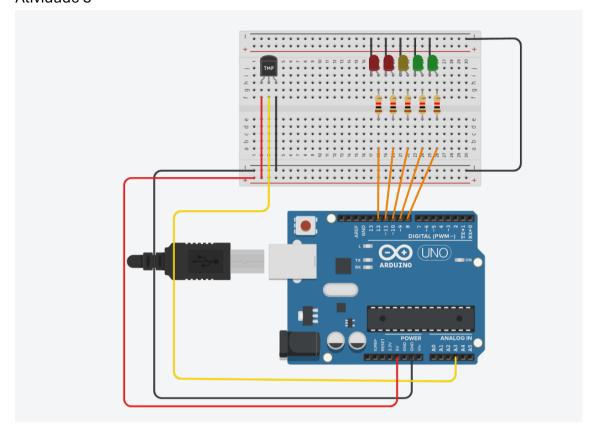
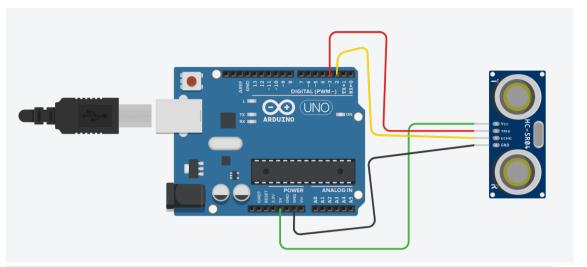
Atividade 3



```
Serial.begin(9600);
        void loop()
           int sensorValue = analogRead(A3);
float voltage = sensorValue * (5.0/1023.0);
Serial.print("Tensao = ");
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           Serial.print("Tensao = ");
Serial.print(voltage);
Serial.print("V");
Serial.println();
delay(2000);
float temp = (voltage-0.5)*100;
Serial.print("Temperatura = ");
           Serial.print(temp);
Serial.print("@C");
           Serial.println();
           if (temp >= -20) {
  digitalWrite(8, HIGH);
            }else{digitalWrite(8, LOW);
           if(temp >= 0){
  digitalWrite(9, HIGH);
}else {digitalWrite(9, LOW);
            if (temp >= 20){
  digitalWrite(10, HIGH);
}else {digitalWrite(10, LOW);
            if (temp >= 40){
  digitalWrite(11, HIGH);
}else {digitalWrite(11, LOW);
41
42
           if (temp >= 50) {
              digitalWrite(12, HIGH);
           } else {digitalWrite(12, LOW);} delay(2000);}
44
45
```



```
1 float time = 0;
 2 float distancia = 0;
 3
 4 void setup ()
 5 {
 7 pinMode (3, OUTPUT) ;
 8 pinMode (2, INPUT);
9 Serial.begin (9600);
10 }
11 void loop ()
12 {
13 digitalWrite (3, LOW);
14 delayMicroseconds (2);
15 digitalWrite (3, HIGH);
16 delayMicroseconds (10);
time = pulseIn (2, HIGH);
Serial.println ("Tempo: " + String (time/1000) + "ms");
19 // time = microssegundos
20 distancia = time/1000000 * 170 * 100;
21 Serial.println ("Distancia: " + String (distancia) + "cm");
22 delay (10);
23 }
```