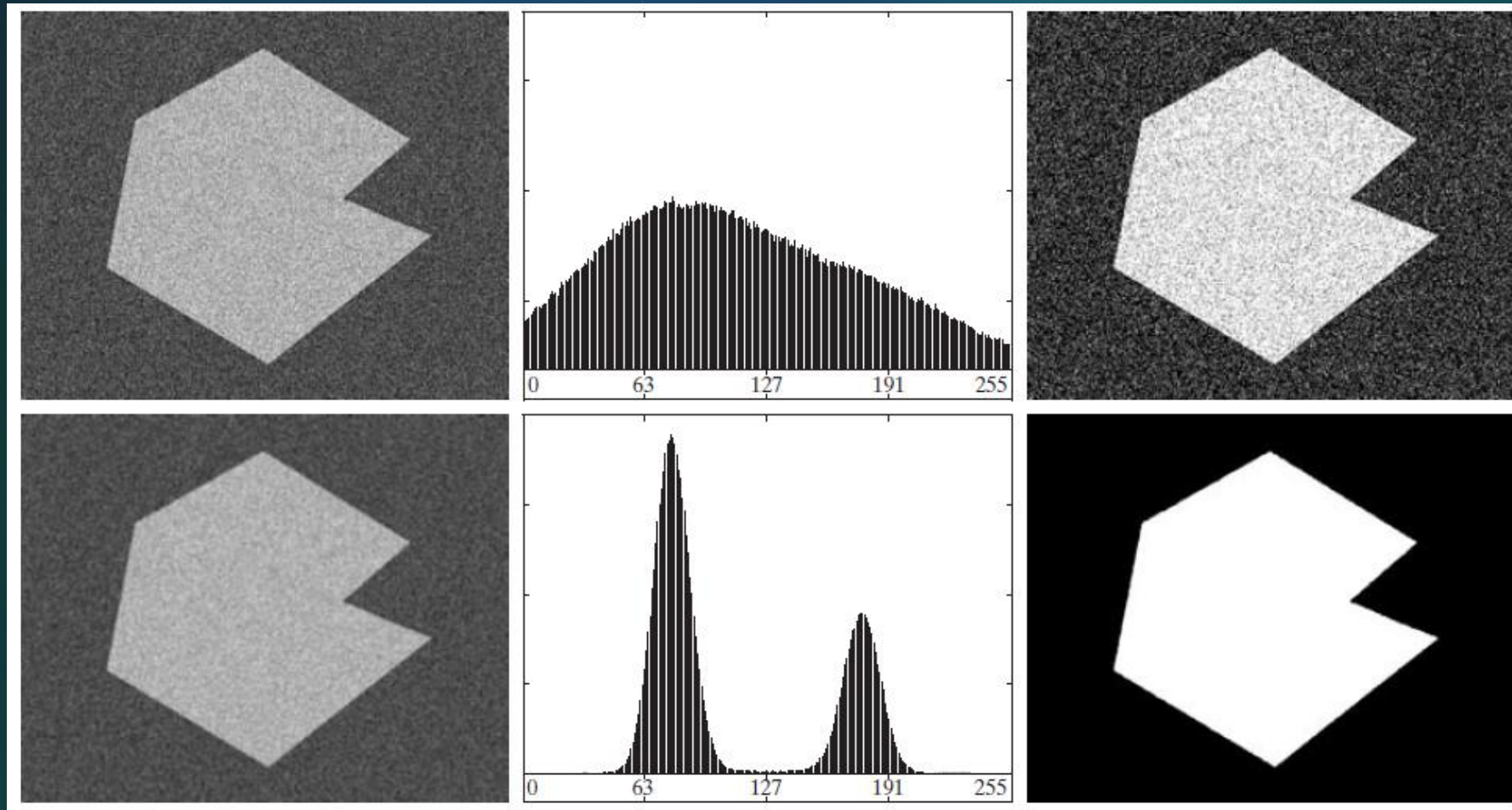


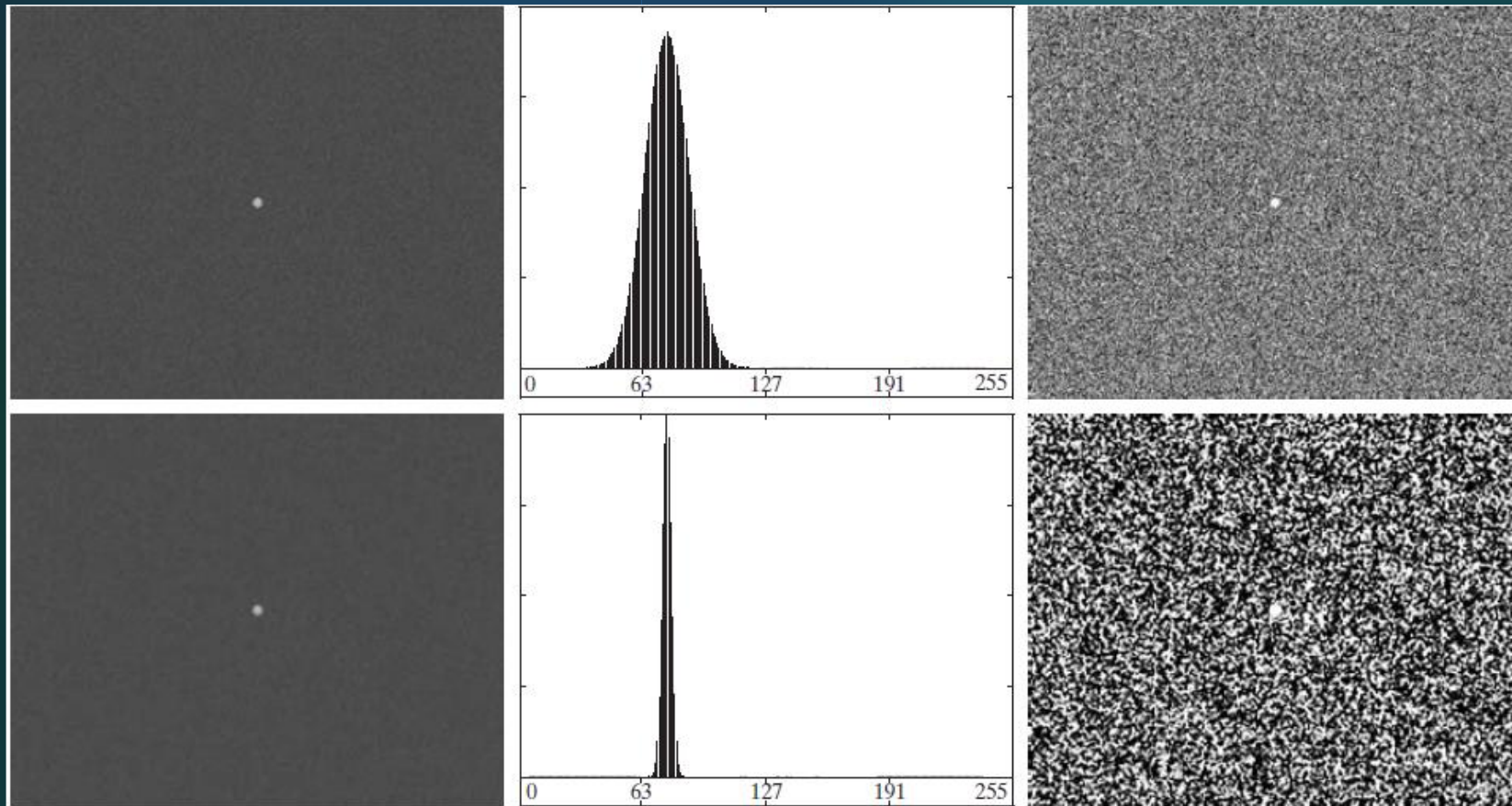
# Segmentation

IMAGE SMOOTHING & EDGES

# Noise & Filtering



# Effect of object/background size

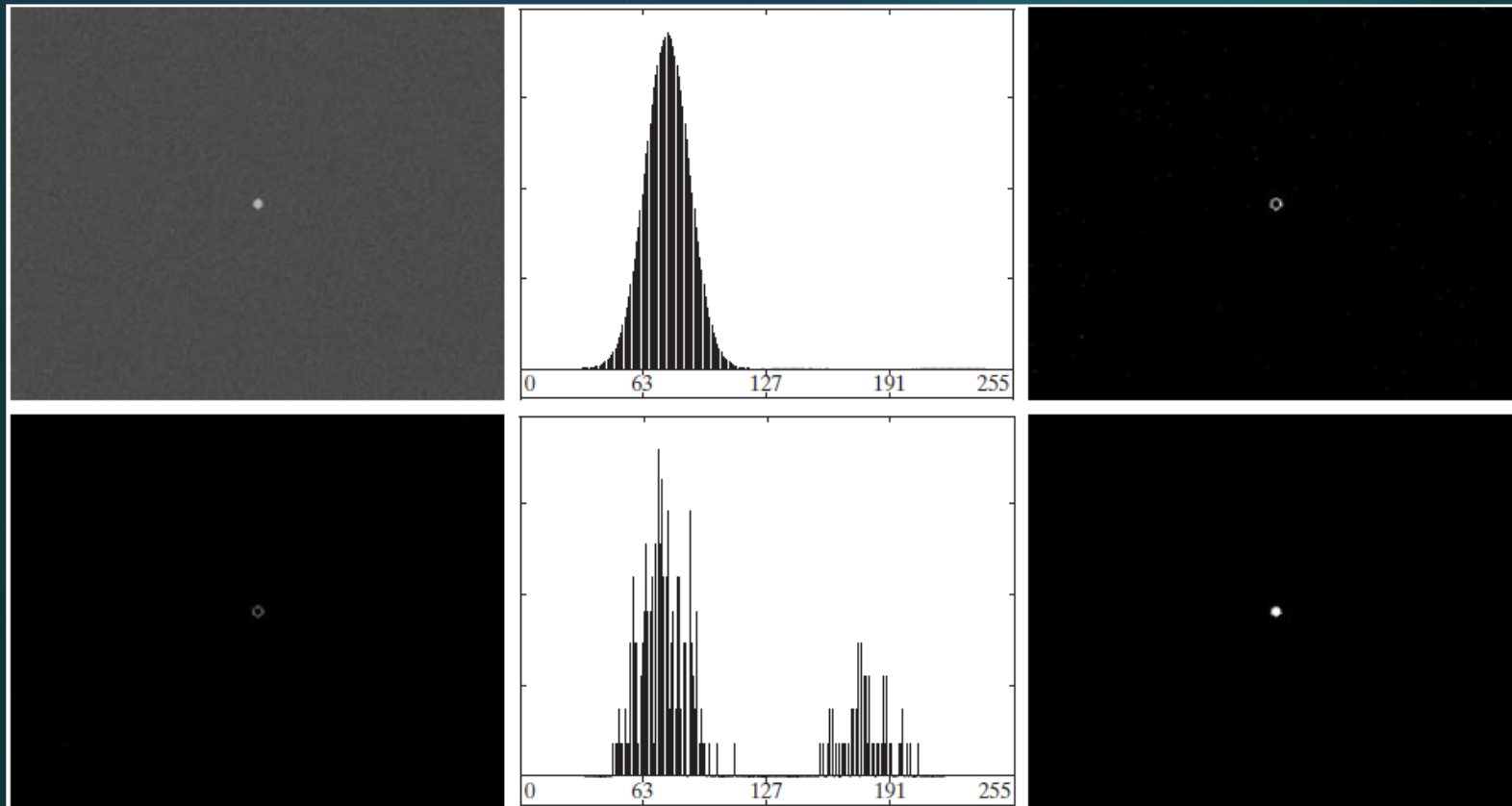


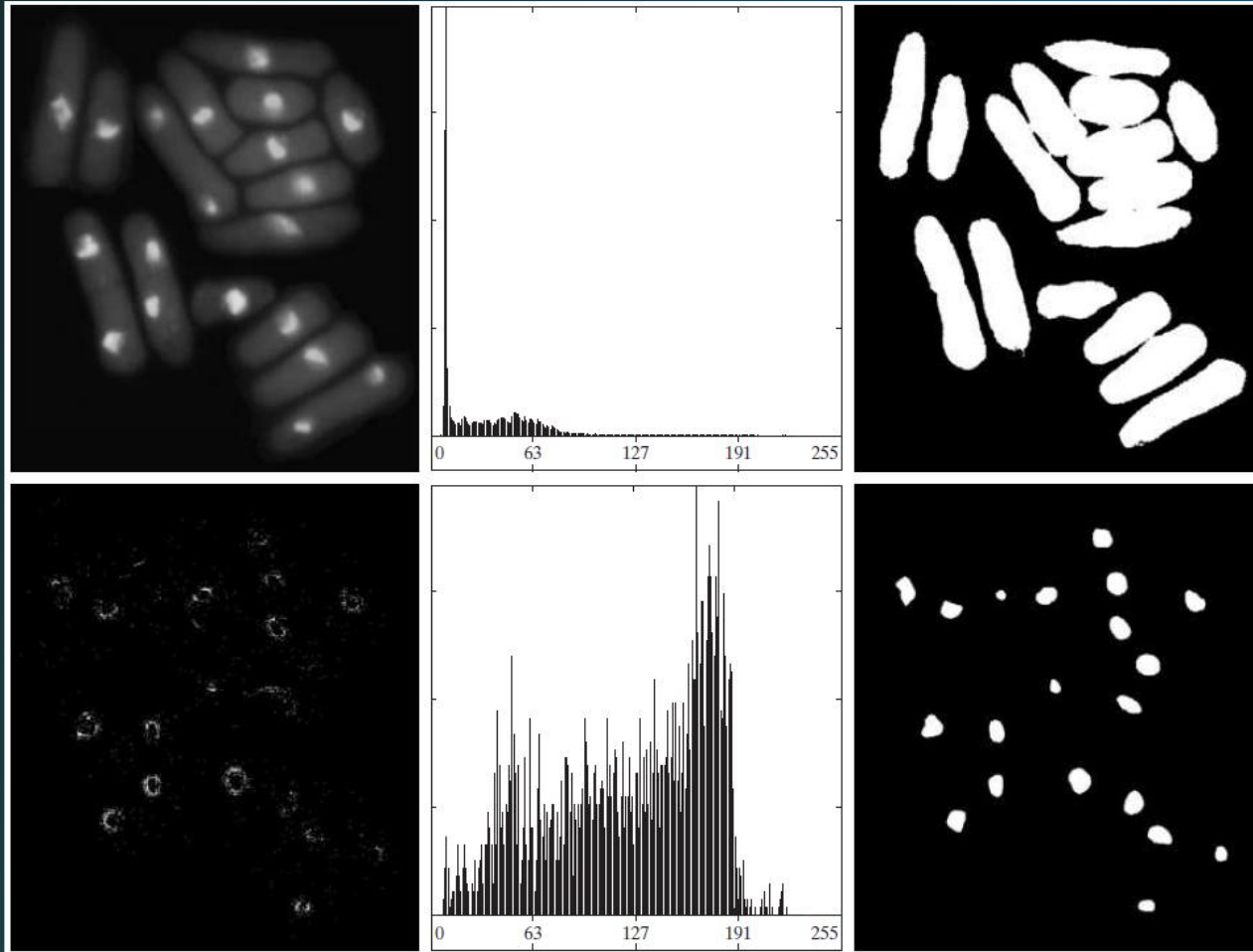


# Using Edges for Thresholding

- Gradient Magnitude
- Laplacian

# Using Edges for Thresholding (Gradient)





Using Edges  
for  
Thresholding  
(Laplacian)

# Algorithm (Edges for thresholding)

- Compute an edge image as either the magnitude of the Gradient, or absolute value of Laplacian, of  $f(x,y)$ .
- Specify a threshold value  $T$ .
- Threshold the image from step 1 using the threshold from step 2 to produce a binary image,  $g_T(x,y)$ . This image is used as a mask image in the following step to select pixels from  $f(x,y)$  corresponding to "strong" edge points.
- Compute a histogram using only the pixels in  $f(x,y)$  that correspond to the locations of the 1-valued pixels in  $g_T(x,y)$ .
- Use the histogram from step 4 to segment  $f(x,y)$  globally.