MEMORY BOUNDED HEURISTIC SEARCH

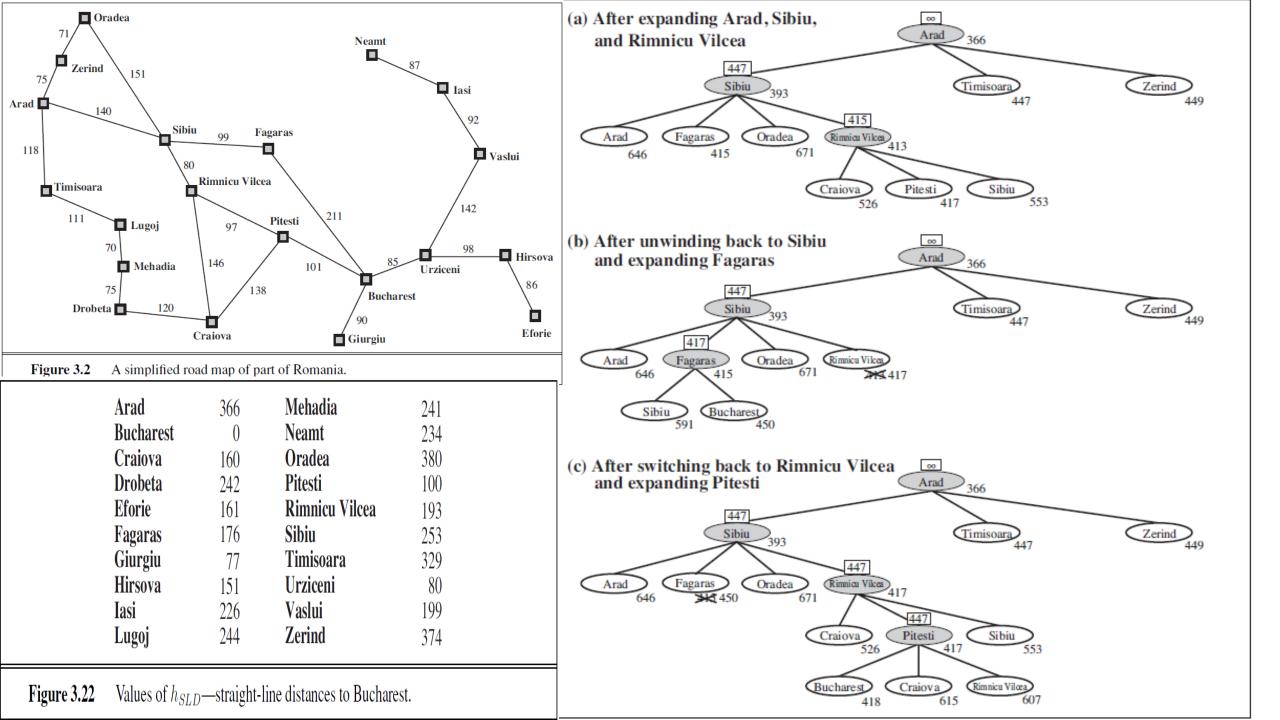


ITERATIVE-DEEPENING A* (IDA*)

• Cutoff = f = cost(g+h)

RECURSIVE BEST-FIRST SEARCH (RBFS)

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function RECURSIVE-BEST-FIRST-SEARCH(problem) returns a solution or failure
   solution, fvalue \leftarrow RBFS(problem, NODE(problem.INITIAL), \infty)
 return solution
function RBFS(problem, node, f_limit) returns a solution or failure, and a new f-cost limit
  if problem.Is-GOAL(node.STATE) then return node
  successors \leftarrow LIST(EXPAND(node))
  if successors is empty then return failure, ∞
  for each s in successors do // update f with value from previous search
      s.f \leftarrow \max(s.PATH-COST + h(s), node.f))
  while true do
      best \leftarrow the node in successors with lowest f-value
      if best. f > f\_limit then return failure, best. f
      alternative \leftarrow the second-lowest f-value among successors
      result, best. f \leftarrow RBFS(problem, best, min(f\_limit, alternative))
      if result \neq failure then return result, best. f
```



IDA* AND RBFS: CHALLENGES

- Low amount of memory utilization
- Forgets all previously expanded paths
- Exponential increase in complexity associated with redundant paths
- Solutions:
- Memory-bounded A*
- 2. Simplified MA*