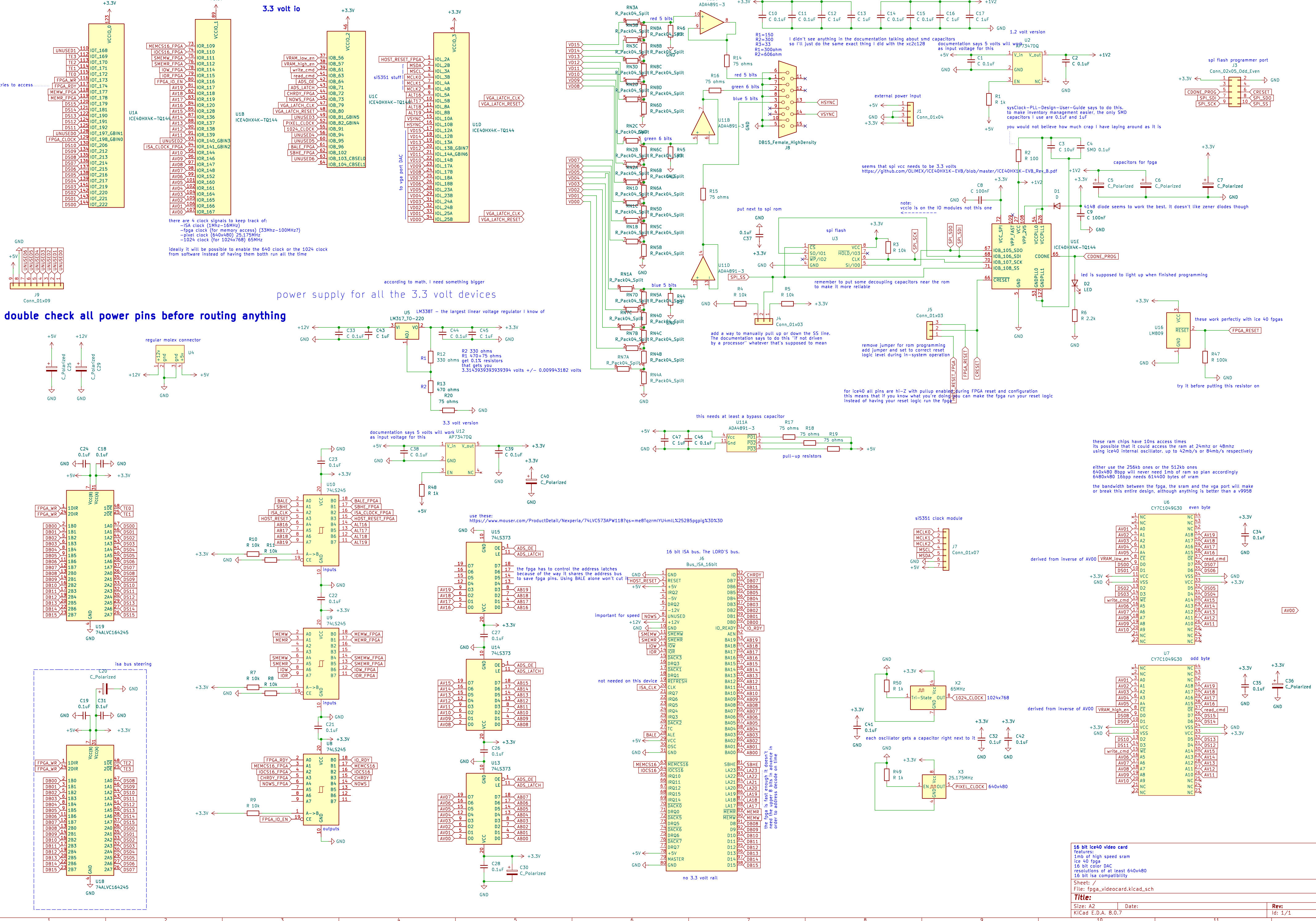


when the host tries to access  
wait states

use these 2:  
<https://www.mouser.com/ProductDetail/Bourns/CAY16-911J4LF7qs=B0uy3wJAhvHuJ8TbQYqYX3D%3D>  
<https://www.mouser.com/ProductDetail/Bourns/CAY16-4750F4LF7qs=NmEazmVvVbX6RANgi73GwX3D%3D>



double check all power pins before routing anything

power supply for all the 3.3 volt devices

according to math, I need something bigger

seems that spi vcc needs to be 3.3 volts

[https://github.com/OLIMEX/ICE40HX1K-EVB/blob/master/ICE40HX1K-EVB\\_Rev\\_B.pdf](https://github.com/OLIMEX/ICE40HX1K-EVB/blob/master/ICE40HX1K-EVB_Rev_B.pdf)

to make inventory management easier, the only SMD capacitors I use are 0.1uF and 1uF

you would not believe how much crap I have laying around as it is

414B diode seems to work the best, it doesn't like zener diodes though

led is supposed to light up when finished programming

these work perfectly with Ice 40 fpgas

try it before putting this resistor on

remove jumper for rom programming

add jumper and set to correct reset logic level during in-system operation

add a way to manually pull up or down the SS line. the documentation says to do this "if not driven by a processor" whatever that's supposed to mean

remember to put some decoupling capacitors near the rom to make it more reliable

put next to spi rom

note: vccio is on the IO modules not this one

1.2 volt version

I didn't see anything in the documentation talking about smd capacitors as input voltage for this

documentation says 5 volts will work

as input voltage for this

so I'll just do the same exact thing I did with the xc2c128

R1=150 R2=300 R3=33 R4=300ohm R5=60ohm

75 ohms

red 5 bits

green 6 bits

blue 5 bits

red 5 bits

75 ohms

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