## Lehrstuhl für STEUERUNGS-UND REGELUNGSTECHNIK

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# MACHINE LEARNING IN ROBOTICS

Exercises 6: Maximum Likelihood

#### Exercise 1

Show that the Maximum a posteriori (MAP) estimate becomes Maximum likelihood (ML) estimate if we assume uniform prior distribution for the parameters  $\theta$ .

## Exercise 2

Suppose that there is a box with three coins and the probability of head for each coin is  $P(H|c_1) = \frac{1}{3}$ ,  $P(H|c_2) = \frac{1}{2}$  and  $P(H|c_3) = \frac{2}{3}$ . One coin was picked at random and tossed 100 times. The result is 49 heads and 51 tails. Predict the coin.

### Exercise 3

The Poisson distribution is a discrete probability distribution that expresses the probability of a given number of events occurring in a fixed interval of time. The probability mass function is given by :  $P(X=k|\mu) = \frac{\mu^k e^{-\mu}}{k!} \text{ where } \mu>0.$ 

Now consider a factory in which a group of industrial robots are used for manufacturing the automobile parts. Sometimes the parts are found to be defective. The number of defective parts produced in n different months are given by  $X = x_1, x_2, \ldots, x_n$ , which are assumed to be i.i.d. poisson random variables.

- a) Use the samples to get a maximum likelihood estimate of  $\mu$ .
- b) For  $\mu = 10$ , find the probability of producing more than 4 defective parts in a month.