## Lehrstuhl für STEUERUNGS-UND REGELUNGSTECHNIK

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# MACHINE LEARNING IN ROBOTICS

Exercises 5: PCA and LDA

#### Exercise 1

We have a mobile robot which has collected images of objects in its surrounding. The robot will use a clustering algorithm for performing groupng of similar images. Since the image data is high dimensional, a useful preprocessing step is to first project it into a lower dimension space before clustering. Now we have  $d \times n$  dimensional data X which has n samples of  $d \times 1$  dimensional vectors. These vectors correspond to image data and the dimension  $d \gg n$ . Now we are interested in calculating the principal components of this data. The principal components correspond to eigenvector of covariance matrix of C

$$C = \frac{1}{n-1} * X_c * X_c^{\mathsf{T}} \tag{1}$$

where  $X_c$  is obtained by subtracting the mean vector from X. Since for large values of d (for grayscale image of size  $640 \times 480$ , d = 307200), this computation can easily hang the onboard system.

A useful trick is to calculate the eigenvector of C1 which is  $n \times n$ 

$$C1 = \frac{1}{n-1} * X_c^{\top} * X_c \tag{2}$$

and now if v is an eigenvector of C1 with corresponding eigenvalue  $\lambda$  then  $v1 = X_c * v$  is an eigenvector of C with corresponding eigenvalue  $\lambda$ . Show that this claim is true.

### Exercise 2

Use proof by induction to show that the linear projection onto an M-dimensional subspace that maximizes the variance of the projected data is defined by the M eigenvectors of the data covariance matrix S, corresponding to the M largest eigenvalues.

#### Exercise 3

Calculate the LDA projection for the following dataset:

Class1 =  $\{(4,1), (2,4), (2,3), (3,6), (4,4)\}$  and Class2 =  $\{(9,10), (6,8), (9,5), (8,7), (10,8)\}$  and using 1-nerest neighbour classifier on the projected data, classify the new point (7,4).