

Solving problems by
Searching

Problem Solving Agents





Agents

- Problem-solving agents: Atomic representation
- Planning agents: Factored or Structured representation

Problem-solving agents

- Goal formulation: Based on current situation and agent's performance measure.
 - Problem formulation: Process of deciding what actions and states to consider, given a goal
 - Search
 - Execution
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- Open loop system
 - Closed loop system

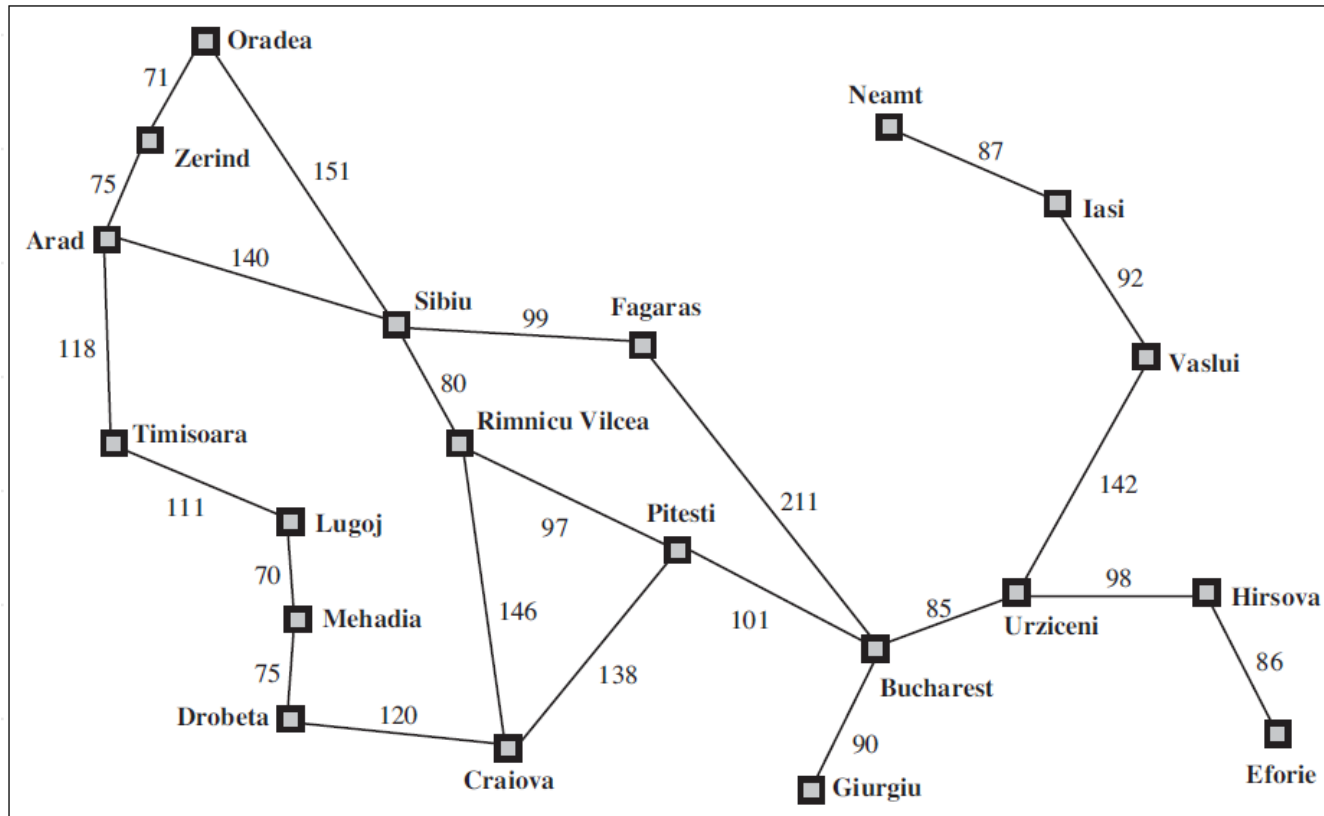



Figure 3.2 A simplified road map of part of Romania.



Formulate, Search, Execute design

```
function SIMPLE-PROBLEM-SOLVING-AGENT(percept) returns an action
  persistent: seq, an action sequence, initially empty
               state, some description of the current world state
               goal, a goal, initially null
               problem, a problem formulation

  state  $\leftarrow$  UPDATE-STATE(state, percept)
  if seq is empty then
    goal  $\leftarrow$  FORMULATE-GOAL(state)
    problem  $\leftarrow$  FORMULATE-PROBLEM(state, goal)
    seq  $\leftarrow$  SEARCH(problem)
    if seq = failure then return a null action
  action  $\leftarrow$  FIRST(seq)
  seq  $\leftarrow$  REST(seq)
  return action
```

Figure 3.1 A simple problem-solving agent. It first formulates a goal and a problem, searches for a sequence of actions that would solve the problem, and then executes the actions one at a time. When this is complete, it formulates another goal and starts over.

Search problems and solutions

- State space
- Initial state
- Goal state
- Actions $\text{ACTIONS (Arad)} = \{\text{Go(Sibiu)}; \text{Go(Timisoara)}; \text{Go(Zerind)}\}$
- Transition model $\text{RESULT(In(Arad), Go(Zerind))} = \text{In(Zerind)}$
- Action cost function (s, a, s')
- Path
- Solution (Optimal)

Graph (Map of Romania)

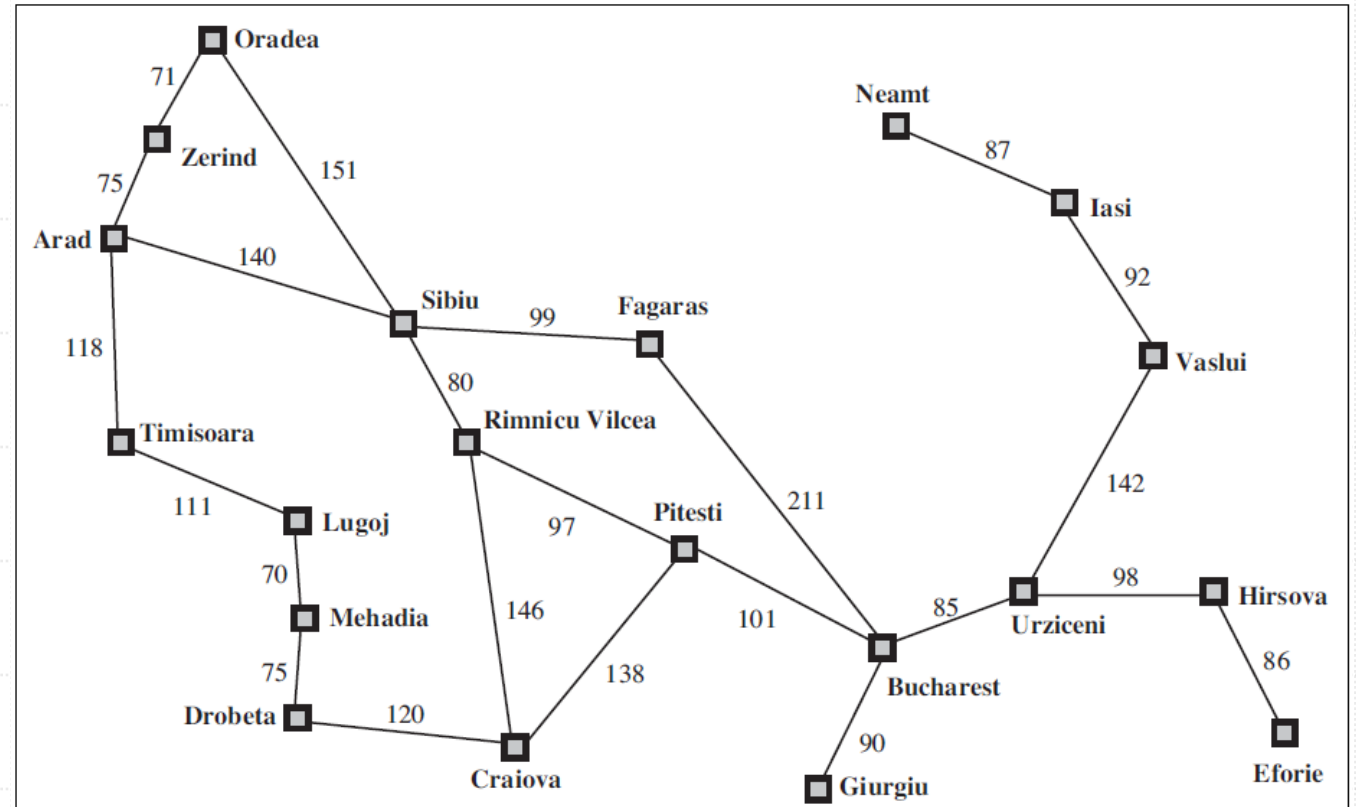


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Formulating problems

- Model
- Abstraction
- Level of Abstraction