

## Recitation 8 – Joint stationarity, Power Spectral Density

### Joint stationarity:

Two random processes  $X(t), Y(t)$  are called **jointly strict sense stationary** (JSSS) iff for all values of  $n$ , any deterministic time series  $t_1, \dots, t_n$  and any constant  $\tau$ , the two following random vectors have the same distribution:

$$\begin{aligned} & [X(t_1), Y(t_1) \cdots, X(t_n), Y(t_n)] \\ & [X(t_1 + \tau), Y(t_1 + \tau) \cdots, X(t_n + \tau), Y(t_n + \tau)] \end{aligned}$$

Two random processes  $X(t), Y(t)$  are called **jointly wide sense stationary** (JWSS) iff the following conditions are met:

- $X(t)$  and  $Y(t)$  are both WSS
- The cross-correlation function of  $X(t), Y(t)$  depends only on time difference

$$R_{XY}(t_1, t_2) = E(X(t_1)Y(t_2)) = R_{XY}(t_1 - t_2)$$

### Properties:

- if  $X(t), Y(t)$  are two independent SSS processes they are also JSSS.
- if  $X(t), Y(t)$  are two independent WSS processes they are also JWSS.
- if  $X(t), Y(t)$  are two JSSS processes they are also JWSS.
- if  $X(t), Y(t)$  are two **jointly Gaussian** JWSS processes they are also JSSS.

### Problem 1:

Let  $X$  and  $Y$  be i.i.d random variables, such that  $X, Y \sim N(0, \sigma^2)$ .

Let us define the following random process:

$$\begin{aligned} Z(t) &= X \cdot \cos(4t) + Y \cdot \sin(4t) \\ A(t) &= X \cdot \cos(4t) \end{aligned}$$

1. Find the expectation function and the auto-covariance function of the processes  $A(t), Z(t)$ .
2. Are  $A(t), Z(t)$  Gaussian random processes?
3. Are  $A(t), Z(t)$  **jointly** Gaussian random processes?
4. Calculate the optimal MMSE estimator of the random variable  $X$  given only the sample  $Z(t_0)$ , and the respective MSE.

5. Calculate the optimal MMSE estimator of the random variable  $X$  given  $\{Z(t)\}_{t=-\infty}^{t=\infty}$  and the respective MSE.
6. For each of the processes  $A(t), Z(t)$  determined whether they are stationary. If so, in what sense?

**Solution:**

1.

$$\eta_Z(t) = E\{X \cdot \cos(4t) + Y \cdot \sin(4t)\} = 0$$

$$\begin{aligned} R_Z(t_1, t_2) &= E\{(X \cdot \cos(4t_1) + Y \cdot \sin(4t_1)) \cdot (X \cdot \cos(4t_2) + Y \cdot \sin(4t_2))\} = \\ &= \sigma^2 \cos(4t_1) \cos(4t_2) + E\{X \cdot Y\} \cdot (\cos(4t_1) \cdot \sin(4t_2) + \cos(4t_2) \cdot \sin(4t_1)) + \sigma^2 \sin(4t_1) \sin(4t_2) = \\ &= \sigma^2 \cos(4t_1) \cos(4t_2) + \sigma^2 \sin(4t_1) \sin(4t_2) = \sigma^2 \cos(4(t_1 - t_2)) \end{aligned}$$

$$\eta_A(t) = E\{X \cdot \cos(4t_1)\} = 0$$

$$R_A(t_1, t_2) = E\{X \cdot \cos(4t_1) \cdot X \cdot \cos(4t_2)\} = E\{X^2\} \cdot \cos(4t_1) \cdot \cos(4t_2) = \sigma^2 \cos(4t_1) \cos(4t_2)$$

2. The pair of variables  $(X, Y)$  are jointly Gaussian. For any time series  $t_1, \dots, t_n$ , the vector  $[Z(t_1), \dots, Z(t_n)]$  constitutes a linear transformation of  $(X, Y)$ :

$$\begin{bmatrix} Z(t_1) \\ \vdots \\ Z(t_n) \end{bmatrix} = \begin{bmatrix} \cos(4t_1) & \sin(4t_1) \\ \vdots & \vdots \\ \cos(4t_n) & \sin(4t_n) \end{bmatrix} \begin{bmatrix} X \\ Y \end{bmatrix}$$

Therefore, the variables  $[Z(t_1), \dots, Z(t_n)]$  are jointly Gaussian – namely,  $Z(t)$  is a Gaussian random process. The same goes for  $A(t)$ .

3. Both of the processes are jointly Gaussian – since the set of variables  $[Z(t_1), \dots, Z(t_n), A(t_1), \dots, A(t_n)]$  constitute a linear transformation of  $(X, Y)$ , and, thus, they are jointly Gaussian.

4. The pair of variables  $(X, Z(t_0))$  are jointly Gaussian, therefore the optimal MMSE estimator is the optimal linear estimator:

$$\hat{X}_{MMSE}(Z(t_0)) = E(X) + \frac{\text{Cov}(X, Z(t_0))}{\text{Var}(Z(t_0))} [Z(t_0) - E(Z(t_0))] = \frac{\text{Cov}(X, Z(t_0))}{\text{Var}(Z(t_0))} Z(t_0)$$

It holds that:

$$\text{cov}(X, Z(t_0)) = \text{cov}(X, X \cdot \cos(4t_0) + Y \cdot \sin(4t_0)) = \sigma^2 \cos(4t_0)$$

$$\text{var}(Z(t_0)) = \text{var}(X \cdot \cos(4t_0) + Y \cdot \sin(4t_0)) = \sigma^2 \cos^2(4t_0) + \sigma^2 \sin^2(4t_0) = \sigma^2$$

Thus:

$$\hat{X}_{MMSE}(Z(t_0)) = \cos(4t_0)Z(t_0)$$

$$MSE = \text{Var}(X) - \text{Var}(\hat{X}_{MMSE}) = \sigma^2 - \cos^2(4t_0)\text{Var}(Z(t_0)) = \sigma^2 - \cos^2(4t_0)\sigma^2 = \sigma^2 \sin^2(4t_0)$$

5. Now all the measurements  $\{Z(t)\}_{t \in R}$  are given, and, in particular,  $Z(0)$  is also given. Therefore, based on section 4, we can estimate  $X$  with no error whatsoever:

$$\begin{aligned}\hat{X}_{MMSE} &= Z(0) = X \\ \text{MSE} &= 0\end{aligned}$$

6.  $A(t)$  is not WSS since its auto-correlation function does not depend only on the time difference:

$$R_A(t_1, t_2) = \sigma^2 \cos(4t_1) \cos(4t_2)$$

So, for example:

$$R_A(0, \pi) \neq R_A(0 + \frac{\pi}{2}, \pi + \frac{\pi}{2})$$

Obviously, it is not SSS as well.

$Z(t)$  is WSS since its expectation function is constant **and** its auto-correlation function depends only on the time difference:

$$\eta_Z(t) = 0$$

$$R_Z(t_1, t_2) = \sigma^2 \cos(4(t_1 - t_2))$$

Since it is a Gaussian random process, it is also SSS.

## **Power Spectral Density of a WSS Random Process**

The Power Spectral Density (PSD) of a WSS random process is defined as:

$$S_{XX}(\omega) = \int_{-\infty}^{+\infty} R_{XX}(\tau) e^{-j\omega\tau} d\tau$$

### **Properties of the Power Spectral Density:**

- Deterministic function
- Real and even function
- $\forall \omega \ S_X(\omega) \geq 0$
- Inverse Fourier transform:

$$R_{XX}(\tau) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} S_{XX}(\omega) e^{j\omega\tau} d\omega$$

Thus:

$$E\{X^2(t)\} = R_{XX}(0) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} S_{XX}(\omega) d\omega$$

- The PSD is a measure of the second order statistics of the random process. Thus, it is possible for two different random processes to have the same PSD.

### **Definition of Cross-Spectral Density:**

For  $X(t), Y(t)$  two real JWSS random processes, the cross-spectral density  $S_{XY}(\omega)$  is defined as:

$$R_{XY}(\tau) \xleftrightarrow{FT} S_{XY}(\omega)$$
$$S_{XY}(\omega) = \int_{-\infty}^{\infty} R_{XY}(\tau) e^{-j\omega\tau} d\tau$$

### **Properties of the Cross-Spectrum:**

- Deterministic function
- Not necessarily real
- The symmetric conjugate property:  $S_{XY}(\omega) = S_{XY}^*(-\omega)$

Proof:

$$S_{XY}(\omega) = \int_{-\infty}^{+\infty} R_{XY}(\tau) e^{-j\omega\tau} d\tau = \overline{\int_{-\infty}^{+\infty} R_{XY}(\tau) e^{-j\omega\tau} d\tau} = \int_{-\infty}^{+\infty} R_{XY}(\tau) e^{-j(-\omega)\tau} d\tau = S_{XY}^*(-\omega)$$

- Inverse Fourier transform:

$$R_{XY}(\tau) = \frac{1}{2\pi} \int_{-\infty}^{\infty} S_{XY}(\omega) e^{j\omega\tau} d\omega$$

- The following property holds (it is easy to see by definition):

$$S_{YX}(\omega) = S_{XY}^*(\omega) = S_{XY}(-\omega)$$
$$S_{YX}(\omega) = \int_{-\infty}^{+\infty} R_{YX}(\tau) e^{-j\omega\tau} d\tau = \int_{-\infty}^{+\infty} R_{XY}(-\tau) e^{-j\omega\tau} d\tau = \int_{-\infty}^{+\infty} R_{XY}(\alpha) e^{j\omega\alpha} d\alpha = \overline{\int_{-\infty}^{+\infty} R_{XY}(\alpha) e^{-j\omega\alpha} d\alpha} = S_{XY}^*(\omega)$$

### **Discrete Time Definitions:**

The definitions for a random process in discrete time are very similar, where the continuous Fourier transforms are exchanged by DTFT. If  $X_n$  is a real and WSS random process in discrete time, then:

$$R_{XX}[k] \xleftrightarrow{DTFT} S_{XX}(e^{j\omega})$$
$$S_{XX}(e^{j\omega}) = \sum_{k=-\infty}^{+\infty} R_{XX}[k] e^{-j\omega k} \quad R_{XX}[k] = \frac{1}{2\pi} \int_0^{2\pi} S_{XX}(e^{j\omega}) e^{j\omega k} d\omega$$

If  $X_n, Y_n$  are real JWSS random processes in discrete time, then:

$$R_{XY}[k] \xleftrightarrow{DTFT} S_{XY}(e^{j\omega})$$
$$S_{XY}(e^{j\omega}) = \sum_{k=-\infty}^{+\infty} R_{XY}[k] e^{-j\omega k} \quad R_{XY}[k] = \frac{1}{2\pi} \int_0^{2\pi} S_{XY}(e^{j\omega}) e^{j\omega k} d\omega$$

**Problem 2:**

Given is the following random process:

$$X(t) = \sin(Wt + \theta)$$

where  $W$  is a random variable with PDF  $f_W(w)$  and  $\theta$  is a random phase that distributes uniformly on the section  $[0, 2\pi)$ .  $W$  and  $\theta$  are independent.

1. Prove that the process  $X(t)$  is a WSS process.

Now it is given that  $W \sim \text{Unif}[W_{\min}, W_{\max}]$ ,  $0 < W_{\min} < W_{\max}$ .

2. Find  $R_X(\tau)$ .
3. Find the PSD of the process  $X(t)$ .

**Solution:**

1. We must show that the expectation and autocorrelation function are not dependent of time.

First, we will show that the expectation is zero for all  $t$ :

$$\begin{aligned} E\{X(t)\} &\stackrel{\substack{\text{linearity of} \\ \text{expectation}}}{=} E\{E\{X(t)|W\}\} = E\left\{\int_{-\infty}^{\infty} X(t) f_{\theta|W}(\theta|W) d\theta\right\} \stackrel{\substack{W, \theta \text{ are} \\ \text{statistically} \\ \text{independent}}}{=} E\left\{\int_{-\infty}^{\infty} X(t) f_{\theta}(\theta) d\theta\right\} \\ &= E\left\{\int_0^{2\pi} \sin(Wt + \theta) \frac{1}{2\pi} d\theta\right\} = E\left\{\frac{1}{2\pi} \int_0^{2\pi} \sin(Wt + \theta) d\theta\right\} = E\{0\} = 0 \end{aligned}$$

Now, we will show that the autocorrelation function is dependent of time difference only:

$$\begin{aligned} R_X(t + \tau, t) &= E\{X(t + \tau) X(t)\} = E\{\sin(Wt + W\tau + \theta) \sin(Wt + \theta)\} = \\ &= \frac{1}{2} E\{\cos(W\tau) - \cos(2Wt + W\tau + 2\theta)\} \end{aligned}$$

where, in the last equality, the following trigonometric identity was used:

$$\sin \alpha \sin \beta = 0.5 \cdot (\cos(\alpha - \beta) - \cos(\alpha + \beta))$$

We will make use of the smoothing theorem once more in order to calculate  $E\{\cos(2Wt + W\tau + 2\theta)\}$ :

$$\begin{aligned} E\{\cos(2Wt + W\tau + 2\theta)\} &= E\{E\{\cos(2Wt + W\tau + 2\theta)|W\}\} = \\ &= E\left\{\frac{1}{2\pi} \int_0^{2\pi} \cos(2Wt + W\tau + 2\theta) d\theta\right\} = E\{0\} = 0 \end{aligned}$$

All in all, we got that:

$$R_X(t + \tau, t) = \frac{1}{2} E\{\cos(W\tau)\} = R_X(\tau)$$

Notice that, in order to calculate  $R_X(\tau)$  explicitly, we need the distribution of  $W$ . However, we were able to show that for **any** distribution of  $W$ , the autocorrelation function is independent of time.

2. It is given that  $W \sim Unif[W_{\min}, W_{\max}]$ , that is to say:

$$f_W(w) = \begin{cases} \frac{1}{W_{\max} - W_{\min}} & \text{if } W \in [W_{\min}, W_{\max}] \\ 0 & \text{o.w.} \end{cases}$$

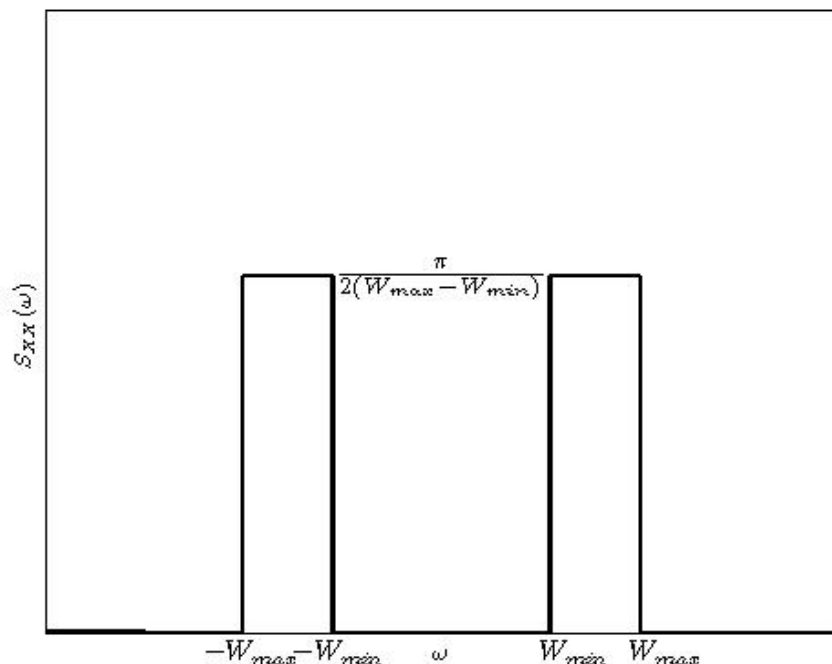
$$\begin{aligned} R_X(\tau) &= \frac{1}{2} E\{\cos(W\tau)\} = \frac{1}{2} \int_{W_{\min}}^{W_{\max}} \frac{1}{W_{\max} - W_{\min}} \cos(W\tau) dW = \frac{1}{2(W_{\max} - W_{\min})} \left. \frac{\sin(W\tau)}{\tau} \right|_{W_{\min}}^{W_{\max}} \\ &= \frac{1}{2(W_{\max} - W_{\min})} \frac{\sin(W_{\max}\tau)}{\tau} - \frac{1}{2(W_{\max} - W_{\min})} \frac{\sin(W_{\min}\tau)}{\tau} \end{aligned}$$

3. We need to find the Fourier transform of the autocorrelation function we found in the previous section.

$$\begin{aligned} \frac{\sin(W_{\min}\tau)}{\tau} &\xrightarrow{FT} \begin{cases} \pi & |\omega| \leq W_{\min} \\ 0 & |\omega| > W_{\min} \end{cases} \\ \frac{\sin(W_{\max}\tau)}{\tau} &\xrightarrow{FT} \begin{cases} \pi & |\omega| \leq W_{\max} \\ 0 & |\omega| > W_{\max} \end{cases} \end{aligned}$$

Therefore:

$$\begin{aligned} S_X(\omega) &= F\{R_X(\tau)\} = \frac{1}{2(W_{\max} - W_{\min})} \left( F\left\{ \frac{\sin(W_{\max}\tau)}{\tau} \right\} - F\left\{ \frac{\sin(W_{\min}\tau)}{\tau} \right\} \right) = \\ &= \frac{\pi}{2(W_{\max} - W_{\min})} \begin{cases} 1 & |\omega| \in [W_{\min}, W_{\max}] \\ 0 & |\omega| \notin [W_{\min}, W_{\max}] \end{cases} \end{aligned}$$



## Extra Questions

### Problem 3:

Let  $X[n]$  be a Gaussian WSS process with expectation 0 and autocorrelation function  $R_X[k]$ , and let  $Z[n], M[n]$  be two i.i.d standard Gaussian processes, that is:

$$Z[n], M[n] \sim N(0,1)$$

The processes  $X[n], Z[n], M[n]$  are independent.

We define the processes:

$$Y[n] = X[n] + Z[n]$$

$$V[n] = X[n-5] + M[n]$$

1. Is  $Y[n]$  stationary? If so, in what sense?
2. Are  $Y[n]$  and  $V[n]$  jointly stationary? If so, in what sense?
3. Is the process  $U[n] = (-1)^n X[n]$  stationary? If so, in what sense?
4. Are the processes  $X[n]$  and  $U[n]$  jointly stationary? If so, in what sense?

### Solution:

1.  $X[n]$  is a WSS Gaussian random process and hence SSS.  $Z[n]$  is also an SSS Gaussian random process.  $Y[n]$  is the sum of two independent Gaussian random processes hence it is Gaussian. In addition  $Y[n]$  is WSS since it is the sum of two **independent** WSS processes. From this it follows that  $Y[n]$  is a Gaussian WSS process and hence SSS.

2.  $Y[n]$  is a Gaussian SSS process as we saw in last section.  $V[n]$  is a Gaussian SSS process from the same reasons. We check that  $Y[n]$  and  $V[n]$  are JWSS:

$$\begin{aligned} R_{YV}[k] &= E[Y[n+k]V[n]] = E[(X[n+k] + Z[n+k])(X[n-5] + M[n])] \\ &= E[X[n+k]X[n-5]] = R_{XX}[k+5] \end{aligned}$$

where we used the fact that  $X[n], M[n], Z[n]$  are independent and  $X[n]$  is WSS. Since  $Y[n]$  and  $V[n]$  are JWSS Gaussian processes they are also JSSS.

3. First let's check that  $U[n]$  is WSS:

$$E(U[n]) = E((-1)^n X[n]) = (-1)^n E(X[n]) = 0$$

$$\begin{aligned} R_U[n+k, n] &= E(U[n+k]U[n]) = E((-1)^{n+k} X[n+k](-1)^n X[n]) \\ &= (-1)^{2n+k} R_X[k] = (-1)^k R_X[k] \end{aligned}$$

We got that the expectation and auto-correlation functions do not depend on time so  $U[n]$  is WSS. Now, since  $X[n]$  is Gaussian, and every sample set of  $U[n]$  is generated via linear transformation on a sample set of  $X[n]$ , every sample set of  $U[n]$  consists a Gaussian random vector. From here it follows that  $U[n]$  is a Gaussian random process, so it is also SSS.

4. The processes are not jointly stationary. We evaluate their cross-correlation function and show that it is dependent on  $n$  :

$$R_{xu}[n+k, n] = E(X[n+k]U[n]) = E(X[n+k](-1)^n X[n]) = (-1)^n R_x[k]$$

Since they are not JWSS they are certainly not JSSS.