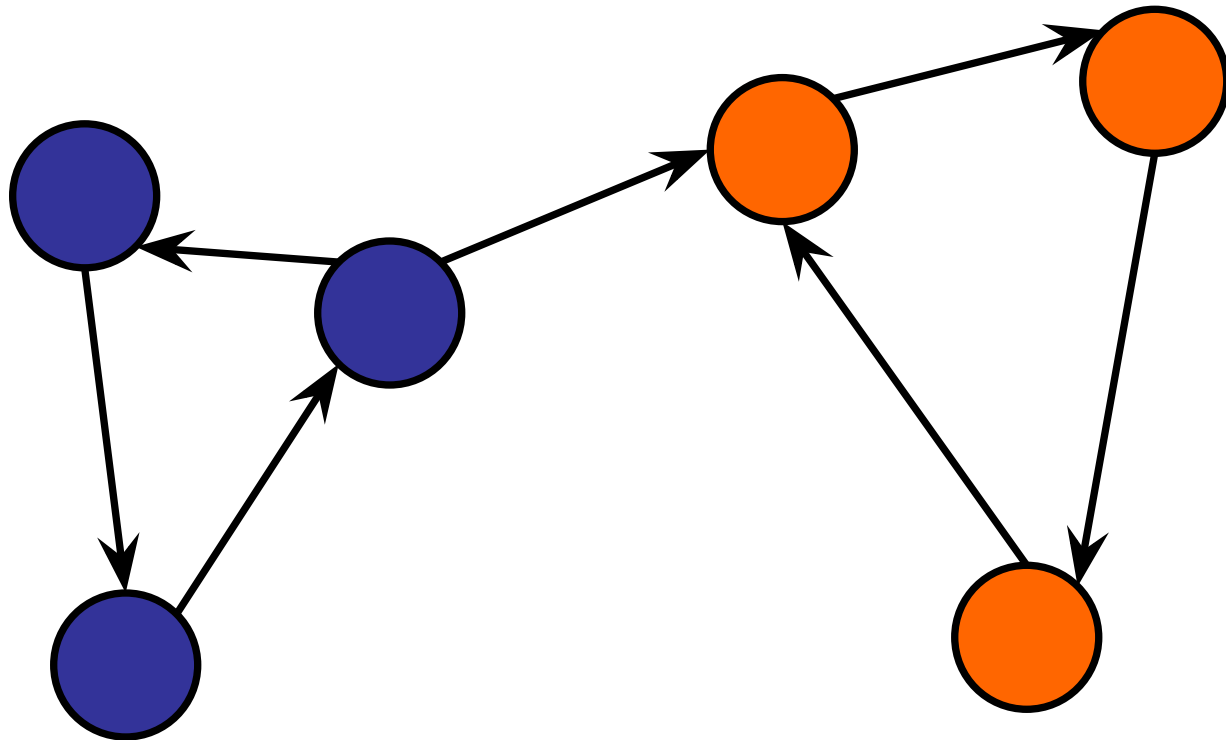


# Connected Components

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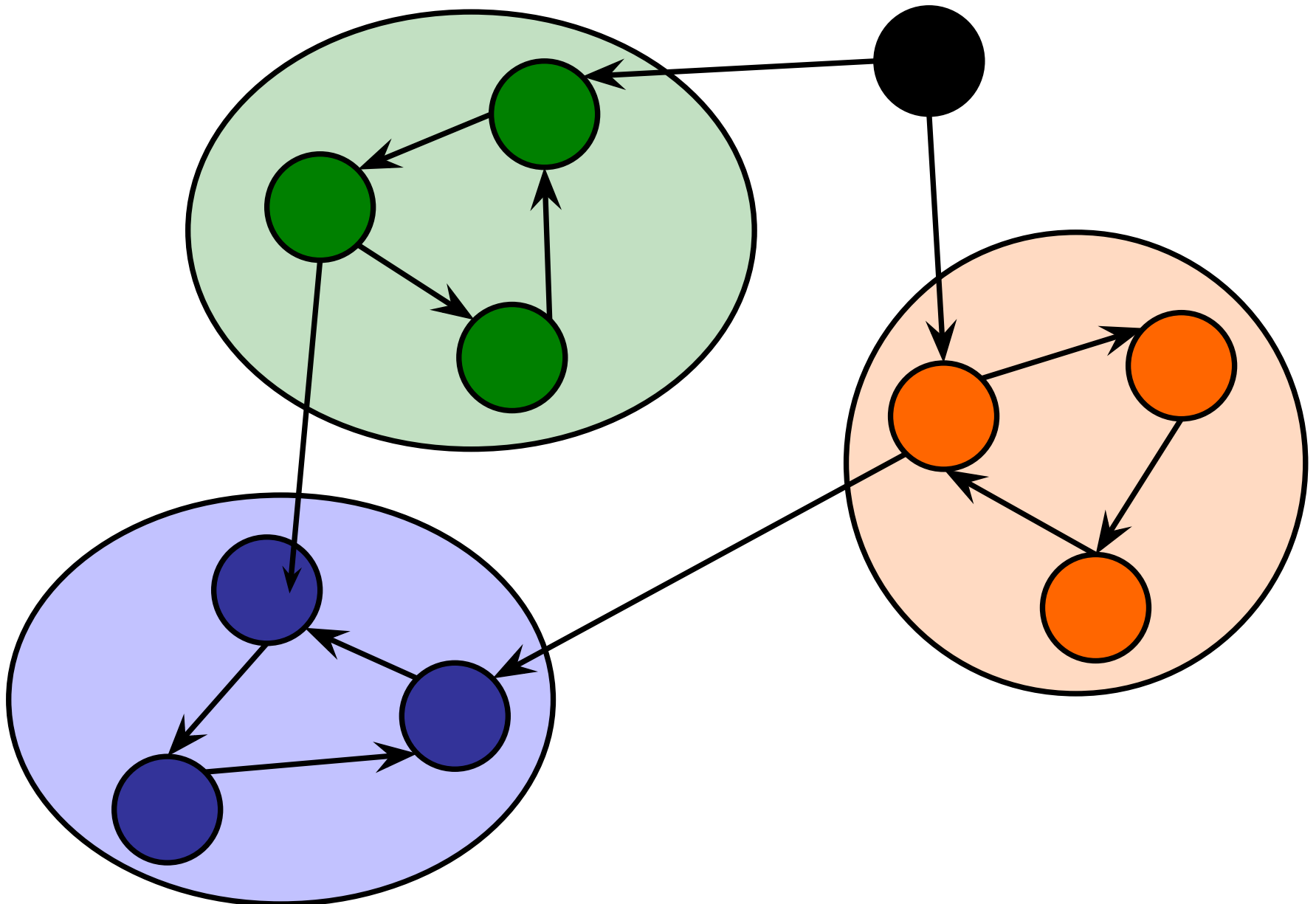
## Strongly connected component

Two nodes  $v, w$  in a SCC are reachable to/from each other.



# Connected Components

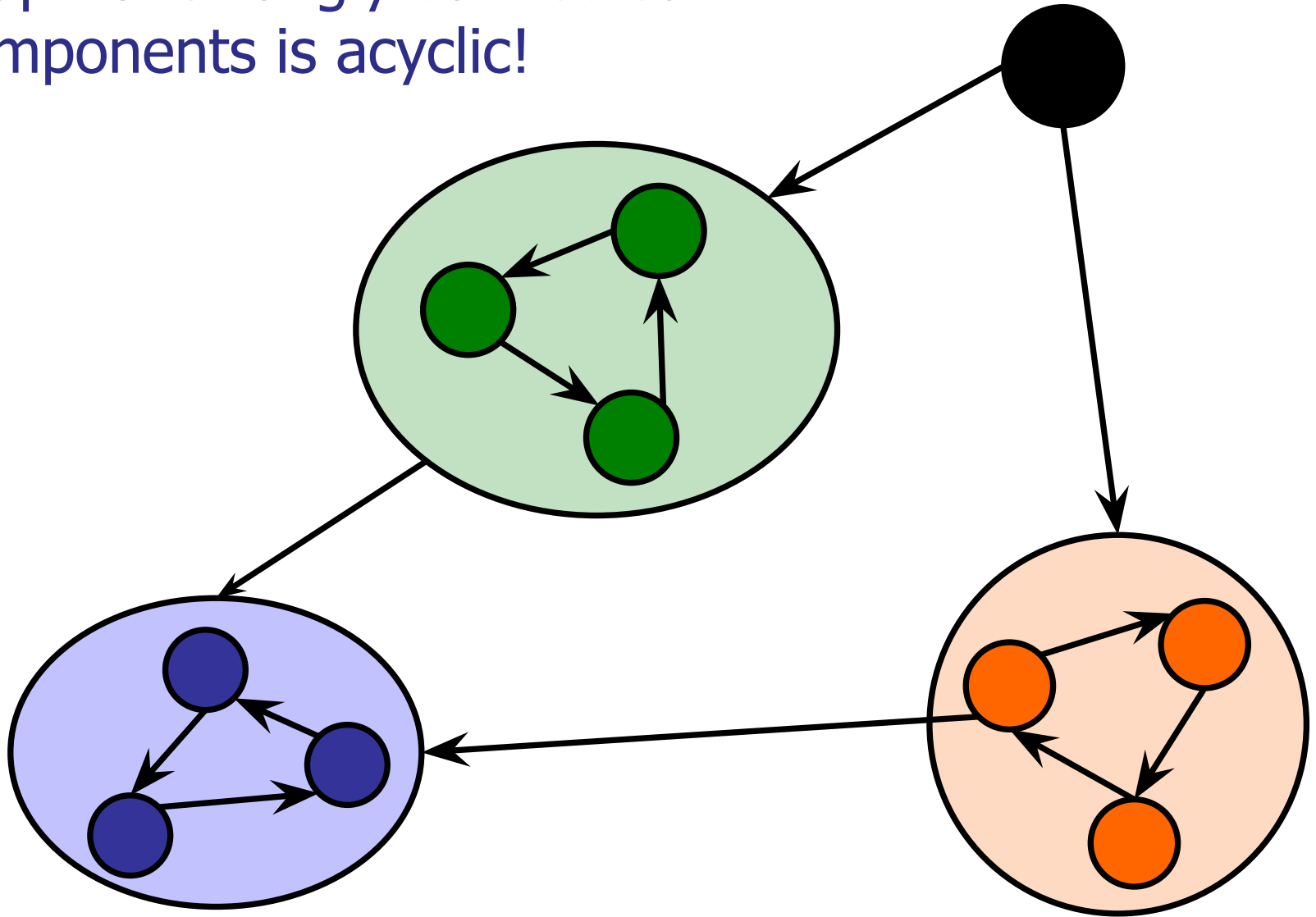
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# Connected Components

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Graph of strongly connected components is acyclic!

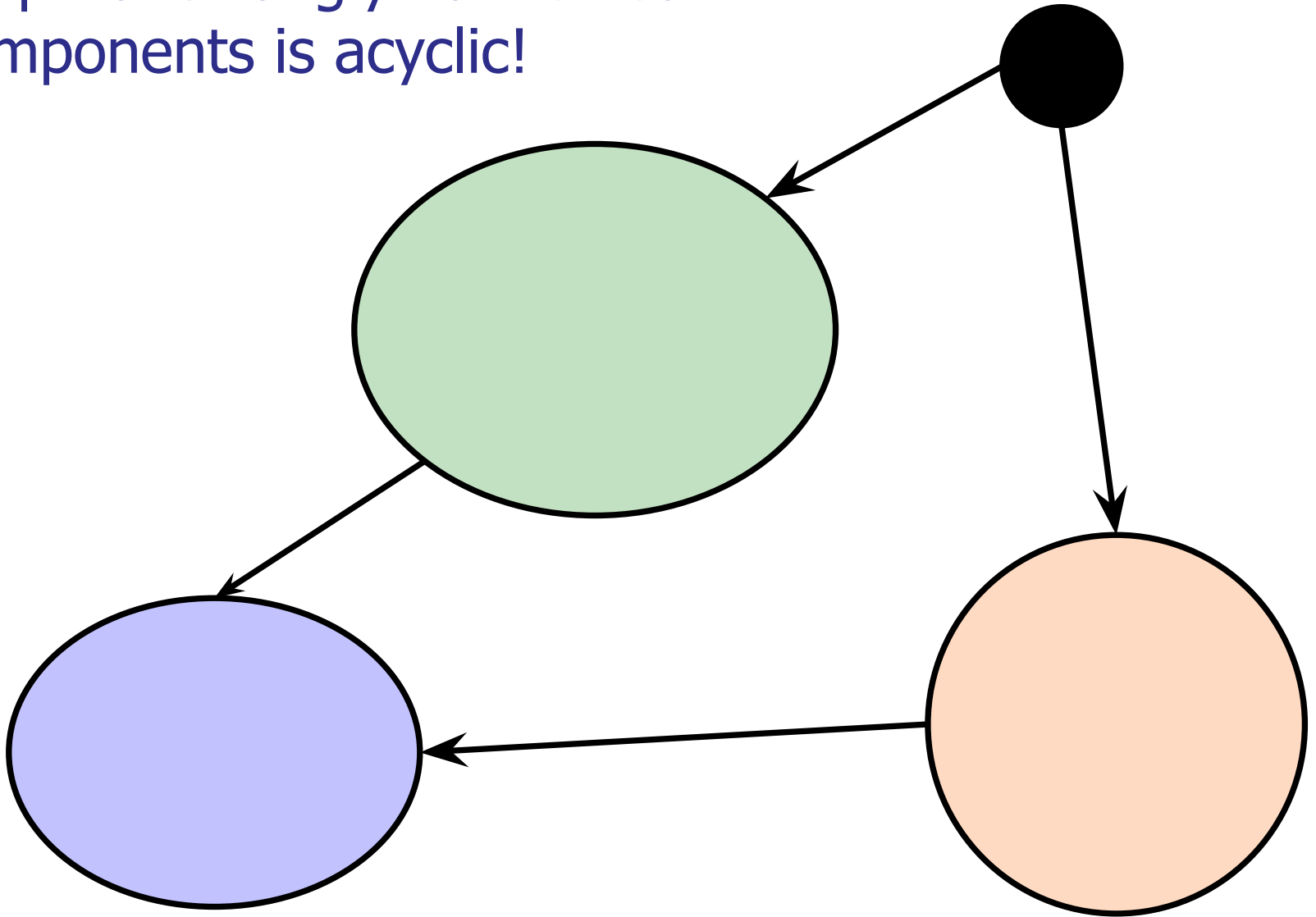




# Connected Components

---

Graph of strongly connected components is acyclic!



# Strongly Connected Components

---

Input:

- Directed Graph

Output:

- A labelling of the nodes to denote which component it belongs to.
- If we consider the graph based on the components, it is acyclic.

# Some other DFS-able problems

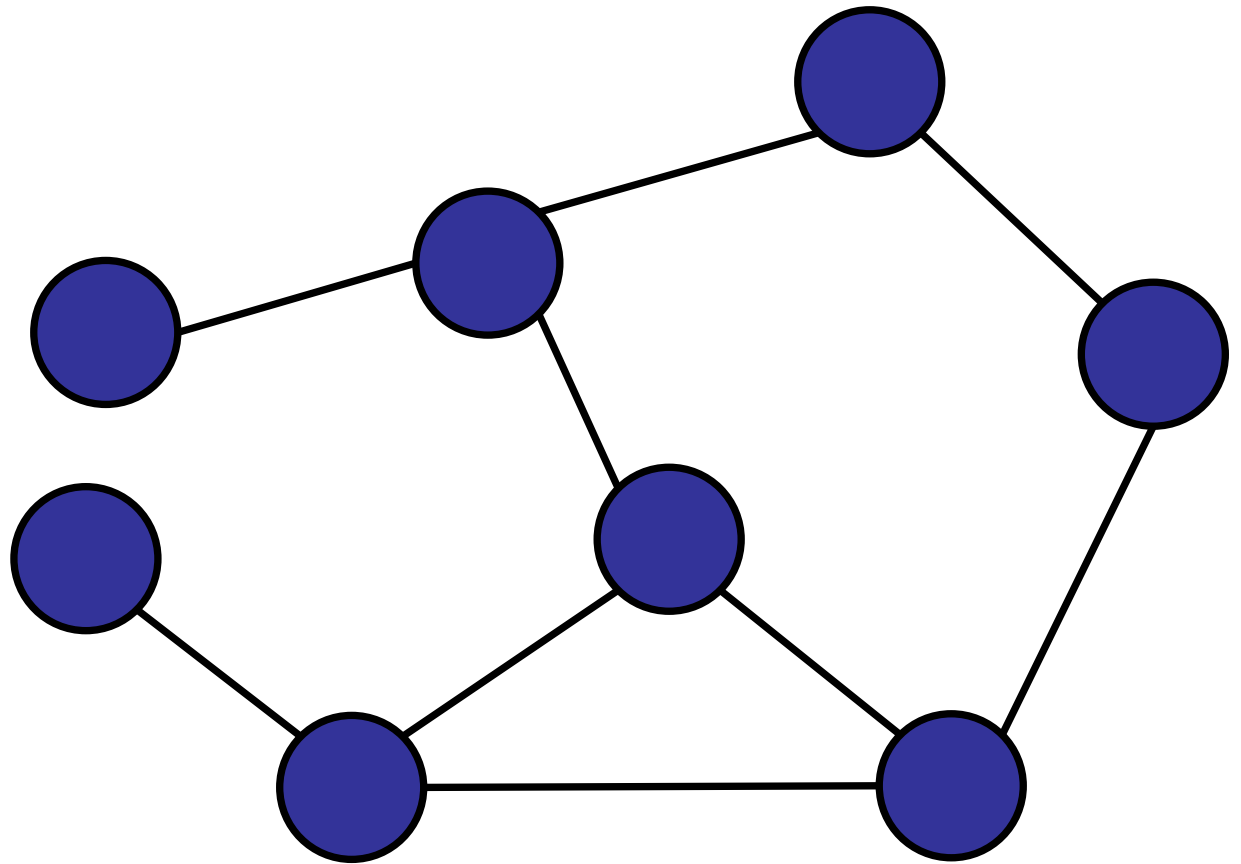
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1. How to tell if a graph is cyclic?
2. How to find strongly connected components?
3. How do we find articulation points?

# Articulation Points

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A node is an **articulation point** if removing it disconnects the graph

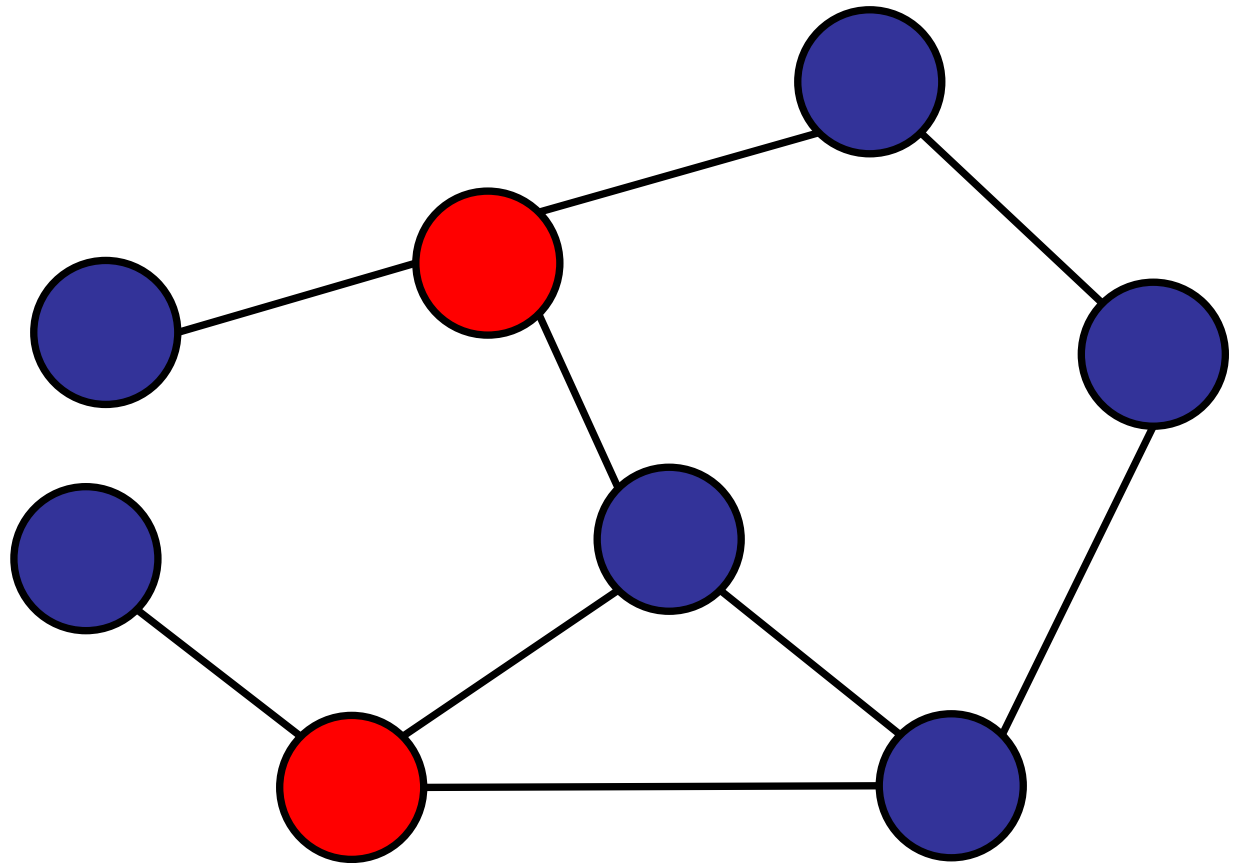




# Articulation Points

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Goal: Given an undirected graph, find all articulation points.



# DFS: Template

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Today:

One DFS to rule them all

- Bridge edges / Articulation Points / Cycle Detection



# DFS: Template

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Idea: What if we marked each node we DFS with 2 things:

1. The **time** we visited it.
2. The **lowest time** we can reach from our neighbours.



# DFS: Template

---

Clarification:

Idea:

1. Mark each node with the **time** we visited it.
2. If we ever visit a neighbour whose **lowest time** is not set, we will consider taking their **time** as our **lowest time**.
3. Setting **lowest time** is only done after our recursion as a post-traversal operation.

# Cycle Finding

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## Clarification:

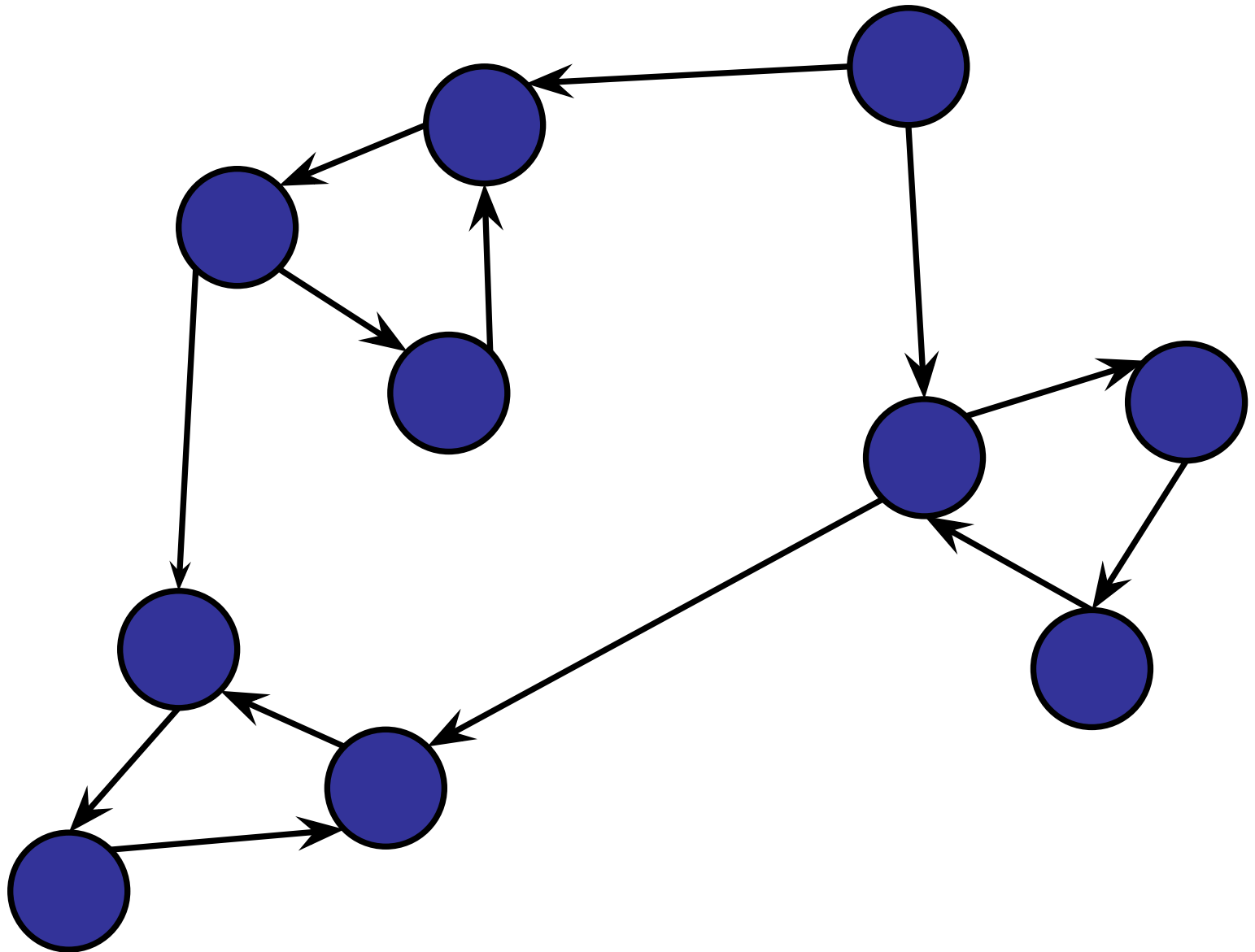
There are 3 possible cases of values to consider for setting a node **u**'s **low time**. This will be the minimum of:

1. Node **u**'s **time** itself.
2. For any neighbour **v** of **u**, whose **time** is set, but **low time** is not set. We consider their **time**.
3. For any neighbour **v** of **u**, whose **time** is not set, we will first recurse on them. And consider their resulting **low time**.

(We'll ignore any neighbours whose **low time** is set before we visit them)

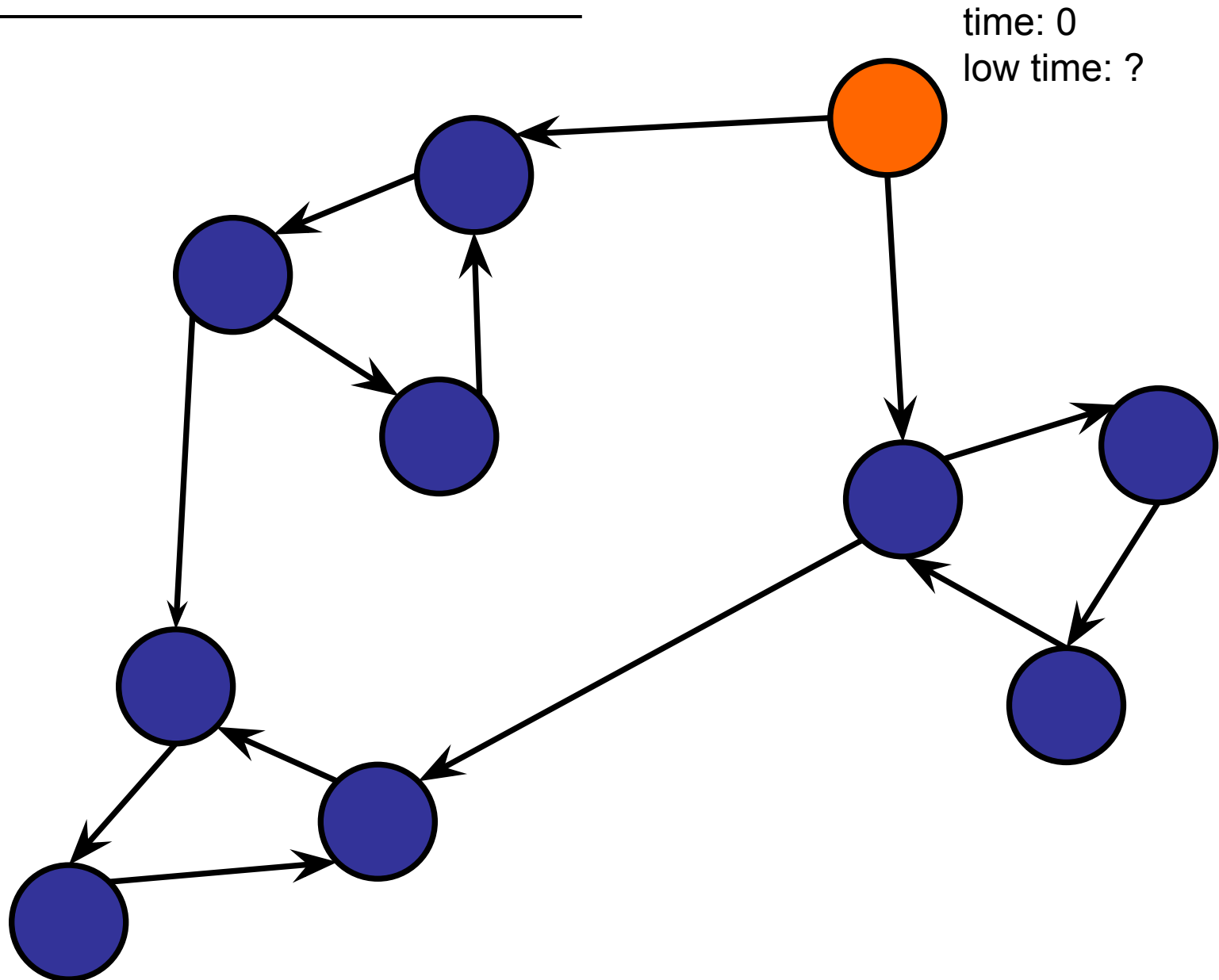
# Connected Components

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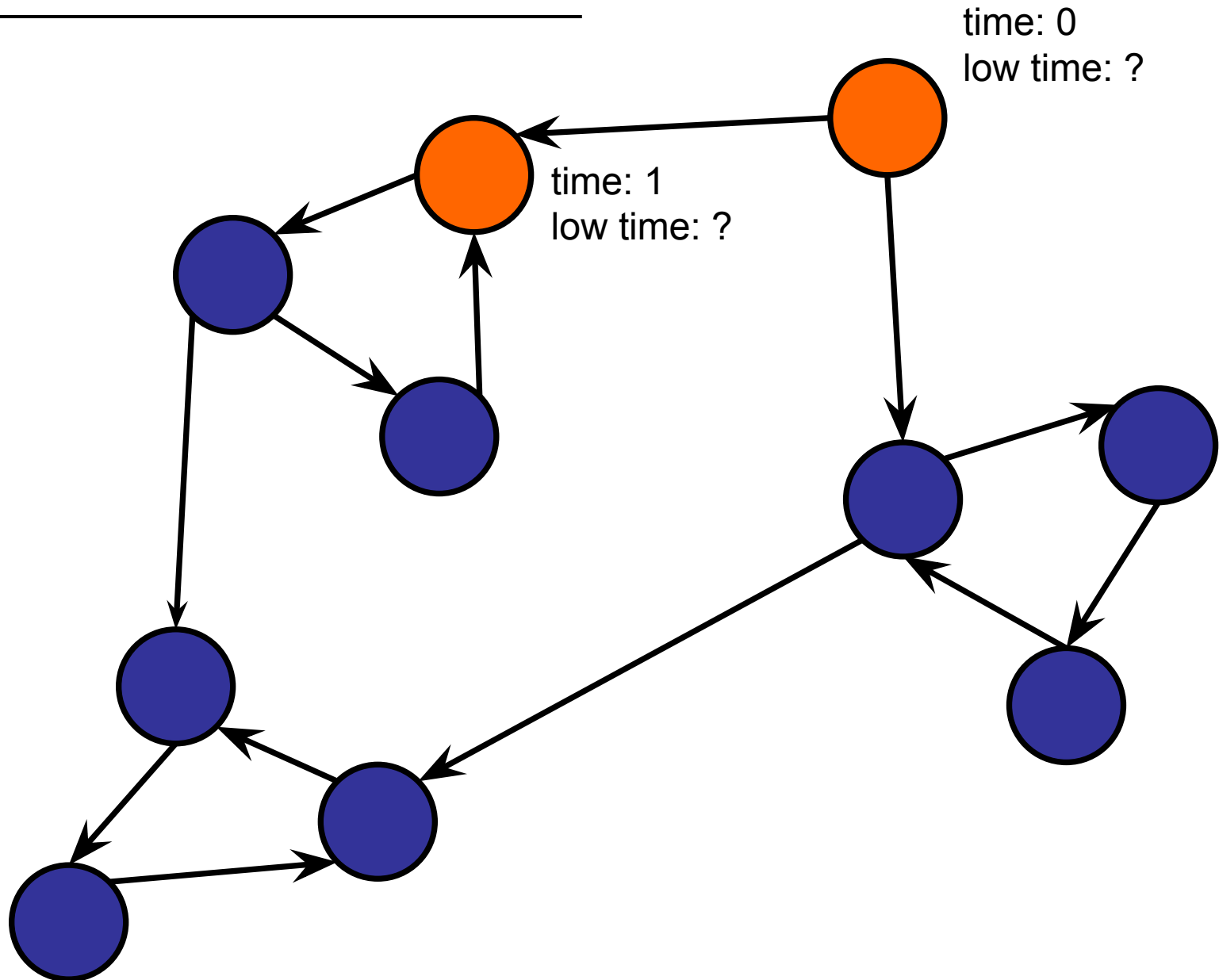
# Connected Components

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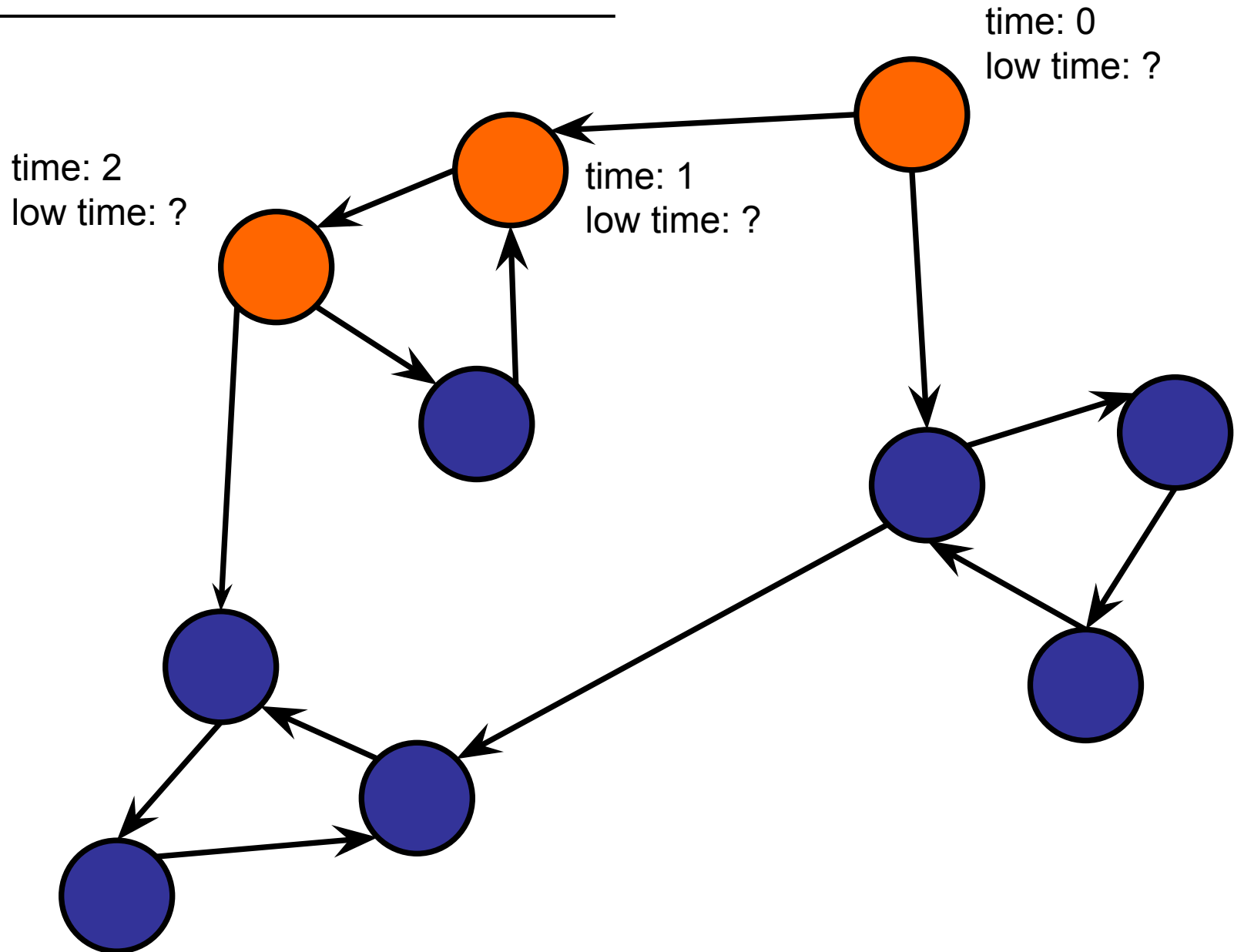
# Connected Components

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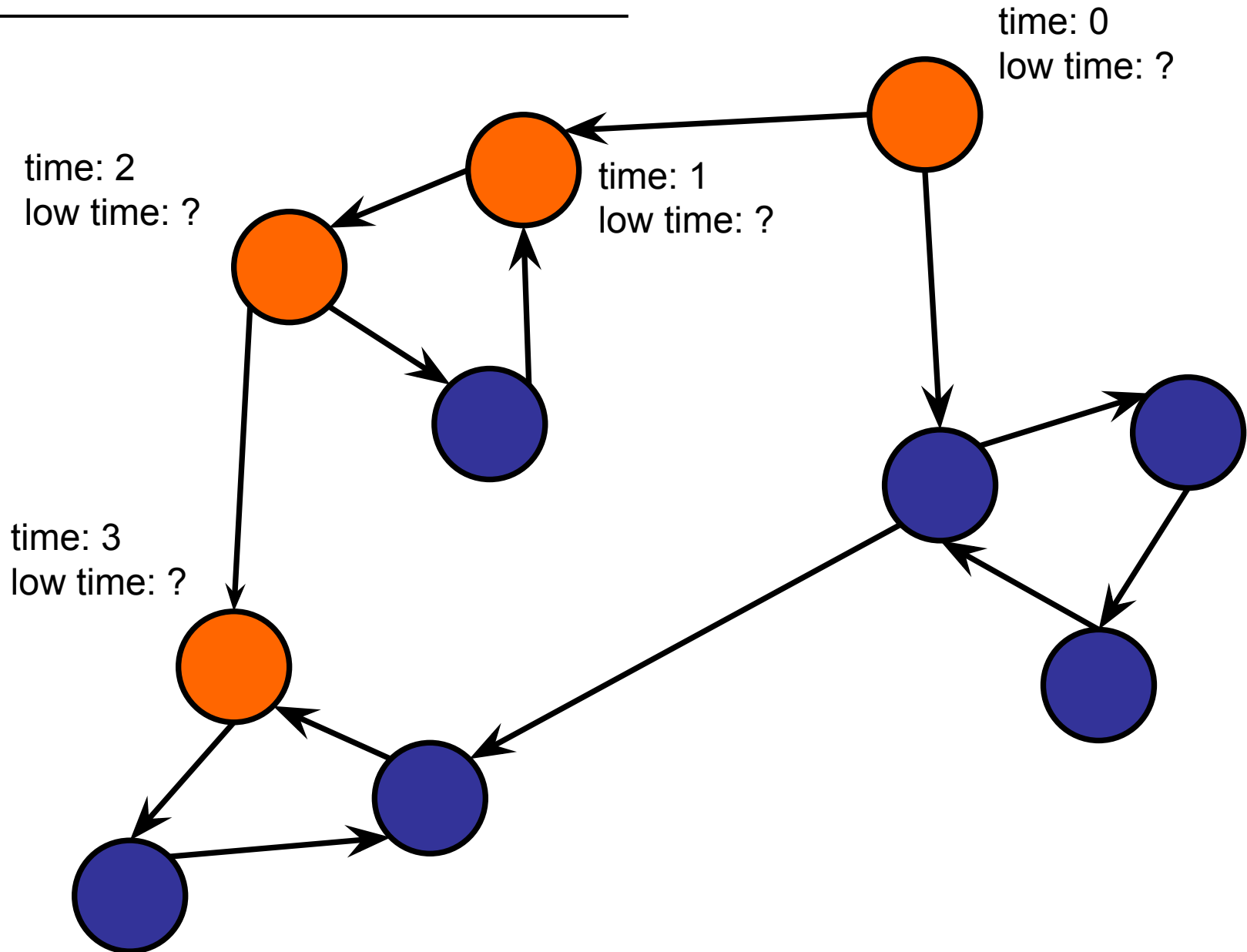
# Connected Components

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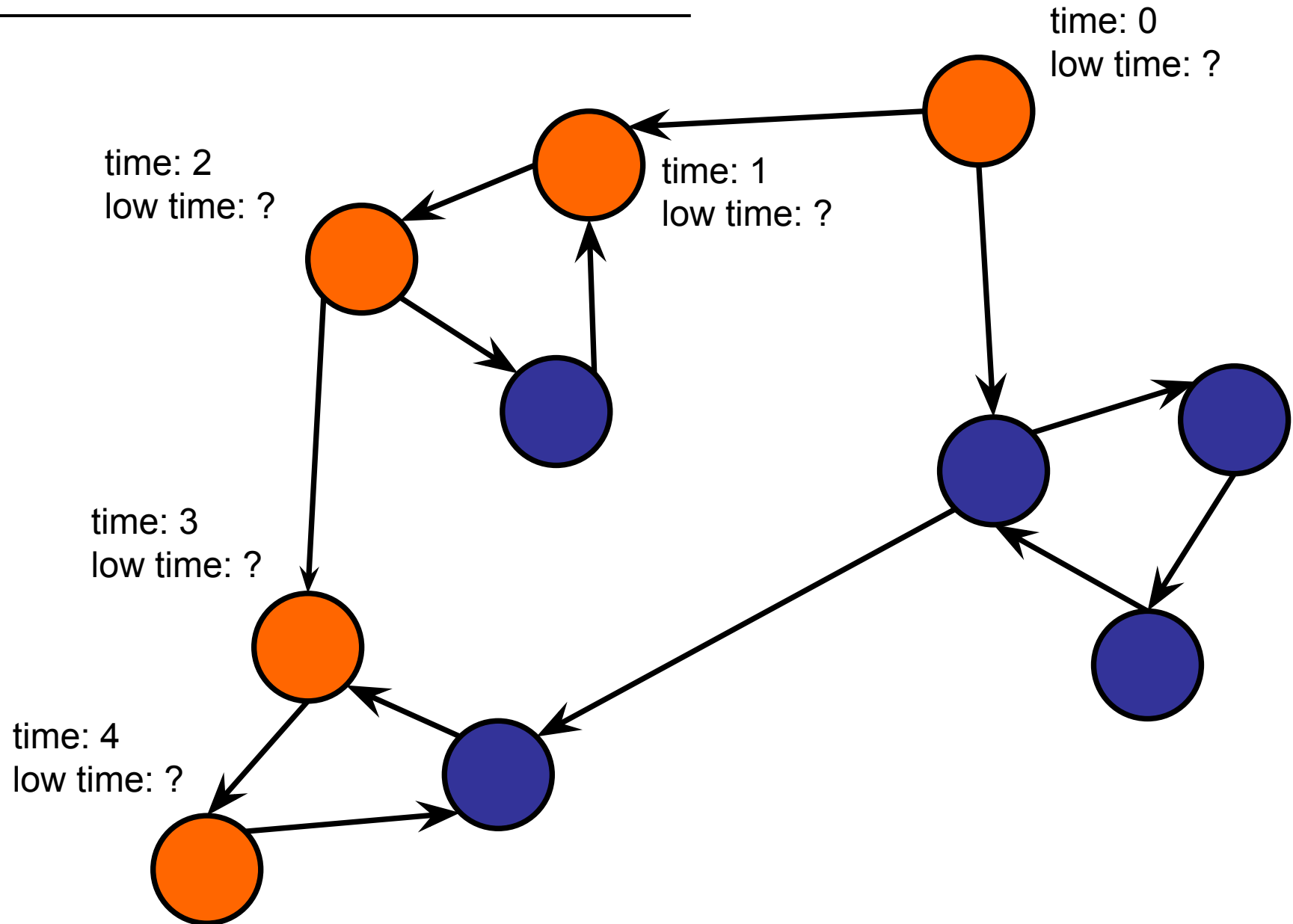
# Connected Components

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# Connected Components

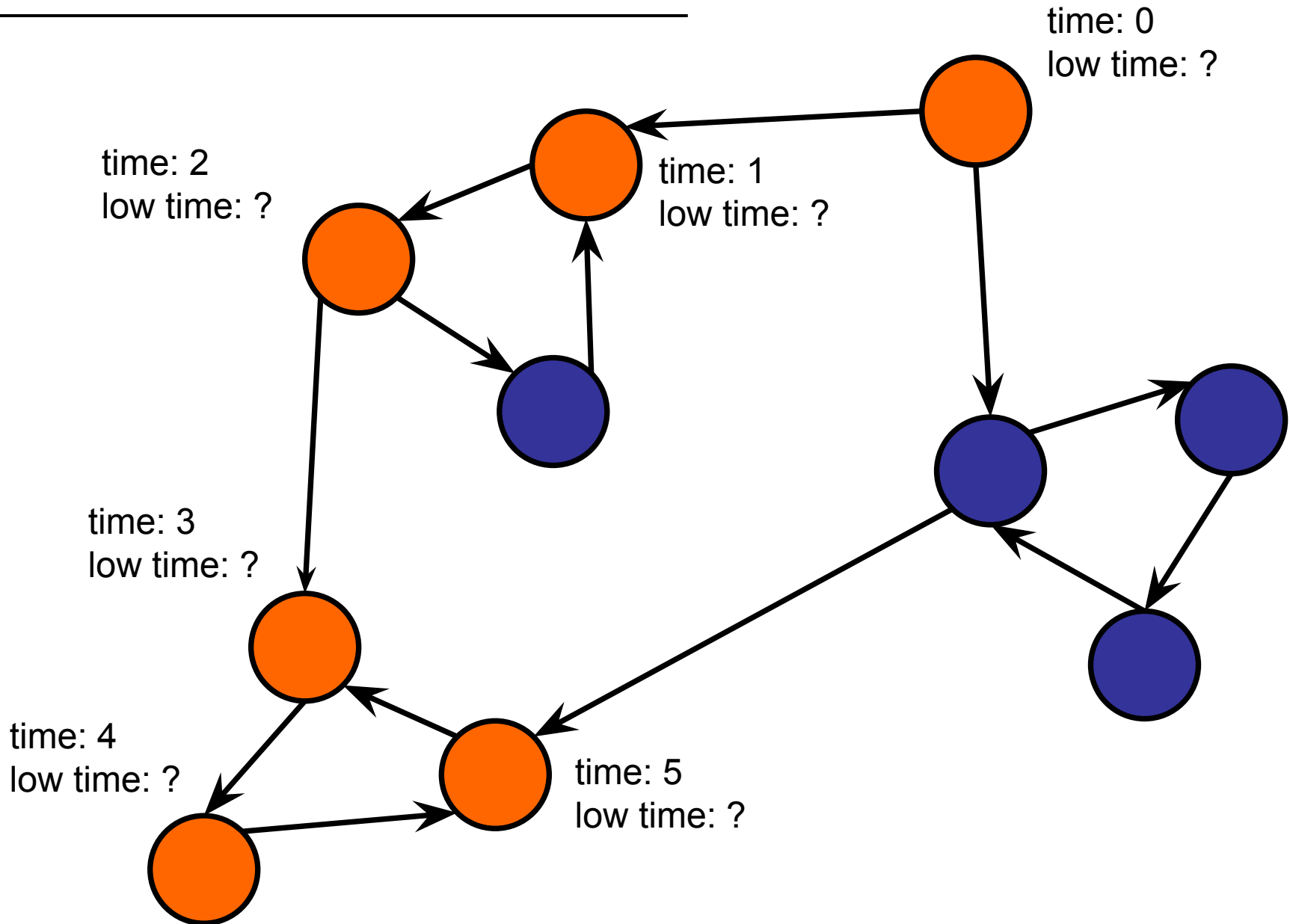
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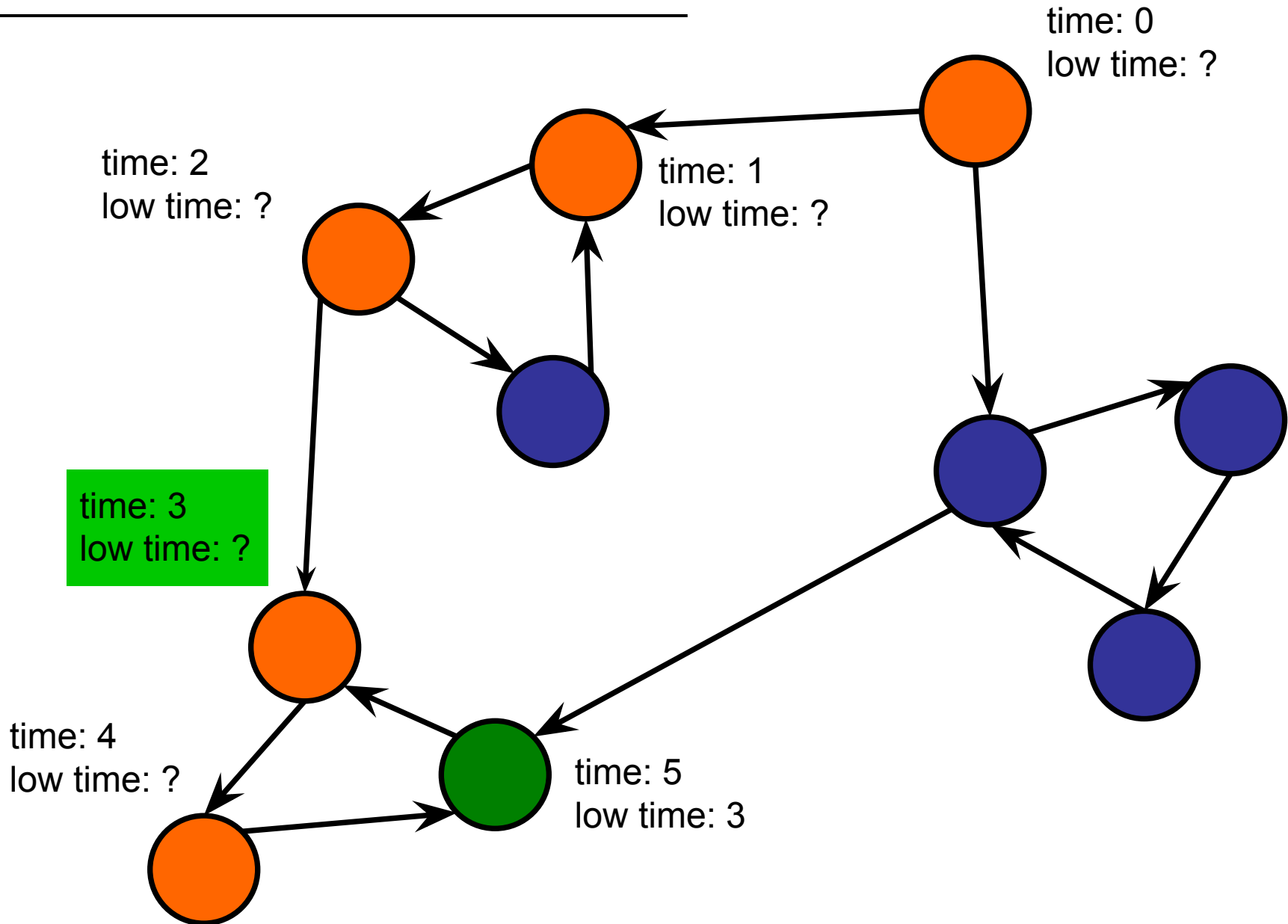
# Connected Components

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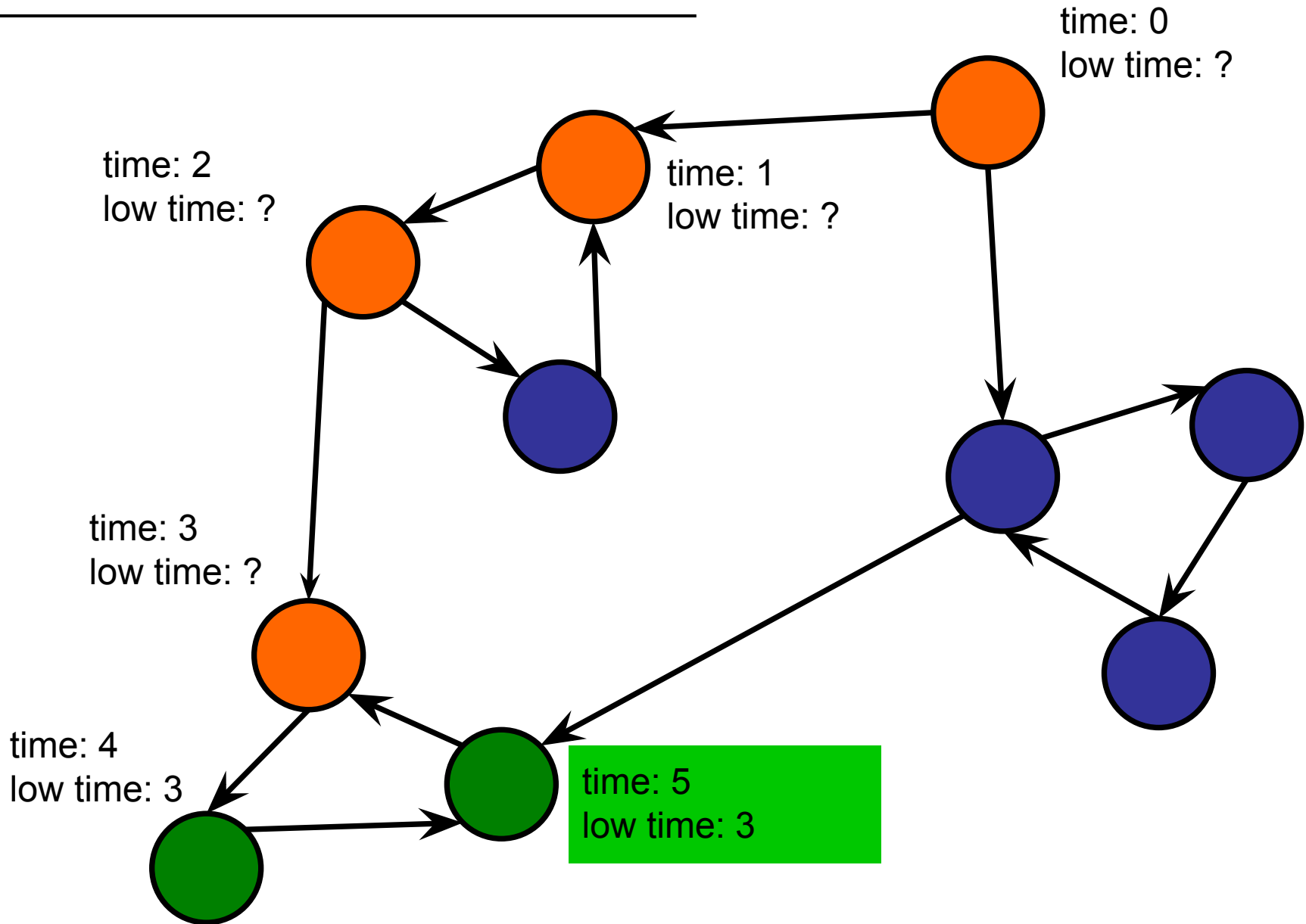
# Connected Components

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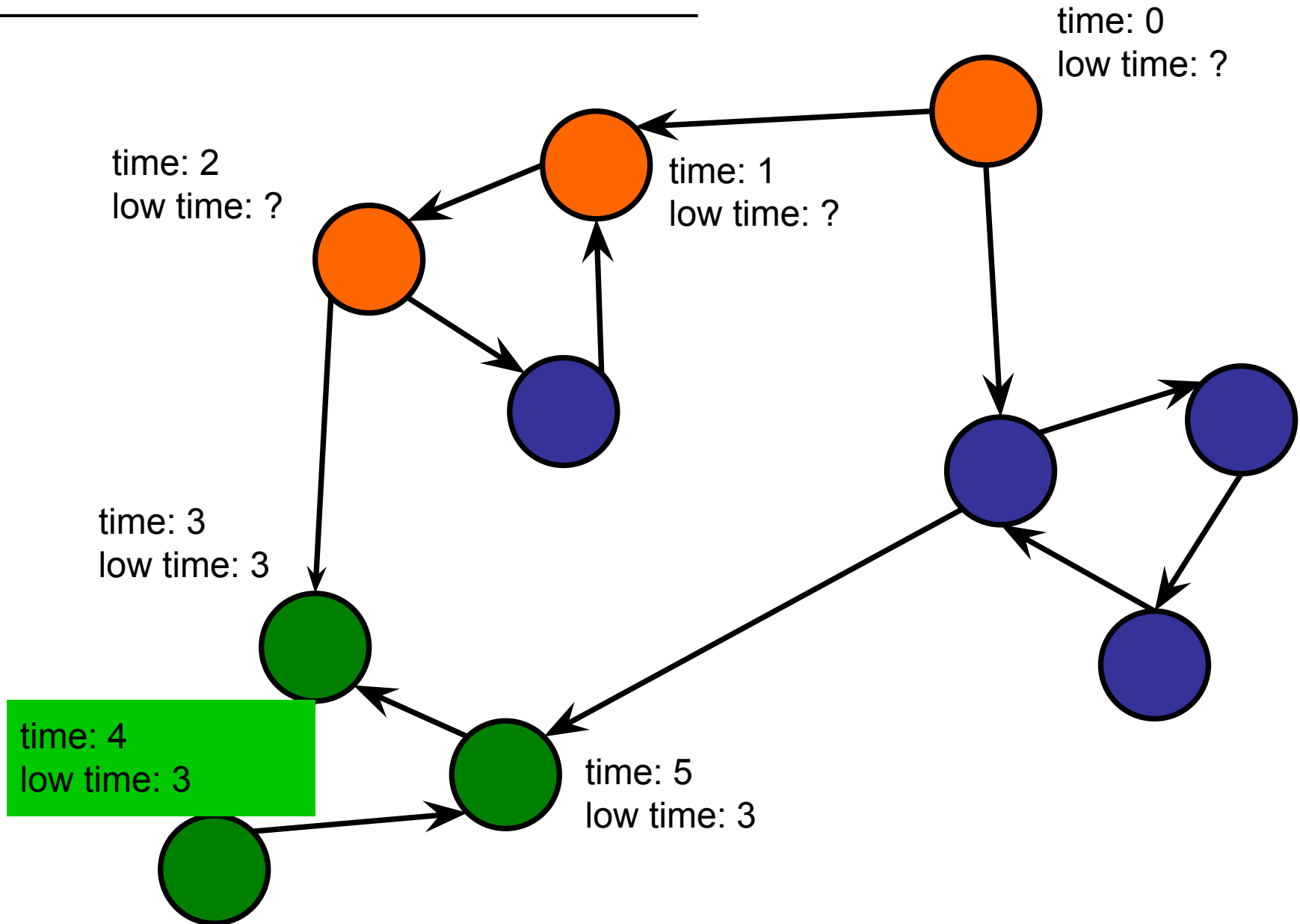
# Connected Components

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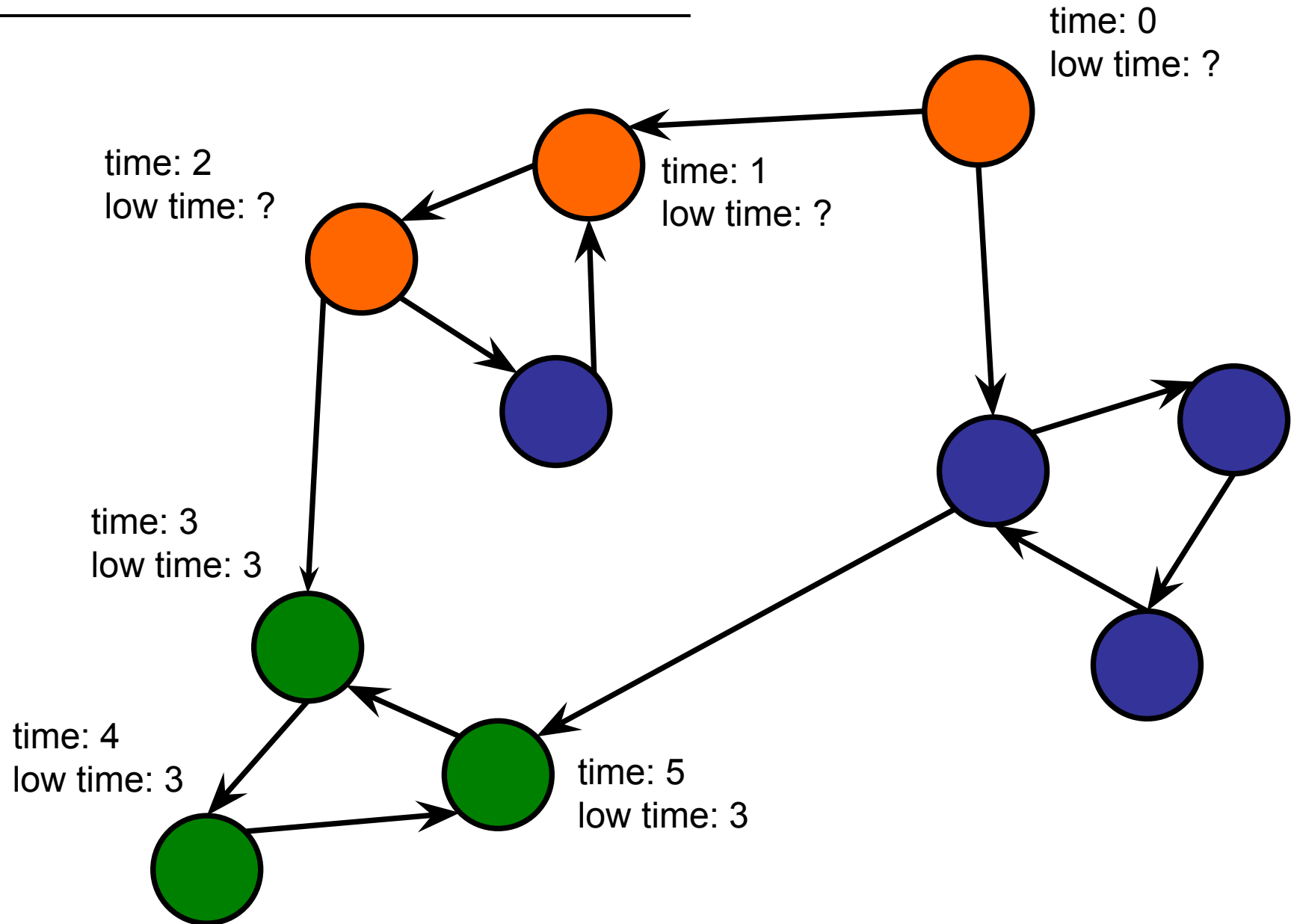
# Connected Components

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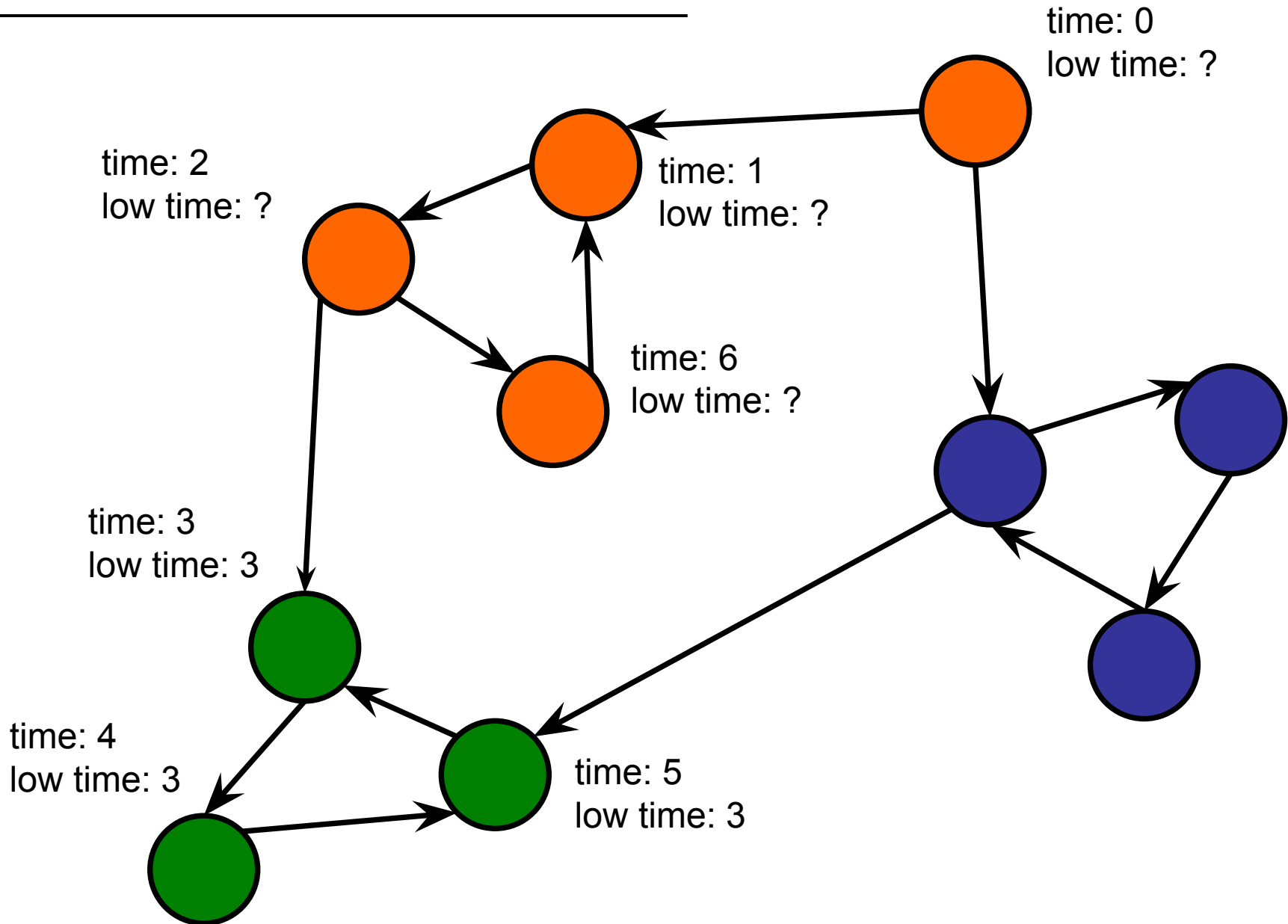
# Connected Components

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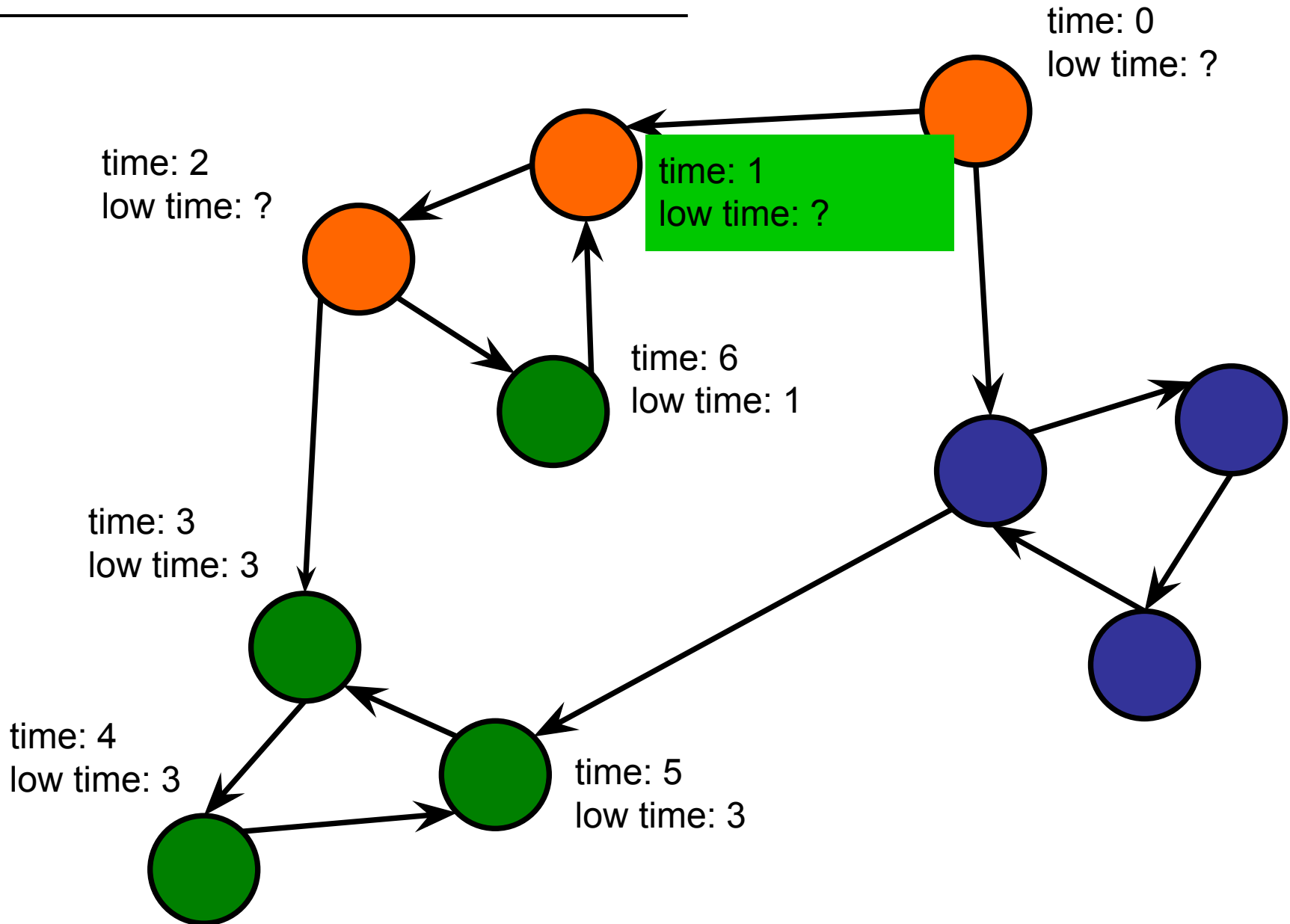
# Connected Components

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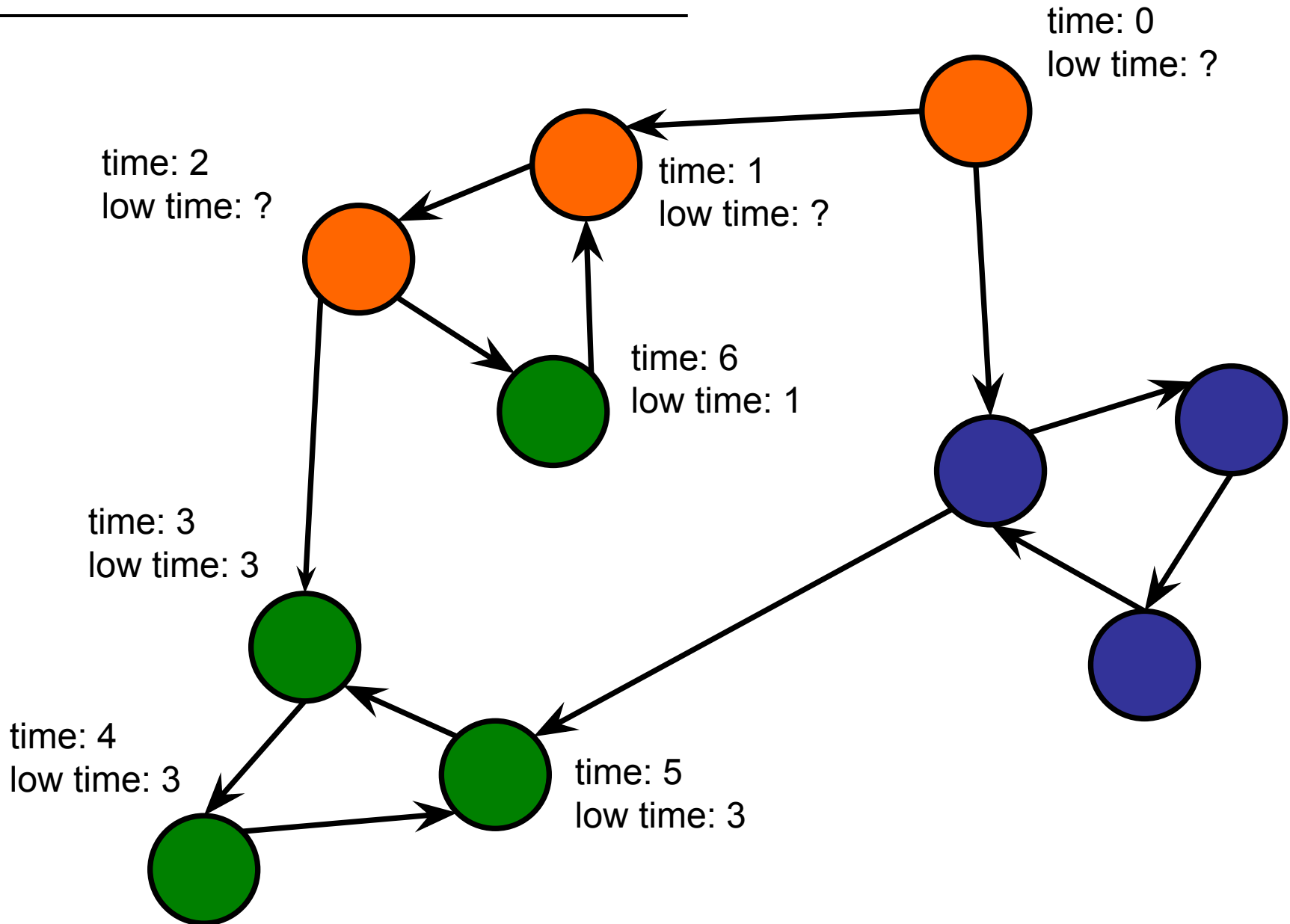
# Connected Components

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# Connected Components

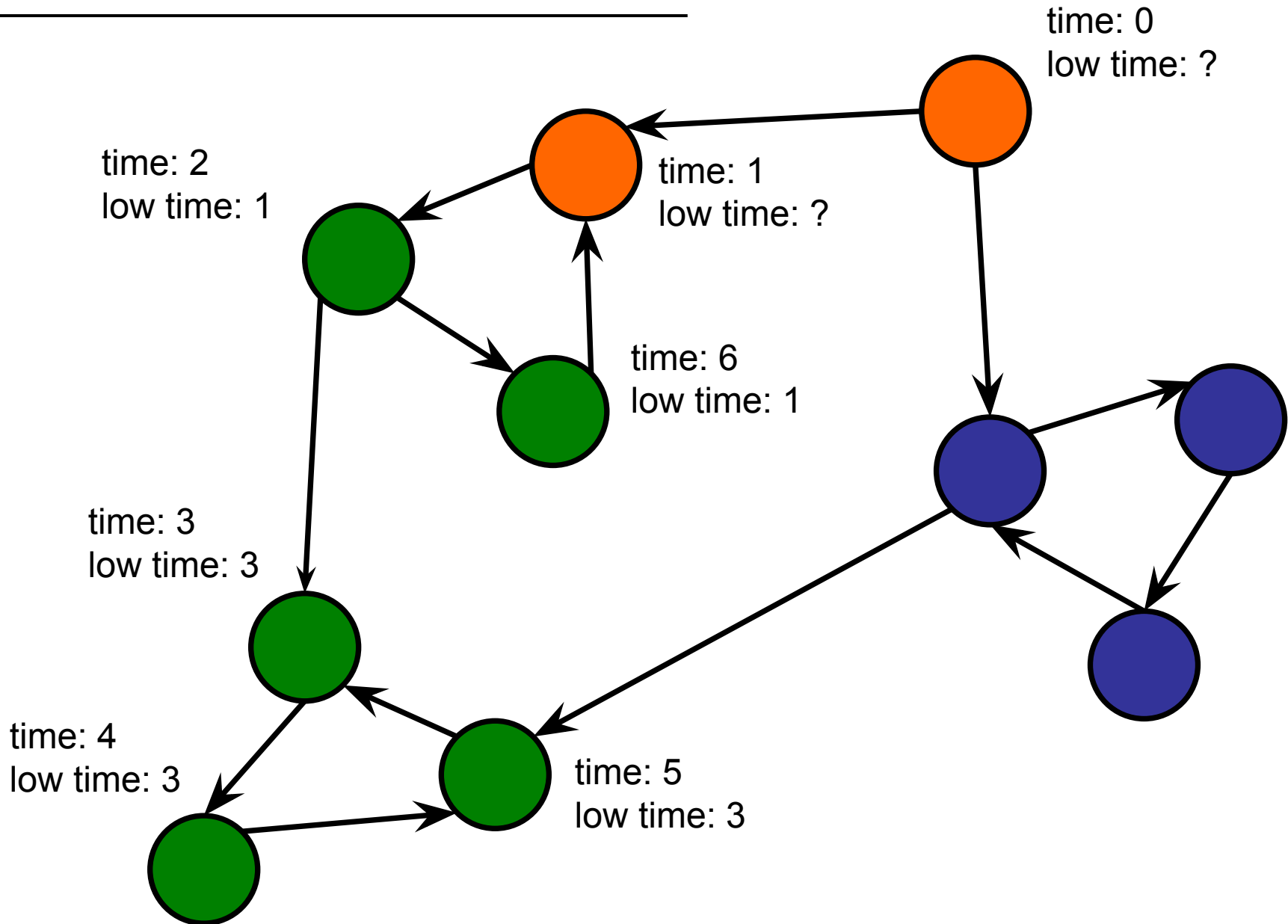
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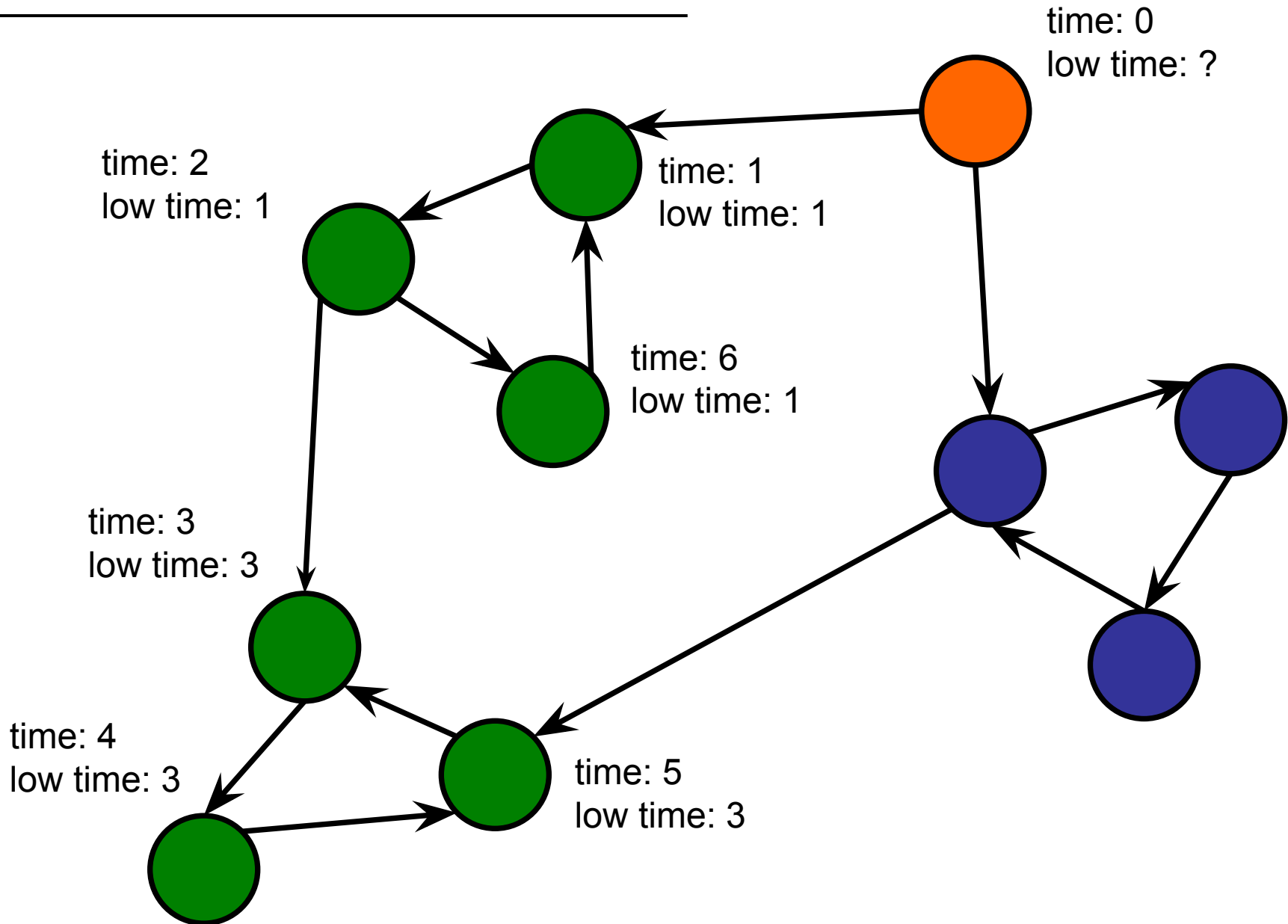
# Connected Components

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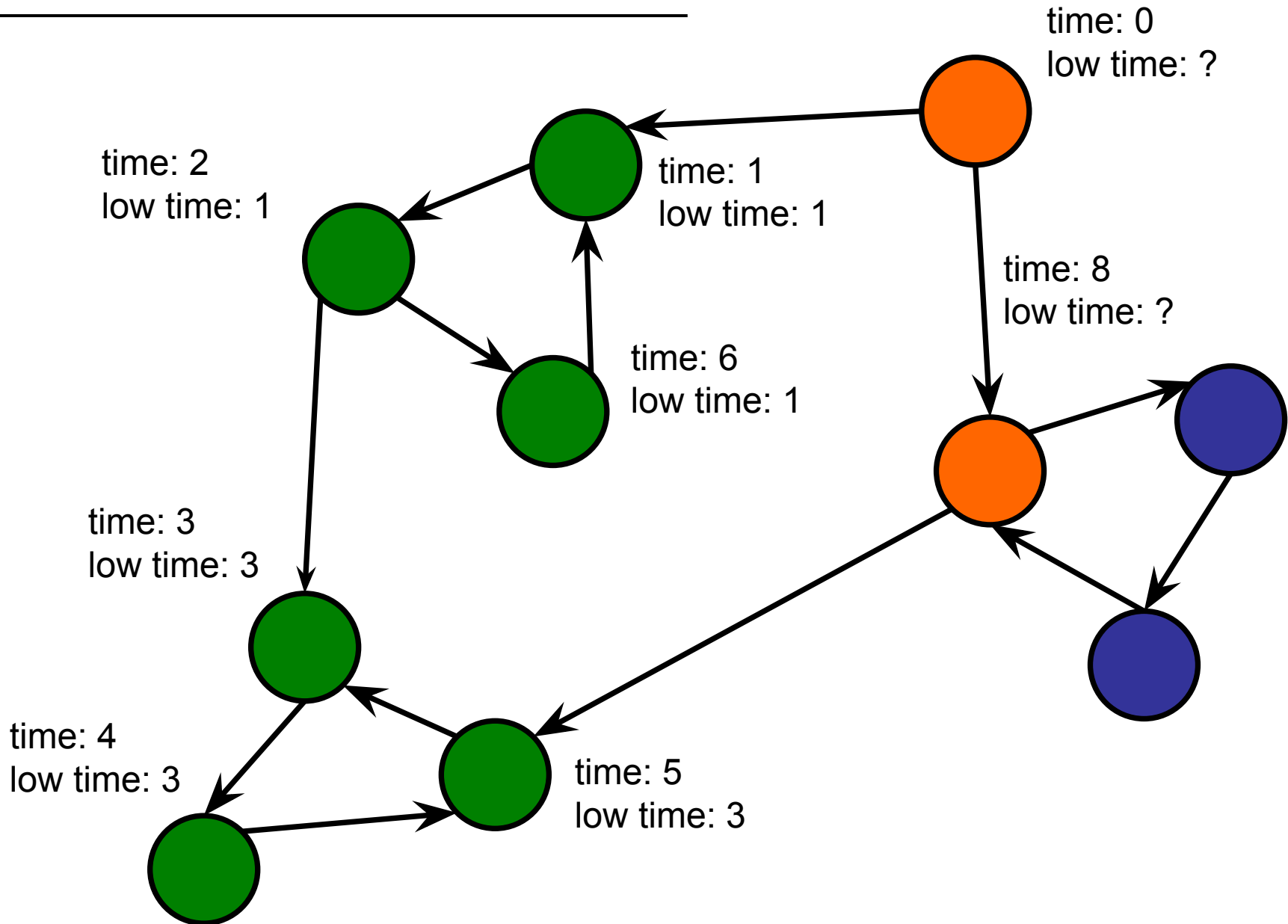
# Connected Components

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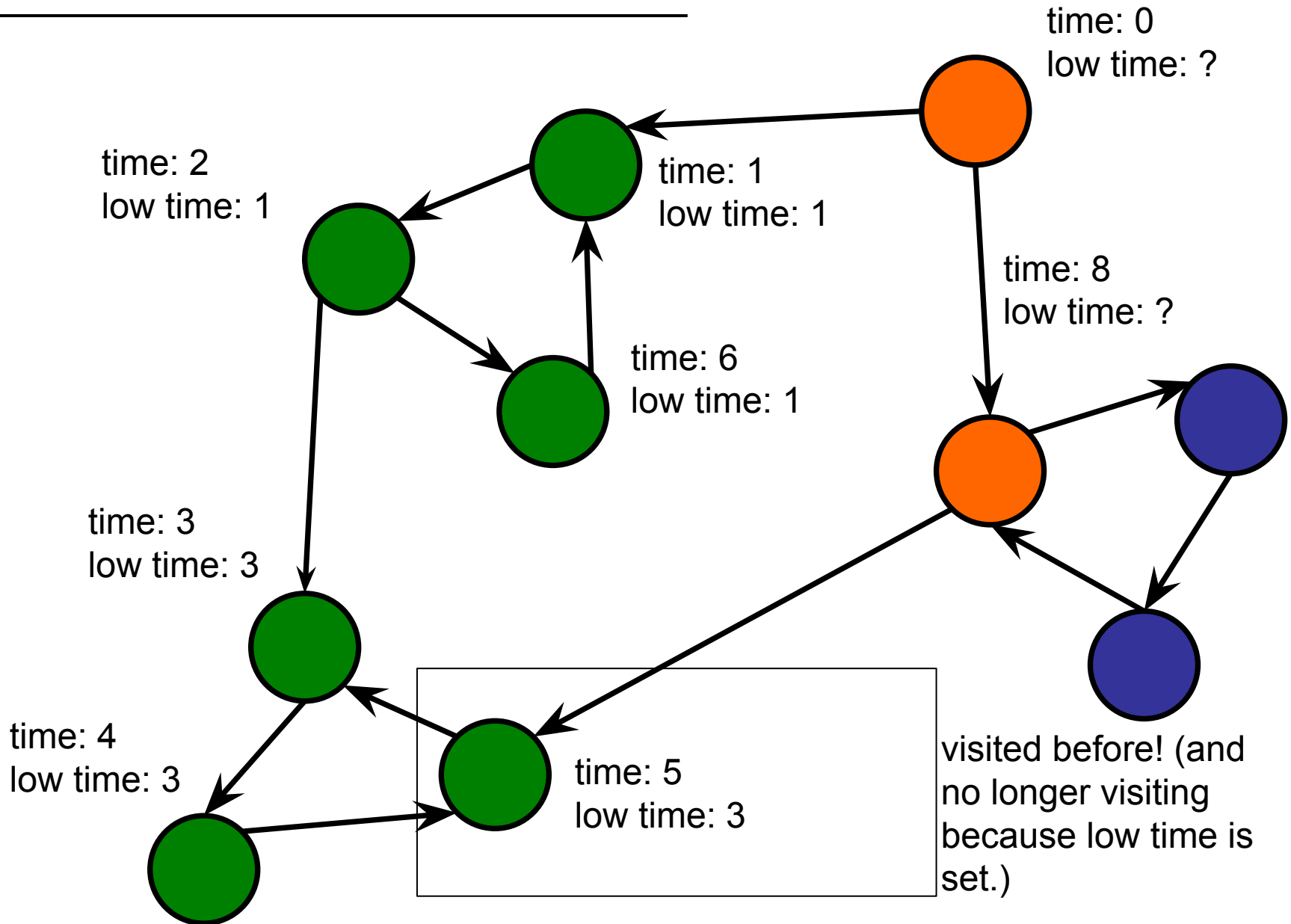


# Connected Components

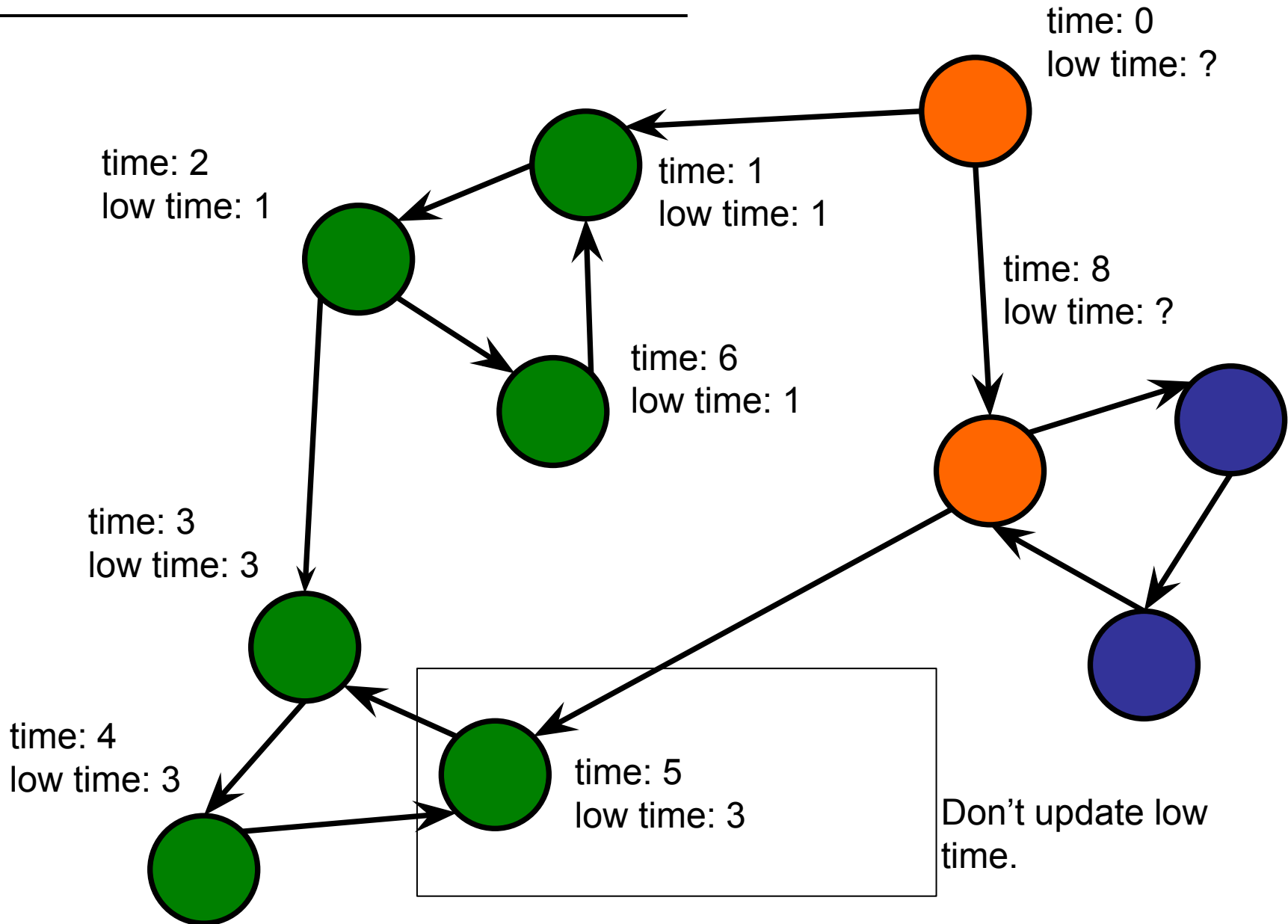
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# Connected Components

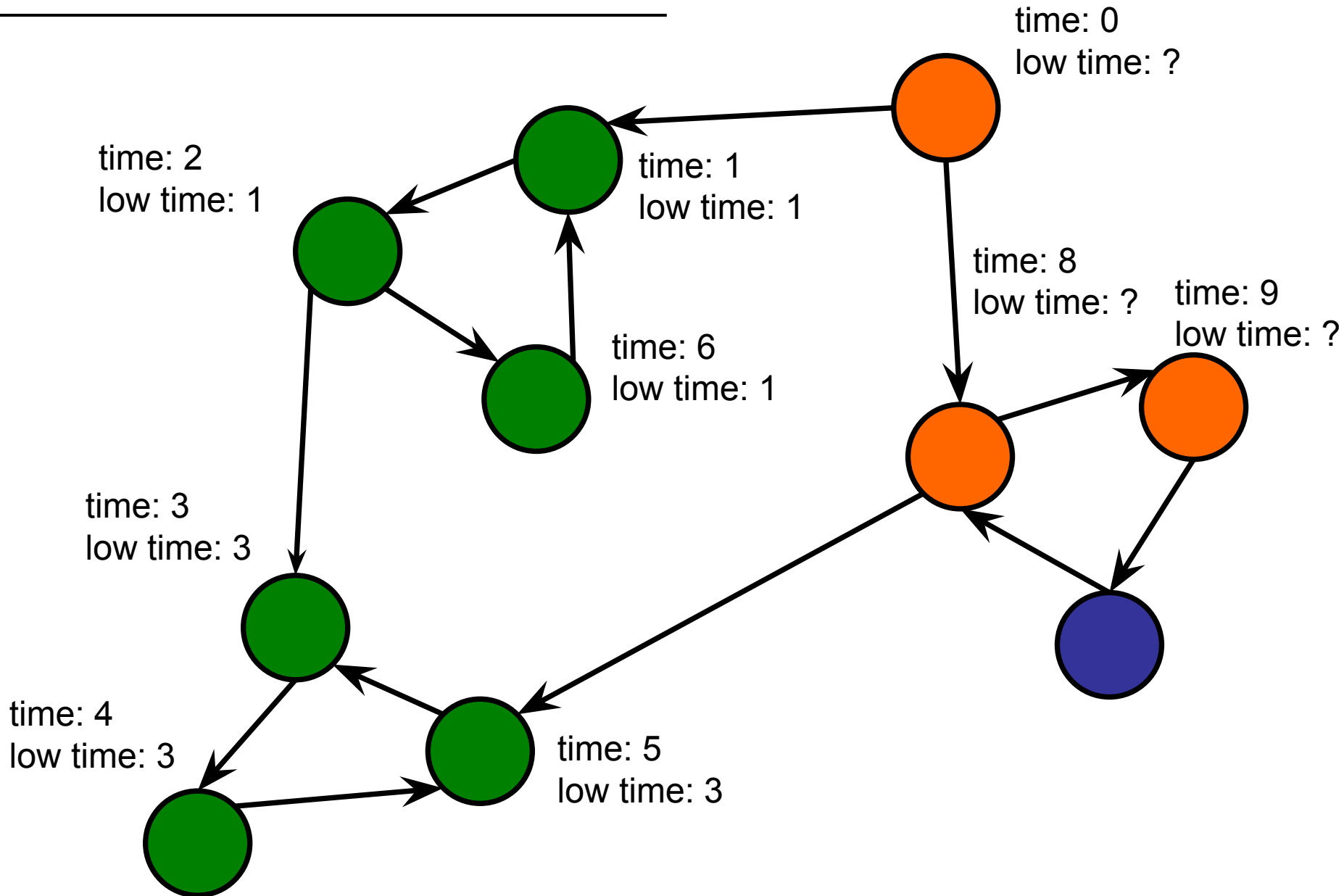


# Connected Components



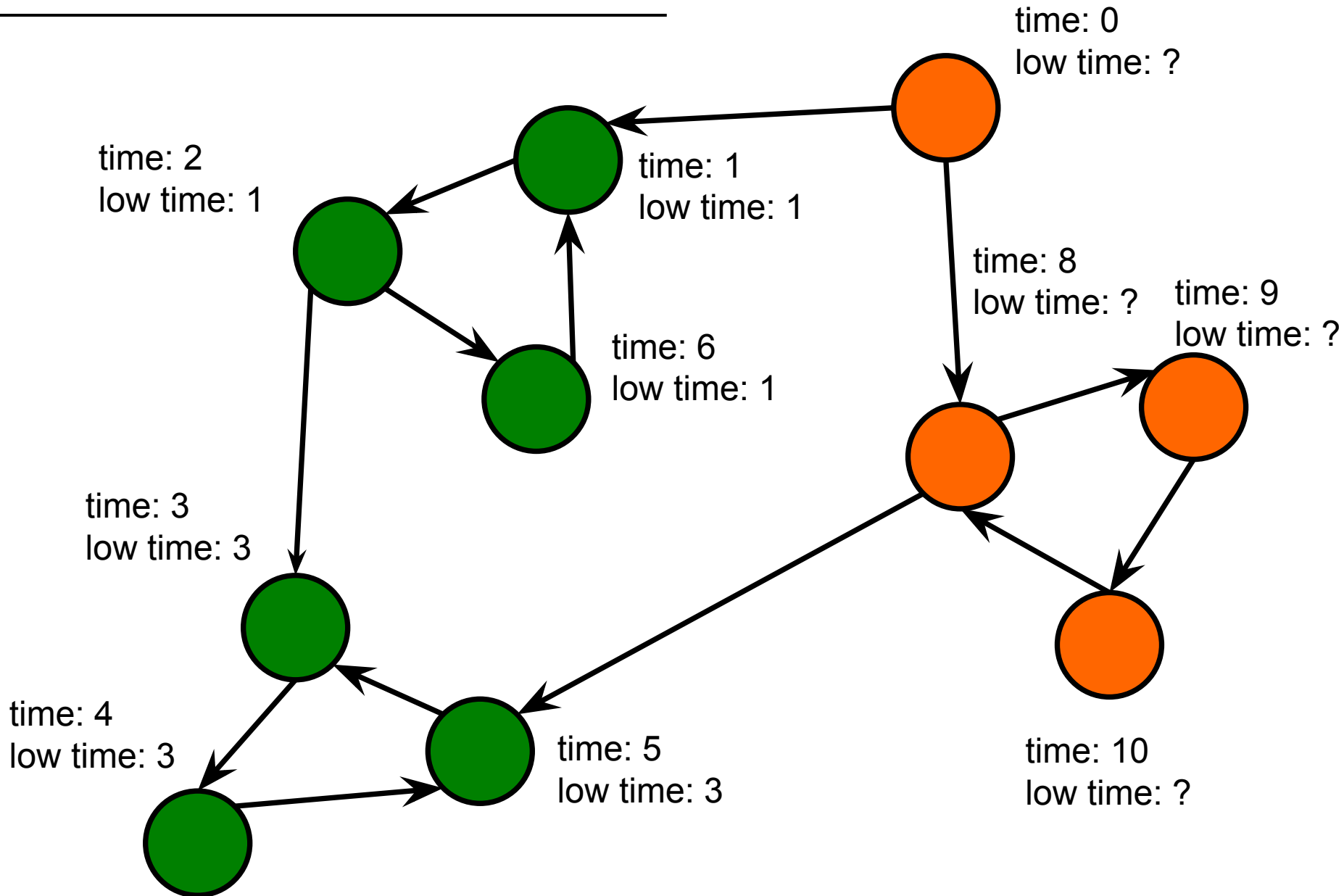
# Connected Components

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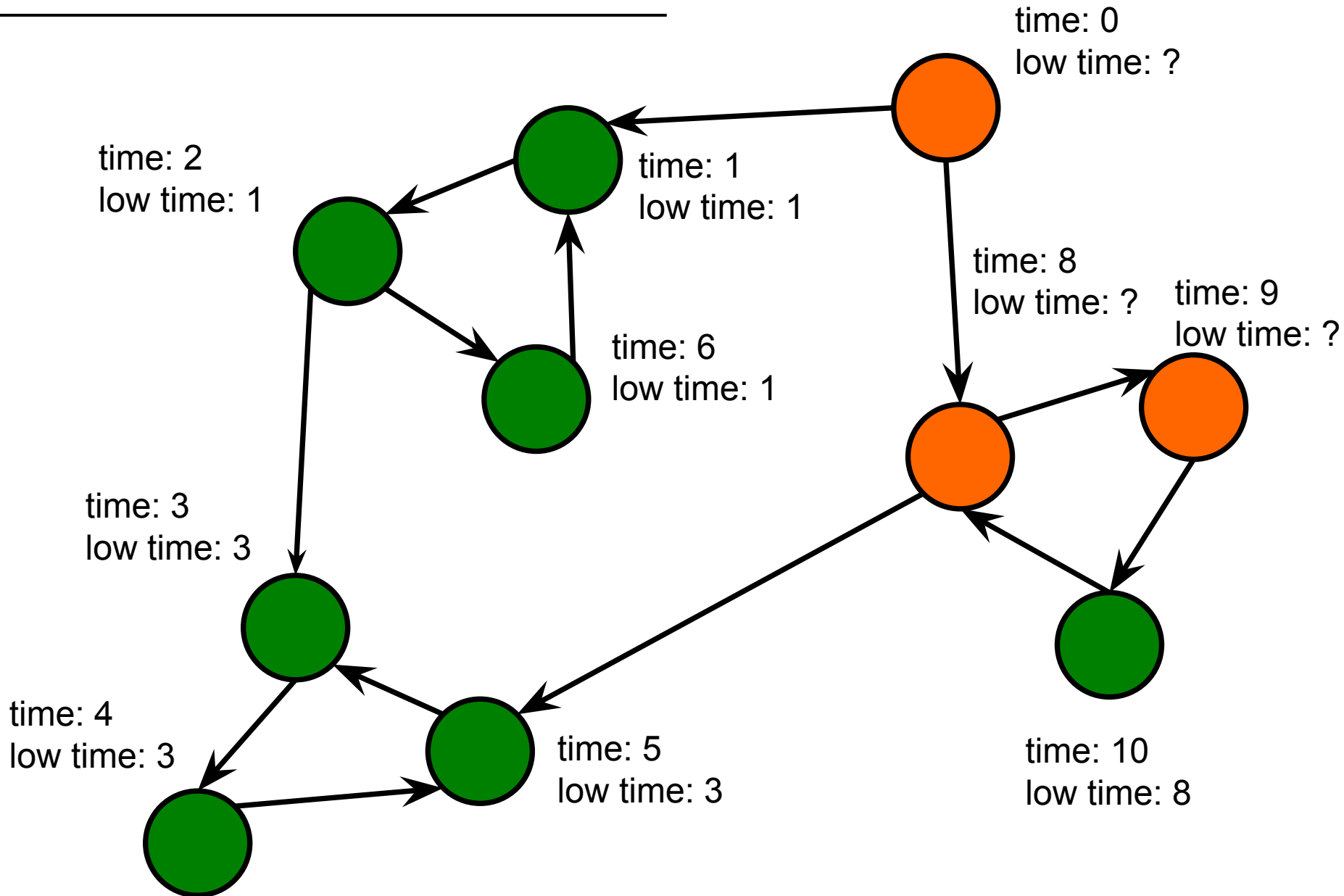
# Connected Components

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# Connected Components

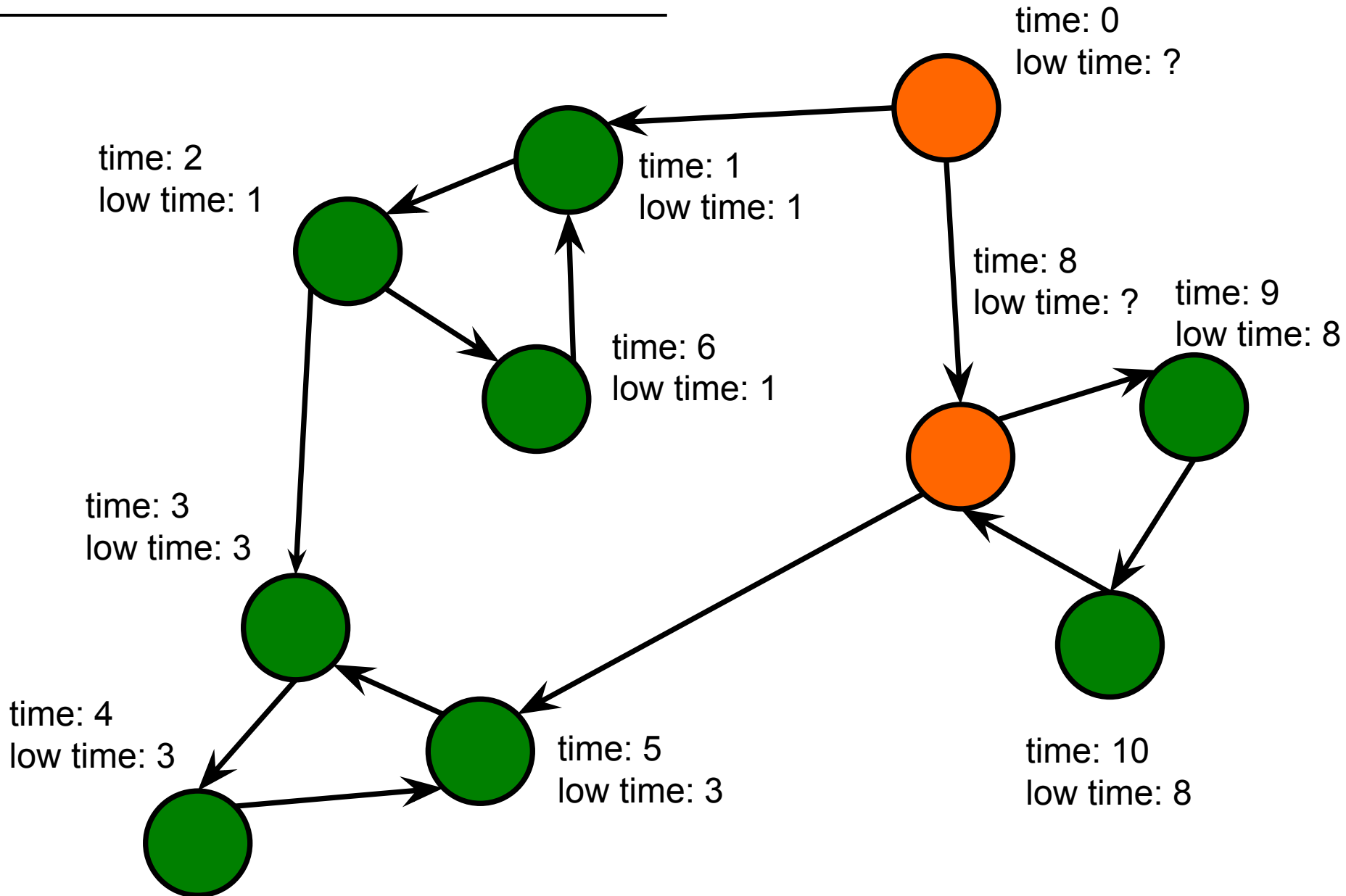
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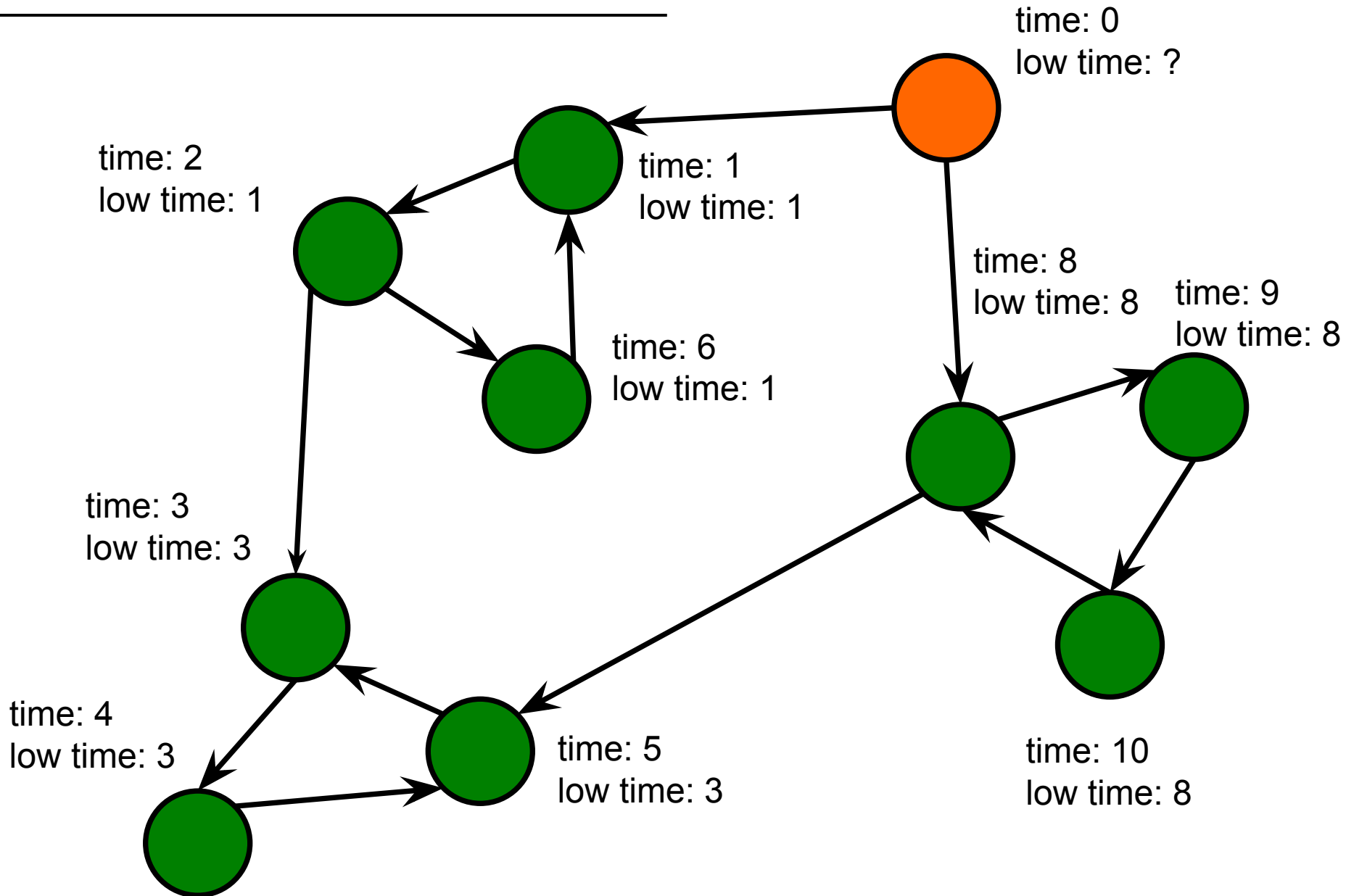
# Connected Components

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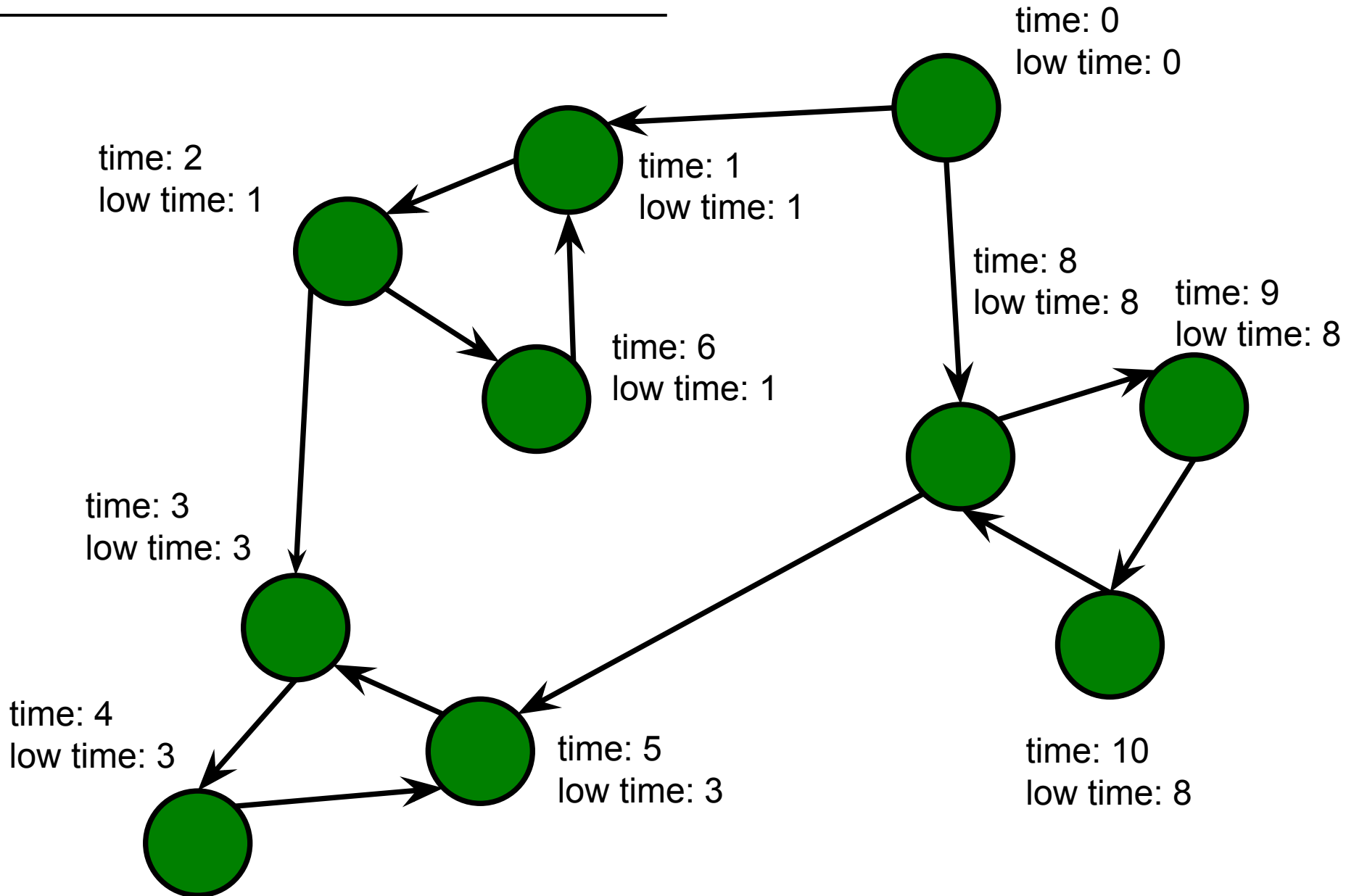
# Connected Components

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# Connected Components

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# Connected Components

---

Low time of a node is the minimum of:

1. Its own time
2. Low time of children that we just (visited)/(recursed from)

# Cycle Finding

---

## Clarification:

There are 3 possible cases of values to consider for setting a node **u**'s **low time**. This will be the minimum of:

1. Node **u**'s **time** itself.
2. For any neighbour **v** of **u**, whose **time** is set, but **low time** is not set. We consider their **time**.
3. For any neighbour **v** of **u**, whose **time** is not set, we will first recurse on them. And consider their resulting **low time**.

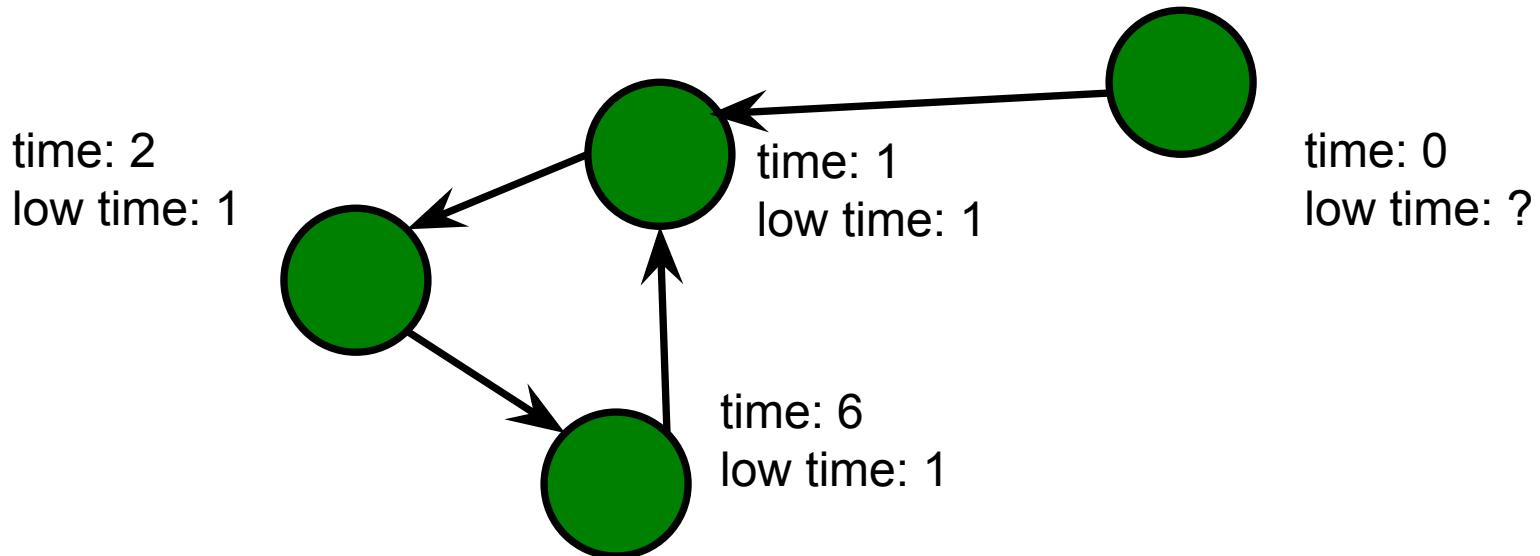
(We'll ignore any neighbours whose **low time** is set before we visit them)

# Cycle Finding

Clarification:

What's the point of **low time**?

The point of the **low time** is to identify the “earliest” node that we can visit (that is actively being visited).



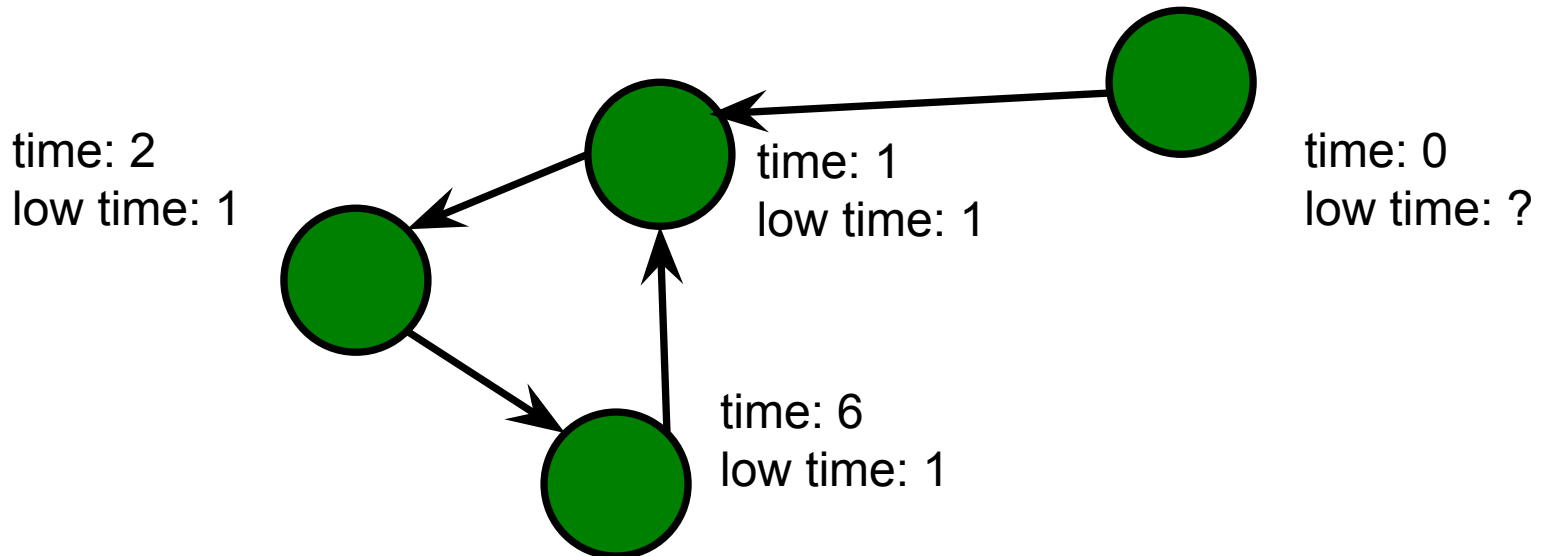
# Cycle Finding

Clarification:

What's the point of **low time**?

The point of the **low time** is to identify the “earliest” node that we can visit (that is actively being visited).

**Important:** We only set low times as a post traversal operation.



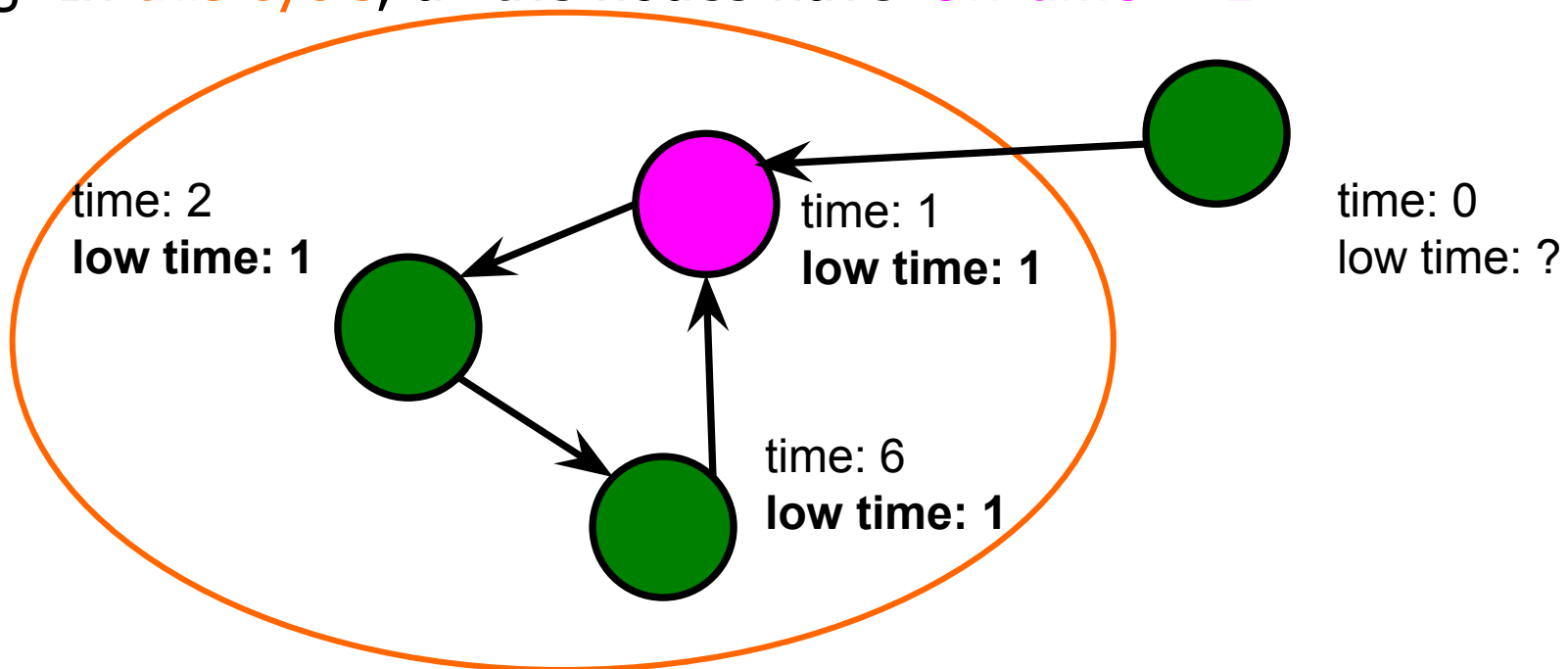
# Cycle Finding

Clarification:

What's the point of **low time**?

The point of the **low time** is to identify the "earliest" node that we can visit (that is actively being visited).

E.g. In **this cycle**, all the nodes have **low time = 1**





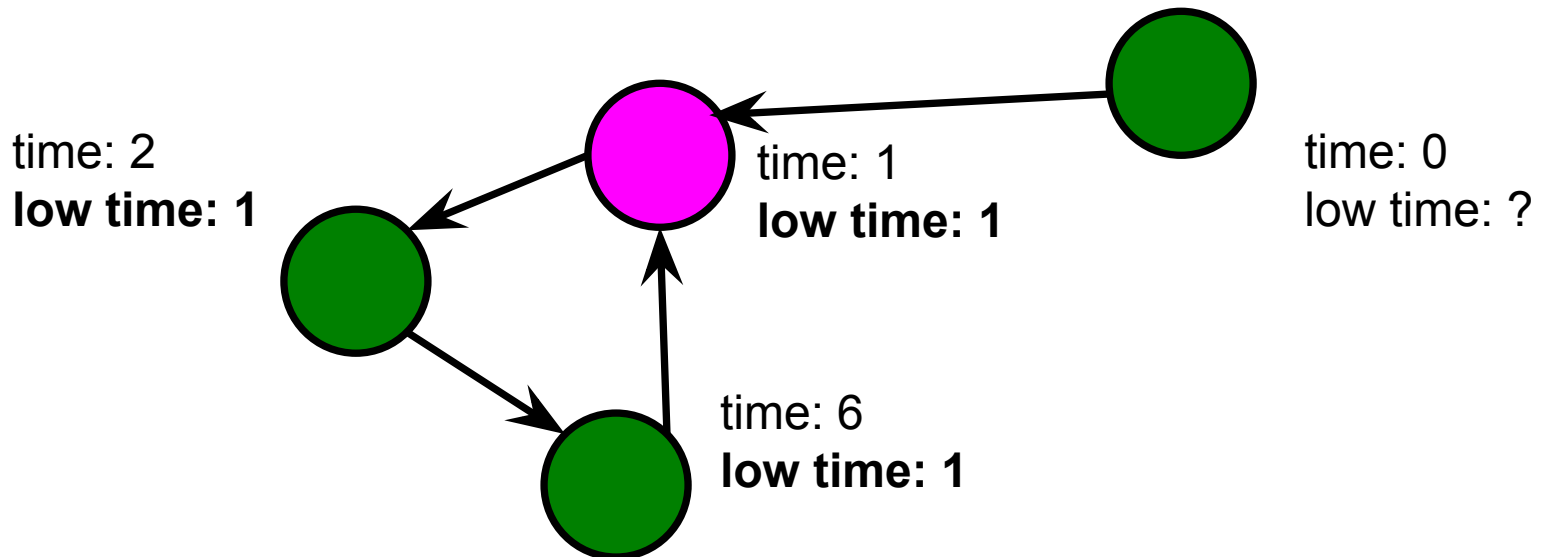
# Cycle Finding

Clarification:

What's the point of **low time**?

The point of the **low time** is to identify the “earliest” node that we can visit (that is actively being visited).

Want to show: we set our **low times** correctly.



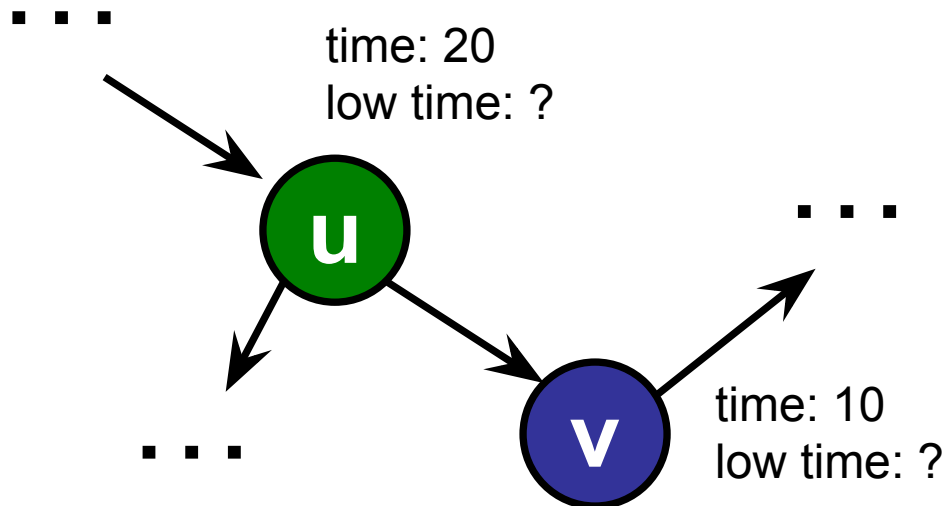
# Cycle Finding

Clarification:

If we are at a node **u**, we look at our neighbour **v**, what does **v** tell us about our **low time**?

Case 1: **v**'s visited already (therefore its **time** is already set).

Either **v**'s **low time** is set or it isn't

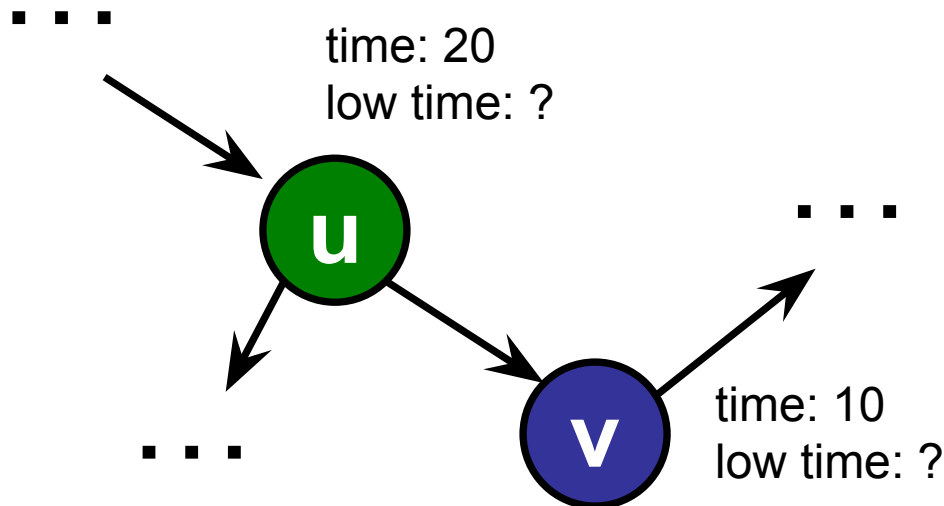


# Cycle Finding

## Clarification:

If we are at a node **u**, we look at our neighbour **v**, what does **v** tell us about our **low time**?

Case 1a: **v**'s visited already and **low time** is not set yet.

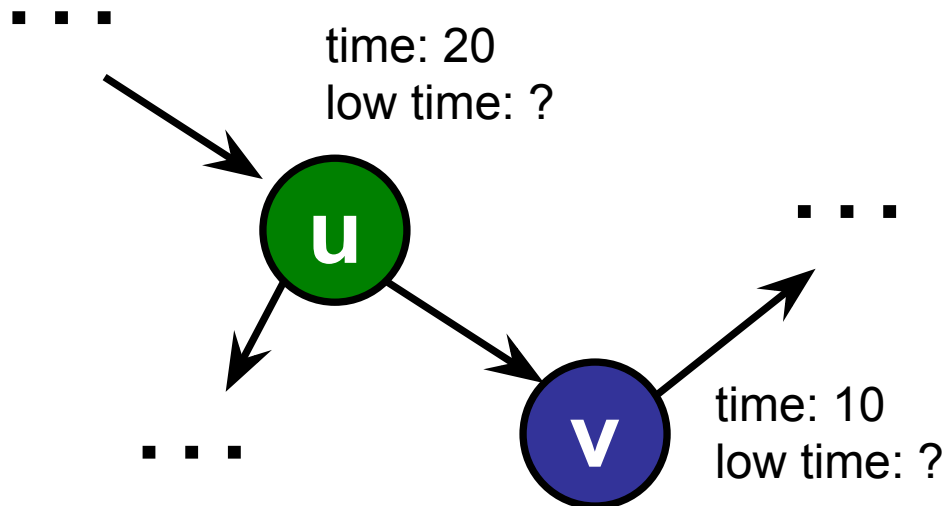


# Cycle Finding

## Clarification:

If we are at a node **u**, we look at our neighbour **v**, what does **v** tell us about our **low time**?

Case 1a: **v**'s visited already and **low time** is not set yet.  
Since we only set **low time** at the end of the traversal, (**v** is still being traversed)/(**v** is still part of the recursion).

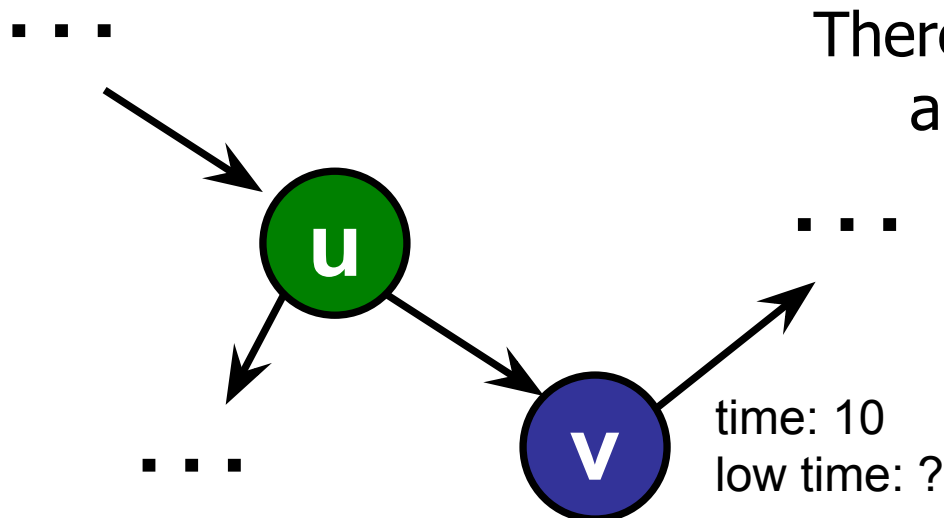


# Cycle Finding

## Clarification:

If we are at a node **u**, we look at our neighbour **v**, what does **v** tell us about our **low time**?

Case 1a: **v**'s visited already and **low time** is not set yet.  
Since we only set **low time** at the end of the traversal, (**v** is still being traversed)/(**v** is still part of the recursion).



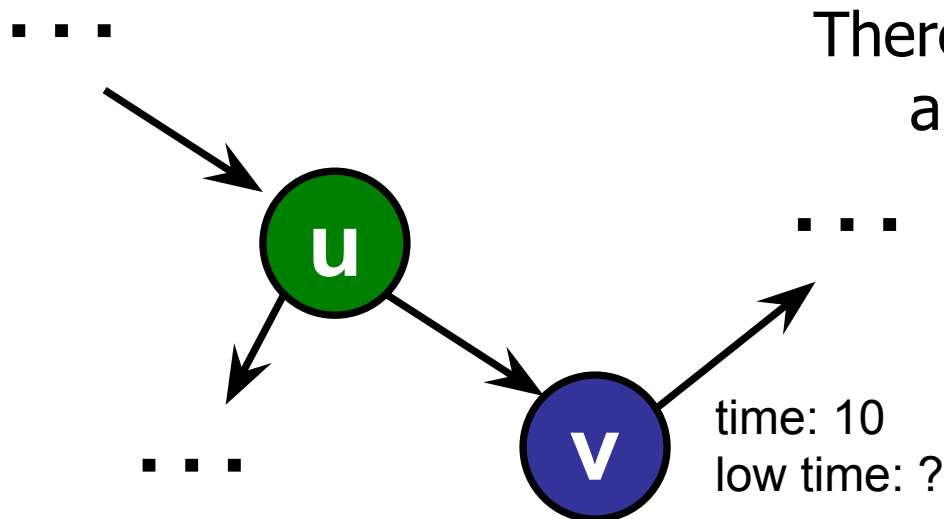
Therefore, **u** reaches **v**  
and **v** reaches **u**.

# Cycle Finding

## Clarification:

If we are at a node **u**, we look at our neighbour **v**, what does **v** tell us about our **low time**?

Case 1a: **v**'s visited already and **low time** is not set yet.  
Since we only set **low time** at the end of the traversal, (**v** is still being traversed)/(**v** is still part of the recursion).



Therefore, **u** reaches **v**  
and **v** reaches **u**.

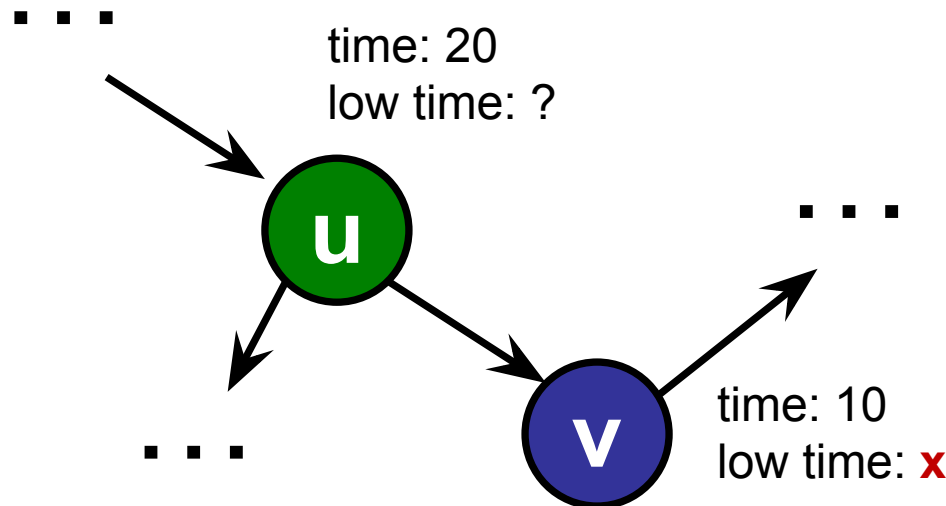
This means that node **u**  
needs to consider **v**'s  
**time** as a potential **low time**.

# Cycle Finding

Clarification:

If we are at a node **u**, we look at our neighbour **v**, what does **v** tell us about our **low time**?

Case 1b: **v**'s visited already and **low time** is already set.

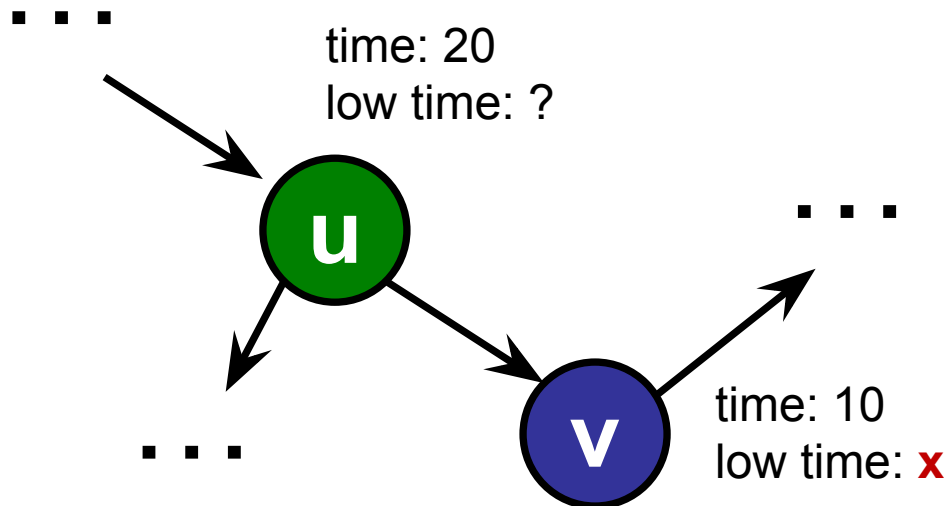


# Cycle Finding

## Clarification:

If we are at a node **u**, we look at our neighbour **v**, what does **v** tell us about our **low time**?

Case 1b: **v**'s visited already and **low time** is already set.  
Since we only set **low time** at the end of the traversal, (**v** is no longer being traversed)/(**v** is not part of the recursion).



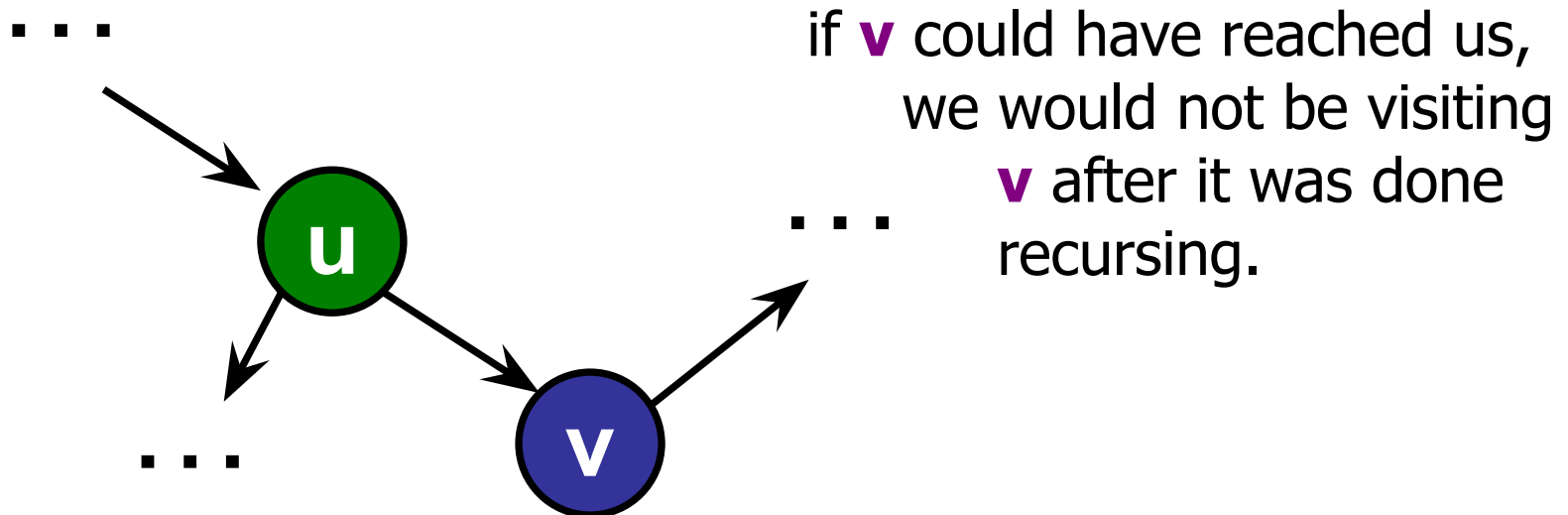


# Cycle Finding

## Clarification:

If we are at a node **u**, we look at our neighbour **v**, what does **v** tell us about our **low time**?

Case 1b: **v**'s visited already and **low time** is already set.  
Since we only set **low time** at the end of the traversal, (**v** is no longer being traversed)/(**v** is not part of the recursion).

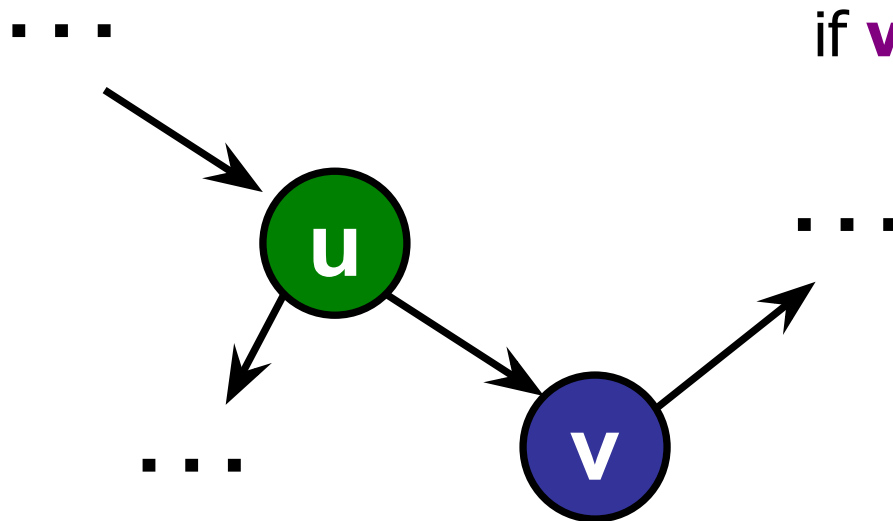


# Cycle Finding

## Clarification:

If we are at a node **u**, we look at our neighbour **v**, what does **v** tell us about our **low time**?

Case 1b: **v**'s visited already and **low time** is already set.  
Since we only set **low time** at the end of the traversal, (**v** is no longer being traversed)/(**v** is not part of the recursion).



if **v** could have reached us,  
we would not be visiting  
**v** after it was done  
recursing.

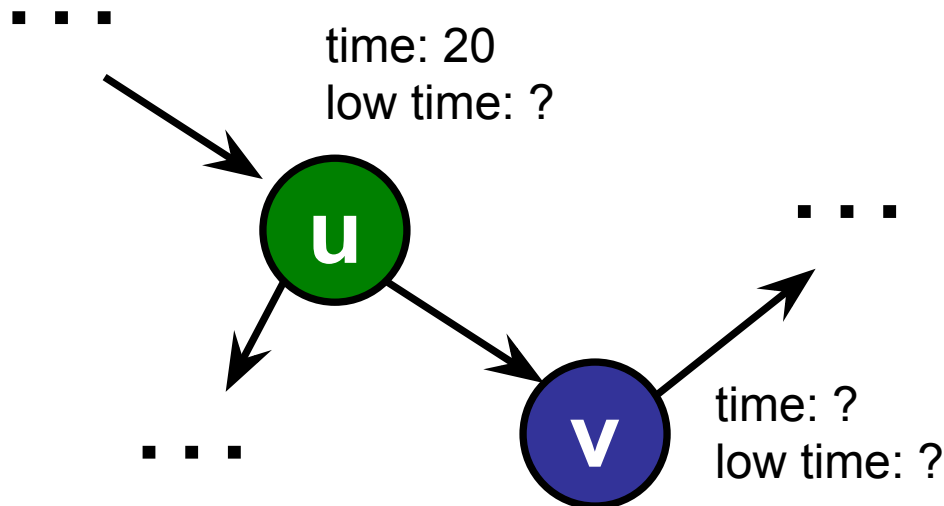
So we don't consider  
taking **v**'s **low time**.

# Cycle Finding

Clarification:

If we are at a node **u**, we look at our neighbour **v**, what does **v** tell us about our **low time**?

Case 2: **v**'s not visited yet  
(therefore its **time** and **low time** is not set).



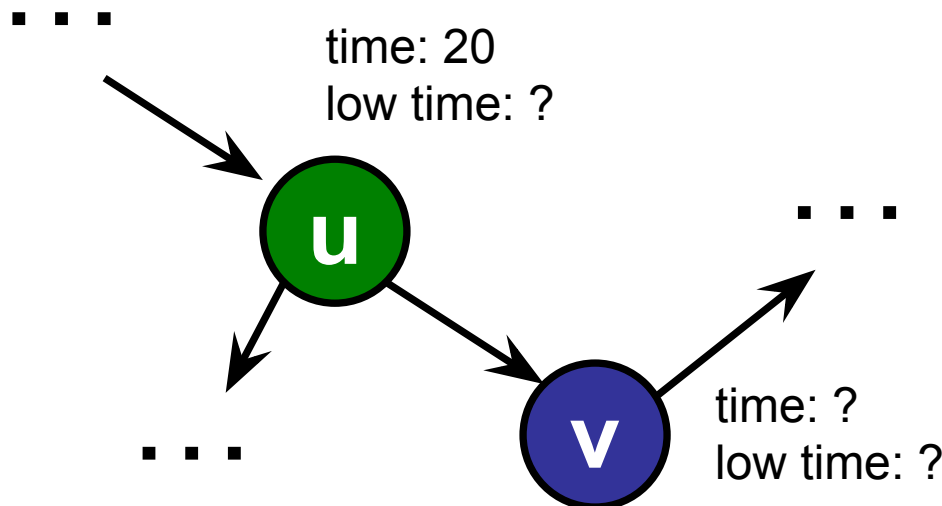
# Cycle Finding

Clarification:

If we are at a node **u**, we look at our neighbour **v**, what does **v** tell us about our **low time**?

Case 2: **v**'s not visited yet  
(therefore its **time** and **low time** is not set).

So we will recurse on **v** to compute its **time** and **low time**.



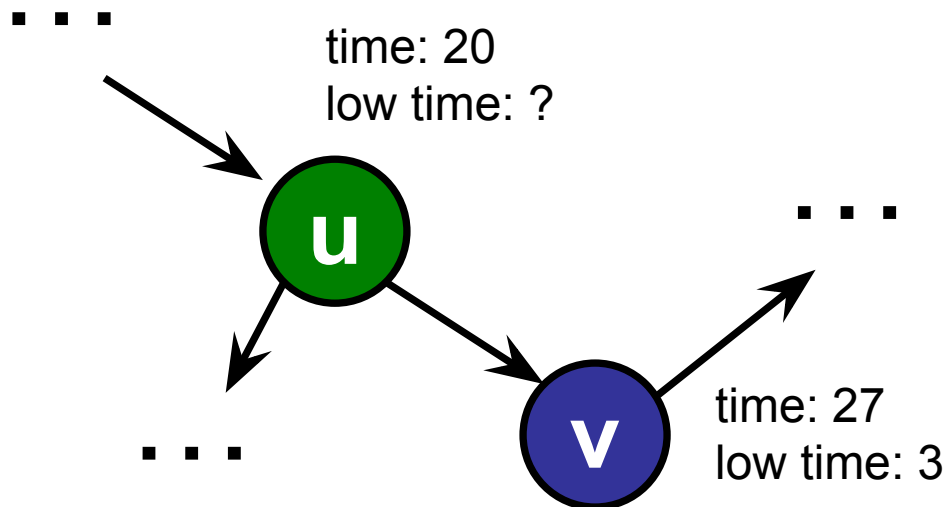
# Cycle Finding

Clarification:

Case 2: **v**'s not visited yet (therefore its **time** and **low time** is not set).

So we will recurse on **v** to compute its **time** and **low time**.

If after that, its **v**'s **low time** is smaller than **u**'s **time**,



# Cycle Finding

---

## Clarification:

Case 2: **v**'s not visited yet (therefore its **time** and **low time** is not set).

So we will recurse on **v** to compute its **time** and **low time**.

If after that, its **v**'s **low time** is smaller than **u**'s **time**,

# Cycle Finding

---

## Clarification:

Case 2: **v**'s not visited yet (therefore its **time** and **low time** is not set).

So we will recurse on **v** to compute its **time** and **low time**.

If after that, its **v**'s **low time** is smaller than **u**'s **time**,

This means that **v** reached a node **w** that was actively being visited.

# Cycle Finding

---

## Clarification:

Case 2: **v**'s not visited yet (therefore its **time** and **low time** is not set).

So we will recurse on **v** to compute its **time** and **low time**.

If after that, its **v**'s **low time** is smaller than **u**'s **time**,

This means that **v** reached a node **w** that was actively being visited.

notice that:

$$\mathbf{w}'\text{s time} = \mathbf{v}'\text{s low time} < \mathbf{u}'\text{s time} < \mathbf{v}'\text{s time}$$

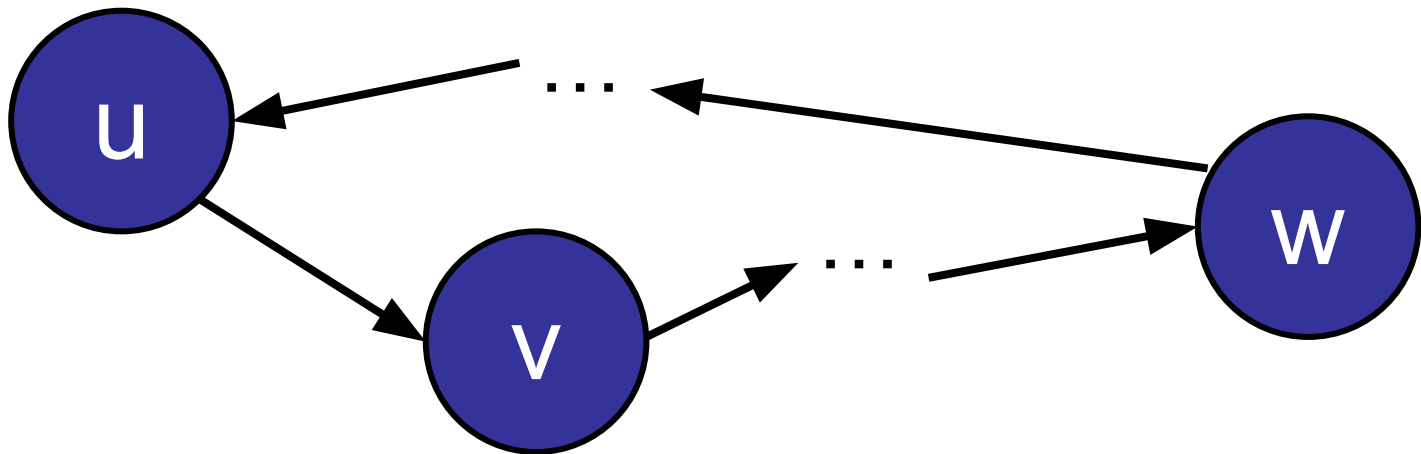


# Cycle Finding

Clarification:

Case 2: **v**'s not visited yet (therefore its **time** and **low time** is not set).

**w**'s **time** = **v**'s **low time** < **u**'s **time** < **v**'s **time**



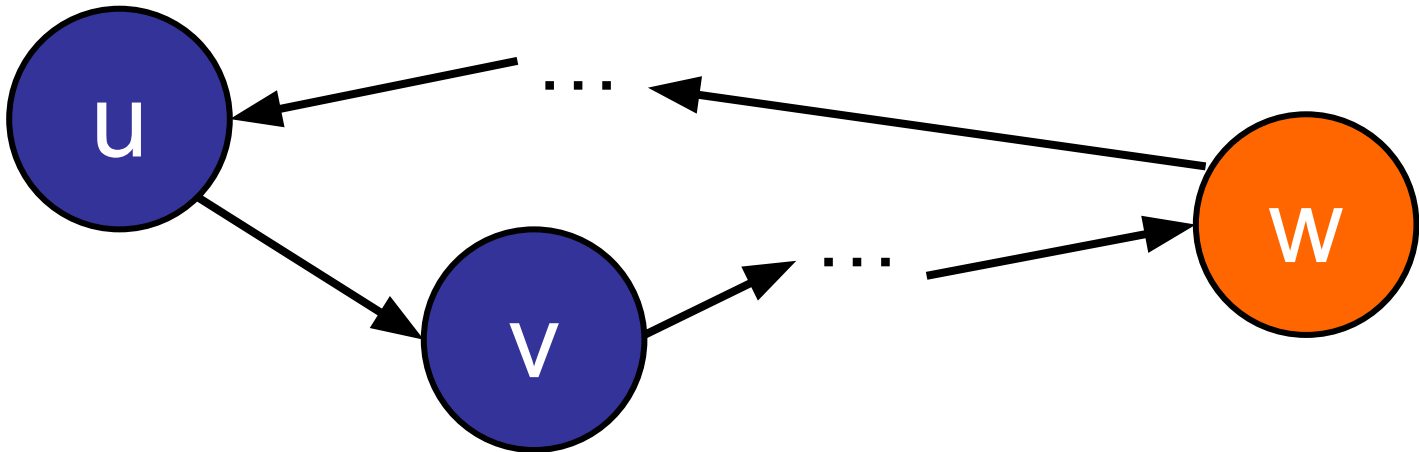
# Cycle Finding

Clarification:

Case 2: **v**'s not visited yet (therefore its **time** and **low time** is not set).

$$\mathbf{w}'\text{'s time} = \mathbf{v}'\text{'s low time} < \mathbf{u}'\text{'s time} < \mathbf{v}'\text{'s time}$$

So **v** can reach **w**. And **w** was part of the current traversal.



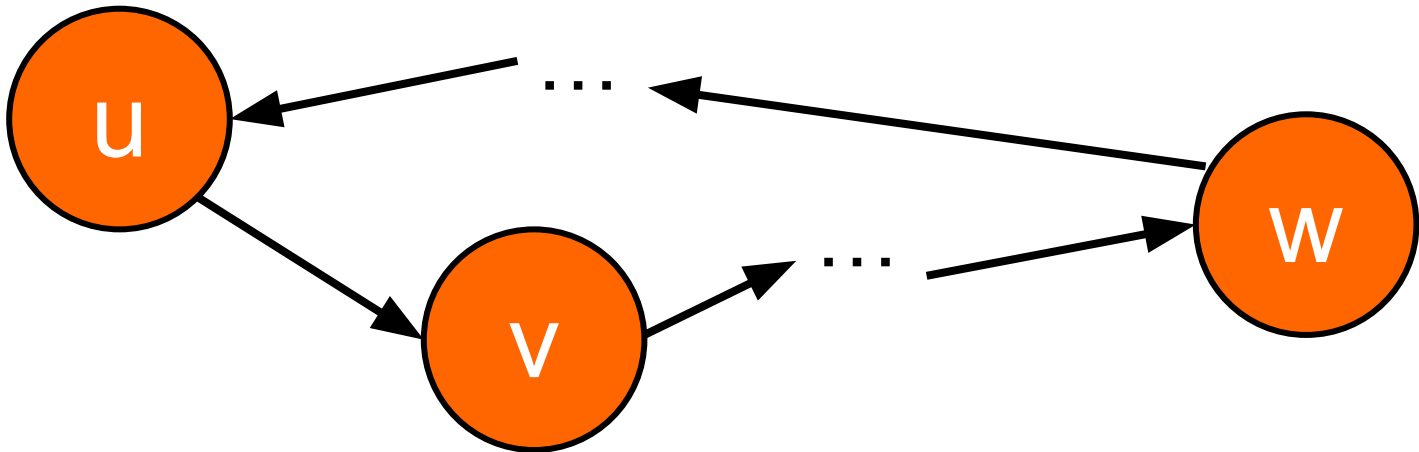
# Cycle Finding

Clarification:

Case 2: **v**'s not visited yet (therefore its **time** and **low time** is not set).

$$\mathbf{w's\ time} = \mathbf{v's\ low\ time} < \mathbf{u's\ time} < \mathbf{v's\ time}$$

So **v** can reach **w**. And **w** was part of the current traversal.  
And both **u** and **v**, were also being traversed when **v** reached **w**.



# Cycle Finding

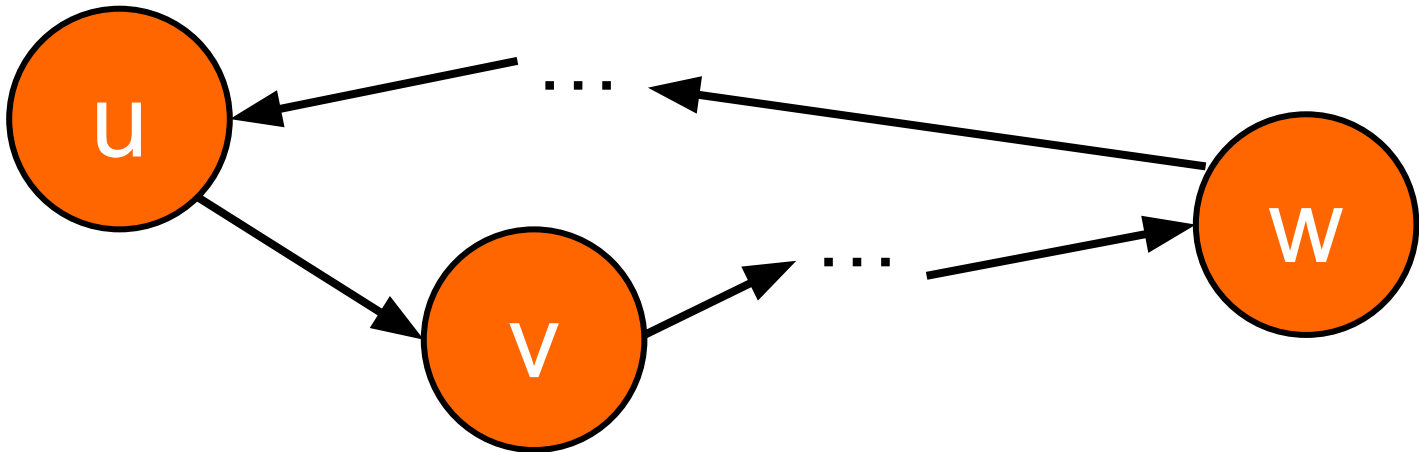
Clarification:

Case 2: **v**'s not visited yet (therefore its **time** and **low time** is not set).

$$\mathbf{w}'\text{'s time} = \mathbf{v}'\text{'s low time} < \mathbf{u}'\text{'s time} < \mathbf{v}'\text{'s time}$$

So **v** can reach **w**. And **w** was part of the current traversal. And both **u** and **v**, were also being traversed when **v** reached **w**.

Since **w**'s **time** < **u**'s **time**, this means **w** reaches **v**.



# Connected Components

---

Low time of a node is the minimum of:

1. Its own time
2. Low time of children that we just (visited)/(recursed from)

Compute the low time at the end of the traversal.

**Post order** traversal!

# Connected Components

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How does low time help us?

# Connected Components

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How does low time help us?

Grouping by low time gives us the connected components!

# Connected Components

---

Correction:

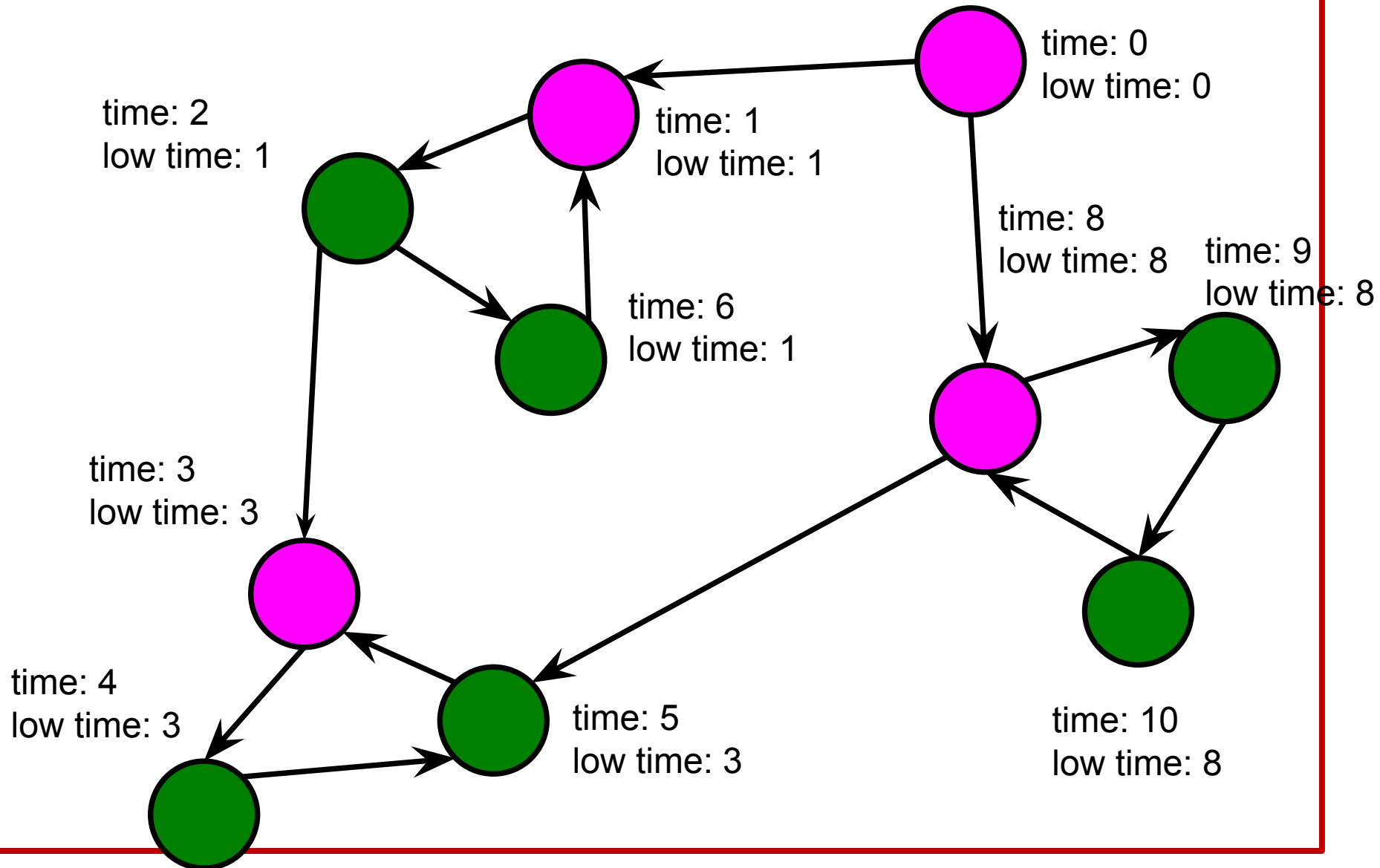
How does low time help us?

Nodes where their **low time** = **time** is are “**roots**”  
of their strongly connected components.



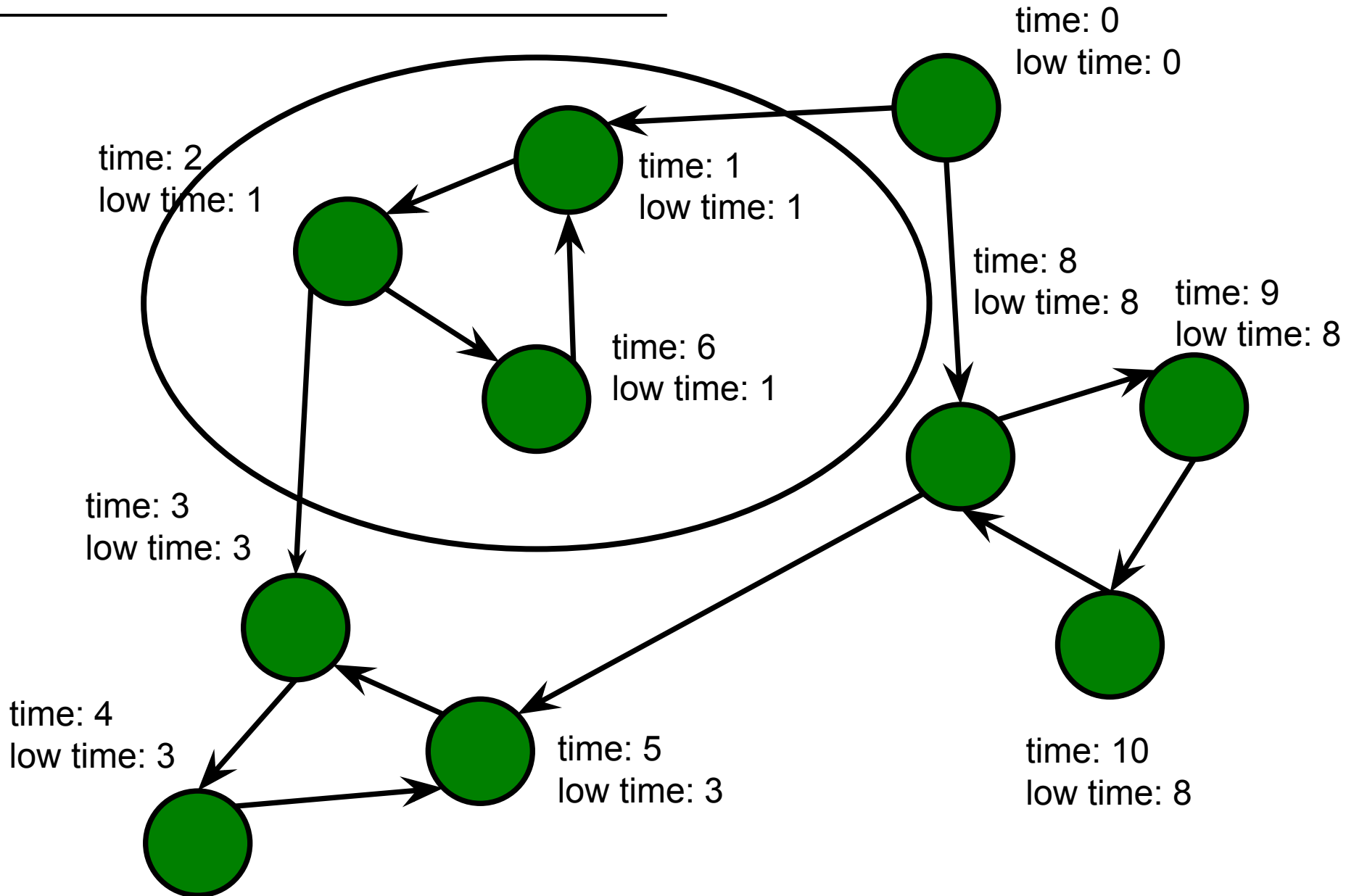
# Connected Components

Correction:



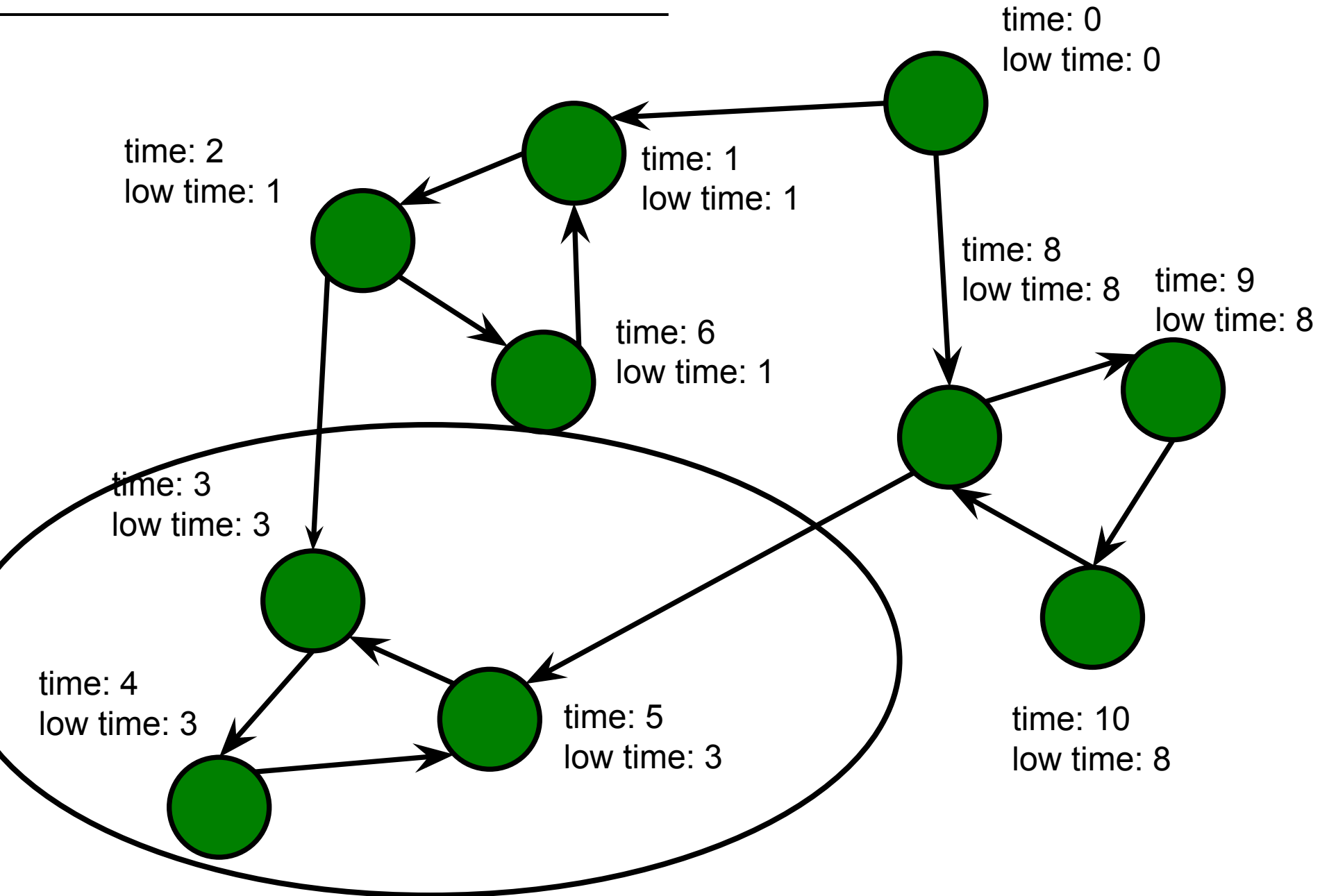
# Connected Components

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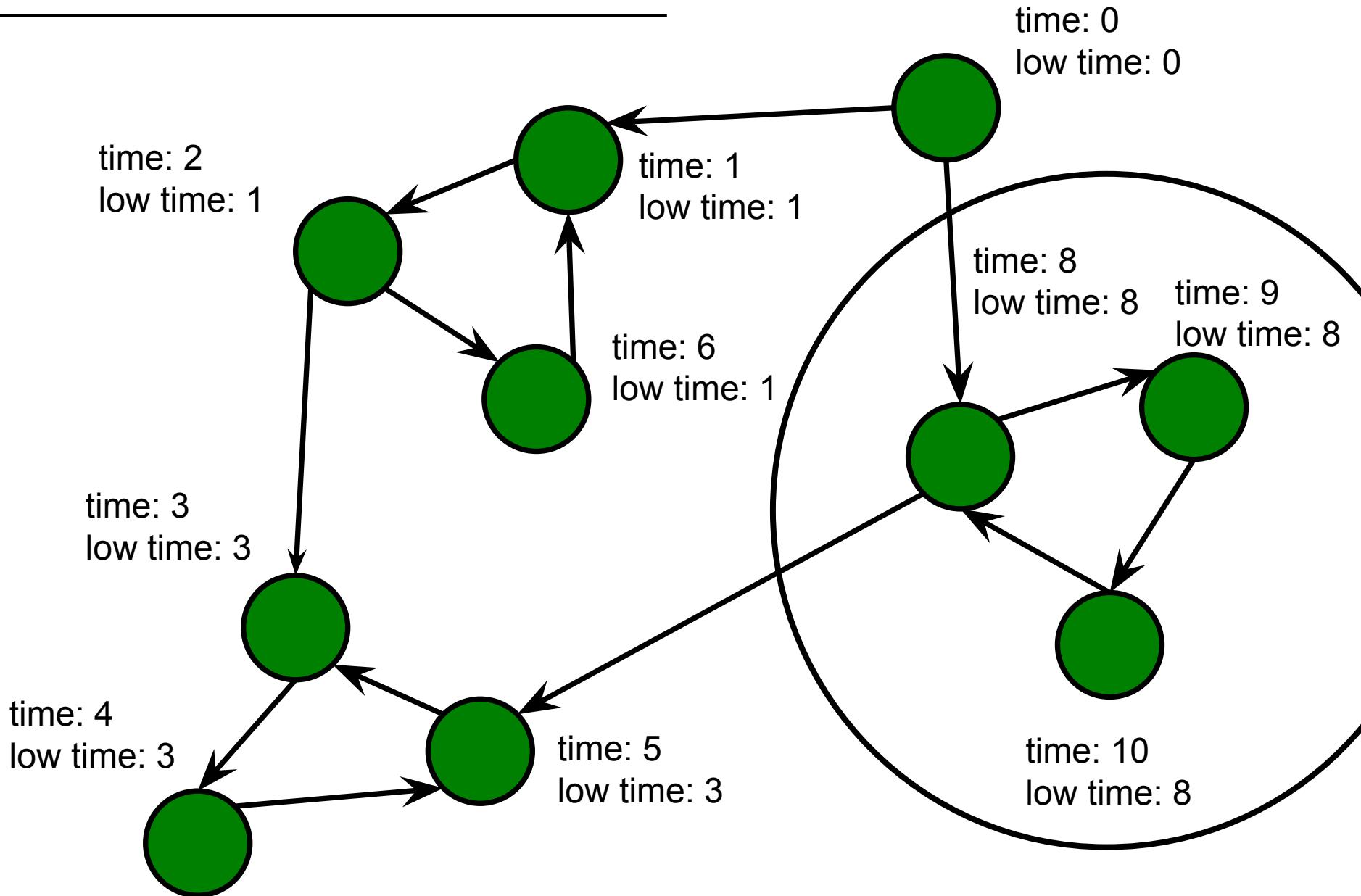
# Connected Components

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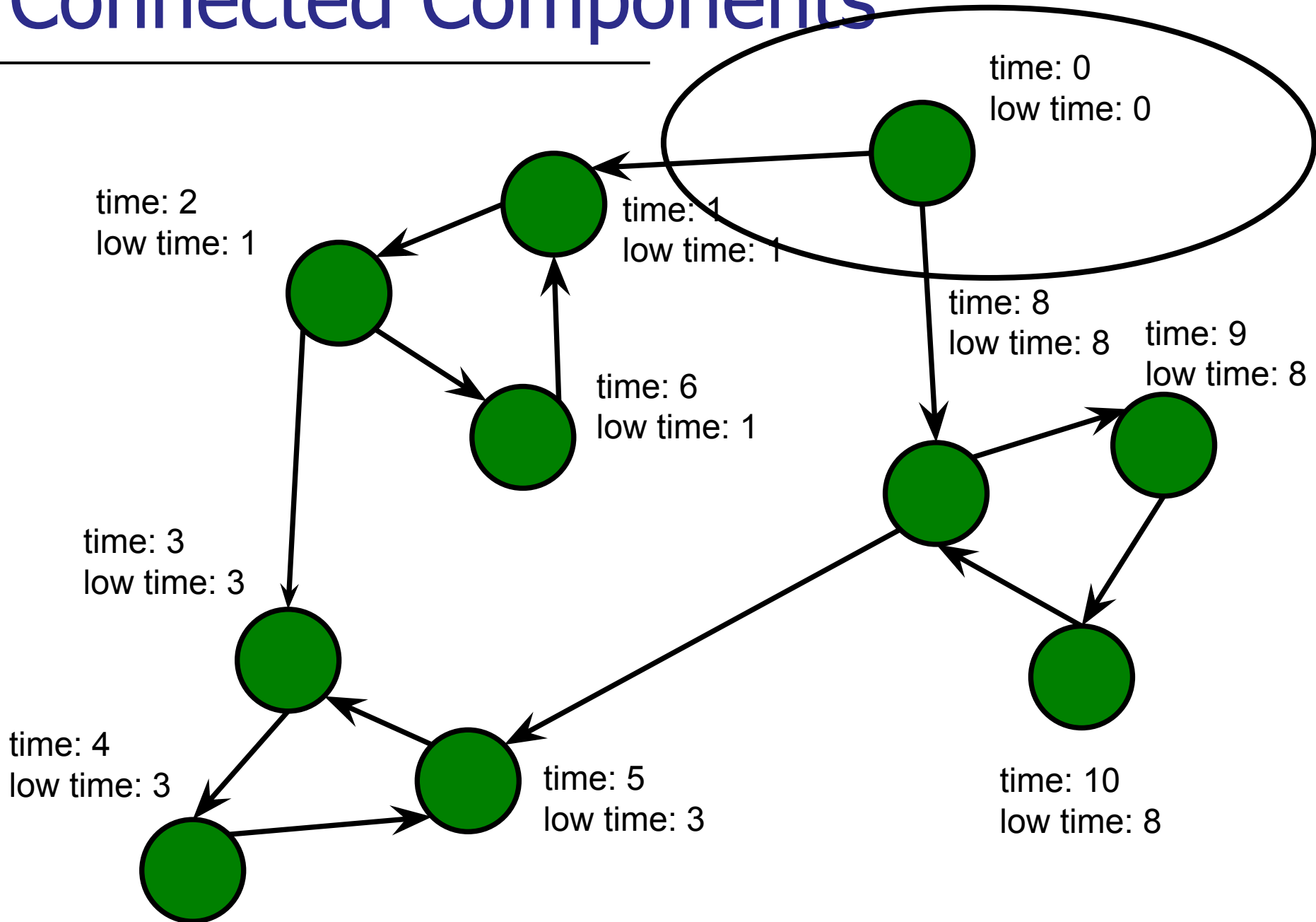
# Connected Components

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# Connected Components

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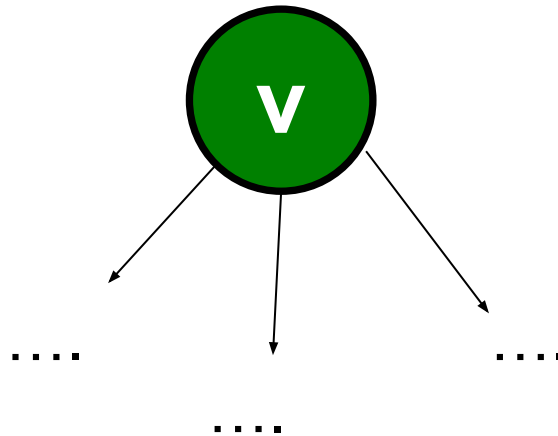
# Connected Components

---

Correction:

Rough Idea:

After we are finished recursing from a node **v**, just before we return, we have processed all nodes **v** could have reached.



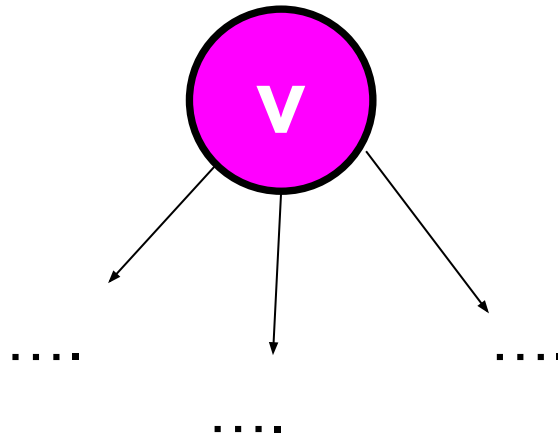
# Connected Components

---

Correction:

Rough Idea:

If node **v**'s **time** = **low time**, then **v** is the "root" of an SCC.



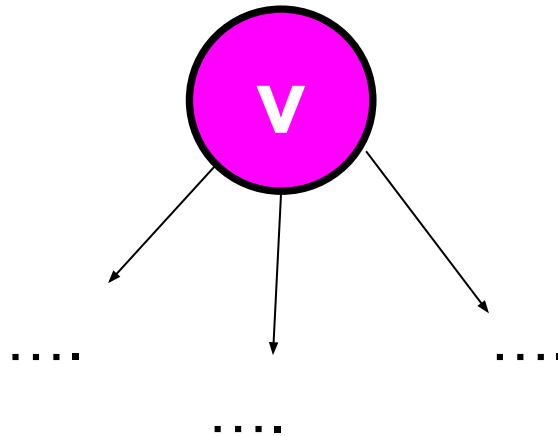
# Connected Components

Correction:

Rough Idea:

If node **v**'s **time** = **low time**, then **v** is the "root" of an SCC.

Want to make use of the fact that by the time we are done with **v**, all nodes in the SCC are "ready" to be grouped.



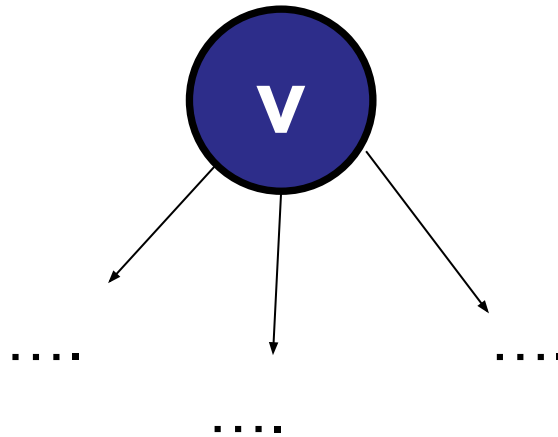


# Connected Components

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Correction:

1. When we first visit a node **v**, push it onto a stack.

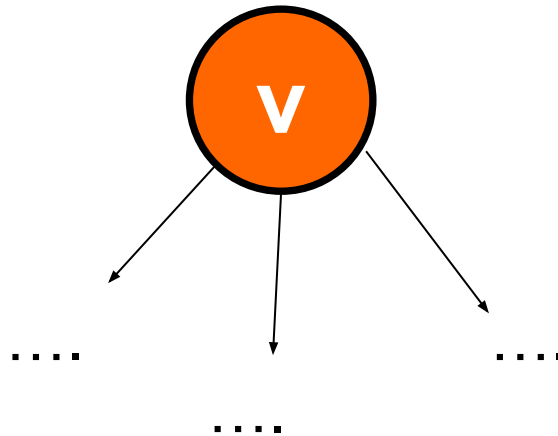


# Connected Components

---

Correction:

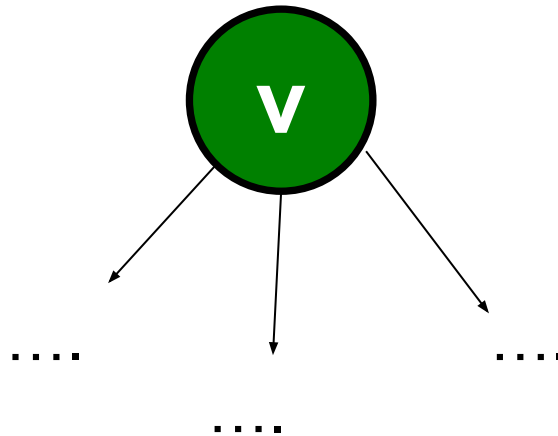
1. When we first visit a node **v**, push it onto a stack.
2. Run the DFS (that tags every node with **time/low time**)



# Connected Components

Correction:

1. When we first visit a node **v**, push it onto a stack.
2. Run the DFS (that tags every node with **time/low time**)
3. After we finish recursing. Before we return,  
if v's **time** = **low time**, then repeatedly pop from  
the stack until we pop **v** also.

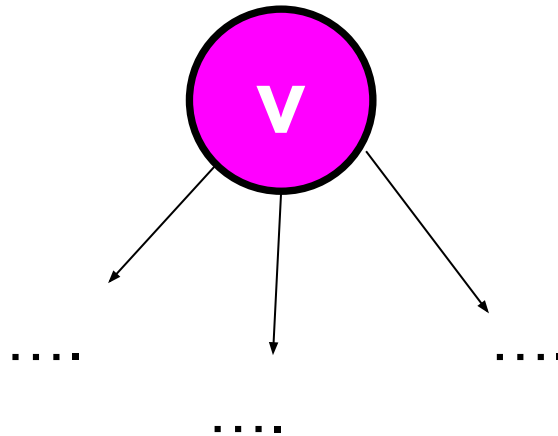


# Connected Components

Correction:

1. When we first visit a node **v**, push it onto a stack.
2. Run the DFS (that tags every node with **time/low time**)
3. After we finish recursing. Before we return,  
if v's **time** = **low time**, then repeatedly pop from  
the stack until we pop **v** also.

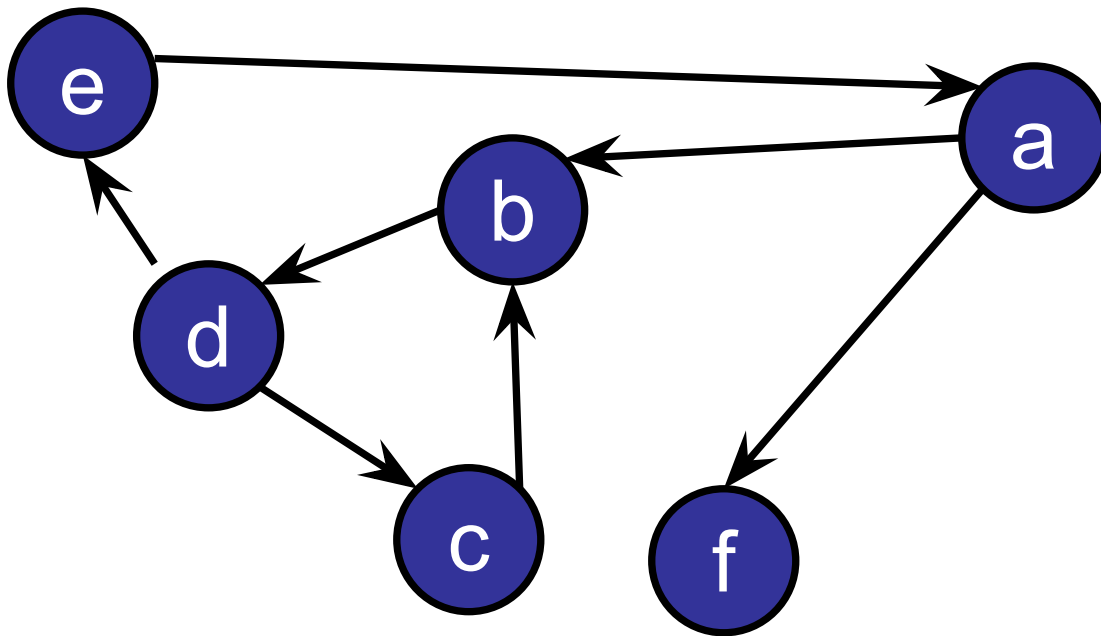
Everything we popped is part of the SCC rooted at **v**



# Connected Components

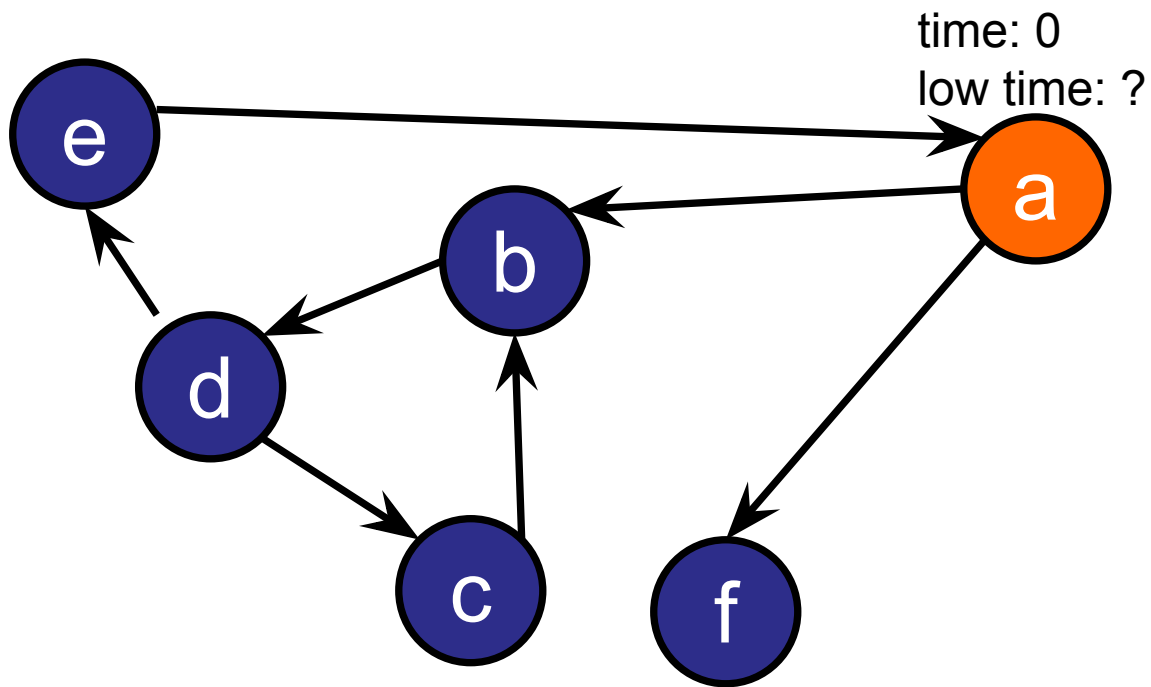
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Correction:



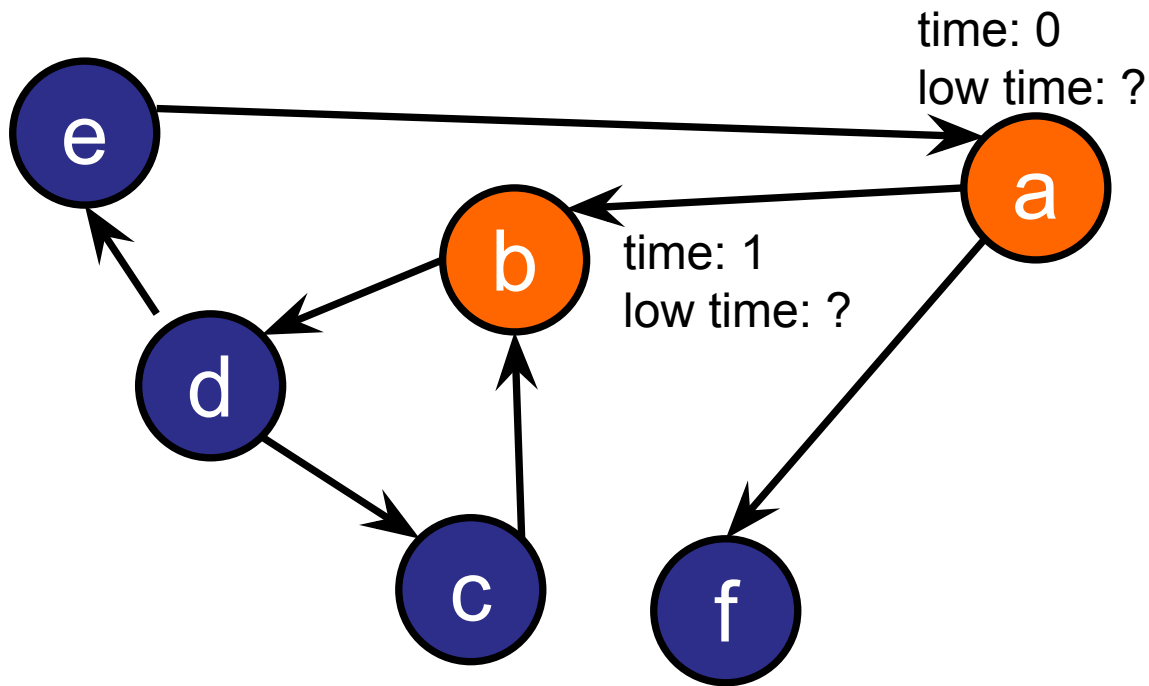
# Connected Components

Correction:



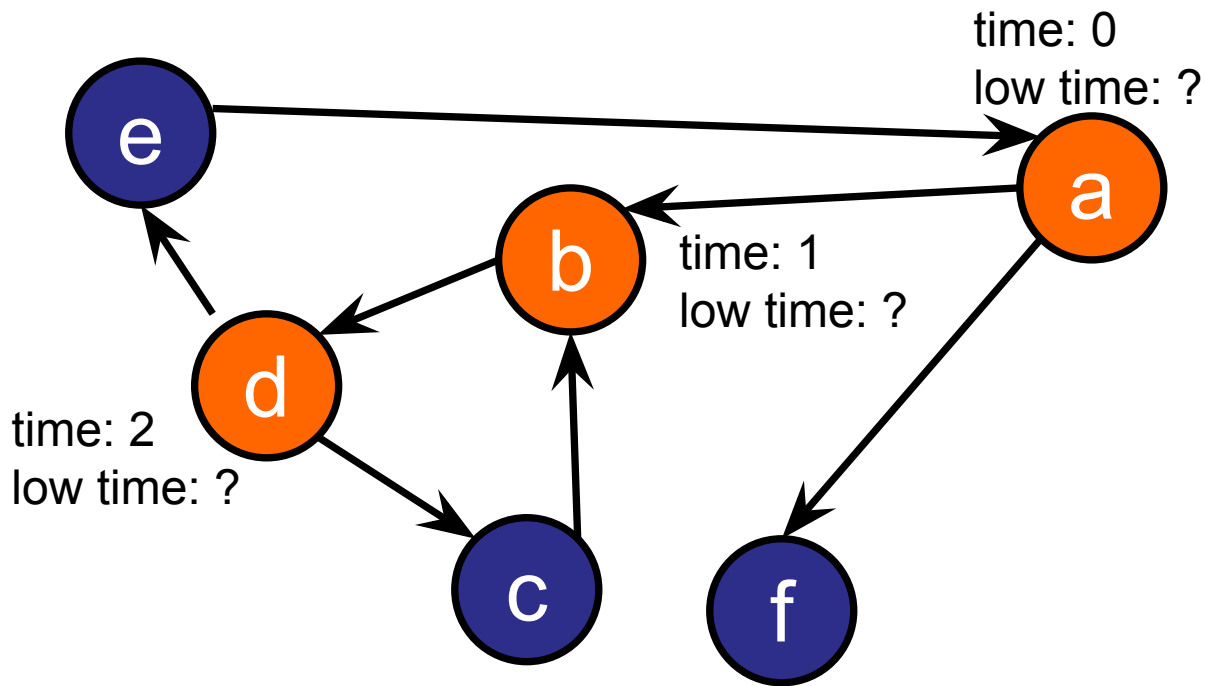
# Connected Components

Correction:



# Connected Components

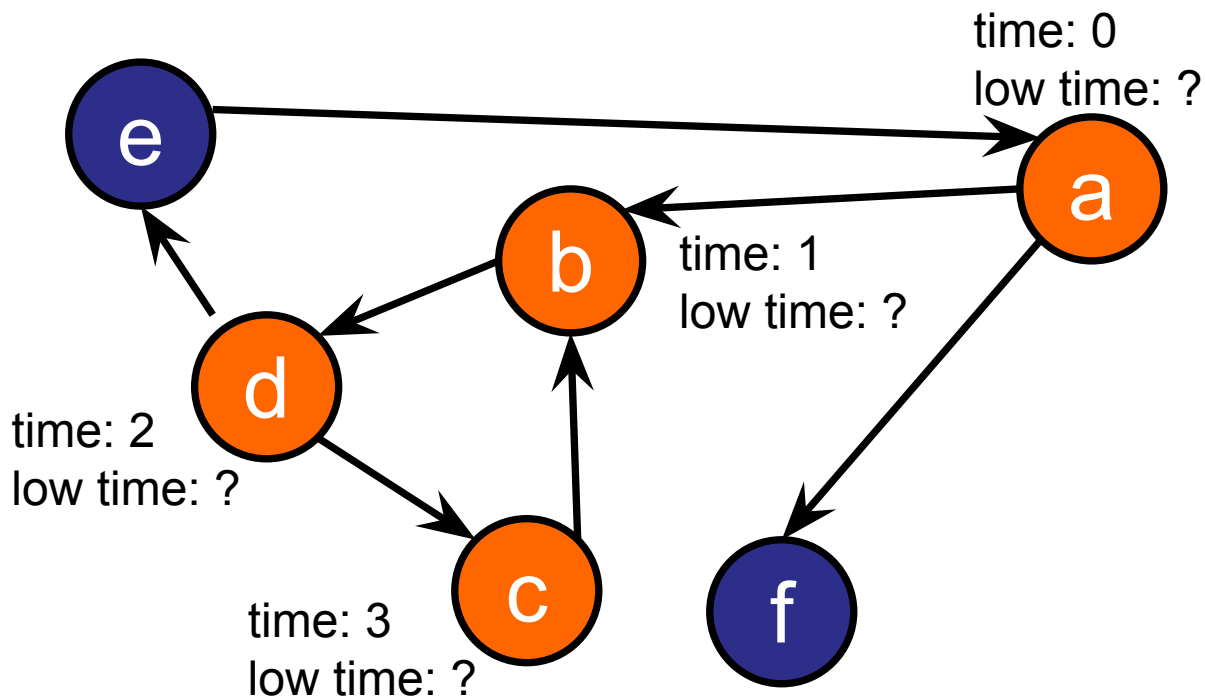
Correction:





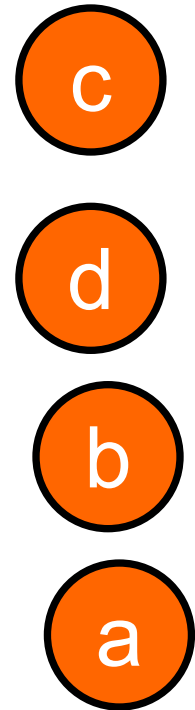
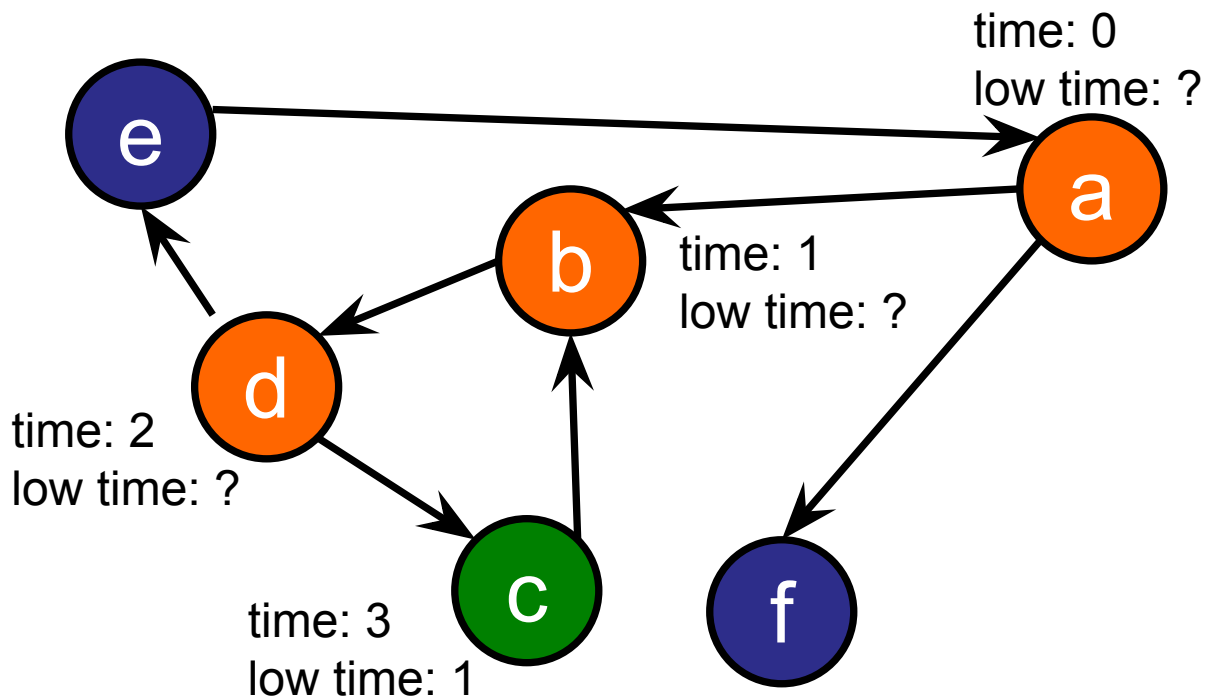
# Connected Components

Correction:



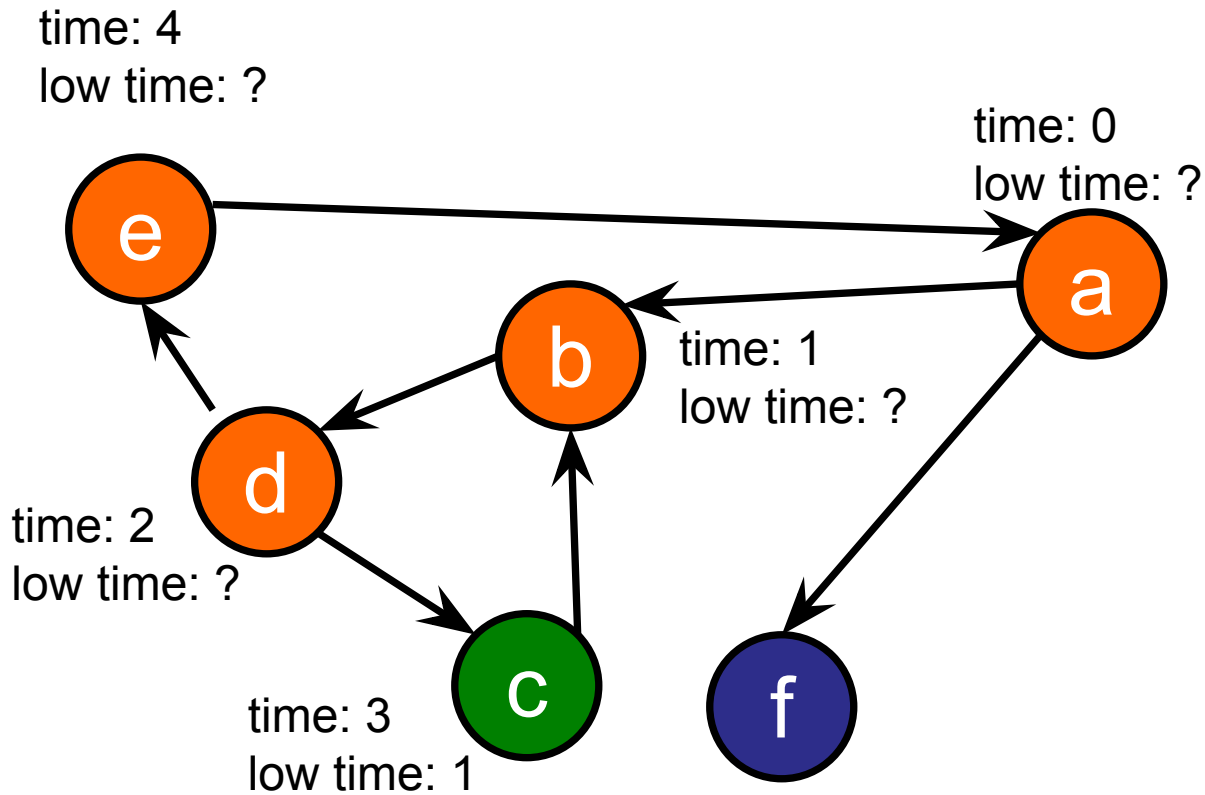
# Connected Components

Correction:



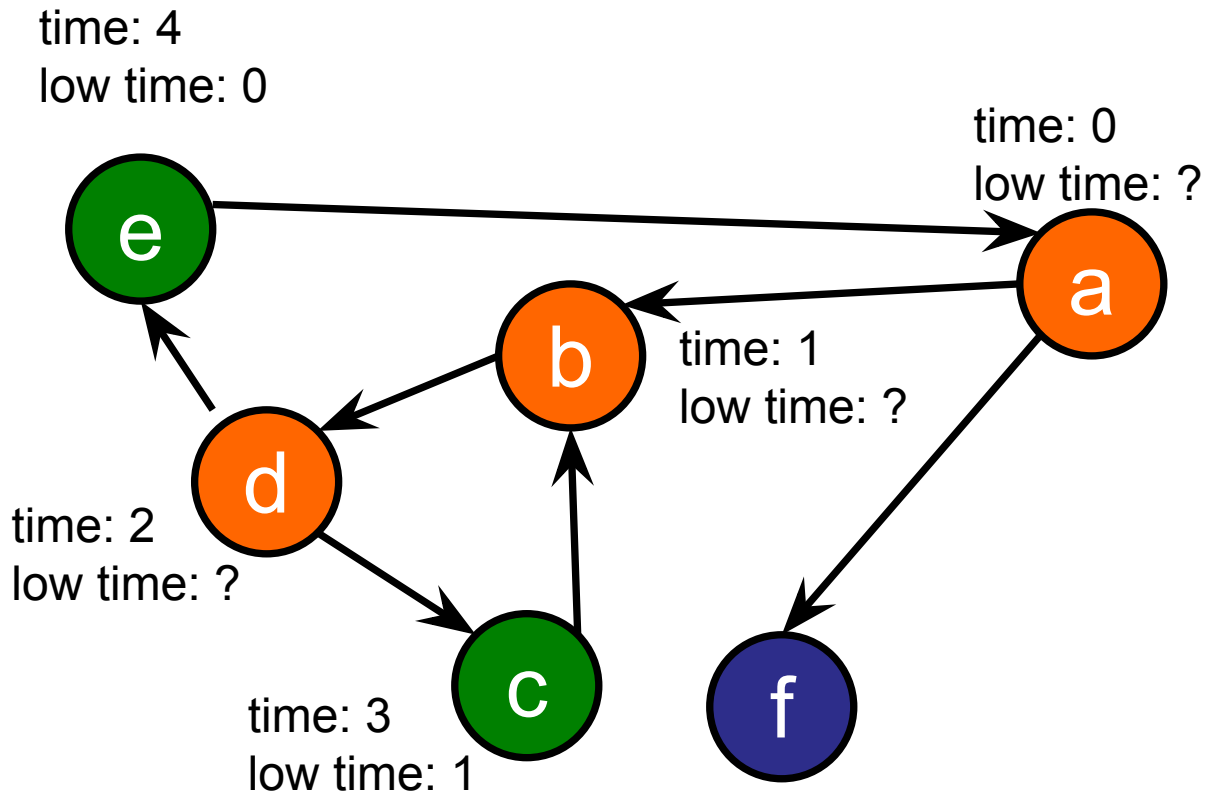
# Connected Components

Correction:



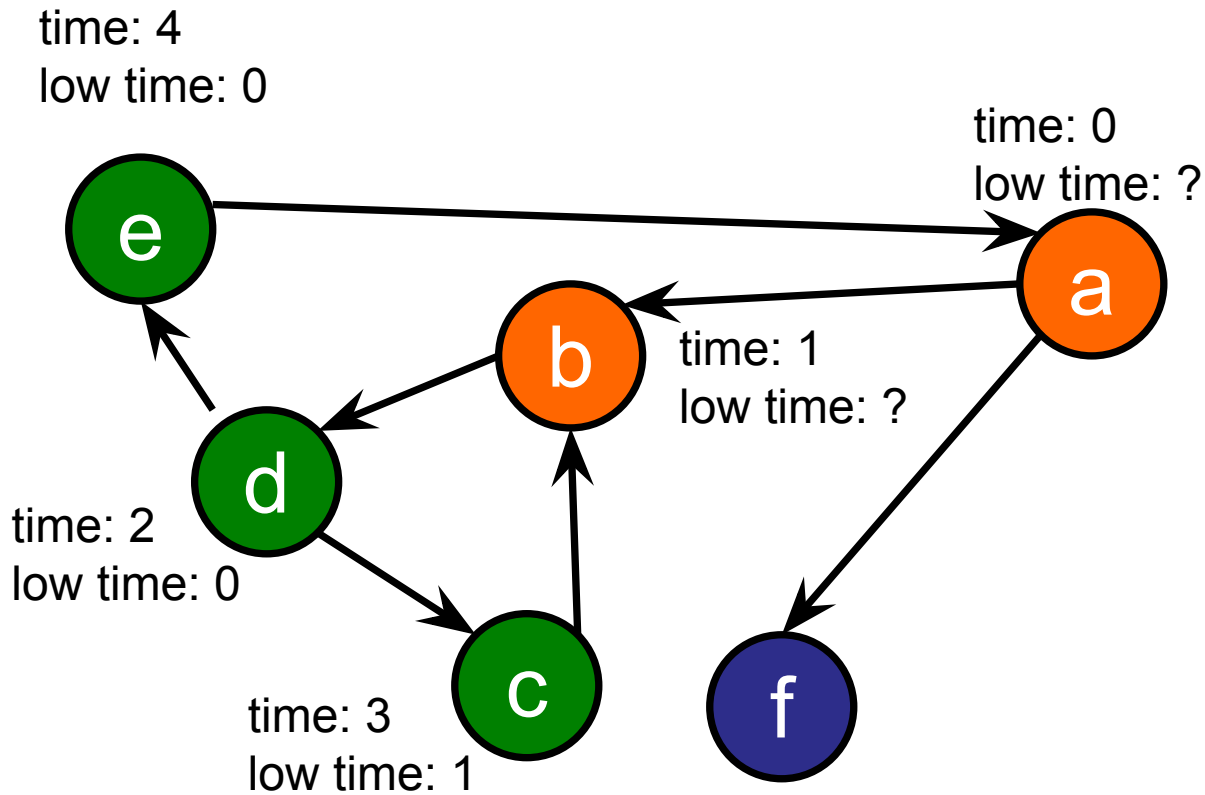
# Connected Components

Correction:



# Connected Components

Correction:

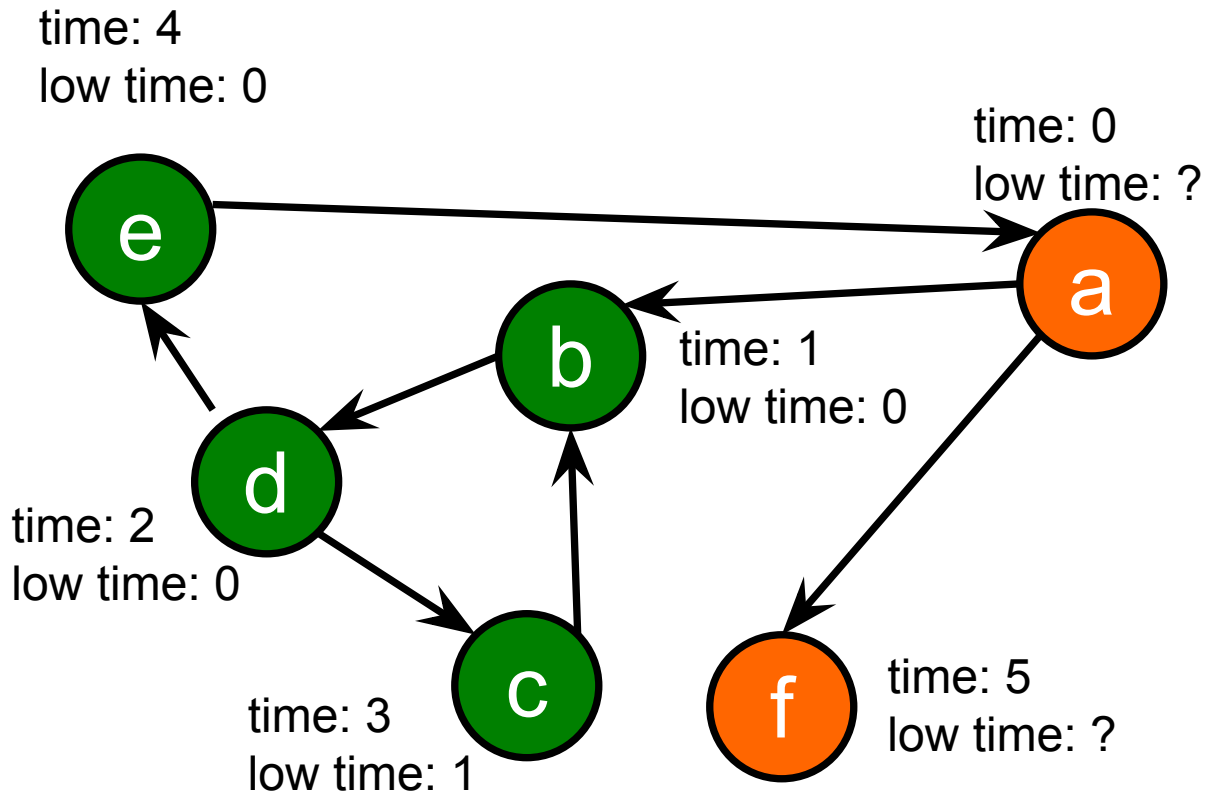


## Correction:



# Connected Components

Correction:



f

e

c

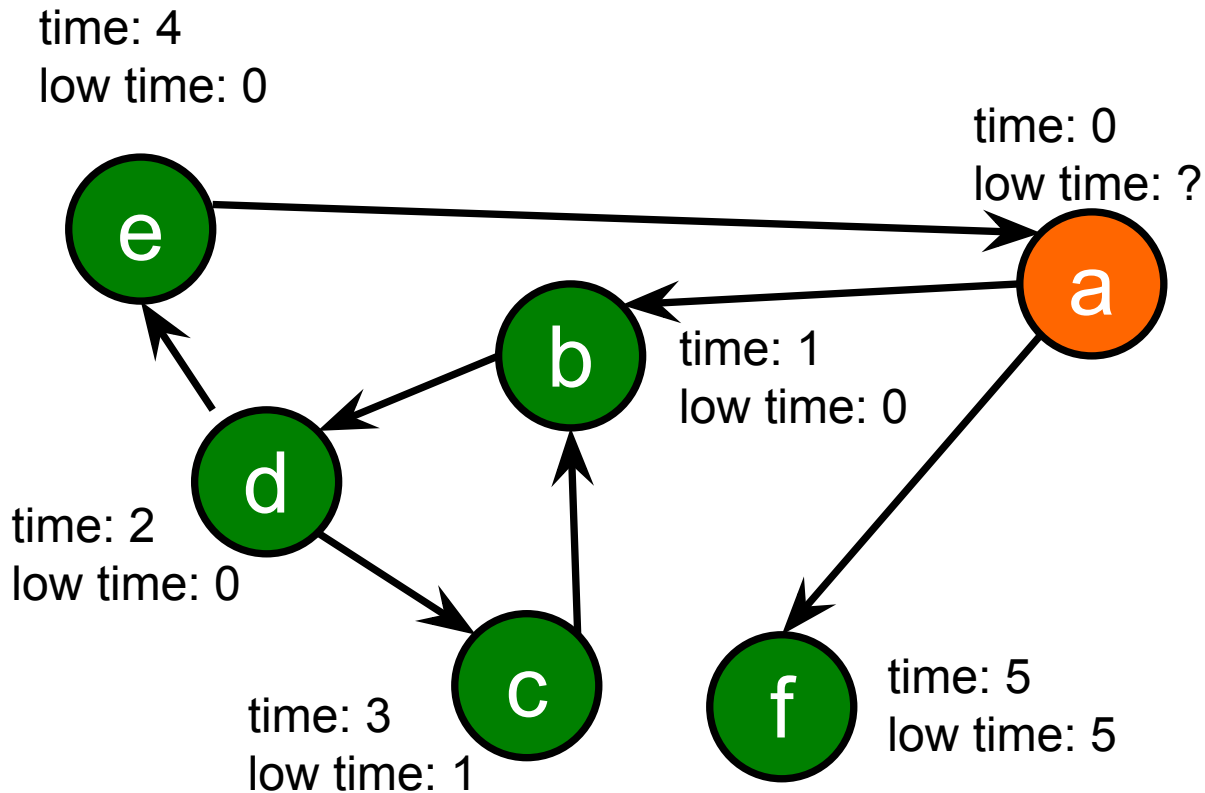
d

b

a

# Connected Components

Correction:



f

e

c

d

b

a

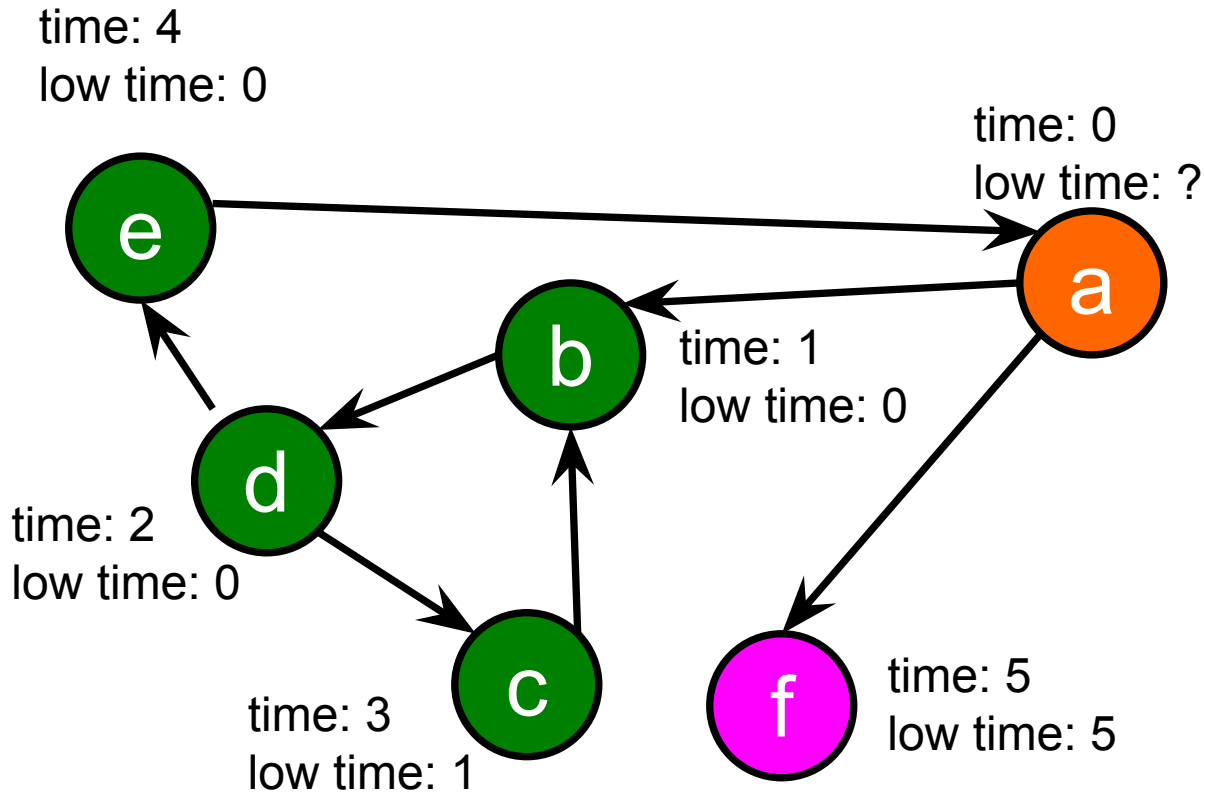


# Connected Components

Correction:

time = low time!

keep popping until we remove f

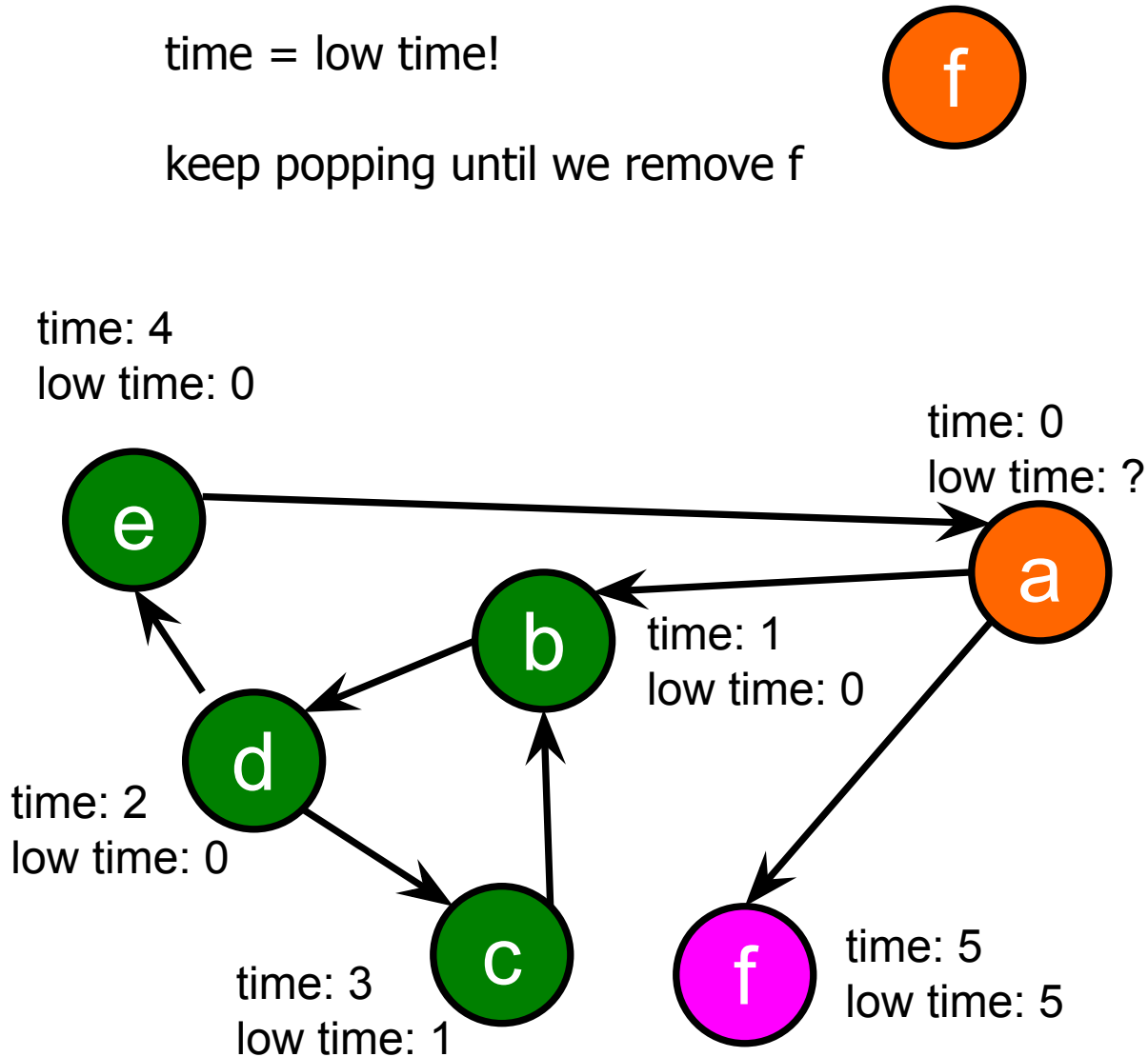


# Connected Components

Correction:

time = low time!

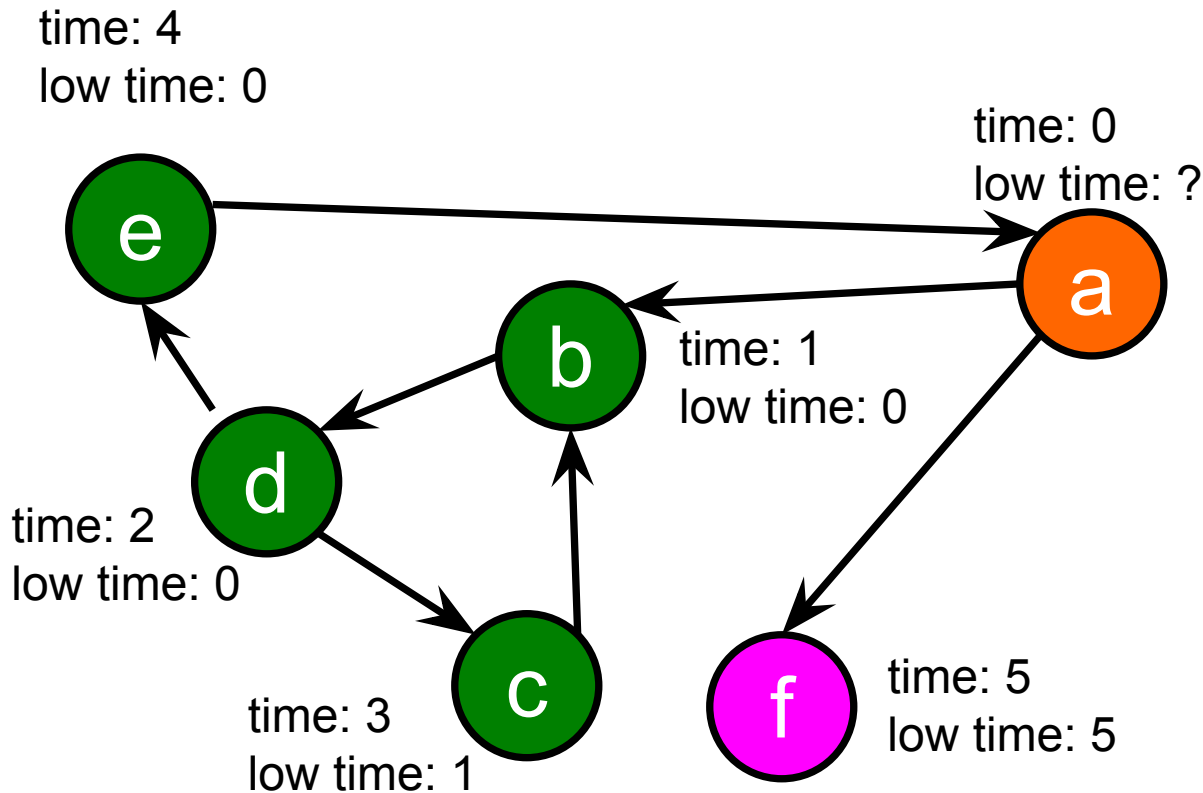
keep popping until we remove f



# Connected Components

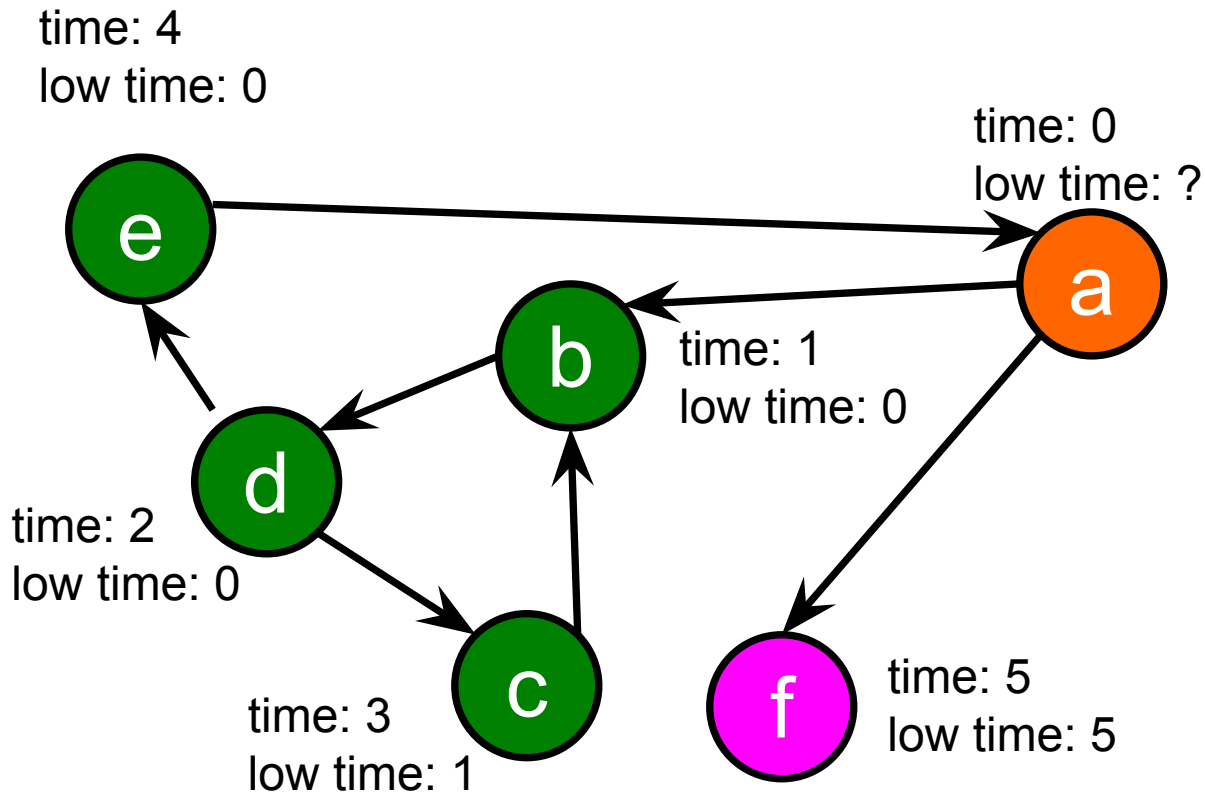
Correction:

SCC formed with f itself.



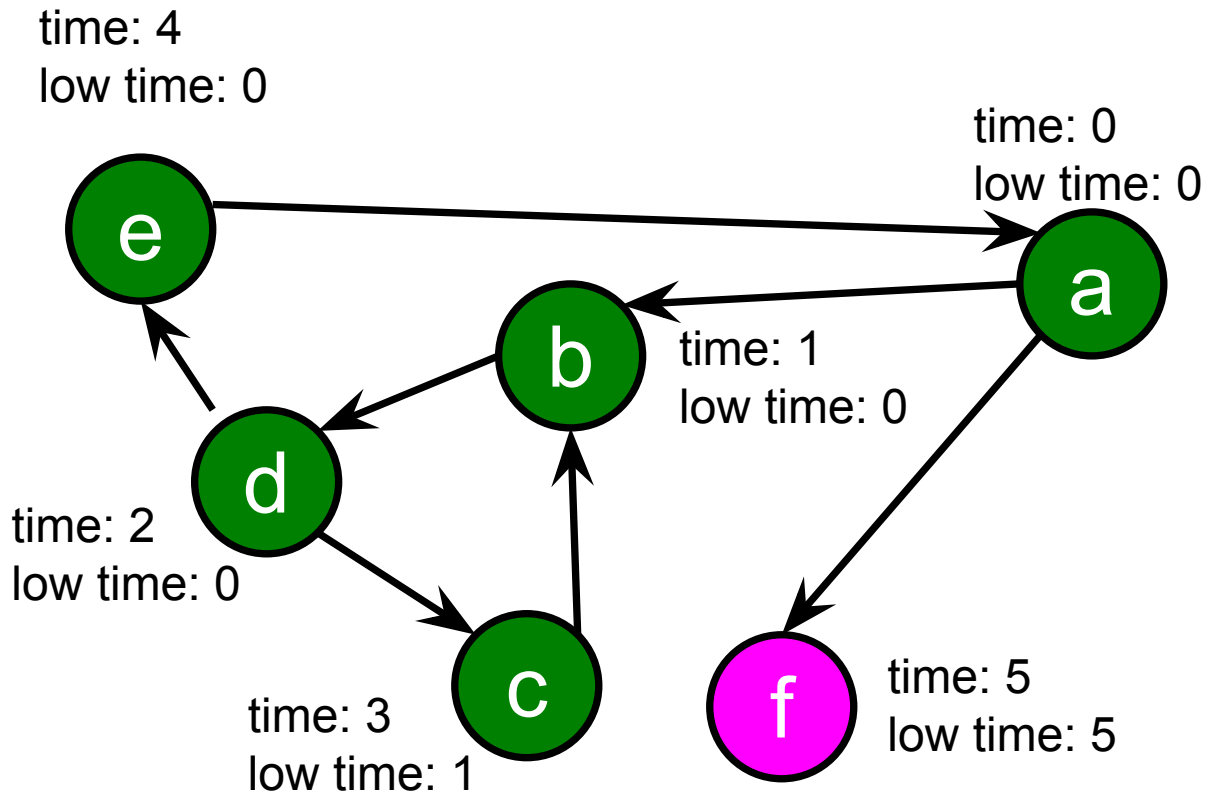
# Connected Components

Correction:



# Connected Components

Correction:



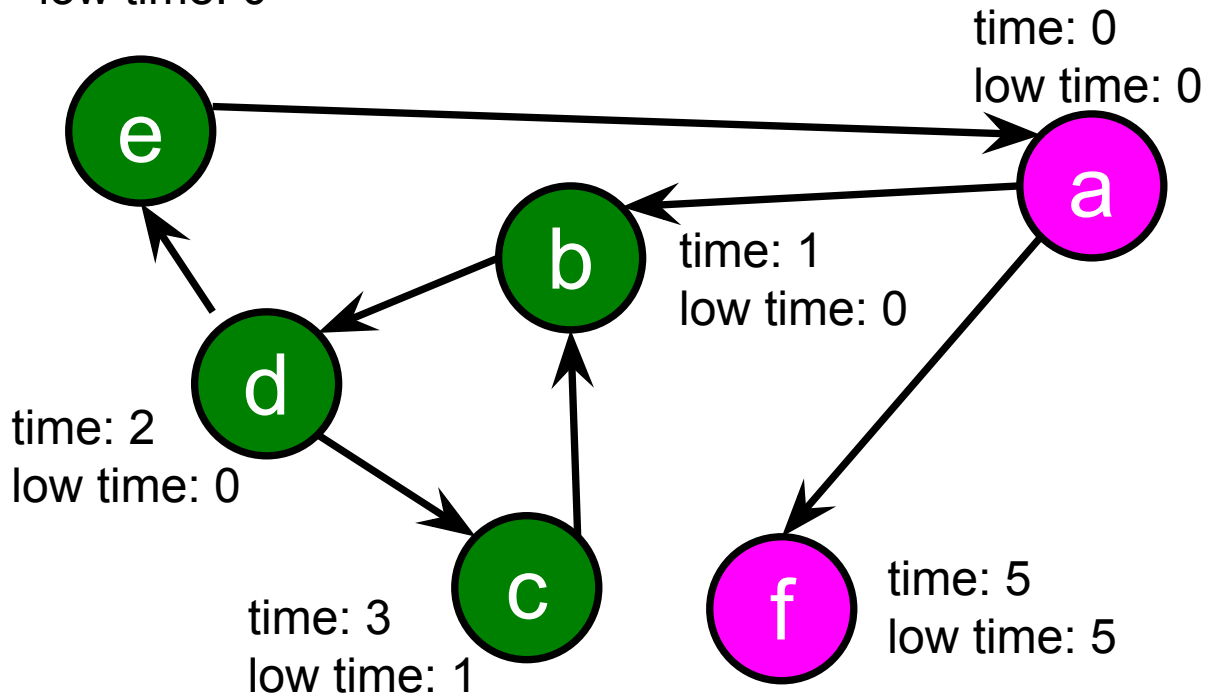
# Connected Components

Correction:

time = low time!

keep popping until we remove a

time: 4  
low time: 0



# Connected Components

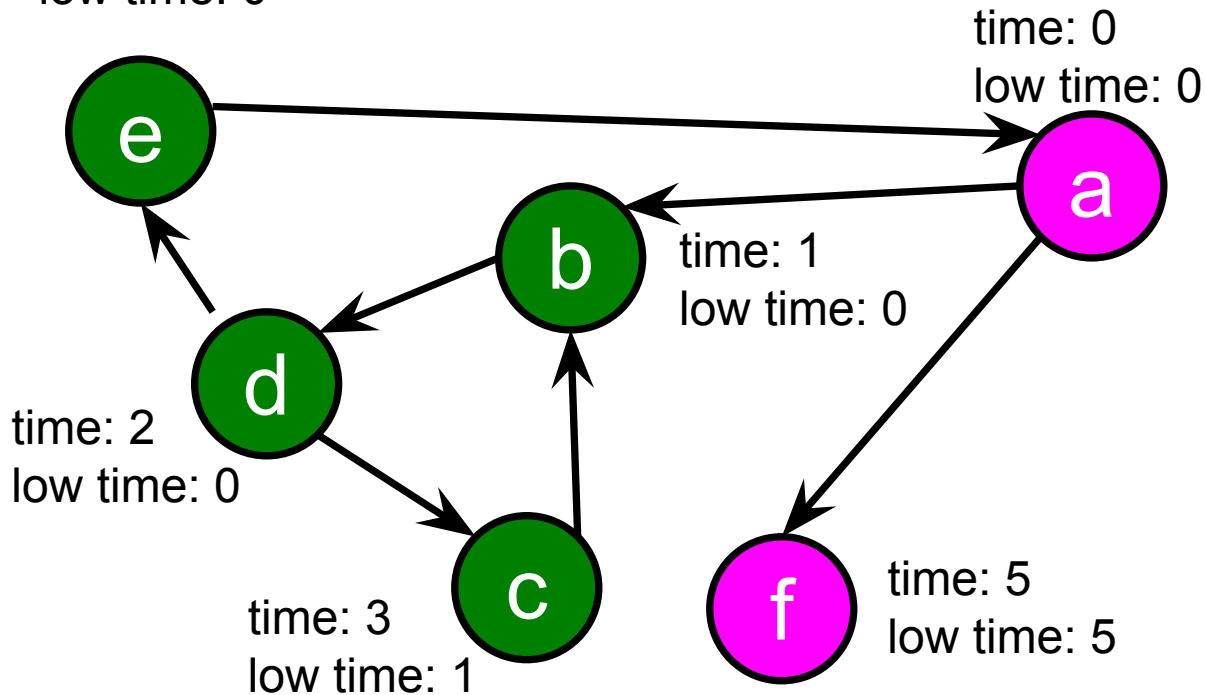
Correction:

time = low time!

keep popping until we remove a



time: 4  
low time: 0



# Connected Components

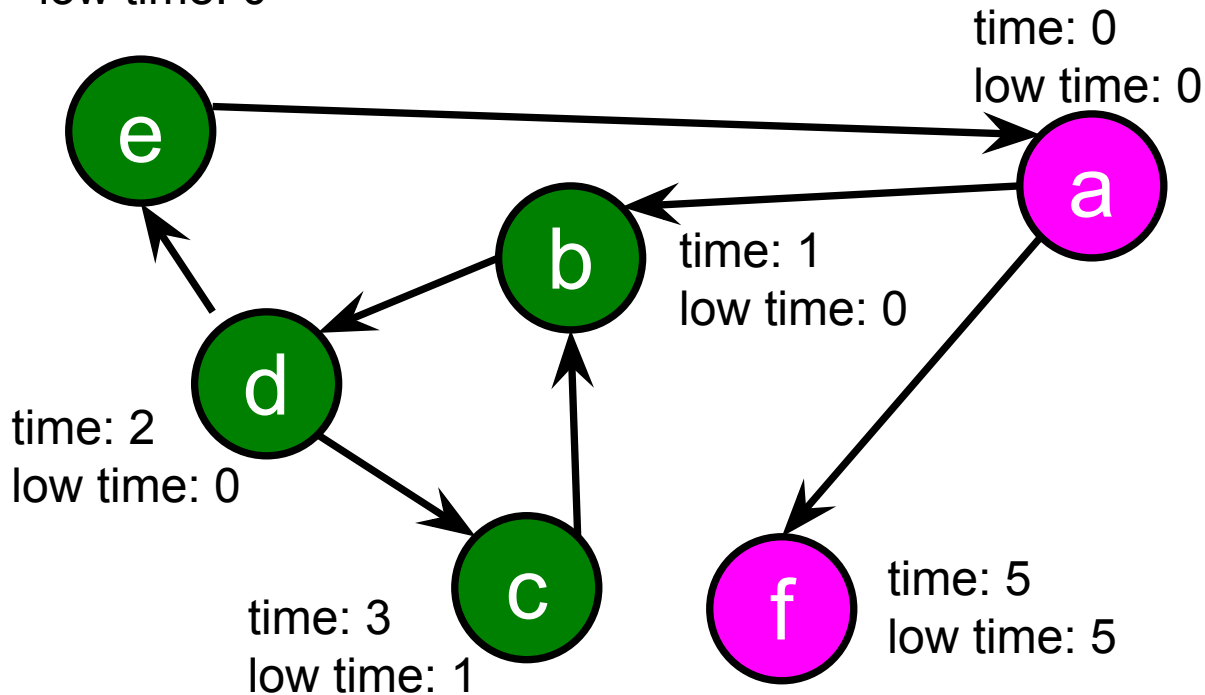
Correction:

time = low time!

keep popping until we remove a



time: 4  
low time: 0





# Connected Components

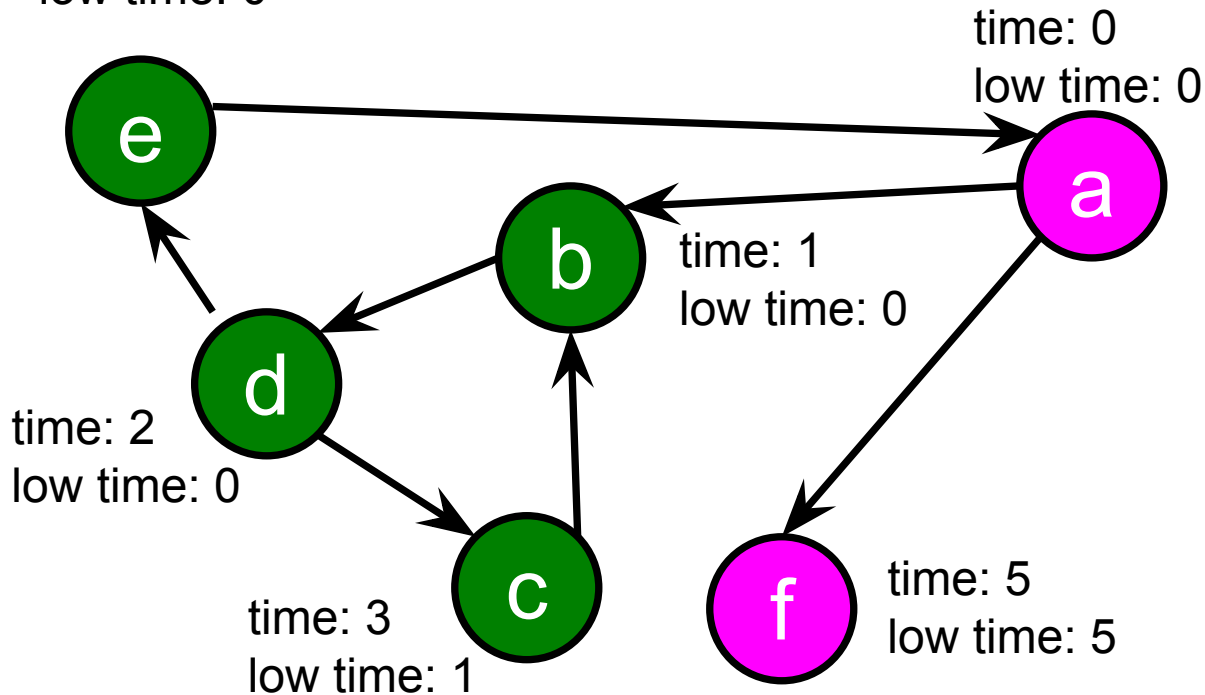
Correction:

time = low time!

keep popping until we remove a



time: 4  
low time: 0



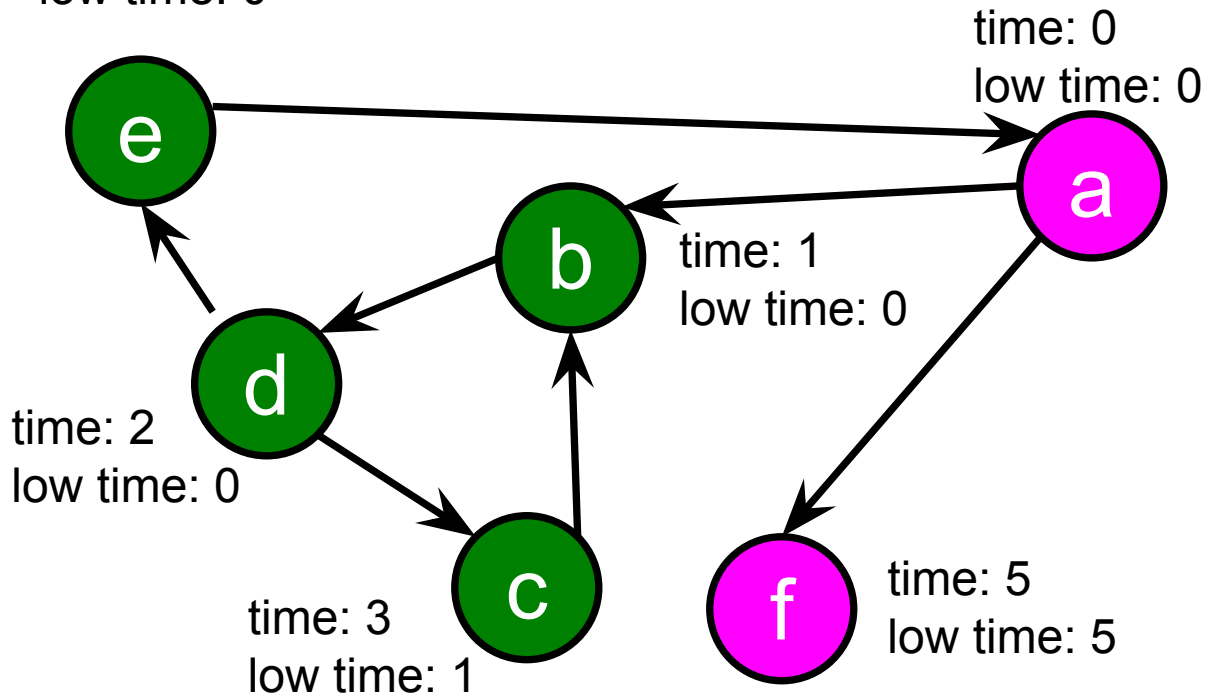
# Connected Components

Correction:

time = low time!

keep popping until we remove a

time: 4  
low time: 0

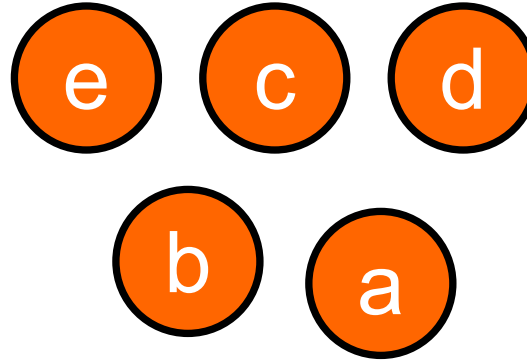


# Connected Components

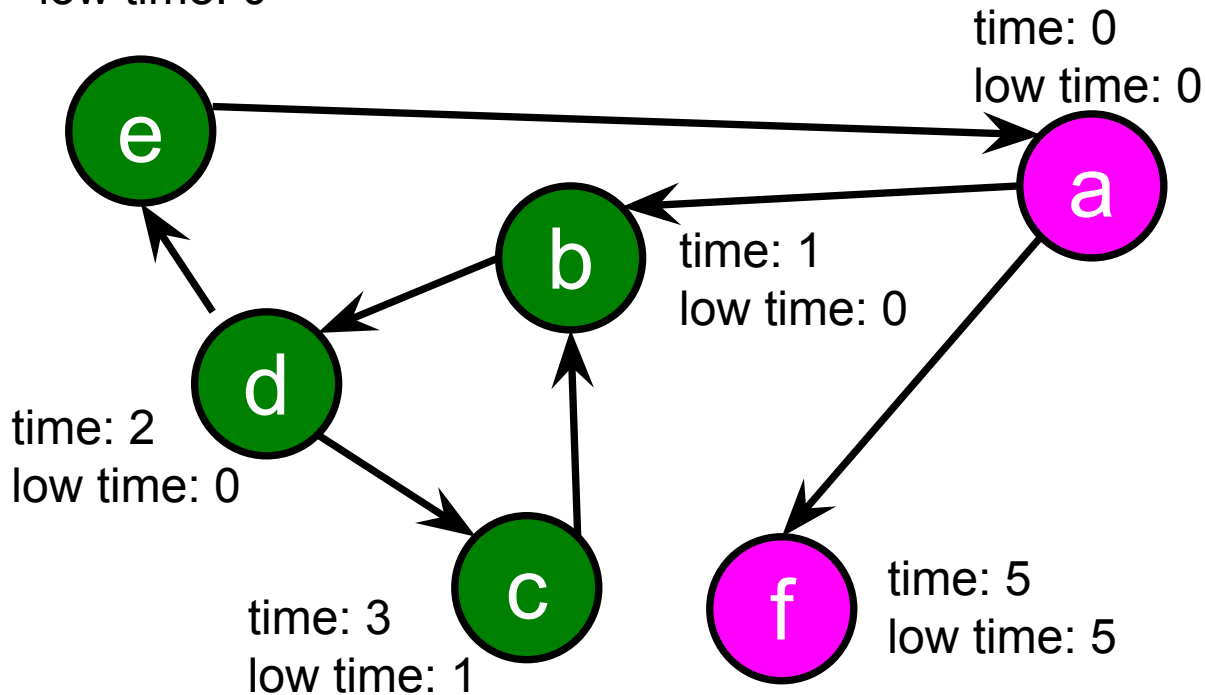
Correction:

time = low time!

keep popping until we remove a



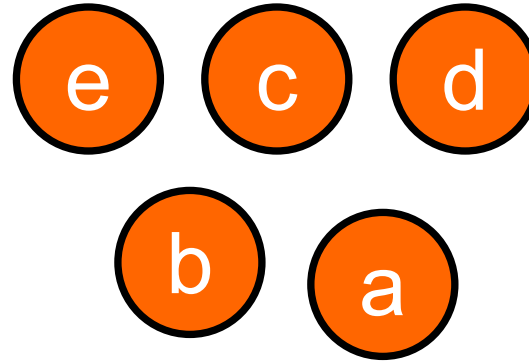
time: 4  
low time: 0



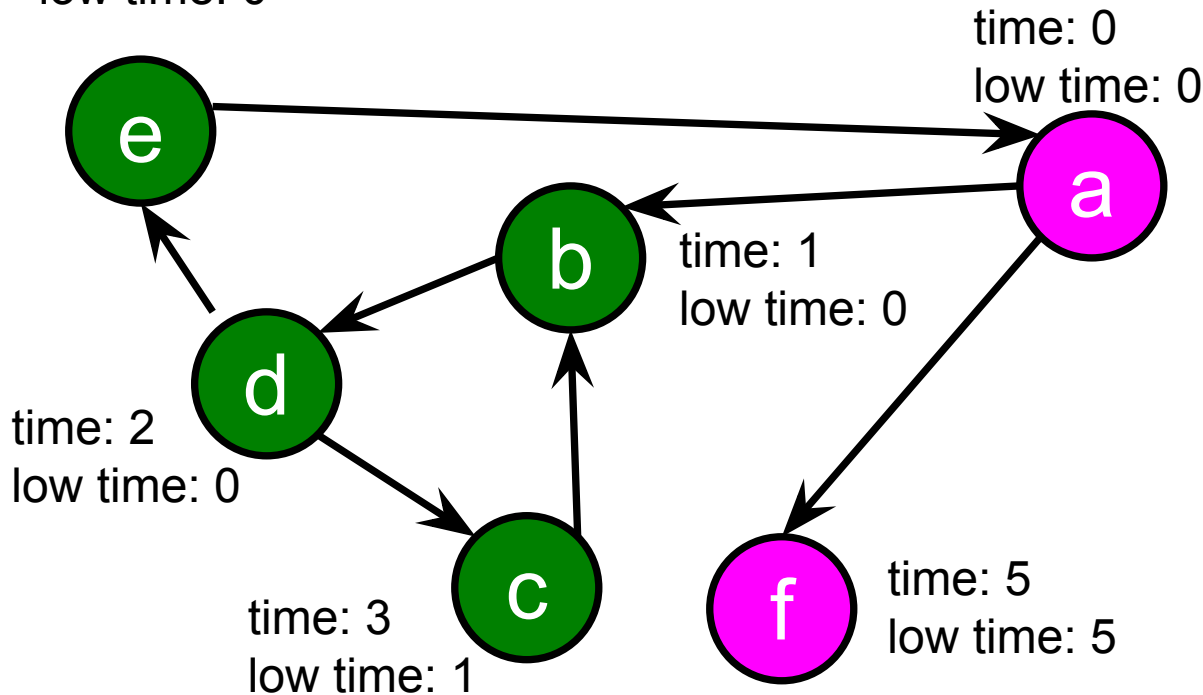
# Connected Components

Correction:

SCC formed with  
 $\{a\ b\ c\ d\ e\}$



time: 4  
low time: 0



# Cycle Detection

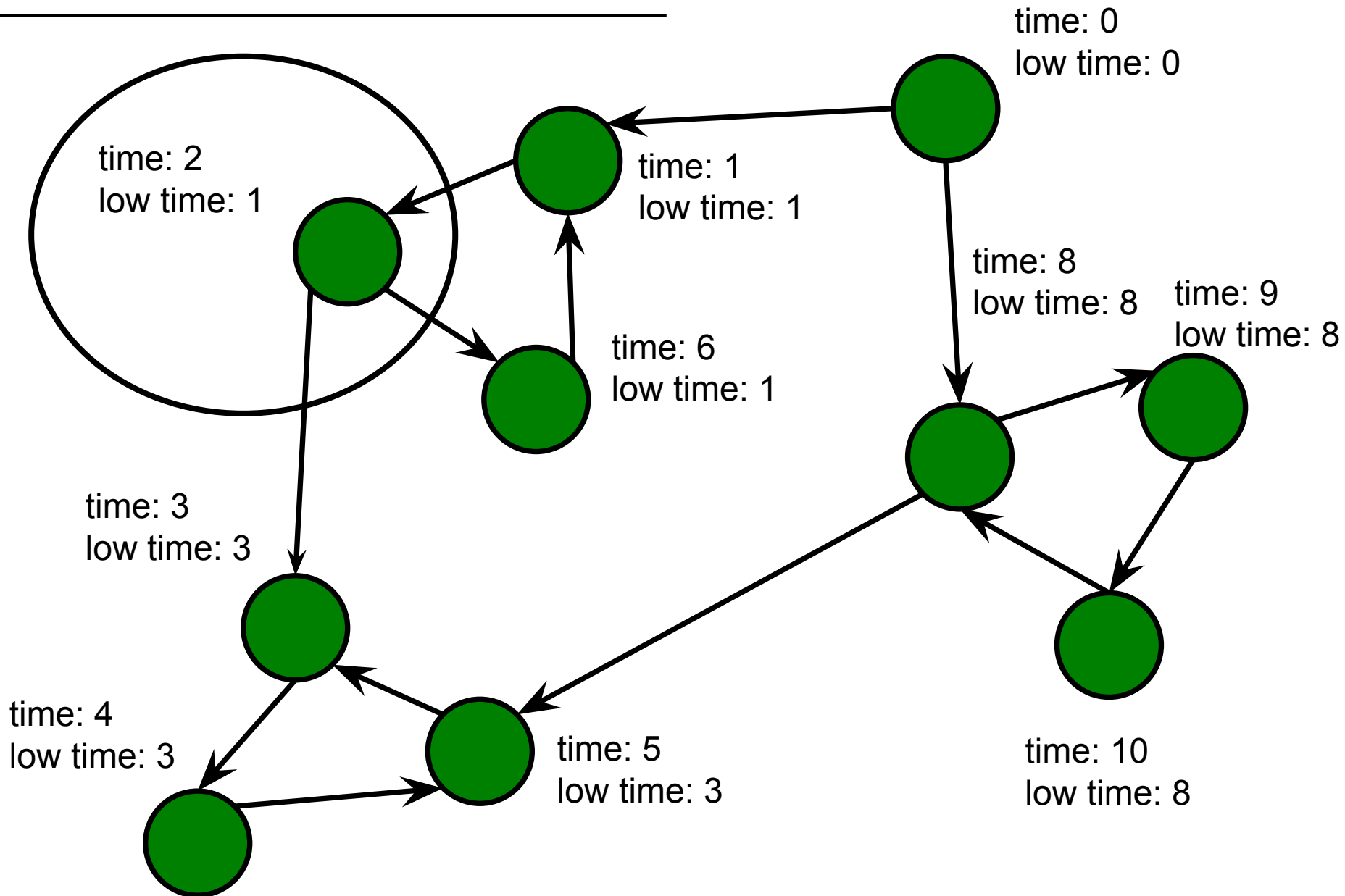
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How does low time help us?

If we ever find a node whose  $\text{low time} < \text{time}$ , then there is a cycle!

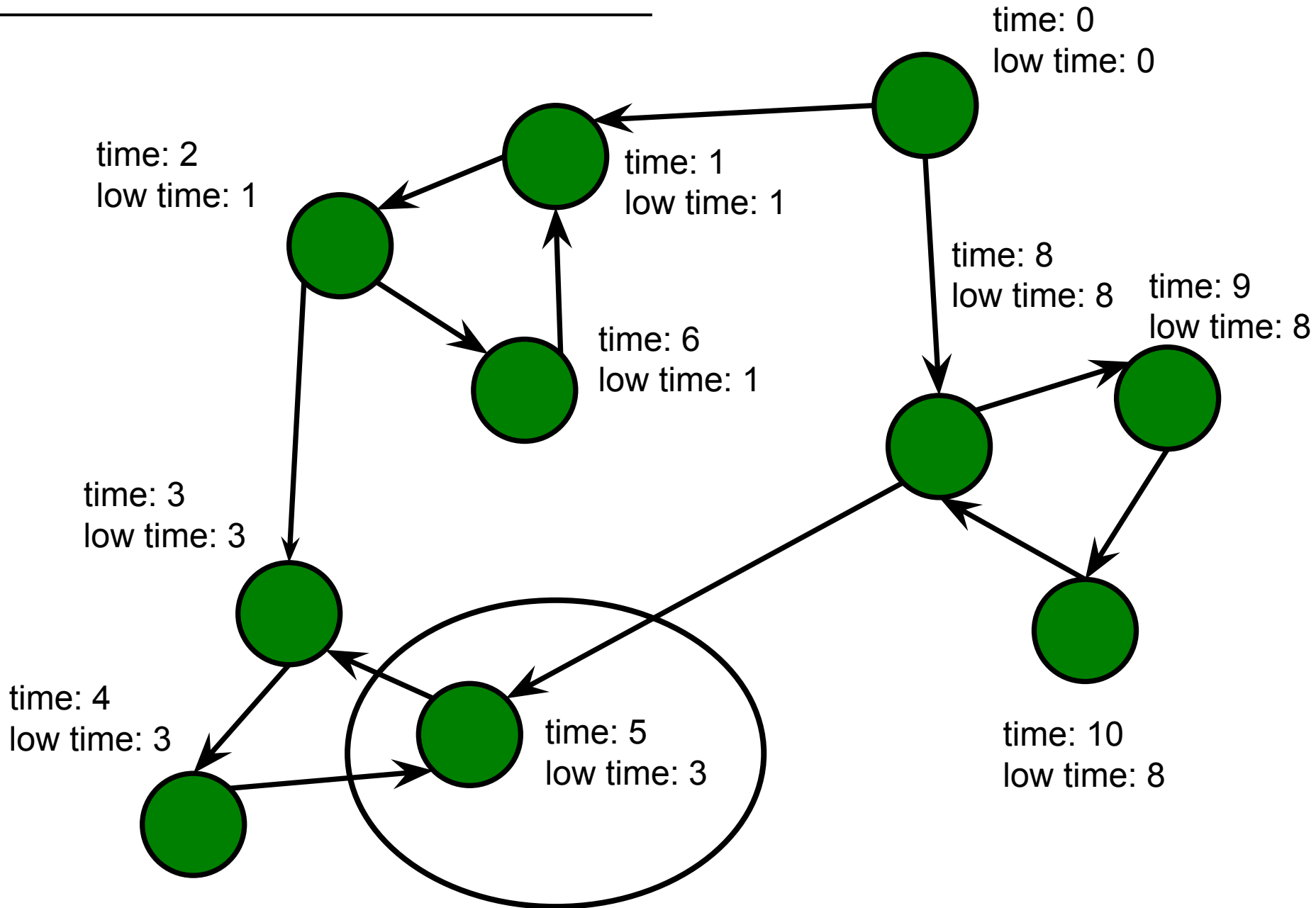
# Cycle Detection

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# Cycle Detection

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# Cycle Detection

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How does low time help us?

If we ever find a node whose **low time** < **time**, then there is a cycle!



# Cycle Detection

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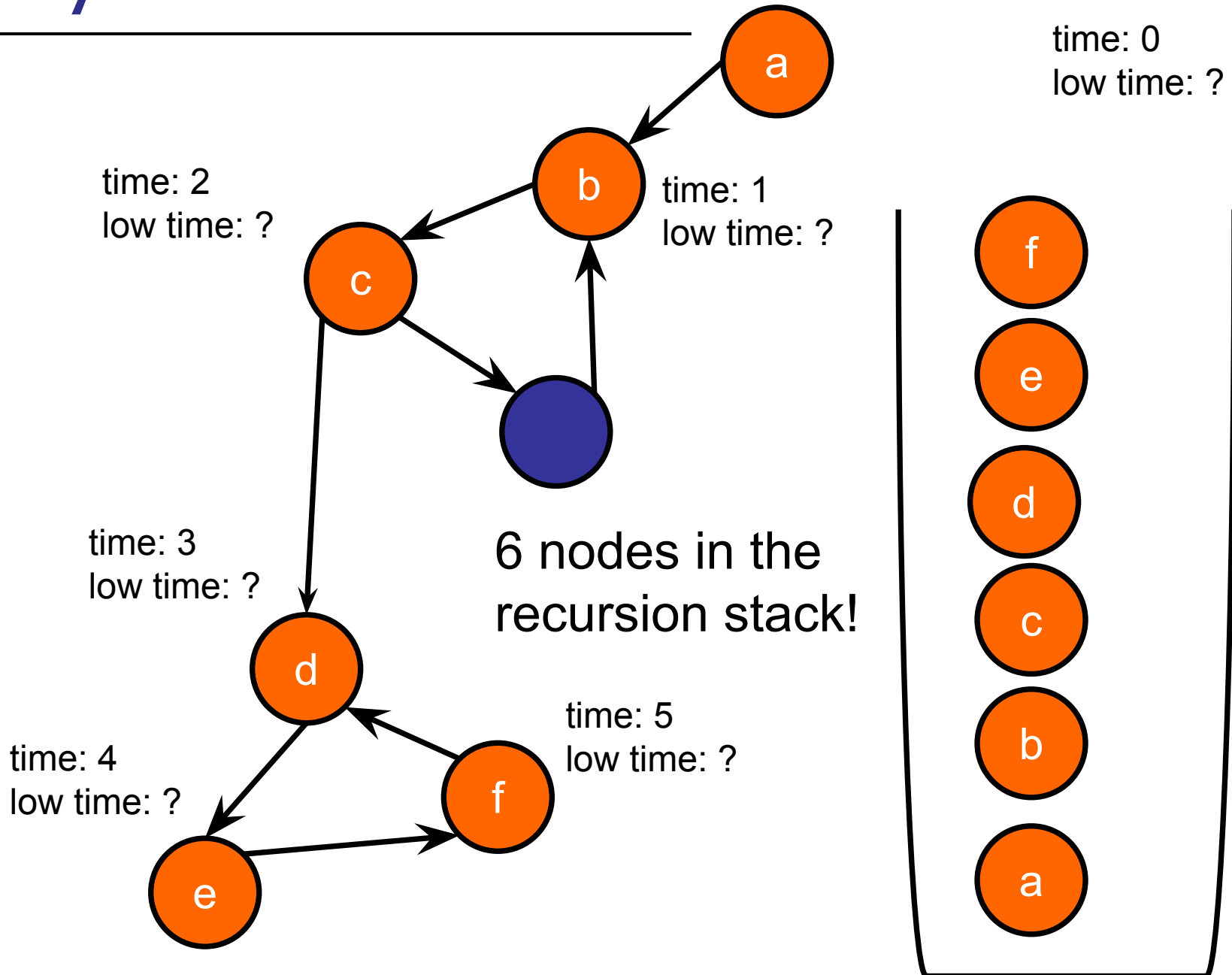
How does low time help us?

If we ever find a node whose  $\text{low time} < \text{time}$ , then there is a cycle!

Recall: We only update low time based on nodes whose low times are not set.

Intuition: A low time that is not yet set  $\rightarrow$  that node is still in the recursion stack

# Cycle Detection



# Articulation Points?

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**Challenge:** Figure out how to run DFS on a directed graph (how should the algorithm change) so that we can find articulation points using low time and time?

**Intuition:** If a node's low time  $<$  time, then it is not an articulation point. Otherwise, it is.

**But how do we handle bidirectional edges?**

# Roadmap

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## Algorithms on Directed Graphs

- Searching directed graphs (DFS / BFS)
- Topological Sort
- Connected Components

## More Algorithms on Undirected Graphs

# Next Week:

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More shortest pathfinding!