



ELEC 474 Machine Vision

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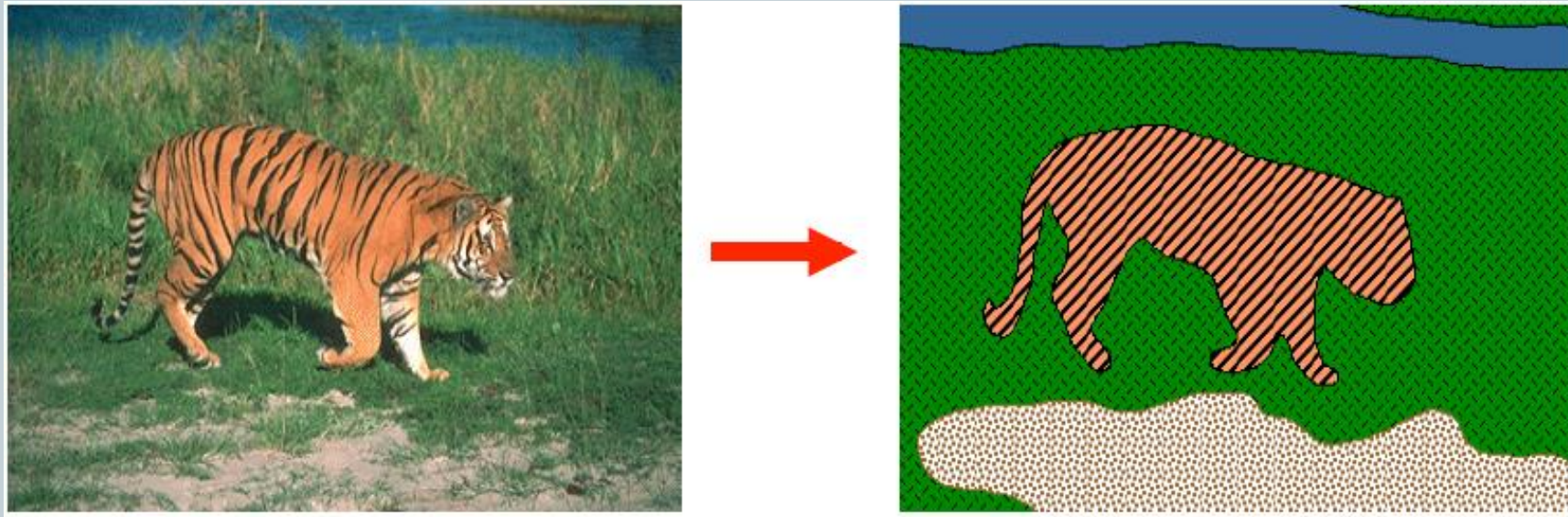
K-MEANS CLUSTERING

Review: Segmentation



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- Identifying groups of pixels that go together



Clustering



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- Clustering: grouping together similar connected points and representing them with a single token
- Criteria for forming a cluster depends on the application
- Some examples:
 - Intensity
 - Colour
 - Distance
 - Texture

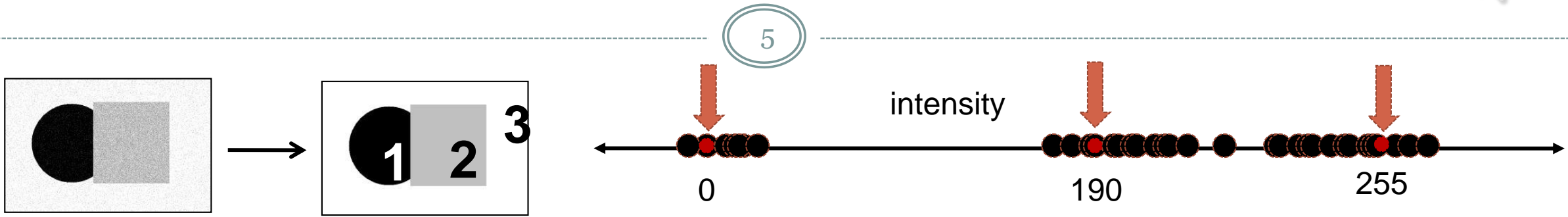
K-Means Clustering



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- K-means clustering is one of the simplest **unsupervised learning** algorithms.
- Supervised Learning
 - Knowledge of output
 - ✦ Learning in the presence of an expert
 - ✦ Training data is labelled
 - Goal: Predict labels of unseen data
 - Examples: Support Vector Machines (SVM), Decision Trees, Neural Networks,
- Unsupervised Learning
 - No knowledge of output
 - Goal: Discover patterns/groupings in data
 - Examples: Clustering, Genetic Algorithms, Autoencoders

K-Means Clustering



- Approach: choose three “centers” as the representative intensities
 - Label every pixel according to which of these centers it is nearest to
- Best cluster centers are those that minimize **Sum of Square Distance (SSD)** between all points x and their nearest cluster center c_i

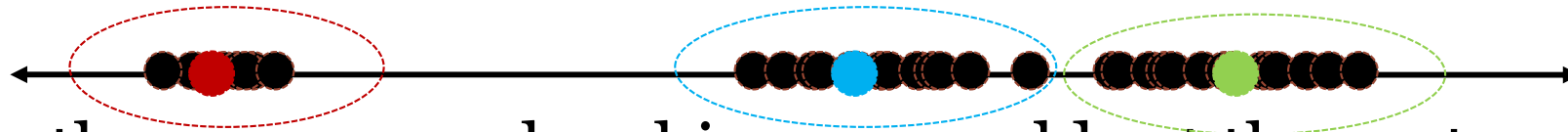
$$SSD = \sum_{clusters\ i} \sum_{x \in cluster\ i} (x - c_i)^2$$

K-Means Clustering

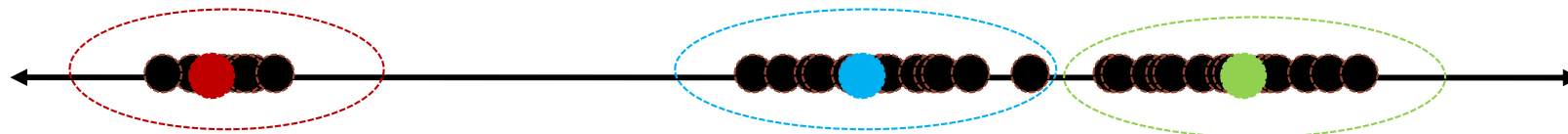


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- “chicken and egg problem”
- If we knew the cluster centers, we could allocate points to groups by assigning each to its closest center



- If we knew the group memberships, we could get the centers by computing the mean per group



K-Means Clustering



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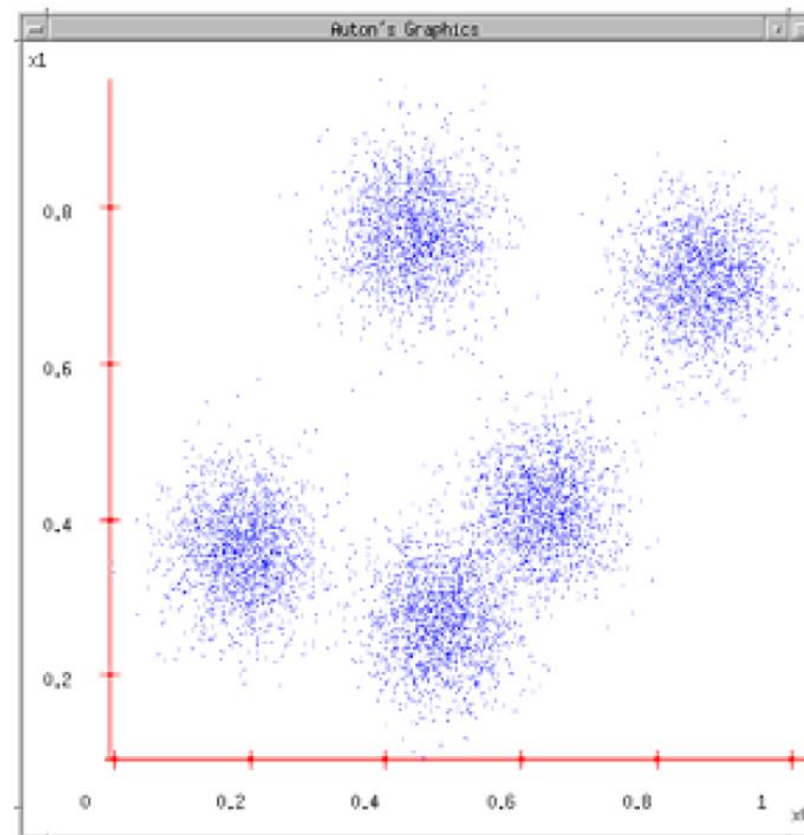
Algorithm:

1. Randomly initialize k points to act as cluster centers (c_1, \dots, c_k)
2. Given cluster centers, determine points in each cluster
 - point x is in cluster i iff $|x - c_i| \leq |x - c_j|$ for all i, j in $\{1..k\}$
3. Given points in each cluster, solve for c_i
4. If c_i have changed, repeat from Step 2

Example: K-Means Clustering



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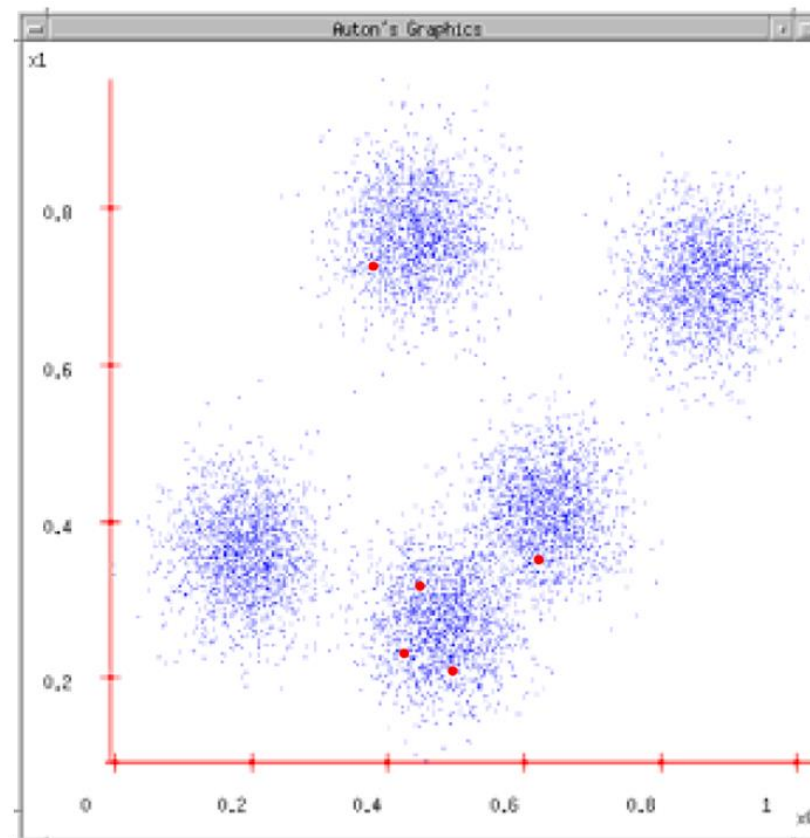


Example: K-Means Clustering



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- Step 1: Randomly initialize k points to act as cluster centers

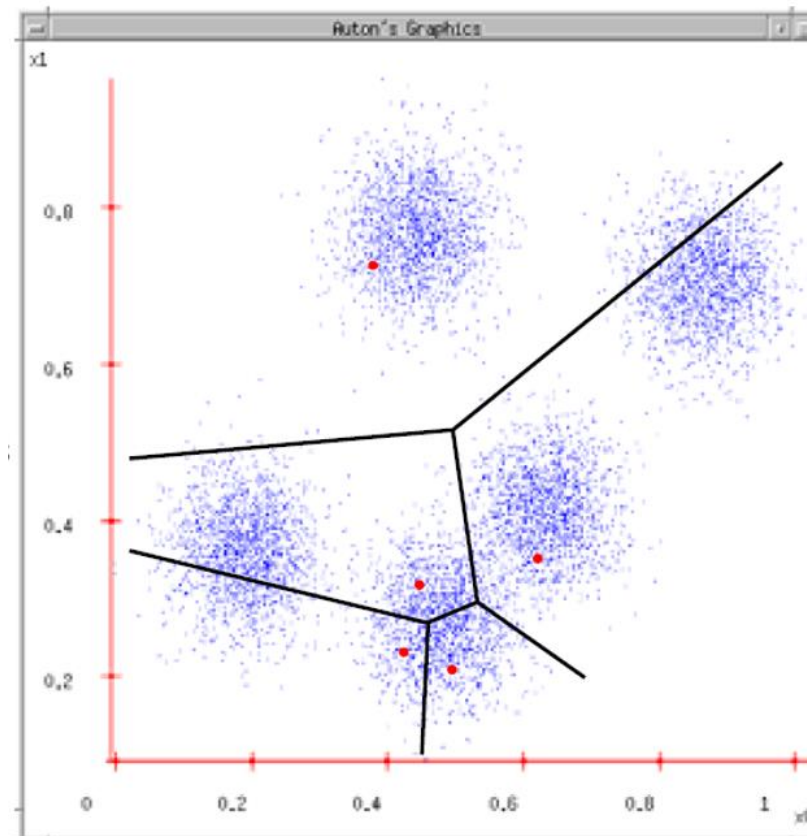


Example: K-Means Clustering



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- Step 2: Given cluster centers, determine points in each cluster

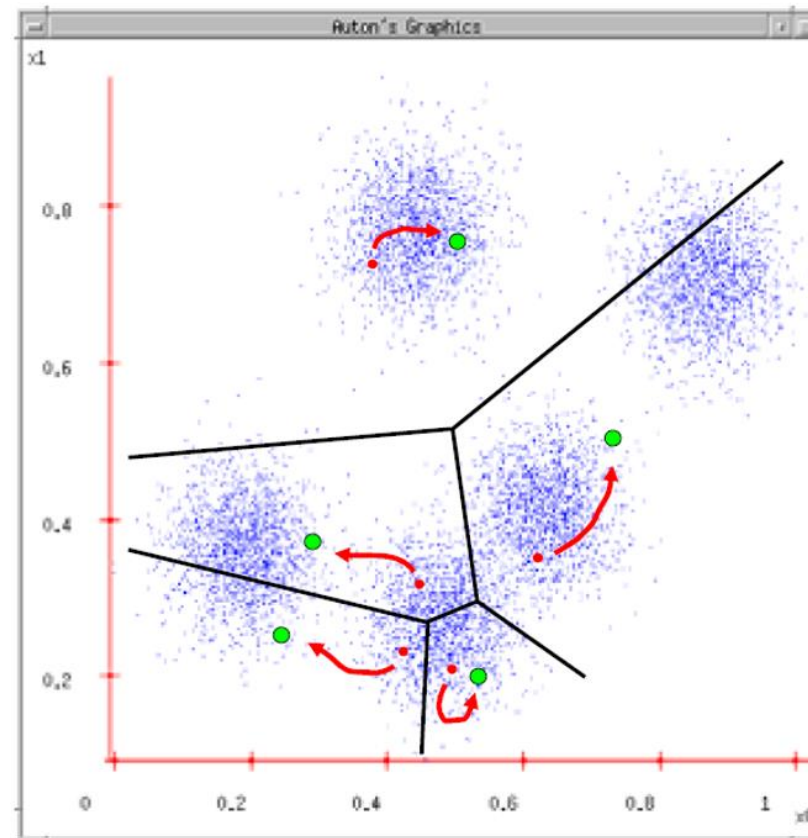


Example: K-Means Clustering



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- Step 3: Given points in each cluster, solve for c_i



Step 4: If c_i have changed, repeat from Step 2

K-Means Clustering



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- Online demo:
 - <https://www.naftaliharris.com/blog/visualizing-k-means-clustering/>

Segmentation as Clustering



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- Depending on what we choose as the **feature space**, the pixels can be grouped in different ways
- Grouping pixels based on **intensity** similarity:



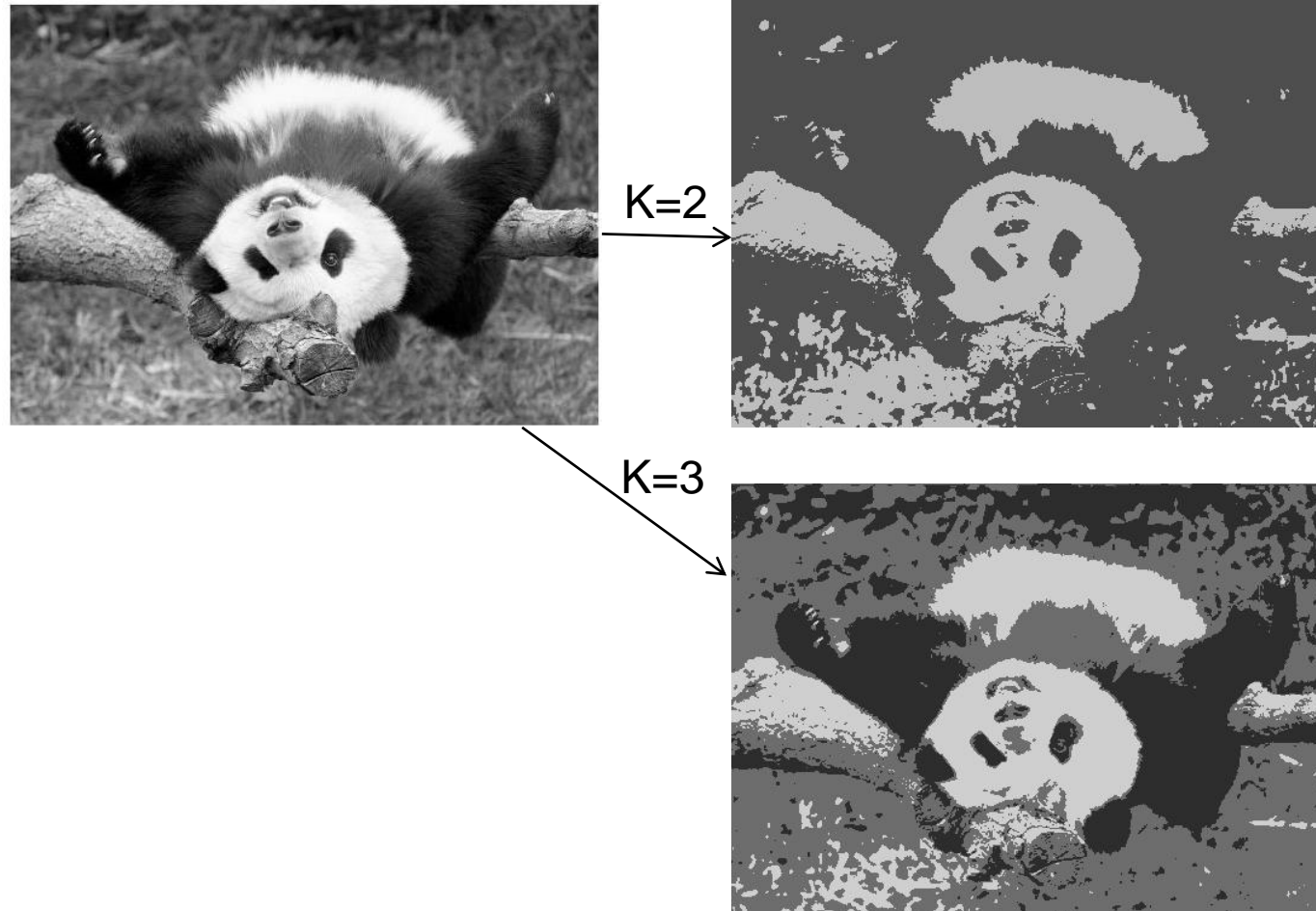
Feature space: intensity value (1-D)



Segmentation as Clustering



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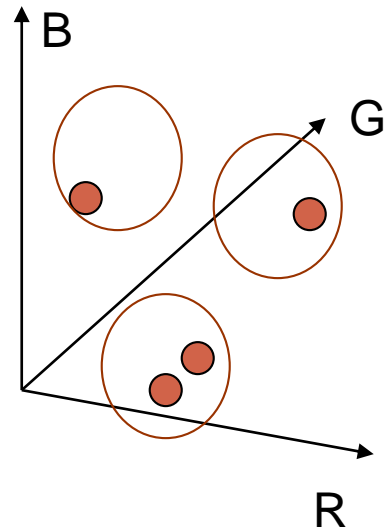


Segmentation as Clustering

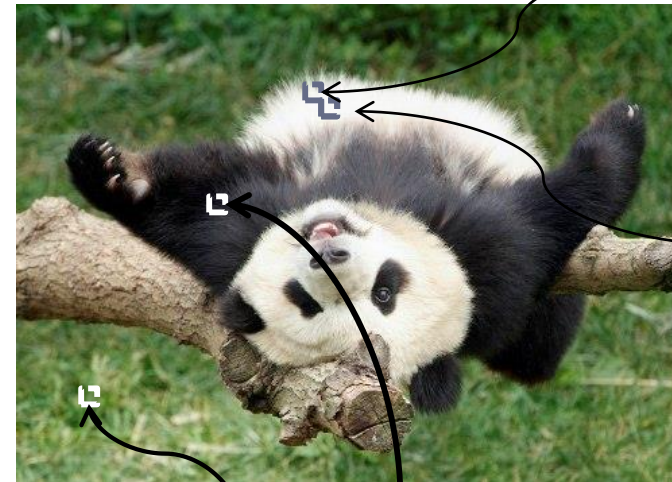


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- Grouping pixels based on **colour** similarity:



Feature space: intensity value (3-D)



R=255
G=200
B=250

R=245
G=220
B=248

R=15
G=189
B=2

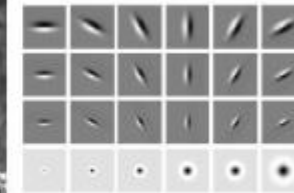
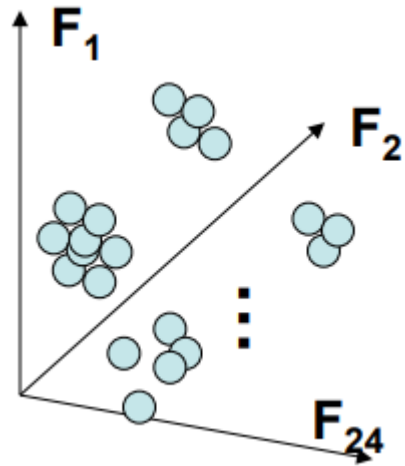
R=3
G=12
B=2

Segmentation as Clustering



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- Grouping pixels based on **texture** similarity



Filter bank of
24 filters

Feature space: filter bank responses (e.g., 24-D)

Segmentation as Clustering

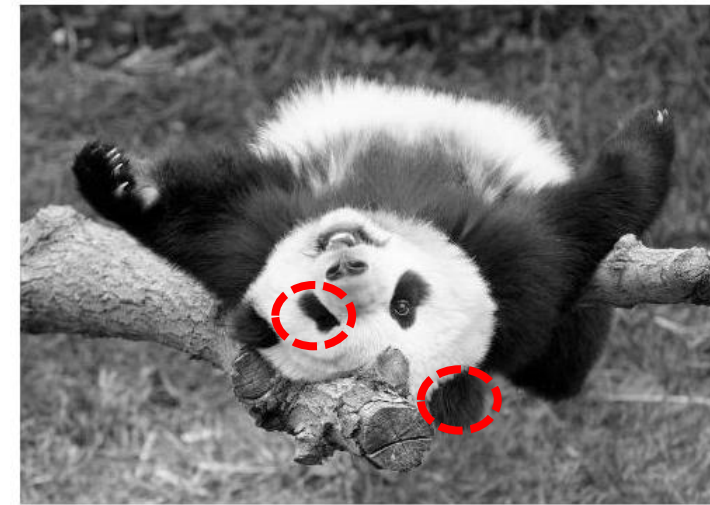


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- Returning to grouping pixels based on **intensity** similarity
- In what case is intensity not enough for segmentation?



Feature space: intensity value
(1-D)



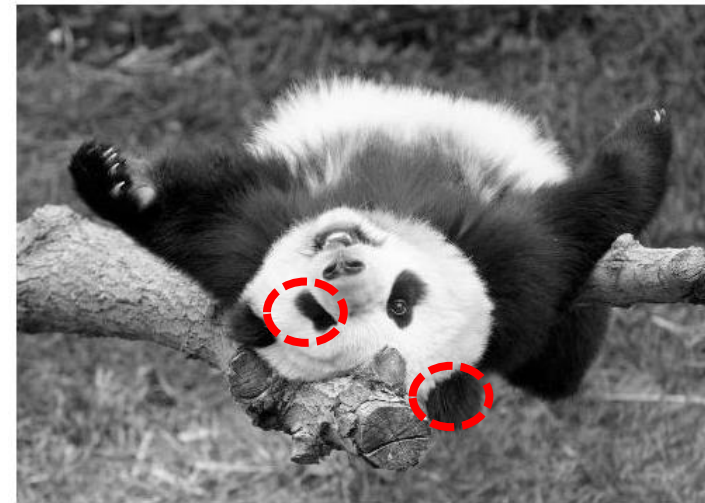
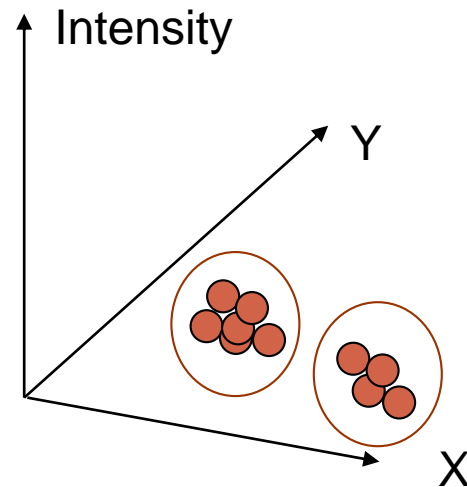
- Clusters based on intensity similarity don't have to be spatially coherent

Segmentation as Clustering



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- Grouping pixels based on **intensity & position** similarity:



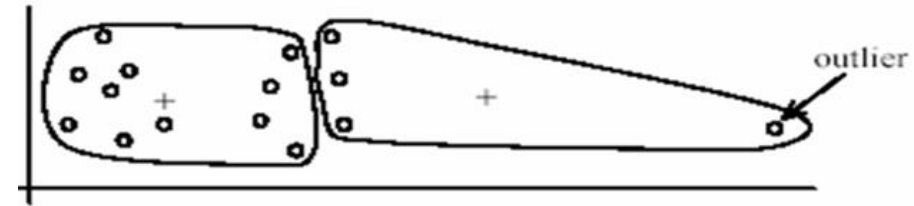
- Both regions are black
- Including **position (x,y)** information allows us to group the regions into two distinct segments

K-Means Clustering

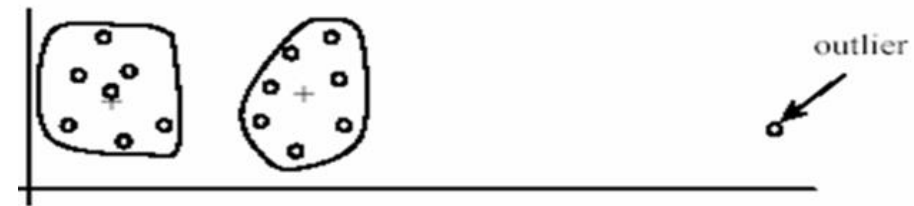


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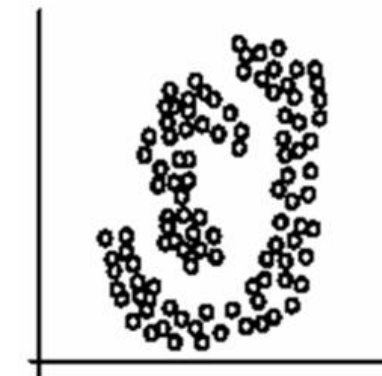
- Pros:
 - Simple and fast
 - Easy to implement
 - Converges to local minimum of within-cluster squared error
- Cons:
 - Specifying k
 - Sensitive to initial centers
 - Sensitive to outliers
 - Detects spherical clusters only



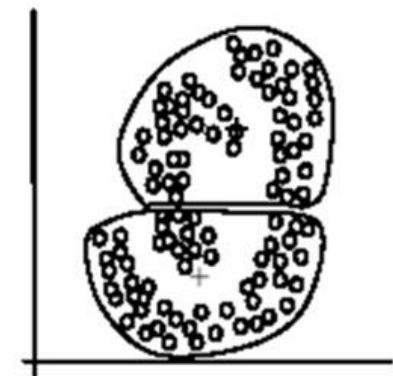
(A): Undesirable clusters



(B): Ideal clusters



(A): Two natural clusters



(B): k -means clusters

K-Means: Choosing K



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- The most common approach is to use **elbow method**
 - Try different values of K
 - Plot the K-means objective versus K
 - Look at the “elbow-point” in the plot
 - ✦ K value below which SSD explodes
- For the above plot, $K = 6$ is the elbow point

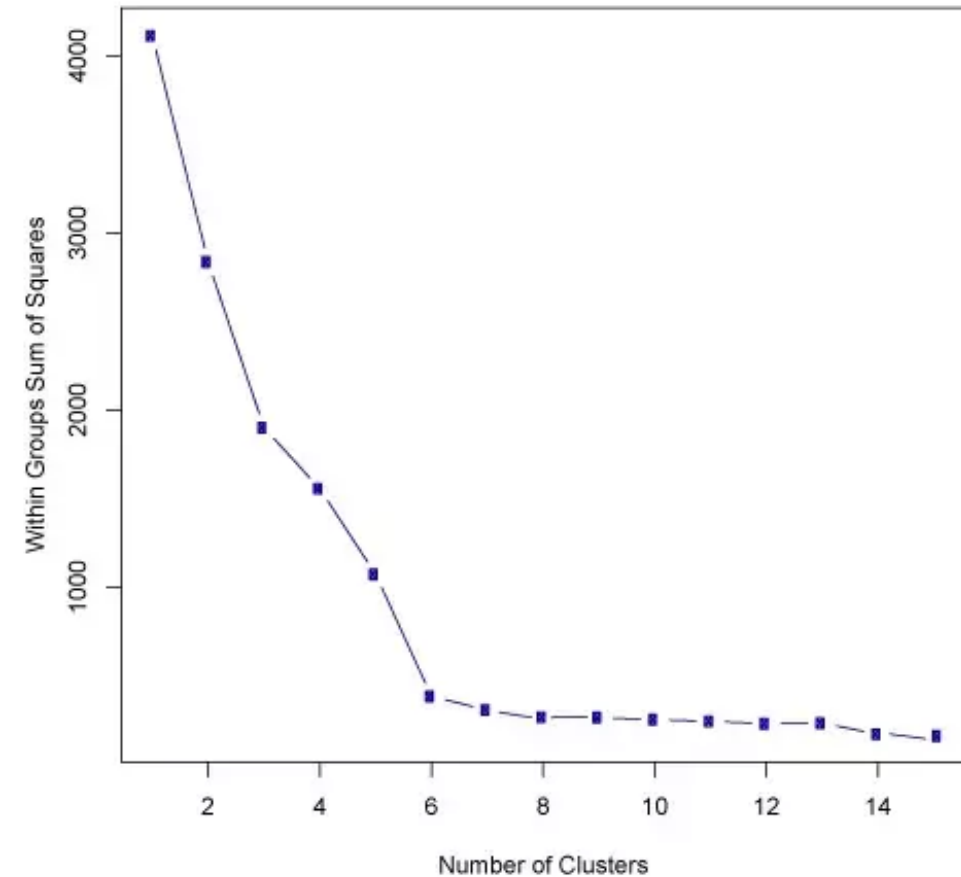


Image source: <https://www.quora.com/How-can-we-choose-a-good-K-for-K-means-clustering>

K-Means: Initialization



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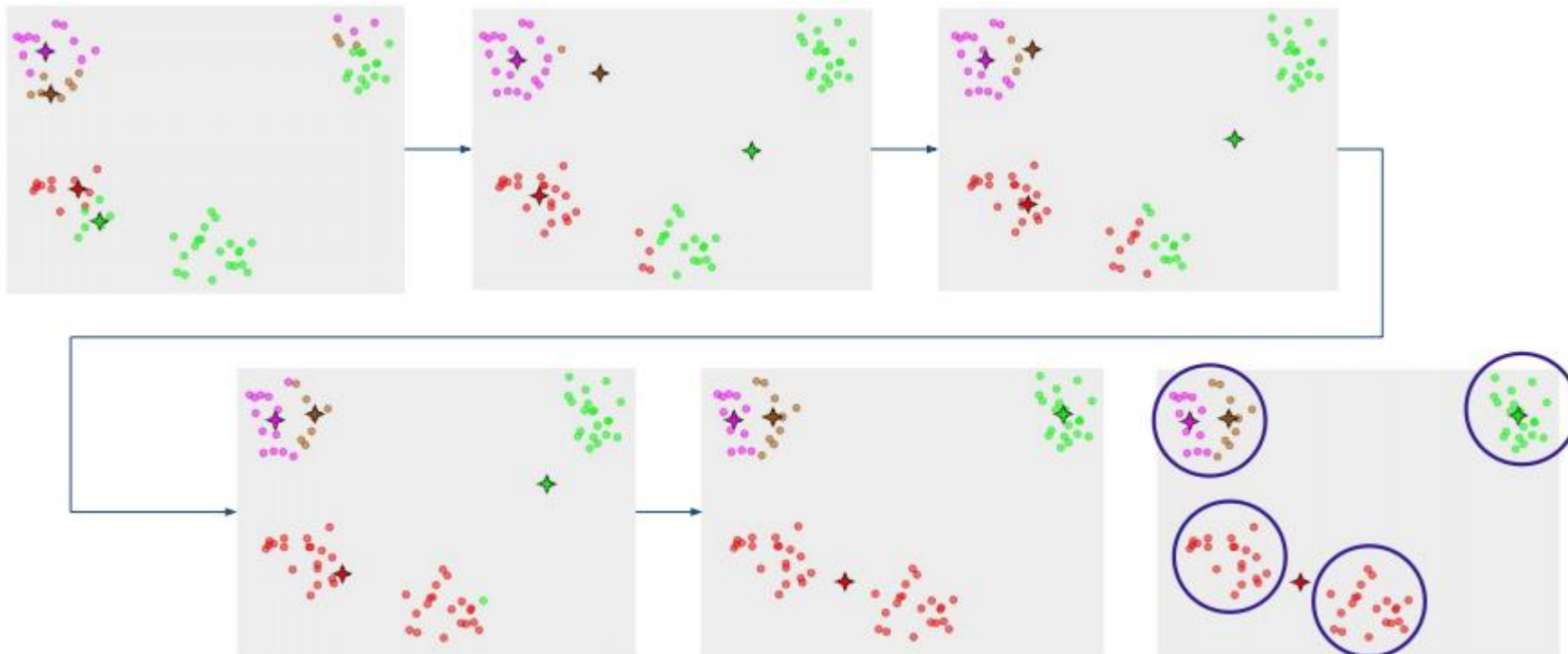
- Initialization = where to distribute the initial c_i
- K-means is extremely sensitive to initialization
- Bad initialization can lead to:
 - Poor convergence speed
 - Bad overall clustering
- How to initialize?
 - Randomly from data
 - Try to find K “spread-out” points
 - ✦ Furthest point algorithm
 - ✦ K-means ++
- Safeguarding measure:
 - Try multiple initializations and choose the best

K-Means: Initialization



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- Bad initialization can lead to:
 - Poor convergence speed
 - Bad overall clustering



Furthest Point Algorithm



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- For **better initialization** of cluster centers
- Algorithm:
 - Pick first center randomly
 - Next center is the point furthest from the first center
 - Next center is the point furthest from both previous centers
 - In general: next center is $\arg \max_x \min_c d(x, c)$

Furthest Point Algorithm



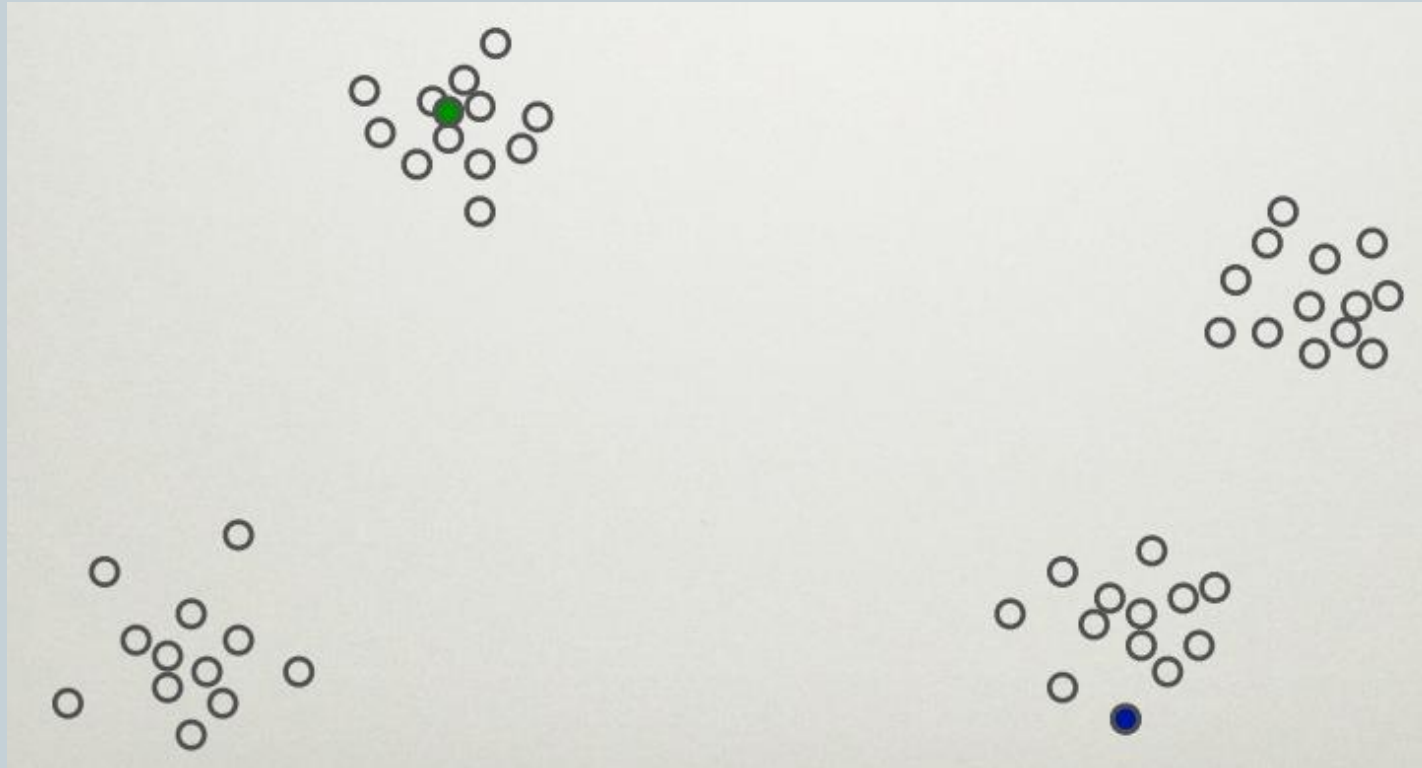
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Furthest Point Algorithm



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Furthest Point Algorithm



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Furthest Point Algorithm



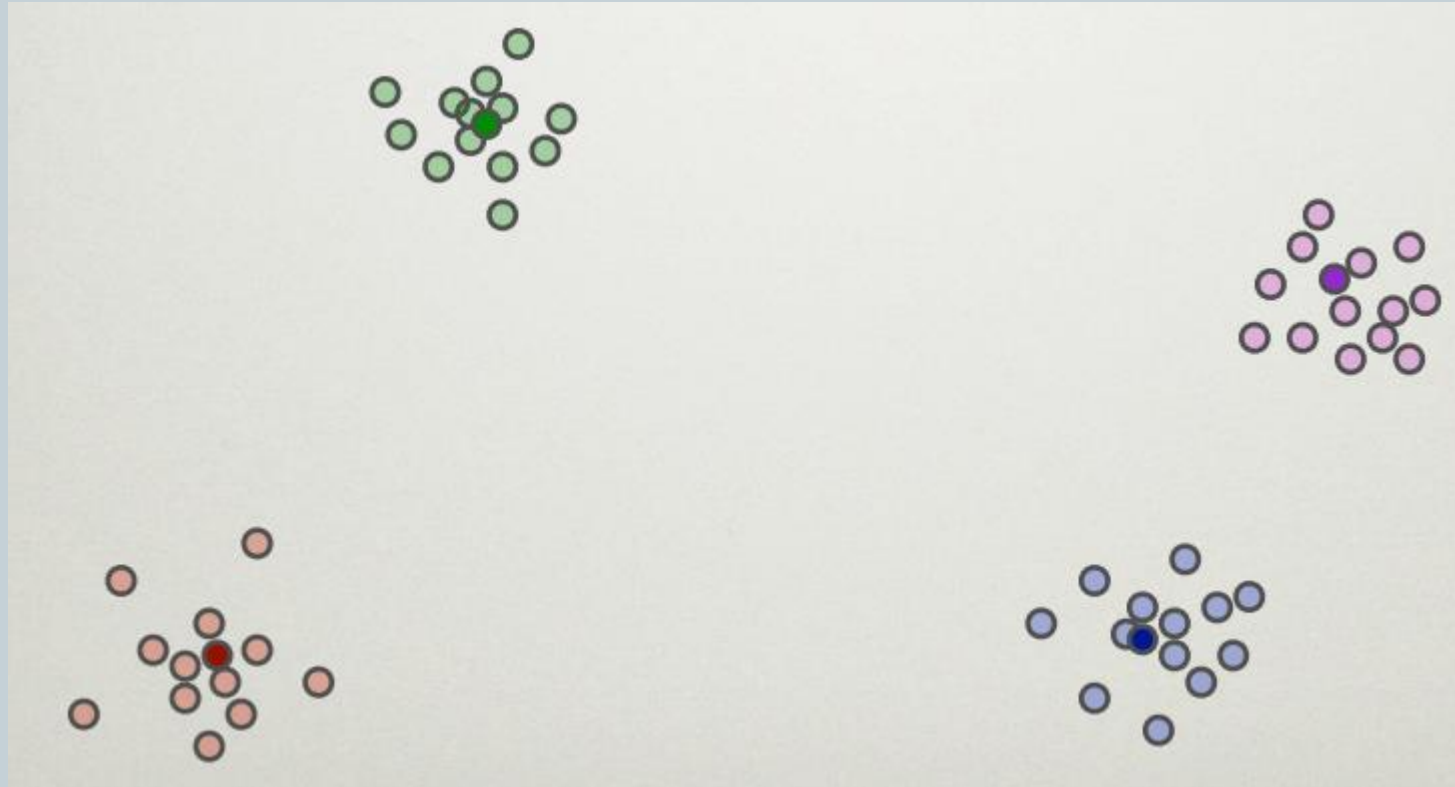
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Furthest Point Algorithm



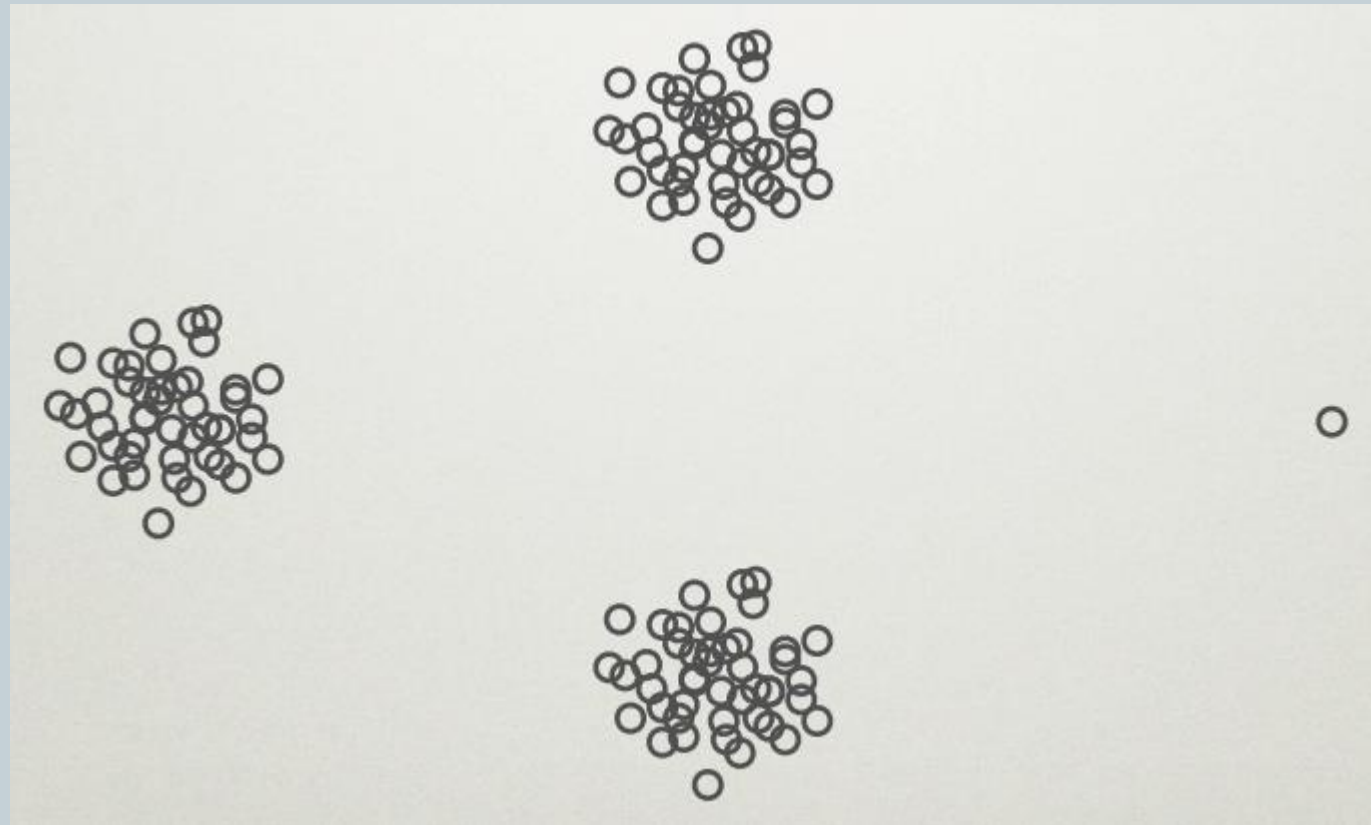
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Sensitivity to Outliers



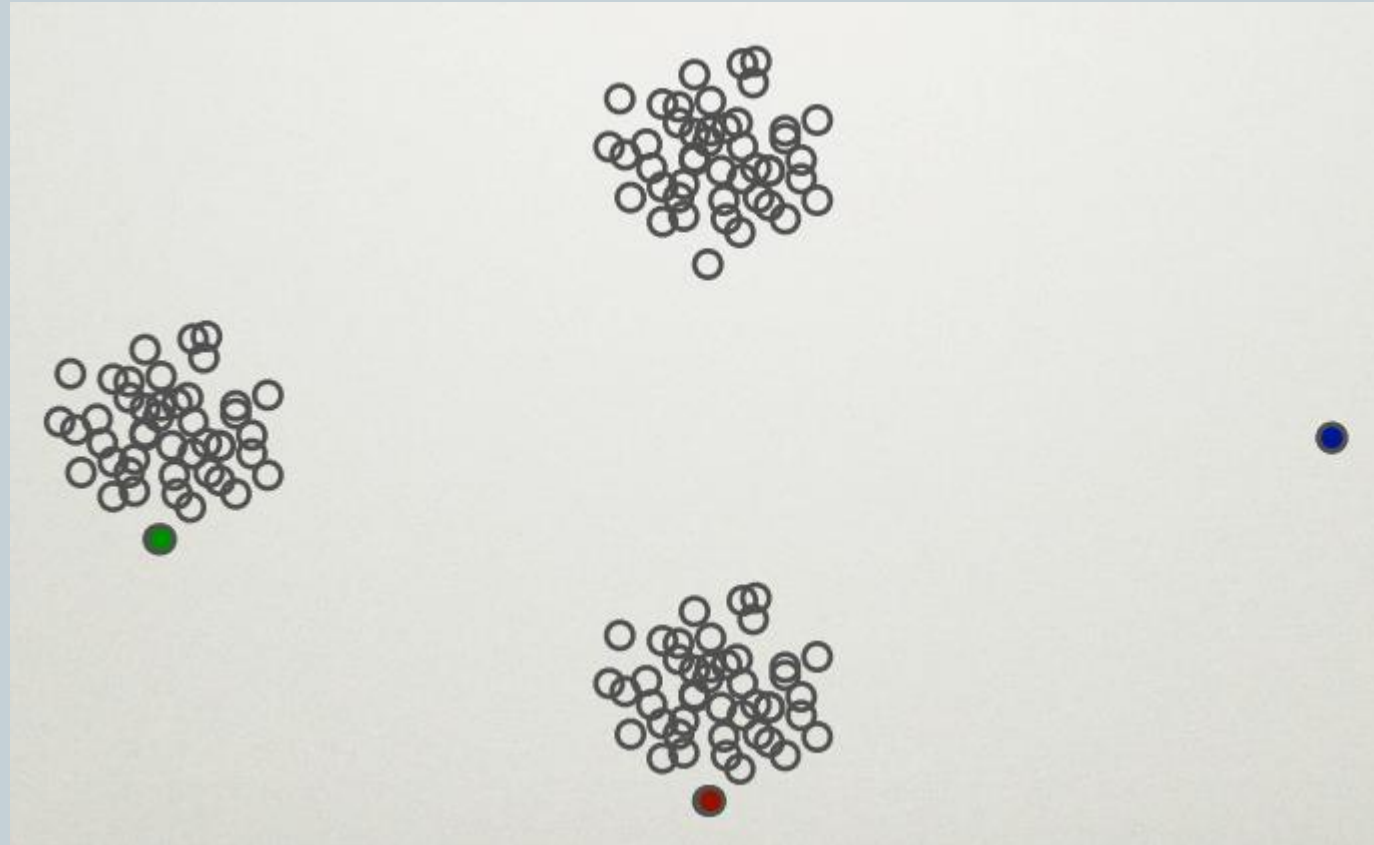
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Sensitivity to Outliers



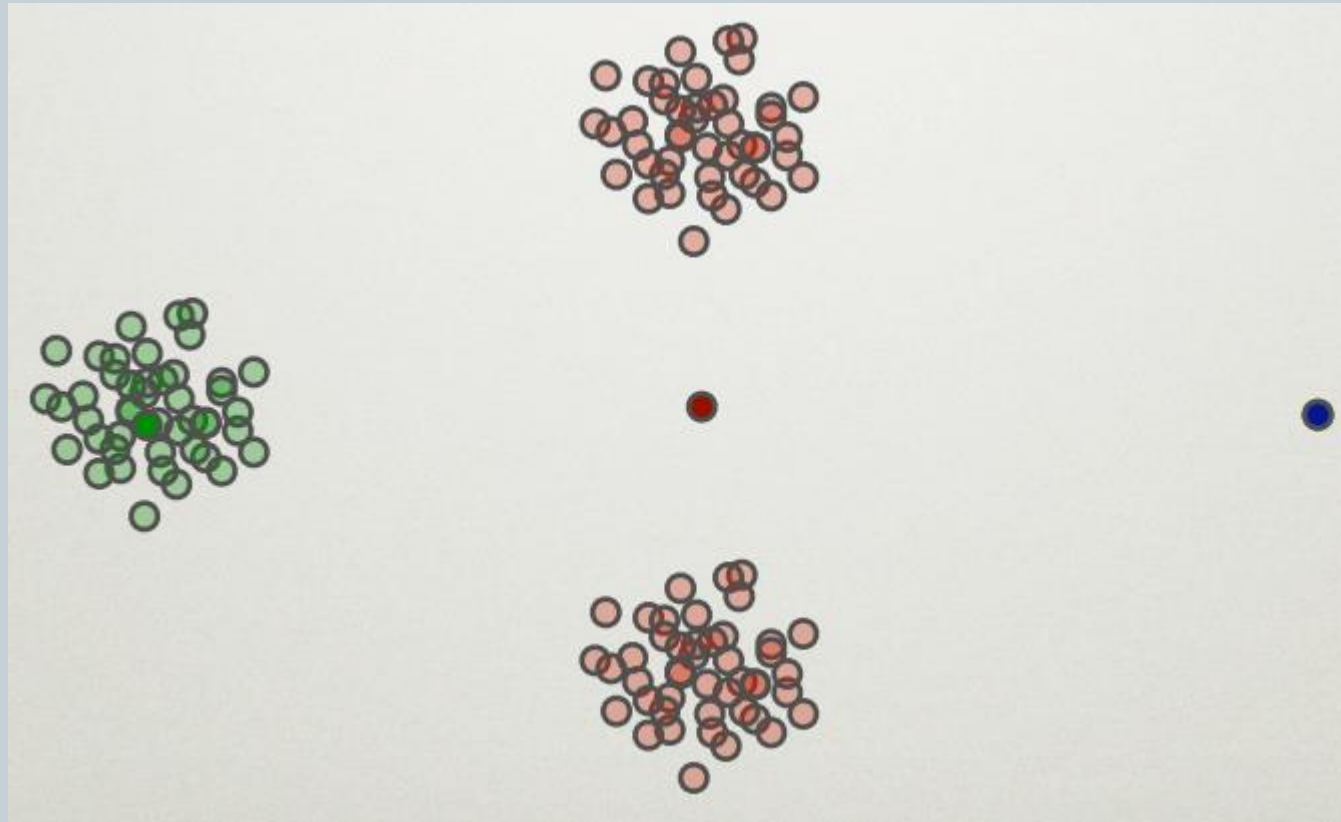
30



Sensitivity to Outliers



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K-Means ++



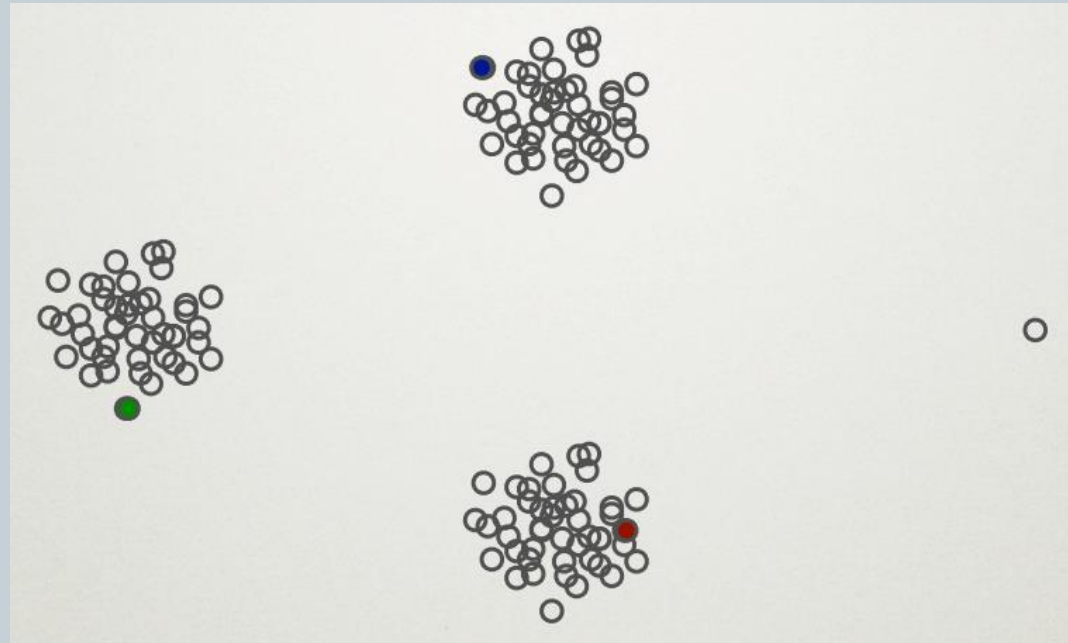
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- Provides **better initialization** as well as **better sensitivity to outliers**
- Algorithm:
 - Randomly choose first center
 - Pick new center with probability proportional to $(x - c_i)^2$
 - Repeat for K centers

K-Means ++



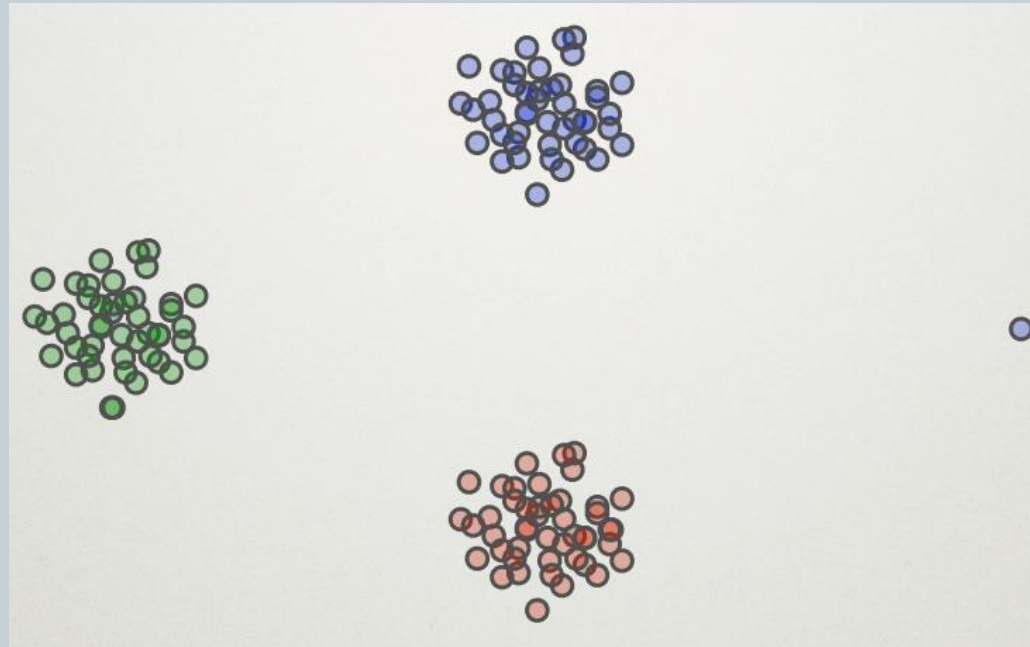
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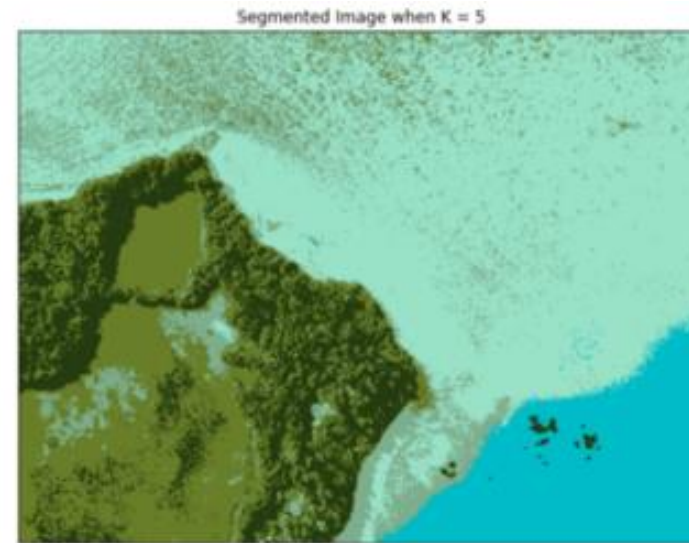


K-Means ++



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<https://towardsdatascience.com/introduction-to-image-segmentation-with-k-means-clustering-83fdo9e2fc3>

Original Image



Segmented Image when $K = 6$



Original Image



Segmented Image when $K = 6$



<https://towardsdatascience.com/introduction-to-image-segmentation-with-k-means-clustering-83fdo9e2fc3>

References and Resources

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- D. Arthur and S. Vassilvitskii, “K-Means++: The advantages of careful seeding,” in Proc. Symp. Discrete Algorithms, 2007, pp. 1027–1035.
- Slide sources
 - Fei-Fei Li
(http://vision.stanford.edu/teaching/cs131_fall1617/lectures/lecture13_kmeans_mean_shift_cs131_2016)
 - Sergei Vassilvitskii and David Arthur
(<http://theory.stanford.edu/~sergei/slides/BATS-Means.pdf>)
 - <http://shabal.in/visuals/kmeans/KMeansPlusPlus.pdf>