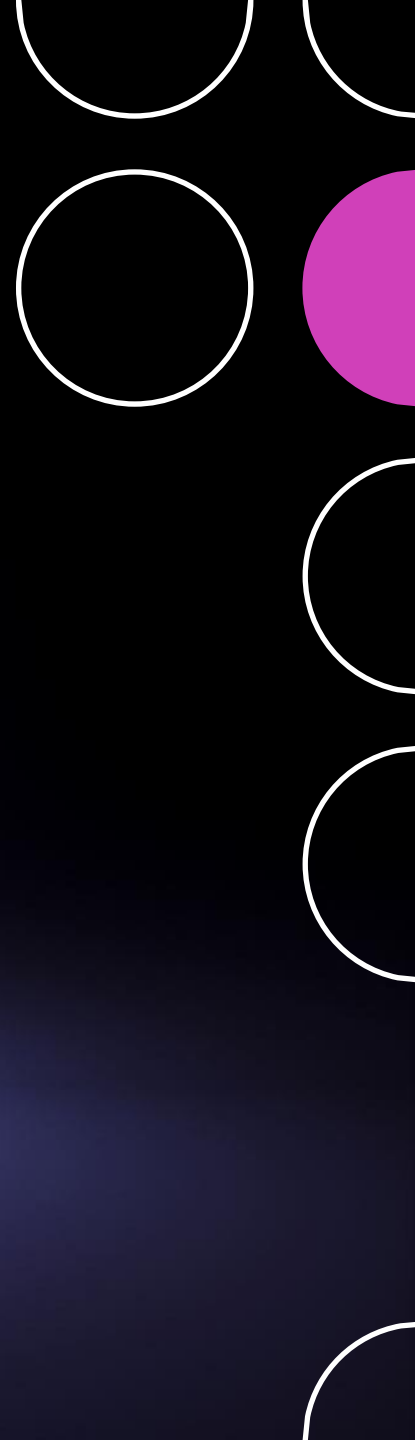


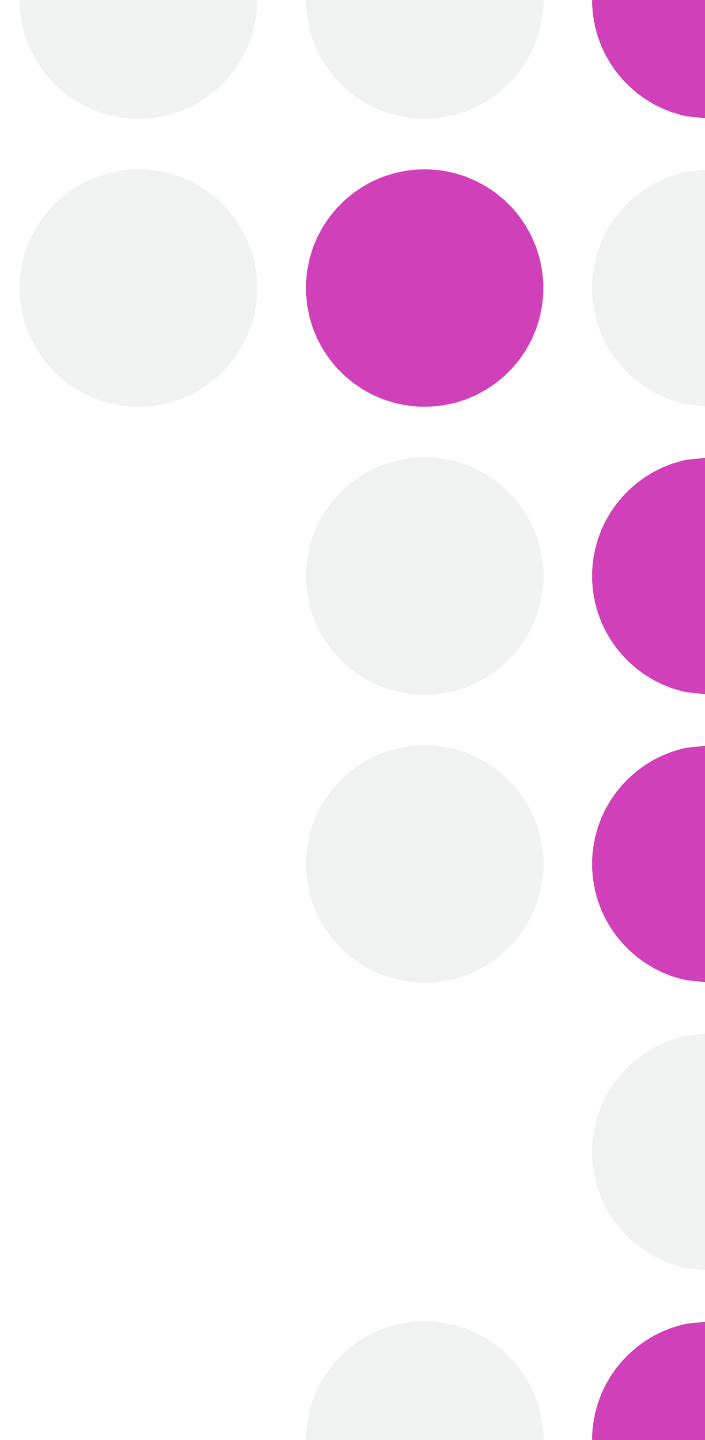
Segmentation as Clustering

K-Means Clustering



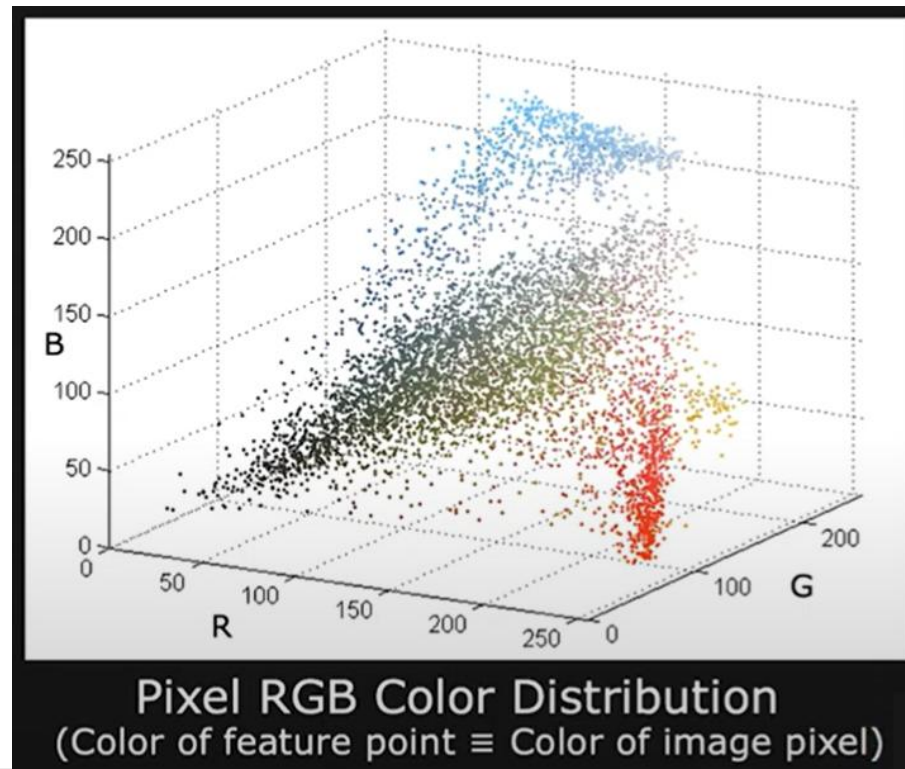
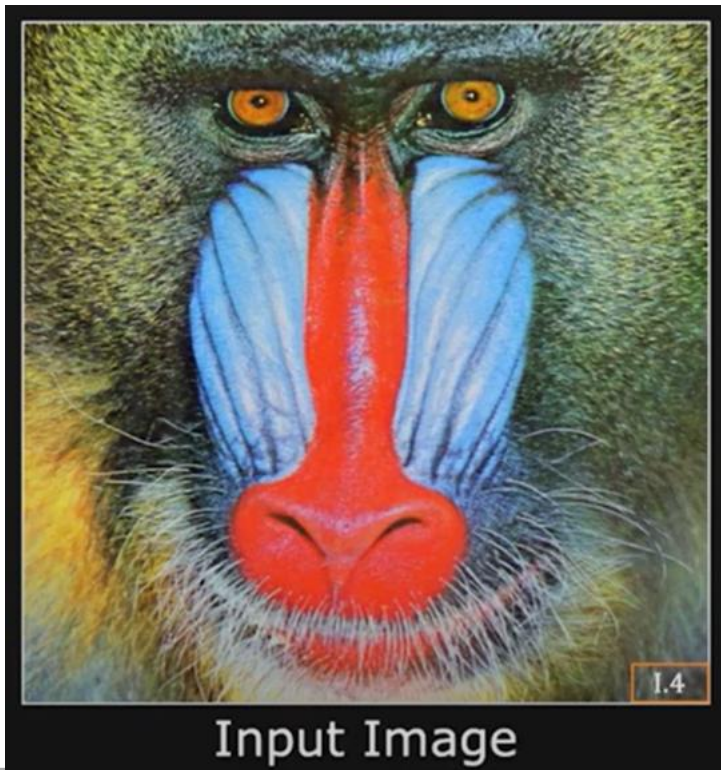
Visual Similarity

- Intensity
 - Color
 - Position
 - Depth
 - Motion
 - Texture etc.
-



Pixels in Euclidean Space

- Euclidean Space: Generalization of 3D Cartesian space to higher dimensions.



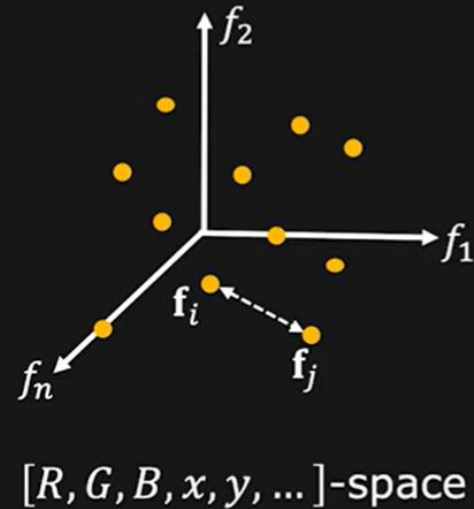
Pixels as feature vector: $[R, G, B, x, y, d, \dots]$

Pixel Similarity

Let i and j be two pixels whose features are \mathbf{f}_i and \mathbf{f}_j .

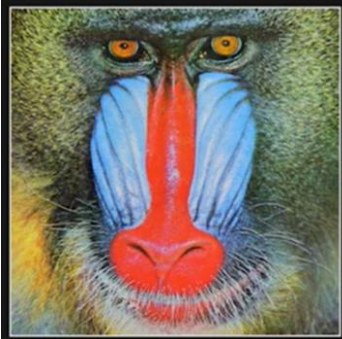
\mathcal{L}^2 Distance between \mathbf{f}_i and \mathbf{f}_j :

$$\mathcal{L}_2(\mathbf{f}_i, \mathbf{f}_j) = \sqrt{\sum_k (f_{ik} - f_{jk})^2}$$

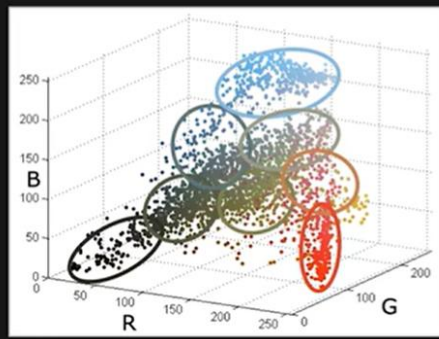


Smaller the Distance, Greater the Similarity

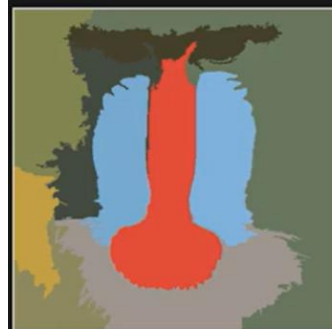
Clustering Similar Pixels



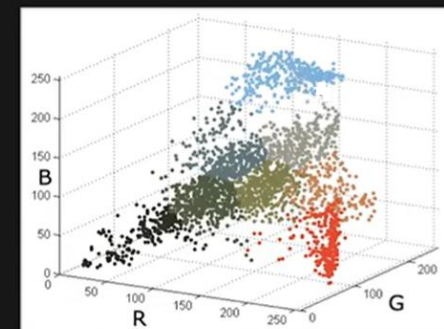
Input Image



Pixel RGB Color Distribution
(Color of feature point \equiv Color of image pixel)



Segmented Image



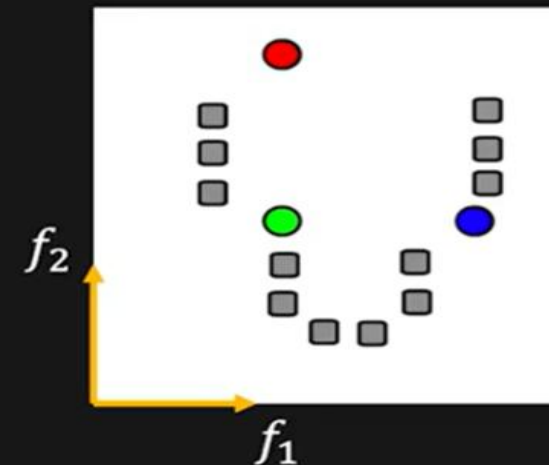
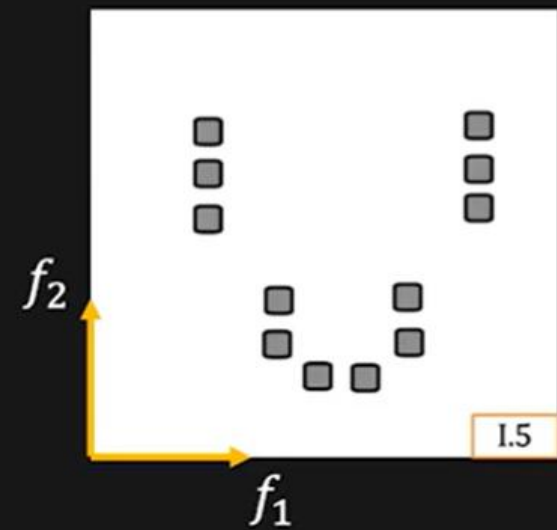
Color-Coded Clusters
(Color of feature point \equiv Color of image segment)

3-Means Clustering

Problem: Segment the given pixel feature distribution into 3 clusters.

Solution:

Step 1: Randomly generate the initial centroids (**means**) of the 3 clusters.

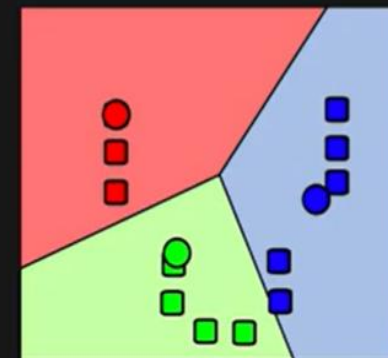
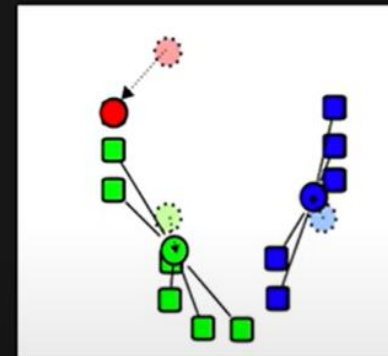
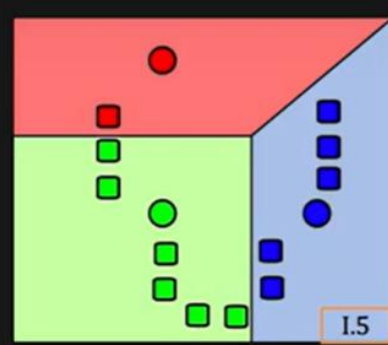


3-Means Clustering

Step 2: Create 3 clusters by assigning each feature point to the nearest mean.

Step 3: Recompute the mean of each cluster.

Step 4: Repeat steps 2 and 3 until convergence.



K-Means Clustering

Given: Image with N pixels and number of clusters k .

Task: Find the k clusters.

Clustering:

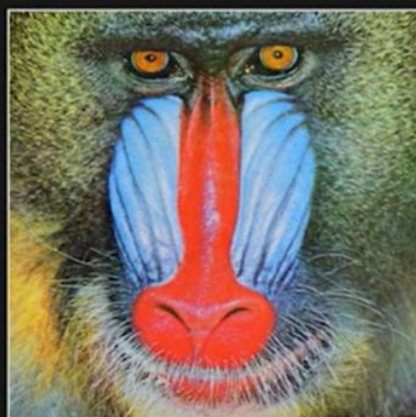
- 1: Pick k points randomly as the initial centroids (means) $\{\mathbf{m}_1, \mathbf{m}_2, \dots, \mathbf{m}_k\}$ of the k clusters in feature space.
- 2: For each pixel \mathbf{x}_j find nearest cluster mean \mathbf{m}_i to pixel's feature \mathbf{f}_j and assign pixel to cluster i .
- 3: Recompute mean for each cluster using its assigned pixels.
- 4: If changes in all k means is less than a threshold ε , stop. Else go to step 2.

K-Means Initialization methods

- Method 1: Select k random feature points as initial centroids. If two points are very close, resample.
 - Method 2: Select k uniformly distributed means within the range of distribution.
 - Method 3: Perform k -means clustering on a subset of pixels and use the result as the initial means.
-



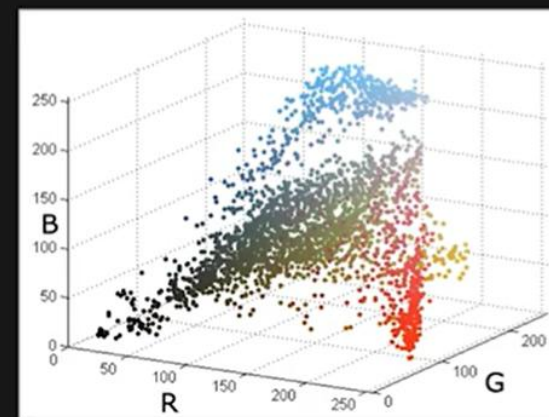
K-Means Clustering Results ($k=2$)



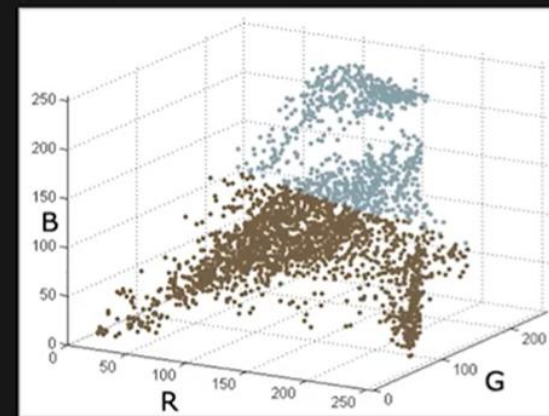
Input Image



Segmented Image
($k = 2$; $\{R, G, B\}$ -space)

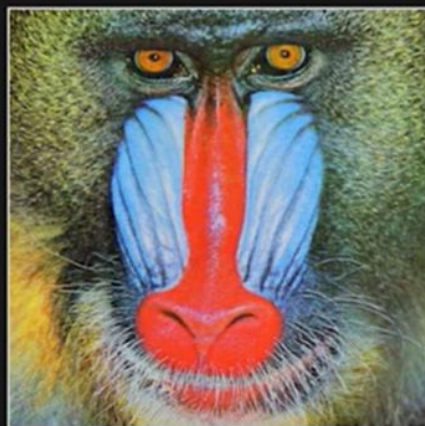


Pixel RGB Color Distribution
(Color of feature point \equiv Color of image pixel)

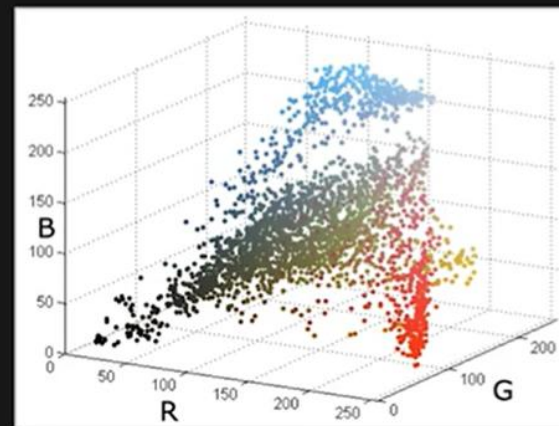


Color-coded Clusters
(Color of feature point \equiv Color of image segment)

K-Means Clustering Results ($k=8$)



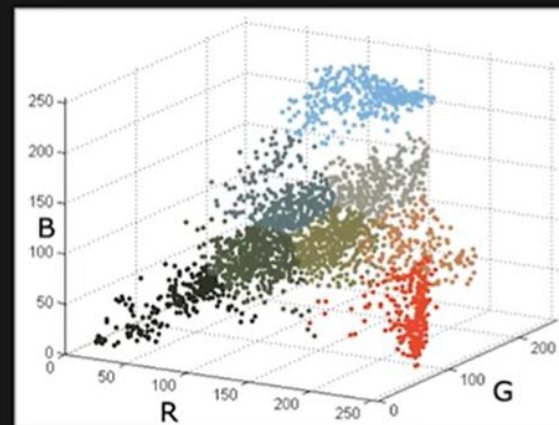
Input Image



Pixel RGB Color Distribution
(Color of feature point \equiv Color of image pixel)



Segmented Image
($k = 8$; $\{R, G, B\}$ -space)

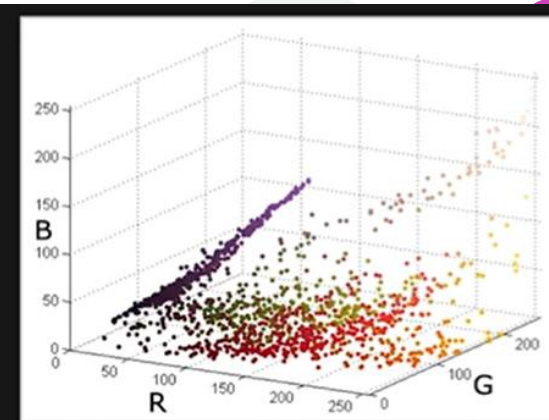


Color-coded Clusters
(Color of feature point \equiv Color of image segment)

K-Means Clustering Results ($k=16$)



Input Image



Pixel RGB Color Distribution



Segmented Image
($k = 16$; $\{R, G, B\}$ -space)



Segmented Image
($k = 16$; $\{R, G, B, x, y\}$ -space)

Note: Disjoint regions could belong to a single cluster.

K-Means Clustering: Remarks

- Simple and reasonably fast
 - Need to pick the number of clusters k
 - Sensitive to initialization
 - Sensitive to outliers
-

