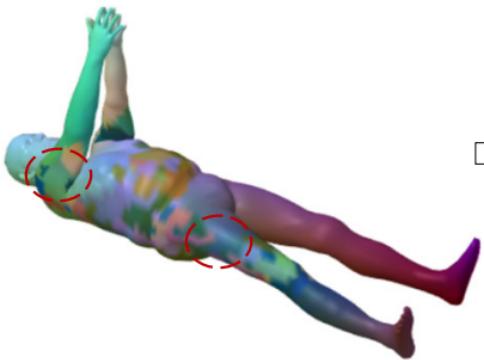


Noisy Pointwise Map



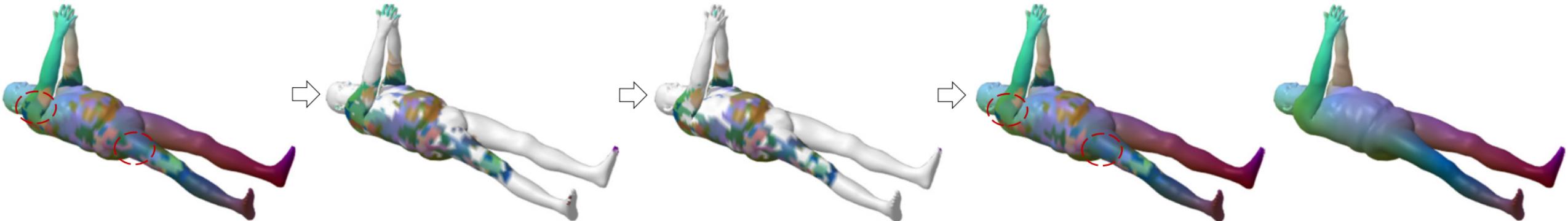
Distinguish Inliers

Local Consistency

Functional Deformation

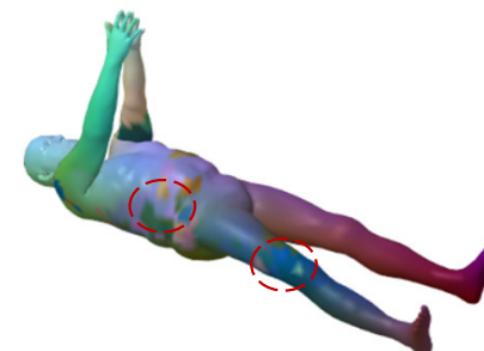
Outlier Refinement

GT



3rd Iteration

Final



4th Iteration