

Figure 1: GPLAR with separate GPs

As shown in Figure 1, h_{2n} is generated by sum of two Gaussian process value, which is the following:

$$\begin{aligned} p(h_{1n}) &= \mathcal{N}(h_{1n}; f_1(\mathbf{x}_n), \sigma^2) \\ p(h_{2n}) &= \mathcal{N}(h_{2n}; f_2(\mathbf{x}_n) + g_2(h_{1n}), \sigma^2) \\ p(h_{3n}) &= \mathcal{N}(h_{3n}; f_3(\mathbf{x}_n) + g_3(h_{1n}) + t_3(h_{2n}), \sigma^2) \end{aligned}$$

Introducing inducing-points into each GP function, we have the approximate posterior and the complete probability of the model as follows,

$$\begin{aligned} p(f_{1:3}, g_{2:3}, t_3, \mathbf{h}_{1:3}, \mathbf{y}_{1:3}) &= p(f_{1 \neq \mathbf{u}_1} | \mathbf{u}_1) p(\mathbf{u}_1) \\ &\quad p(f_{2 \neq \mathbf{u}_2} | \mathbf{u}_2) p(\mathbf{u}_2) p(g_{2 \neq \mathbf{v}_2} | \mathbf{v}_2) p(\mathbf{v}_2) \\ &\quad p(f_{3 \neq \mathbf{u}_3} | \mathbf{u}_3) p(\mathbf{u}_3) p(g_{3 \neq \mathbf{v}_3} | \mathbf{v}_3) p(\mathbf{v}_3) p(t_{3 \neq \mathbf{w}_3} | \mathbf{w}_3) p(\mathbf{w}_3) \times \\ &\quad \prod_n p(h_{1n} | f_1, \mathbf{x}_n) p(h_{2n} | f_2, g_2, \mathbf{x}_n, h_{1n}) p(h_{3n} | f_3, g_3, t_3, \mathbf{x}_n, h_{1n}, h_{2n}) \\ &\quad p(y_{1n} | h_{1n}) p(y_{2n} | h_{2n}) p(y_{3n} | h_{3n}) \end{aligned}$$

$$\begin{aligned} q(f_{1:3}, g_{2:3}, t_3, \mathbf{h}_{1:3}) &= p(f_{1 \neq \mathbf{u}_1} | \mathbf{u}_1) q(\mathbf{u}_1) \\ &\quad p(f_{2 \neq \mathbf{u}_2} | \mathbf{u}_2) q(\mathbf{u}_2) p(g_{2 \neq \mathbf{v}_2} | \mathbf{v}_2) q(\mathbf{v}_2) \\ &\quad p(f_{3 \neq \mathbf{u}_3} | \mathbf{u}_3) q(\mathbf{u}_3) p(g_{3 \neq \mathbf{v}_3} | \mathbf{v}_3) q(\mathbf{v}_3) p(t_{3 \neq \mathbf{w}_3} | \mathbf{w}_3) q(\mathbf{w}_3) \times \\ &\quad \prod_n p(h_{1n} | f_1, \mathbf{x}_n) p(h_{2n} | f_2, g_2, \mathbf{x}_n, h_{1n}) p(h_{3n} | f_3, g_3, t_3, \mathbf{x}_n, h_{1n}, h_{2n}) \end{aligned}$$

Lower bound to the marginal log-likelihood becomes,

$$\begin{aligned} \mathcal{L}_{ELBO} &= \mathbb{E}_q \left[\log \frac{p(f_{1:3}, g_{2:3}, t_3, \mathbf{h}_{1:3}, \mathbf{y}_{1:3})}{q(f_{1:3}, g_{2:3}, t_3, \mathbf{h}_{1:3})} \right] \\ &= \sum_{l,n} \mathbb{E}_q \log p(y_{ln} | h_{ln}) - \sum_{l=1}^3 KL[q(\mathbf{u}_l) \| p(\mathbf{u}_l)] - \sum_{l=2}^3 KL[q(\mathbf{v}_l) \| p(\mathbf{v}_l)] - \sum_{l=3}^3 KL[q(\mathbf{w}_l) \| p(\mathbf{w}_l)] \end{aligned}$$

where the expectation log-term requires computation of the following:

$$\int p(f_{l \neq \mathbf{u}_l^1}^1 | \mathbf{u}_l^1) q(u_l^1) \dots p(f_{l \neq \mathbf{u}_l^l}^l | \mathbf{u}_l^l) q(u_l^l) p(h_{ln} | f_l^{1 \dots l}, \mathbf{x}_n, h_{1n}, \dots, h_{(l-1)n}) \\ q(h_{1n}) q(h_{2n} | h_{1n}) \dots q(h_{(l-1)n} | h_{1n} \dots h_{(l-2)n}) \\ \log p(y_{ln} | h_{ln}) d\mathbf{h}$$

where $p(h_{ln} | f_l^{1 \dots l}, \mathbf{x}_n, h_{1n}, \dots, h_{(l-1)n}) = \mathcal{N}(h_{ln}; f_l^1(\mathbf{x}_n) + f_l^2(h_{1n}) + \dots + f_l^l(h_{(l-1)n}), \sigma^2)$ and the function $f_l^{1 \dots l}$ can be integrated out analytically as follows,

$$q(h_{ln} | h_{1n}, \dots, h_{(l-1)n}) = \int p(f_{l \neq \mathbf{u}_l^1}^1 | \mathbf{u}_l^1) q(u_l^1) \dots p(f_{l \neq \mathbf{u}_l^l}^l | \mathbf{u}_l^l) q(u_l^l) p(h_{ln} | f_l^{1 \dots l}, \mathbf{x}_n, h_{1n}, \dots, h_{(l-1)n}) df \\ = \mathcal{N}(h_{ln}; \mu_l(\hat{\mathbf{x}}_n), \sigma_l^2(\hat{\mathbf{x}}_n))$$

where,

$$\mu_l(\hat{\mathbf{x}}_n) = K_l^1(\mathbf{x}_n, \mathbf{Z}_l^1) K_l^1(\mathbf{Z}_l^1, \mathbf{Z}_l^1)^{-1} \mathbf{m}_l^1 + K_l^2(h_{1n}, \mathbf{Z}_l^2) K_l^2(\mathbf{Z}_l^2, \mathbf{Z}_l^2)^{-1} \mathbf{m}_l^2 + \dots + K_l^l(h_{(l-1)n}, \mathbf{Z}_l^l) K_l^l(\mathbf{Z}_l^l, \mathbf{Z}_l^l)^{-1} \mathbf{m}_l^l \\ \sigma_l^2(\hat{\mathbf{x}}_n) = K_l^1(\mathbf{x}_n, \mathbf{x}_n) + K_l^1(\mathbf{x}_n, \mathbf{Z}_l^1) K_l^1(\mathbf{Z}_l^1, \mathbf{Z}_l^1)^{-1} (K_l^1(\mathbf{Z}_l^1, \mathbf{Z}_l^1) - \mathbf{S}_l^1) K_l^1(\mathbf{Z}_l^1, \mathbf{Z}_l^1)^{-1} K_l^1(\mathbf{Z}_l^1, \mathbf{x}_n) \\ + K_l^2(h_{1n}, h_{1n}) + K_l^2(h_{1n}, \mathbf{Z}_l^2) K_l^2(\mathbf{Z}_l^2, \mathbf{Z}_l^2)^{-1} (K_l^2(\mathbf{Z}_l^2, \mathbf{Z}_l^2) - \mathbf{S}_l^2) K_l^2(\mathbf{Z}_l^2, \mathbf{Z}_l^2)^{-1} K_l^2(\mathbf{Z}_l^2, h_{1n}) \\ + \dots \\ + K_l^l(h_{(l-1)n}, h_{(l-1)n}) + K_l^l(h_{(l-1)n}, \mathbf{Z}_l^l) K_l^l(\mathbf{Z}_l^l, \mathbf{Z}_l^l)^{-1} (K_l^l(\mathbf{Z}_l^l, \mathbf{Z}_l^l) - \mathbf{S}_l^l) K_l^l(\mathbf{Z}_l^l, \mathbf{Z}_l^l)^{-1} K_l^l(\mathbf{Z}_l^l, h_{(l-1)n}) \\ + \sigma^2$$

Here, $\mathbf{Z}_l^2 \dots \mathbf{Z}_l^l$ will be vectors, since input is univariate.

Model 1: Forward direction is in red, backward direction is in black, observations are in bold:

| | | | | |
|-------------------------|------------|--------------------|--------------------|-----------------------------|
| h_{1n} : | $g_1(x_n)$ | $h_{13}(g_3(x_n))$ | $h_{12}(g_2(x_n))$ | $h_{123}(h_{23}(g_3(x_n)))$ |
| h_{2n} : | $g_2(x_n)$ | $h_{21}(g_1(x_n))$ | $h_{23}(g_3(x_n))$ | |
| h_{3n} : | $g_3(x_n)$ | $h_{31}(g_1(x_n))$ | $h_{32}(g_2(x_n))$ | $h_{321}(h_{21}(g_1(x_n)))$ |

The number of GPs will explode as the Pascal's Triangle.

The above model can also be relaxed as Model 2:

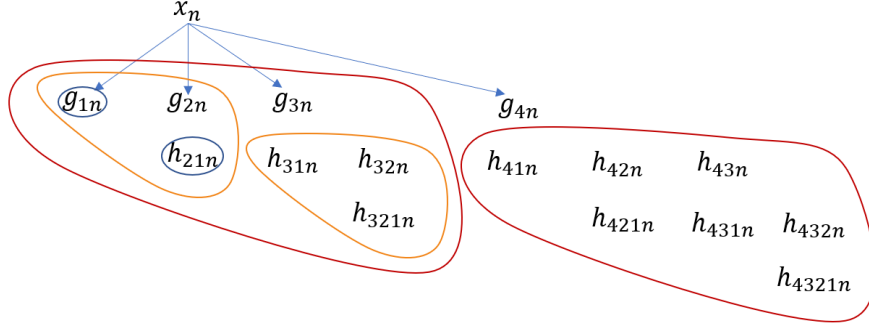
| | | | | | | |
|------------|------------------|------------------|------------|------------------|------------------|------------|
| t_{1n} : | | | $g_1(x_n)$ | $g_{13}(b_{3n})$ | $g_{12}(b_{2n})$ | : b_{1n} |
| t_{2n} : | | $g_{21}(t_{1n})$ | $g_2(x_n)$ | $g_{23}(b_{3n})$ | | : b_{2n} |
| t_{3n} : | $g_{32}(t_{2n})$ | $g_{31}(t_{1n})$ | $g_3(x_n)$ | | | : b_{1n} |

where the hidden variables in two directions share the GP over input as follows,

$$t_{1n} = g_1(x_n) \\ t_{2n} = g_2(x_n) + g_{21}(t_{1n}) \\ t_{3n} = g_3(x_n) + g_{32}(t_{2n}) + g_{31}(t_{1n}) \\ \\ b_{3n} = g_3(x_n) \\ b_{2n} = g_2(x_n) + g_{23}(b_{3n}) \\ b_{1n} = g_1(x_n) + g_{12}(b_{2n}) + g_{13}(b_{3n}) \\ \\ h_{1n} = g_1(x_n) + g_{12}(b_{2n}) + g_{13}(b_{3n}) \\ h_{2n} = g_2(x_n) + g_{21}(t_{1n}) + g_{23}(b_{3n}) \\ h_{3n} = g_3(x_n) + g_{32}(t_{2n}) + g_{31}(t_{1n})$$

Just like Model 1, Model 2's backwards direction does not have any duplicated function over time. The number of GPs is L^2 , where L is number of outputs. However, the dependencies will still run through aggregated hidden variables, except that time and each previous output are explicitly separated.

For Model 1 forward version:



$$\begin{aligned}
p(\mathbf{y}, g_{1:3}, h_{21,31,32,321}) &= p(g_{1 \neq \mathbf{u}_1} | \mathbf{u}_1) p(g_{2 \neq \mathbf{u}_2} | \mathbf{u}_2) p(g_{3 \neq \mathbf{u}_3} | \mathbf{u}_3) p(\mathbf{u}_1) p(\mathbf{u}_2) p(\mathbf{u}_3) \\
&\quad p(h_{21 \neq \mathbf{v}_1} | \mathbf{v}_1) p(h_{31 \neq \mathbf{v}_2} | \mathbf{v}_2) p(h_{32 \neq \mathbf{v}_3} | \mathbf{v}_3) p(\mathbf{v}_1) p(\mathbf{v}_2) p(\mathbf{v}_3) \\
&\quad p(h_{321 \neq \mathbf{w}_1} | \mathbf{w}_1) p(\mathbf{w}_1) \\
&\quad \prod_n p(y_{1n}; g_1(x_n), \sigma_1^2) \\
&\quad p(y_{2n}; g_2(x_n) + h_{21}(g_1(x_n)), \sigma_2^2) \\
&\quad p(y_{3n}; g_3(x_n) + h_{31}(g_1(x_n)) + h_{32}(g_2(x_n)) + h_{321}(h_{21}(g_1(x_n))), \sigma_3^2)
\end{aligned}$$

$$\begin{aligned}
q(g_{1:3}, h_{21,31,321}) &= p(g_{1 \neq \mathbf{u}_1} | \mathbf{u}_1) p(g_{2 \neq \mathbf{u}_2} | \mathbf{u}_2) p(g_{3 \neq \mathbf{u}_3} | \mathbf{u}_3) q(\mathbf{u}_1) q(\mathbf{u}_2) q(\mathbf{u}_3) \\
&\quad p(h_{21 \neq \mathbf{v}_1} | \mathbf{v}_1) p(h_{31 \neq \mathbf{v}_2} | \mathbf{v}_2) p(h_{32 \neq \mathbf{v}_3} | \mathbf{v}_3) q(\mathbf{v}_1) q(\mathbf{v}_2) q(\mathbf{v}_3) \\
&\quad p(h_{321 \neq \mathbf{w}_1} | \mathbf{w}_1) q(\mathbf{w}_1)
\end{aligned}$$

$$\begin{aligned}
\mathcal{L}_{ELBO} &= \mathbb{E}_q \left[\frac{p(\mathbf{y}, g_{1:3}, h_{21,31,32,321})}{q(g_{1:3}, h_{21,31,321})} \right] \\
&= \sum_n \int q(g_{1n} | x_n) \log p(y_{1n} | g_{1n}, \sigma_1^2) \\
&\quad + \sum_n \int q(g_{1n} | x_n) q(g_{2n} | x_n) q(h_{21n} | g_{1n}) \log p(y_{2n} | g_{2n}, h_{21n}, \sigma_2^2) \\
&\quad + \sum_n \int q(g_{1n} | x_n) q(g_{2n} | x_n) q(g_{3n} | x_n) \\
&\quad \quad q(h_{21n} | g_{1n}) q(h_{31n} | g_{1n}) q(h_{32n} | g_{2n}) q(h_{321n} | h_{21n}) \log p(y_{3n} | g_{3n}, h_{31n}, h_{32n}, h_{321n}, \sigma_3^2) \\
&\quad - \sum_{\mathbf{u}: \text{all inducing points}} KL(q(\mathbf{u}) || p(\mathbf{u}))
\end{aligned}$$

where $q(\cdot | \cdot)$ is the variational posterior with inducing points analytically marginalized out. The following table shows the space where each GP's inducing inputs should lie.

| | |
|-------------|----------------------------|
| $g_{1:3}$ | \mathcal{X} |
| $h_{21,31}$ | $g_1(\mathcal{X})$ |
| h_{32} | $g_2(\mathcal{X})$ |
| h_{321} | $h_{21}(g_2(\mathcal{X}))$ |

If bi-directional is implemented, the expectation log-term will be:

$$\begin{aligned}
& \sum_n \int q(g_{1n}|x_n)q(g_{2n}|x_n)q(g_{3n}|x_n) \\
& \left[\int q(h_{13n}|g_{3n})q(h_{12n}|g_{2n})q(h_{23n}|g_{3n})q(h_{123n}|h_{23n}) \log p(y_{1n}|g_{1n}, h_{13n}, h_{12n}, h_{123n}, \sigma_1^2) \right. \\
& \int q(h_{21n}|g_{1n})q(h_{23n}|g_{3n}) \log p(y_{2n}|g_{2n}, h_{21n}, h_{23n}, \sigma_2^2) \\
& \left. \int q(h_{21n}|g_{1n})q(h_{31n}|g_{1n})q(h_{32n}|g_{2n})q(h_{321n}|h_{21n}) \log p(y_{3n}|g_{3n}, h_{31n}, h_{32n}, h_{321n}, \sigma_3^2) \right]
\end{aligned}$$