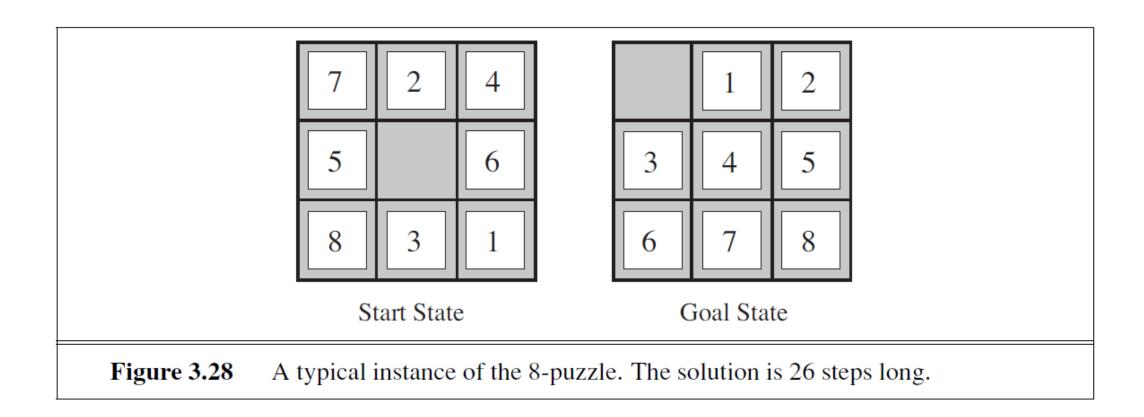
HEURISTIC FUNCTION



Heuristic Function



Heuristic Function

- Average solution cost is about 22 steps.
- Branching factor is about 3.
 - Empty tile is in the middle then four moves are possible.
 - Empty tile is on the edge then three moves are possible.
 - Empty tile is in the corner then two moves are possible.
- Exhaustive tree search of depth 22 will have about 3²² (b^d) nodes.
- Graph search will have about 9!/2 nodes.

Good heuristic function?

- A function that never overestimates the number of steps to the goal. This function can be used if we want to find shortest solution by applying A* search.
- h₁ = number of misplaced tiles.
- h_2 = the sum of the distances of the tiles from their goal positions.

- $h_1 = 8$
- $h_2 = 18$
- True solution cost = 26

Effect of heuristic accuracy on performance

- Effective branching factor b*
- If the total number of nodes generated by A* for a particular problem is N
- Solution depth is d
- b* is the branching factor that a uniform tree of depth d would have to have in order to contain N+1 nodes.

$$N + 1 = 1 + b^* + (b^*)^2 + ... + (b^*)^d$$

- Consider d = 5 & N = 52 then b* = ?
- $-b^* = 1.92$
- Well defined heuristic would have b* close to 1.

Effect of heuristic accuracy on performance

	Search Cost (nodes generated)			Effective Branching Factor		
d	IDS	$A^*(h_1)$	$A^*(h_2)$	IDS	$A^*(h_1)$	$A^*(h_2)$
2	10	6	6	2.45	1.79	1.79
4	112	13	12	2.87	1.48	1.45
6	680	20	18	2.73	1.34	1.30
8	6384	39	25	2.80	1.33	1.24
10	47127	93	39	2.79	1.38	1.22
12	3644035	227	73	2.78	1.42	1.24
14	_	539	113	_	1.44	1.23
16	_	1301	211	_	1.45	1.25
18	_	3056	363	_	1.46	1.26
20	_	7276	676	_	1.47	1.27
22	_	18094	1219	_	1.48	1.28
24	_	39135	1641	_	1.48	1.26

Figure 3.29 Comparison of the search costs and effective branching factors for the ITERATIVE-DEEPENING-SEARCH and A* algorithms with h_1 , h_2 . Data are averaged over 100 instances of the 8-puzzle for each of various solution lengths d.

How to generate heuristic function?

- 1. Admissible heuristics from relaxed problems
- 2. Admissible heuristics from subproblems
- 3. Learning heuristics from experience

Admissible heuristics from relaxed problems

- A tile can move from square A to square B if
 - A is horizontally or vertically adjacent to B and B is blank.
- Relaxed problems
 - A tile can move from square A to square B if A is adjacent to B.
 - A tile can move from square A to square B if B is blank.
 - A tile can move from square A to square B.
 - $h(n) = max\{h_1(n), ..., h_m(n)\}$

Admissible heuristics from subproblems: Pattern database

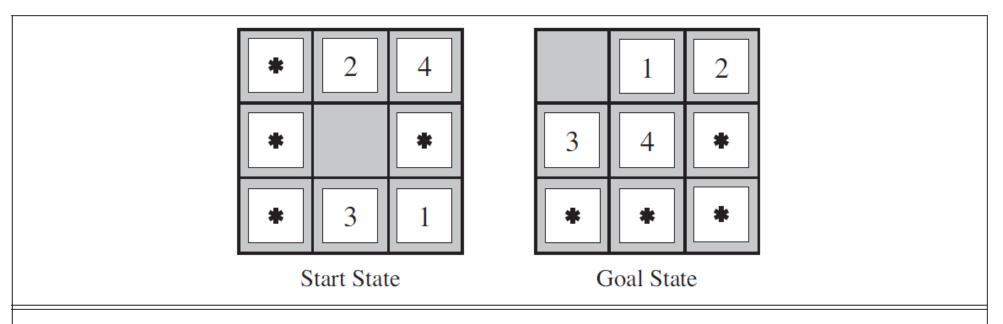


Figure 3.30 A subproblem of the 8-puzzle instance given in Figure 3.28. The task is to get tiles 1, 2, 3, and 4 into their correct positions, without worrying about what happens to the other tiles.

Learning heuristics from experience

- Solve lots of problems and learn from experience.
- Identify features
 - One feature learning: Number of misplaced tiles!
 - Two features learning:
 - Number of misplaced tiles!
 - Number of pairs of adjacent tiles that are nor adjacent in the goal state

$$h(n) = c_1 x_1(n) + c_2 x_2(n)$$