Lehrstuhl für STEUERUNGS-UND REGELUNGSTECHNIK

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MACHINE LEARNING IN ROBOTICS

Exercises: HMM

Exercise 1

Two HMMs with different structure are shown in Fig. 1.

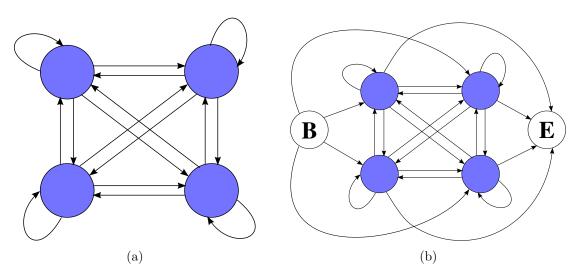


Figure 1: HMMs with different structures.

- a) Consider the HMM in Fig. 1(a). Show that the sum of the probability of all possible state sequences $Q = [q_1, \dots, q_L]$ of length L is equal to 1.
- b) Assume that the HMM has a begin (B) and an end (E) state, as in Fig. 1(b). The end state has probability ε . Show that the sum of the probability over all state sequences $\mathcal{Q} = [q_1, \dots, q_L]$ of length L (and properly terminating by making a transition to the end state) is $p = \varepsilon (1 \varepsilon)^{L-1}$. Use this result to show that the sum of the probability over all possible state sequences of any length is 1.

<u>Hint</u>: Use the result $\sum_{i=0}^{\infty} x^i = 1/(1-x)$ for 0 < x < 1.

Solution Exercise 1

a) The probability for a sequence $\mathcal{Q} = [q_1, \dots, q_L]$ with length L is

$$p(Q) = p(q_L|q_{L-1}, \dots, q_2|q_1, q_1) = p(q_L|q_{L-1})p(q_{L-1}|q_{L-2})\dots p(q_2|q_1)p(q_1)$$

The sum of the probability of all possible state sequences of length L is

$$\sum_{\forall \mathcal{Q}, L} p(\mathcal{Q}) = \sum_{q_1} \sum_{q_2} \cdots \sum_{q_L} p(q_L|q_{L-1}) p(q_{L-1}|q_{L-2}) \dots p(q_2|q_1) p(q_1)$$

where $\forall \mathcal{Q}, L$ indicates we are considering all the sequences of length L.

Note that, for a particular q_i , the sum of transition probability for all possible q_{i+1} is 1, i.e.

$$\sum_{q_L} p(q_L|q_{L-1}) = 1, \sum_{q_{L-1}} p(q_{L-1}|q_{L-2}) = 1, \cdots, \sum_{q_2} p(q_2|q_1) = 1$$

Then

$$\sum_{\forall \mathcal{Q}, L} p(\mathcal{Q}) = \sum_{q_1} \sum_{q_2} \cdots \sum_{q_L} p(q_L | q_{L-1}) p(q_{L-1} | q_{L-2}) \dots p(q_2 | q_1) p(q_1)$$
$$= \sum_{q_1} \sum_{q_2} p(q_2 | q_1) p(q_1) = \sum_{q_1} p(q_1) = 1$$

b) The sum of the probability of all possible state sequences of length L and terminating in E is

$$\sum_{\forall \mathcal{Q}, L} p(\mathcal{Q}) = \sum_{q_1} \sum_{q_2} \cdots \sum_{q_L} p(q_E|q_L) p(q_L|q_{L-1}) p(q_{L-1}|q_{L-2}) \dots p(q_1)$$

where $\forall \mathcal{Q}, L$ indicates we are considering all the sequences of length L.

Note that

$$\sum_{q_1} p(q_1) = 1$$
 and $p(q_E|q_L) = arepsilon$

and that, for a particular q_i , the sum of transition probability for all possible q_{i+1} (except for i+1=E) is $1-\varepsilon$, i.e.

$$\sum_{q_L} p(q_L|q_{L-1}) = 1 - \varepsilon, \sum_{q_{L-1}} p(q_{L-1}|q_{L-2}) = 1 - \varepsilon, \cdots, \sum_{q_2} p(q_2|q_1) = 1 - \varepsilon$$

Then

$$\sum_{\forall Q,L} p(Q) = \sum_{q_1} \sum_{q_2} \cdots \sum_{q_L} p(q_E|q_L) p(q_L|q_{L-1}) p(q_{L-1}|q_{L-2}) \dots p(q_1)$$

$$= \varepsilon \sum_{q_1} \sum_{q_2} \cdots \sum_{q_L} p(q_L|q_{L-1}) p(q_{L-1}|q_{L-2}) \dots p(q_1) = \varepsilon (1 - \varepsilon)^{L-1}$$

The sum of the probability over all possible state sequences of any length is

$$\sum_{\forall \mathcal{Q}} p(\mathcal{Q}) = \sum_{L=1}^{\infty} \sum_{\forall \mathcal{Q}, L} p(\mathcal{Q}) = \sum_{L=1}^{\infty} \varepsilon (1 - \varepsilon)^{L-1} = \varepsilon \sum_{L-1=0}^{\infty} (1 - \varepsilon)^{L-1} = \varepsilon \frac{1}{\varepsilon} = 1$$

Exercise 2

A Hidden Markov Model with 2 states $\{s_1 = H, s_2 = C\}$ and 3 possible observations based on the number of observed sizes $\{small, medium, large\}$ is given with transition probability matrix:

$$A = \left(\begin{array}{cc} 0.7 & 0.3\\ 0.4 & 0.6 \end{array}\right)$$

and observation matrix:

$$B = \left(\begin{array}{ccc} 0.1 & 0.4 & 0.5 \\ 0.7 & 0.2 & 0.1 \end{array}\right)$$

The prior probabilities of states are $\pi_1 = 0.6, \pi_2 = 0.4$.

- a) Compute the probability of the state sequence $\{q_1=H\ q_2=H\ q_3=C\ q_4=C\}.$
- b) Compute the probability $P(o_1 = S \ o_2 = M \ o_3 = S \ o_4 = L \mid q_1 = H \ q_2 = H \ q_3 = C \ q_4 = C)$.

Solution Exercise 2

- a) $P(q_1)P(q_2|q_1)P(q_3|q_2)P(q_4|q_3) = 0.6 * 0.7 * 0.3 * 0.6 = 0.0756.$
- b) Compute the probability $P(o_1|q_1)P(o_2|q_2)P(o_3|q_3)P(o_4|q_4) = 0.1*0.4*0.7*0.1 = 0.0028.$