

PHYSICALLY-BASED SIMULATION OF SOFT BODIES IN INTERACTIVE SYSTEMS AND GAMES

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Project Introduction

- Interactive Game with Physically-based Interactive System
- ☐ Interactive System consists of Soft-Bodies & Rigid-Bodies
- Implementation of Forces applied on Soft-Bodies & Rigid-Bodies

Simulation Methods

- Verlet Integration [Advanced Character Physics T.J.]
- Rigid Body Simulation using Particles
- Collision Detection & Handling
- Soft-Body Simulation

MILESTONES – What we achieved

Project Goals

- Set up Basic Scene
- 2. Rigid-Body Implementation
- 3. Collision Handling for Rigid-Body
 - OBB vs OBB (90%)
 - OBB vs Sphere
 - Sphere vs Sphere
- 4. Soft-Body Implementation <
- Soft-Body Collision Handling
- 6. Interactivity

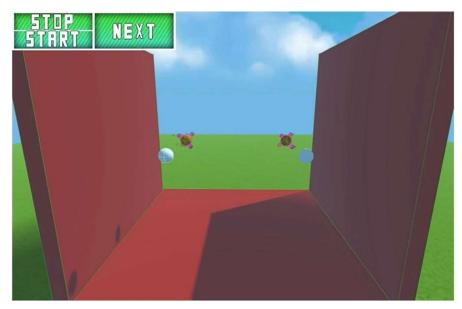
"Above and Beyond!": Additional Goals

- 1. Cloth Simulator
 - . Tool with parameter settings
 - II. Collisions with Spheres/Obb
- 2. Dynamic Octree (90%) 🔔
- Soft-Bodies of rigged and skinned meshes

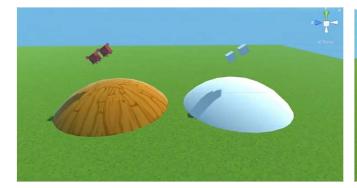
Sphere | Sphere

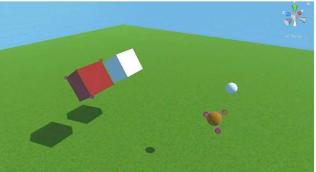
Sphere | OBB

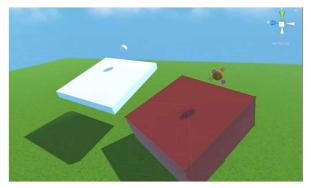
OBB | OBB

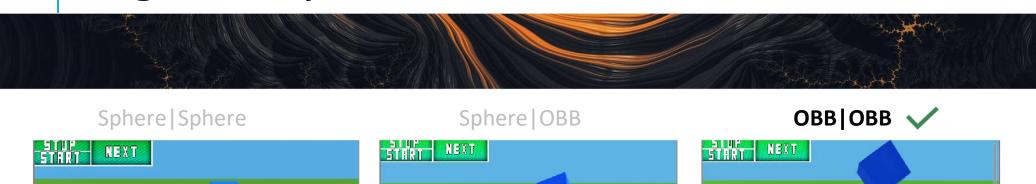


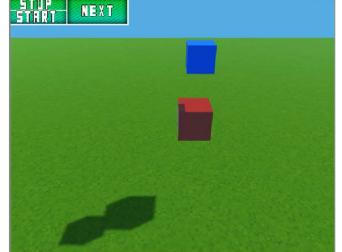


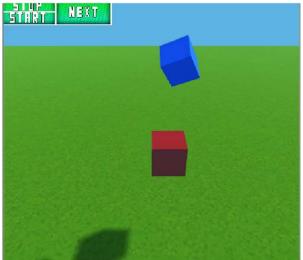


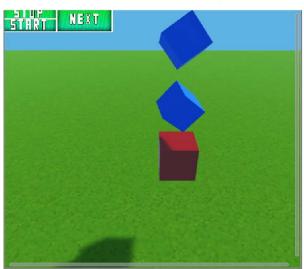




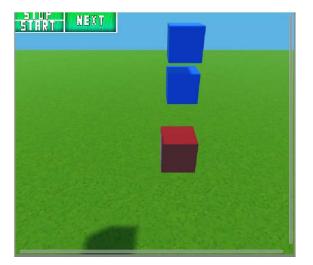




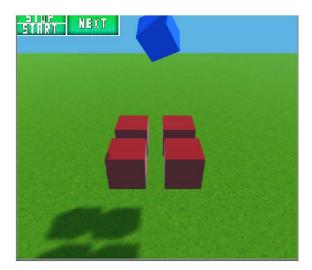




Sphere | Sphere

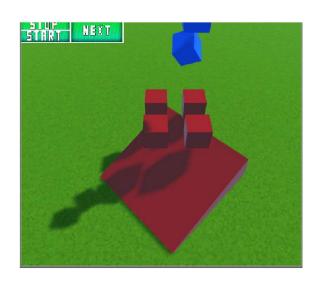


Sphere | OBB

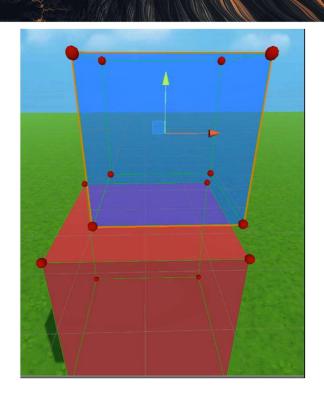


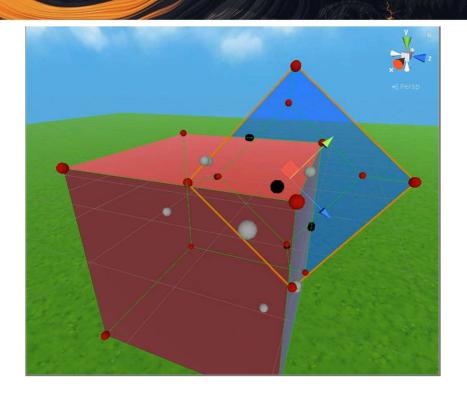
OBB OBB 🛕



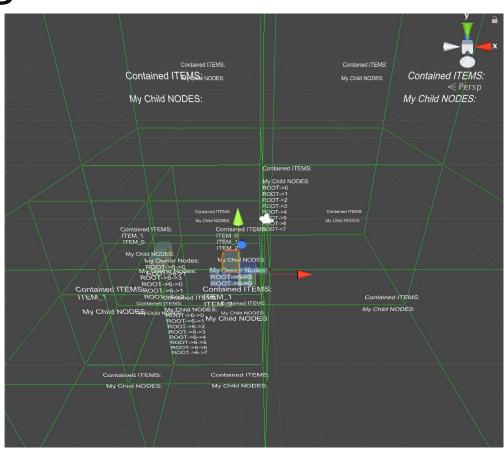


Challenges – OBB | OBB Collision



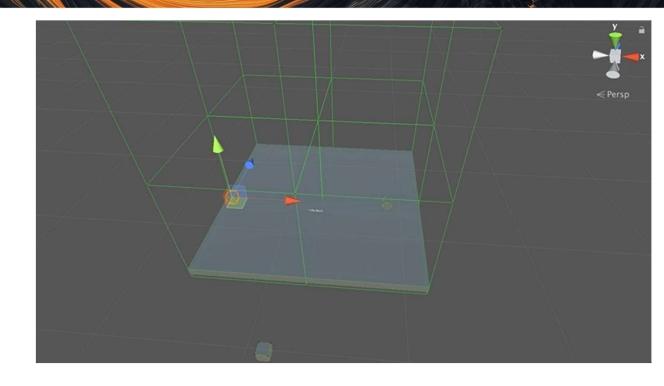


Challenges - Octree



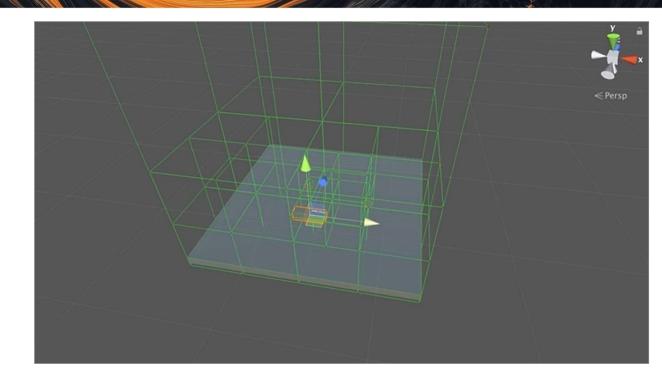
Challenges - Octree

Octree for collision detection

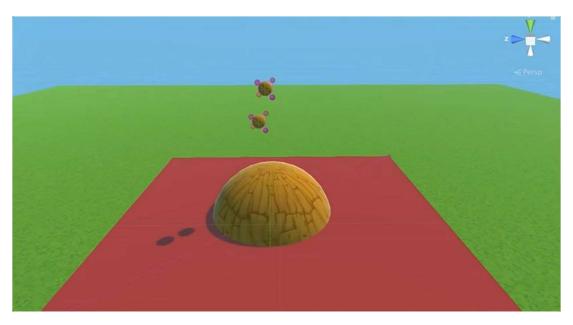


Challenges - Octree

Octree for collision detection

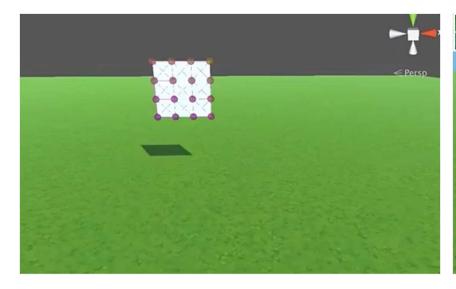


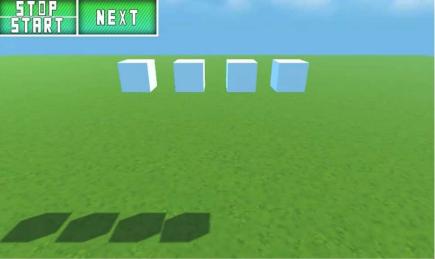




Soft Body

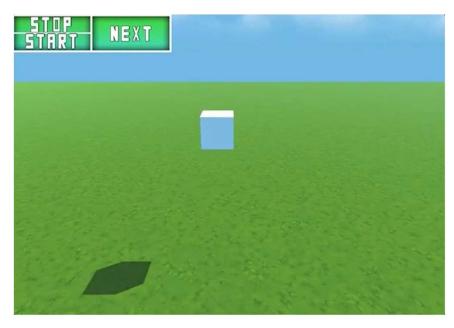
Constraint solver using mesh



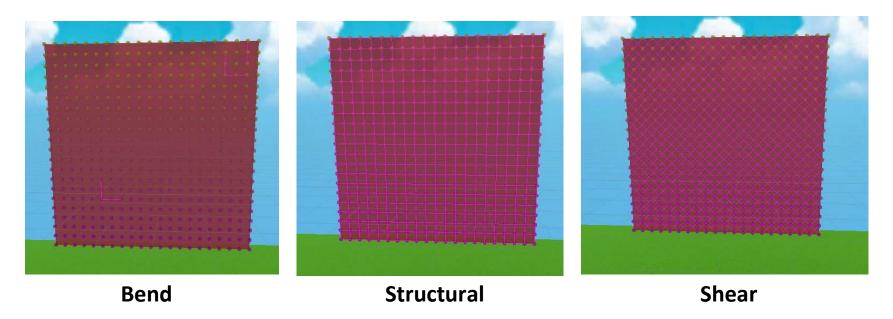


Soft Body

What we struggled with in the start

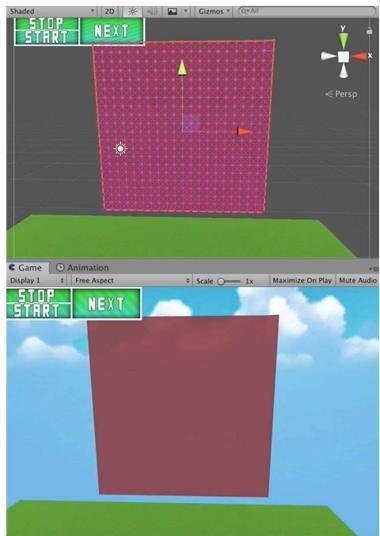


Composition/Construction





Only with shear and structural constraints

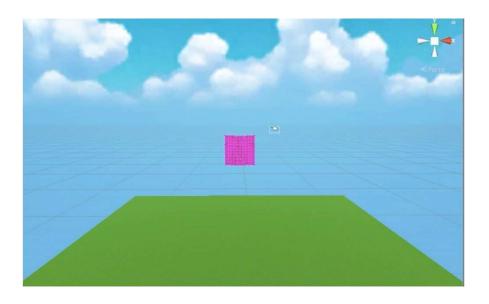


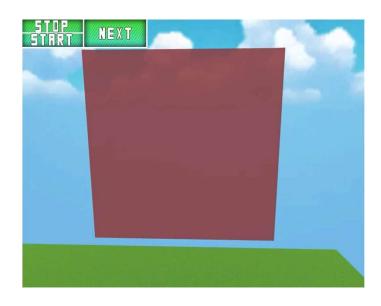


Collisions

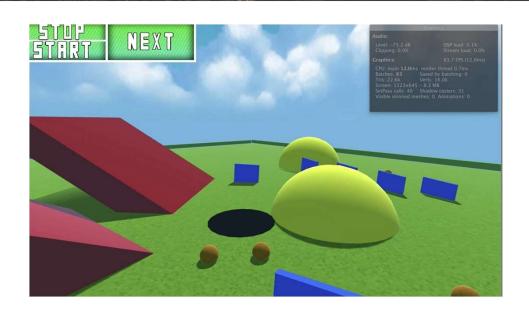








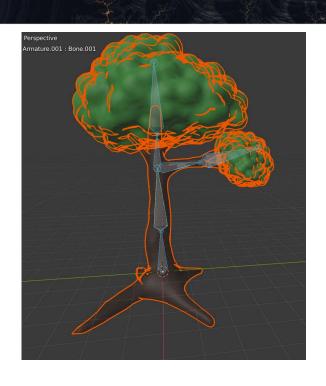
Interactivity



Softbodies of skinned meshes



Softbodies of skinned meshes





The Return of the Meatballs



THANKS!