

$$\begin{aligned}
 1. \text{ The Lagrangian is } L(t, x, Z, z, v) &= \frac{1}{t} - \text{tr}(Z \left(\sum_{i=1}^P x_i v_i v_i^T + tI \right)) - Z^T x + v^T (1^T x - 1) \\
 &= \frac{1}{t} + t \text{tr}(Z) - \text{tr}(Z \sum_{i=1}^P x_i v_i v_i^T) - Z^T x + v^T 1^T x - v \\
 &= \frac{1}{t} + t \text{tr}(Z) - \sum_{i=1}^P \text{tr}(Z x_i v_i v_i^T) - Z^T x + v^T 1^T x - v \\
 &= \frac{1}{t} + t \text{tr}(Z) - \sum_{i=1}^P x_i \text{tr}(v_i^T Z v_i) - Z^T x + v^T 1^T x - v \\
 &= \frac{1}{t} + t \text{tr}(Z) + \sum_{i=1}^P x_i (-v_i^T Z v_i - z_i + v) - v
 \end{aligned}$$

The dual function is thus $g(Z, z, v) = \inf_{t>0} L(t, x, Z, z, v)$

$$= \begin{cases} z \sqrt{\text{tr} Z} - v & \text{if } v_i^T Z v_i + z_i = v, Z \succ 0 \\ -\infty & \text{o.w.} \end{cases}$$

The dual problem is thus

$$\begin{aligned}
 \max & \quad 2\sqrt{\text{tr} Z} - v \\
 \text{s.t.} & \quad v_i^T Z v_i + z_i = v \\
 & \quad Z \succ 0, z \geq 0
 \end{aligned}$$

It can be simplified to

$$\begin{aligned}
 \max & \quad 2\sqrt{\text{tr} Z} - v \\
 \text{s.t.} & \quad v_i^T Z v_i \leq v \\
 & \quad Z \succ 0
 \end{aligned}$$

2(a) We know \hat{x} minimizes $\sum_{i=1}^m \phi(a_i^\top x - b_i)$, so the gradient of $\sum_{i=1}^m \phi(a_i^\top x - b_i)$ evaluated at \hat{x} is zero: $\sum_{i=1}^m \hat{r}_i (\hat{r}_i + \varepsilon)^{\frac{1}{2}} a_i = 0$

Now we consider the dual problem of ℓ_1 -norm approximation problem:

$$\max \sum_{i=1}^m b_i \lambda_i$$

$$\text{s.t. } |\lambda_i| \leq 1, i=1, \dots, m$$

$$\sum_{i=1}^m \lambda_i a_i = 0$$

Thus, we see $\lambda_i = -\frac{\hat{r}_i}{(\hat{r}_i^2 + \varepsilon)^{\frac{1}{2}}}, i=1, \dots, m$ is dual feasible. Thus, the dual objective function value at this λ is $\sum_{i=1}^m b_i \lambda_i = \sum -\frac{b_i \hat{r}_i}{(\hat{r}_i^2 + \varepsilon)^{\frac{1}{2}}}$, which is a lower bound for P^* : $P^* \geq \sum_{i=1}^m -\frac{b_i \hat{r}_i}{(\hat{r}_i^2 + \varepsilon)^{\frac{1}{2}}} = \sum_{i=1}^m (a_i^\top \hat{x} - b_i) \frac{\hat{r}_i}{(\hat{r}_i^2 + \varepsilon)^{\frac{1}{2}}} = \sum_{i=1}^m \frac{\hat{r}_i^2}{(\hat{r}_i^2 + \varepsilon)^{\frac{1}{2}}}$

(b). Starting from the result above, subtract $\|A\hat{x} - b\|_1$ from both sides:

$$P^* - \|A\hat{x} - b\|_1 \geq \sum_{i=1}^m \left(\frac{\hat{r}_i^2}{(\hat{r}_i^2 + \varepsilon)^{\frac{1}{2}}} - |\hat{r}_i| \right)$$

Rearrange this inequality:

$$\|A\hat{x} - b\|_1 \leq P^* + \sum_{i=1}^m |\hat{r}_i| \left(1 - \frac{|\hat{r}_i|}{(\hat{r}_i^2 + \varepsilon)^{\frac{1}{2}}} \right)$$

$$\begin{aligned}
 3. \text{ The Lagrangian is } L(x, r, v) &= \sum_{i=1}^m \phi(r_i) + \sum_{i=1}^m v_i (a_i^T x - b_i - r_i) \\
 &= \sum_{i=1}^m (\phi(r_i) - v_i r_i) + x^T A^T v - b^T v
 \end{aligned}$$

$$\begin{aligned}
 \text{The dual is thus } g(v) &= \inf_{r \in R^m} \left(\sum_{i=1}^m (\phi(r_i) - v_i r_i) \right) + \inf_{x \in R^n} (x^T A^T v - b^T v) \\
 &= \sum_{i=1}^m \inf_{r \in R} (\phi(r_i) - v_i r_i) - b^T v, \text{ if } A^T v = 0 \\
 &= - \sum_{i=1}^m \sup_{r \in R} (\phi(r_i) - v_i r_i) - b^T v, \text{ if } A^T v \neq 0 \\
 &= - \sum_{i=1}^m \phi^*(v_i) - b^T v, \text{ if } A^T v = 0
 \end{aligned}$$

where $\phi^*(v_i)$ is the ~~congo~~ conjugate function of penalty function $\phi(u)$.

$$\begin{aligned}
 \text{The Lagrangian dual is thus } \max_{v \in R^m} & - \sum_{i=1}^m \phi^*(v_i) - b^T v \\
 \text{s.t. } & A^T v = 0
 \end{aligned}$$

The problem thus becomes finding the conjugate function of each penalty function.

$$\begin{aligned}
 \text{(a). Deadzone-linear: The conjugate function is } \phi^*(v_i) &= \begin{cases} |v_i|, & \text{if } |v_i| \leq 1 \\ \infty, & \text{if } |v_i| > 1 \end{cases} \\
 \text{Hence, the dual problem is } \max & - \sum_{i=1}^m |v_i| - b^T v \\
 \text{s.t. } & A^T v = 0 \\
 & |v_i| \leq 1, i=1, \dots, m
 \end{aligned}$$

$$\begin{aligned}
 \text{which can be simplified to } \max & - \|v\|_1 - b^T v \\
 \text{s.t. } & A^T v = 0 \\
 & \|v\|_\infty \leq 1, i=1, \dots, m
 \end{aligned}$$

(b). Huber penalty: the conjugate function is $\phi^*(v_i) = \begin{cases} \frac{v_i^2}{4}, & \text{if } |v_i| \leq 2 \\ \infty, & \text{otherwise} \end{cases}$

Hence, the dual problem is $\max -\sum_{i=1}^m \frac{v_i^2}{4} - b^T v$

$$\text{s.t. } A^T v = 0$$

$$|v_i| \leq 2, i=1, \dots, m$$

which can be simplified to $\max -\frac{1}{4} \|v\|_2^2 - b^T v$

$$\text{s.t. } A^T v = 0$$

$$\|v\|_\infty \leq 2$$

(c). Log-barrier: the conjugate function is $\phi^*(v_i) = \sup_{|x|<1} (v_i x + \log(1-x^2)) = -1 + \sqrt{1+v_i^2} + \log(-1+\sqrt{1+v_i^2}) - 2\log|v_i| + \log 2$

Hence, the dual problem is $\max -\sum_{i=1}^m (-1 + \sqrt{1+v_i^2} + \log(-1+\sqrt{1+v_i^2}) - 2\log|v_i| + \log 2) - b^T v$

$$\text{s.t. } A^T v = 0$$

(d). Relative deviation from one: the conjugate function is $\phi^*(v_i) = \begin{cases} -2\sqrt{-v_i}, & \text{if } v_i \leq -1 \\ v_i - 1, & \text{if } -1 \leq v_i \leq 1 \\ -\infty, & \text{if } v_i > 1 \end{cases}$

If $v_i > 1$ for any feasible v_i , the dual objective function value becomes unbounded, which leads to infeasibility in the primal. Hence, here, for to avoid that, we make $v_i \leq 1$ a constraint:

Dual is $\max -\sum_{i=1}^m \phi^*(v_i) - b^T v$

$$\text{s.t. } A^T v = 0$$

$$v \leq 1$$

where $\phi^*(v_i) = \begin{cases} -2\sqrt{-v_i}, & v_i \leq -1 \\ v_i - 1, & v_i \geq -1 \end{cases}$

4. (a) Let $t_i \geq \|A_i x - b\|$, for $i=1, \dots, k$

Then we can rewrite the problem as $\min P^T t$
 s.t. $\|A_i x - b\| \leq t_i, i=1, \dots, k$

$$1). \ell_1\text{-norm: } \min \sum_{i=1}^k P_i \mathbb{1}^T t$$

$$\text{s.t. } -t_i \leq A_i x - b \leq t_i, i=1, \dots, k$$

which is an LP with $x \in \mathbb{R}^n, t \in \mathbb{R}^k, i=1, \dots, k$

$$2). \ell_2\text{-norm: } \min P^T t$$

$$\text{s.t. } \|A_i x - b\|_2 \leq t_i, i=1, \dots, k$$

which is a SOCP with $x \in \mathbb{R}^n, t \in \mathbb{R}^k$

$$3). \ell_\infty\text{-norm: } \min P^T t$$

$$\text{s.t. } -t_i \mathbb{1} \leq A_i x - b \leq t_i \mathbb{1}, i=1, \dots, k$$

which is an LP with $x \in \mathbb{R}^n, t \in \mathbb{R}^k$

(b). Let's take a look at $\sup_{l_{ij} \leq a_{ij} \leq u_{ij}} |a_i^T x - b_i|$, which is the supremum of the absolute value of one component in $Ax - b$ over all possible choice of a_i^T , a vector where each component is bounded by l_{ij} and u_{ij} .

$$\sup_{l_{ij} \leq a_{ij} \leq u_{ij}} |a_i^T x - b_i| = \sup_{l_{ij} \leq a_{ij} \leq u_{ij}} (\max(a_i^T x - b_i, -a_i^T x + b_i)) = \max(\sup_{l_{ij} \leq a_{ij} \leq u_{ij}} (a_i^T x - b_i), \sup_{l_{ij} \leq a_{ij} \leq u_{ij}} (-a_i^T x + b_i))$$

$$\text{Now, consider } \sup_{l_{ij} \leq a_{ij} \leq u_{ij}} (a_i^T x - b_i) = \left| \sum_{j=1}^n \sup_{l_{ij} \leq a_{ij} \leq u_{ij}} (a_{ij} x_j) \right| - b_i = \sum_{j=1}^n (\bar{a}_{ij} x_j + v_{ij} |x_j|) - b_i,$$

$$= \bar{a}_i^T x + v_i^T |x| - b_i;$$

$$\text{where } \bar{a}_{ij} = \frac{l_{ij} + u_{ij}}{2}, v_{ij} = \frac{u_{ij} - l_{ij}}{2}.$$

Similarly, $\sup_{d_{ij} \leq a_{ij} \leq u_{ij}} (-a_i^T x + b_i) = -\bar{a}_i^T x + v_i^T |x| + b_i$

Therefore, $\sup_{d_{ij} \leq a_{ij} \leq u_{ij}} |\bar{a}_i^T x - b_i| = |\bar{a}_i^T x - b_i| + v_i^T |x|$

1). ℓ_1 -norm: $\min \sum_{i=1}^m (|\bar{a}_i^T x - b_i| + v_i^T |x|)$, which can be expressed as

$$\begin{aligned} & \min \mathbb{1}^T (y + Vw) \quad \text{which is an LP with } y \in \mathbb{R}^m, x \in \mathbb{R}^n, w \in \mathbb{R}^n. \\ \text{s.t. } & -y \leq \bar{A}x - b \leq y \\ & -w \leq x \leq w. \end{aligned}$$

2). ℓ_2 -norm: $\min \sum_{i=1}^m (|\bar{a}_i^T x - b_i| + v_i^T |x|)^2$, which can be expressed as

$$\begin{aligned} & \min t \quad \text{which is a SOCP with } y \in \mathbb{R}^m, x \in \mathbb{R}^n, w \in \mathbb{R}^n, t \in \mathbb{R} \\ \text{s.t. } & -y \leq \bar{A}x - b \leq y \\ & -w \leq x \leq w \\ & \|y + Vw\|_2 \leq t, \end{aligned}$$

3) ℓ_∞ -norm: $\min \max_{i=1,\dots,m} (|\bar{a}_i^T x - b_i| + v_i^T |x|)$, which can be expressed as

$$\begin{aligned} & \min t \quad \text{which is an LP with } y \in \mathbb{R}^m, x \in \mathbb{R}^n, w \in \mathbb{R}^n, t \in \mathbb{R} \\ \text{s.t. } & -y \leq \bar{A}x - b \leq y \\ & -w \leq x \leq w \\ & -t \mathbb{1} \leq \overline{\bar{A}x - b} + Vw \leq t \mathbb{1}, \end{aligned}$$

$$(c). P_i = \{a \mid C_i a \leq d_i\}.$$

$$\sup_{a \in P_i} |a^T x - b_i| = \sup_{a \in P_i} \max(a^T x - b_i, -a^T x + b_i) = \max(\sup_{a \in P_i} (a^T x - b_i), \sup_{a \in P_i} (-a^T x + b_i))$$

By LP strong duality

$$\sup_{a \in P_i} a^T x = \inf \{d_i^T v \mid C_i^T v = x, v \geq 0\} \quad \sup_{a \in P_i} -a^T x = \inf \{d_i^T w \mid C_i^T w = -x, w \geq 0\}$$

Therefore, $t_i \geq \sup_{a \in P_i} |a^T x - b_i|$ iff there exist v, w , such that

$$v, w \geq 0, x = C_i^T v = -C_i^T w, d_i^T v \leq t_i, d_i^T w \leq t_i$$

This allows us to pose the original problem as

$$\begin{aligned} & \min \|t\| \\ \text{s.t. } & x = C_i^T v_i, x = -C_i^T w_i, i=1, \dots, m \\ & d_i^T v_i \leq t_i, d_i^T w_i \leq t_i, i=1, \dots, m \\ & v_i \geq 0, w_i \geq 0, i=1, \dots, m \end{aligned}$$

1). ℓ_1 -norm: $\min \|t\|$

$$\begin{aligned} \text{s.t. } & x = C_i^T v_i, x = -C_i^T w_i, i=1, \dots, m \\ & d_i^T v_i \leq t_i, d_i^T w_i \leq t_i, i=1, \dots, m \\ & v_i \geq 0, w_i \geq 0, i=1, \dots, m \end{aligned}$$

which is an LP with $t \in \mathbb{R}^m$, $x \in \mathbb{R}^n$, $v_i \in \mathbb{R}^m$, $w_i \in \mathbb{R}^m$, $i=1, \dots, m$

2) ℓ_2 -norm: $\min_u u$
 s.t. $x = C_i^T v_i, x = -C_i^T w_i, i=1, \dots, m$
 $d_i^T v_i \leq t_i, d_i^T w_i \leq t_i, i=1, \dots, m$
 $v_i \geq 0, w_i \geq 0, i=1, \dots, m$
 $\|t\|_2 \leq u,$

which is a SOCP with $u \in \mathbb{R}^+$, $t \in \mathbb{R}^m$, $x \in \mathbb{R}^n$, $v_i \in \mathbb{R}^m$, $w_i \in \mathbb{R}^m$, $i=1, \dots, m$

3) ℓ_∞ -norm: $\min_t t$
 s.t. $x = C_i^T v_i, x = -C_i^T w_i, i=1, \dots, m$
 $d_i^T v_i \leq t, d_i^T w_i \leq t, i=1, \dots, m$
 $v_i \geq 0, w_i \geq 0, i=1, \dots, m$

which is an LP with $t \in \mathbb{R}$, $x \in \mathbb{R}^n$, $v_i \in \mathbb{R}^m$, $w_i \in \mathbb{R}^m$, $i=1, \dots, m$