1. (a) x is an EP of $P \iff f(x)$ is an EP of Q

- direction: Assume f(x) is not an EP of Q. Then $f(x) = \lambda y + (1-\lambda) z$ for some $y, z \in Q$, $\lambda \in [0,1]$. We apply g to both sides and have $\chi = g(f(x)) = g(\lambda y + (1-\lambda)z) = \lambda g(y) + (1-\lambda)g(z)$, which implies that χ can be written as a convex combination of another two points χ can be written as a convex combination of another χ contradiction χ
- direction: Similarly, we first assume x is not an EP of f, which means $x = \lambda y + (1-\lambda) z$ for some $y, z \in f$, $\lambda \in [0,1]$. We apply f to both sides and we have $f(x) = f(\lambda y + (1-\lambda)z) = \lambda f(y) + (1-\lambda)f(z)$, which implies f(x) is not an EP in Q. Contradiction f(x)
- (b). Consider the following affine mapping $f(x) = \widehat{A} \times + \widehat{b}, \text{ where } \widehat{A} = \begin{bmatrix} I \\ A \end{bmatrix}_{(n+k)\times n}, \widehat{b} = \begin{bmatrix} 0 \\ -b \end{bmatrix}_{(n+k)\times 1}, \quad x \in \mathbb{R}^n$ $g(y) = A'y + b', \text{ where } A' = \begin{bmatrix} I & 0 \end{bmatrix}_{n\times (n+k)}, \quad b' = 0_{n\times 1}, \quad y \in \mathbb{R}^{n+k}$ It can be easily shown that g(f(x)) = x for all $x \in \mathbb{P}$, and f(g(y)) = y for all $y \in \mathbb{R}$.
 Thus, P and Q are isomorphic.

2. Let \hat{x} be an EP of Q. If \hat{x} is also an extreme point, good If is not an Efoff, then in he know Let \hat{x} be an EP of Q. If \hat{x} happens to be the EP of \hat{P} , great! Suppose \hat{x} is not an EP of Γ We know that \hat{x} has n active constraints since \hat{x} is an EP. One of them is the $a^{T}x = b$ constraint and this means \hat{x} has another n-1 active constriants that are associated with P This means & lies on the segment defined by these n-1 active constraints, which has two extreme points on each & side. Hence, & can be unitten as a convex combination of these two extreme points. 3. Proof by contradiction: Assume there the optimal solution $x' \in \Gamma$ does not satisfy Ax'=c. That is, there exists x' s.t. Ax' 7c, x'zo, and c'x'cctx* $Ax'>C \Rightarrow (Ax')^{\top}>C^{\top} \Rightarrow (Ax')^{\top}x^*>C^{\top}x^*>C^{\top}x'$. We can see that the left-hand is $[A \times')^T \times^* = \chi' A^T \times^* = \chi'' A \times^* = \chi'' C = C^T \chi'$. Hence, we get $C^T \times' > C^T \times'$, Contradiction Thus, every optimal solution x* should satisfy Ax'=C, x'=0. 4. Idea: Write an equivalent statement (a') to (a), Apply theorem of alternative to get (b'), prove (b) is equivalent to b. (a) can be rewritten as the following statement: (a): $\exists x \in \mathbb{R}^n$ s.t. $\widehat{A} \times \subseteq \widehat{b}$, where $\widehat{A} = \begin{bmatrix} A \\ C \\ -C \end{bmatrix} \in \mathbb{R}^{(m+2p)\times n}$, $\widehat{b} = \begin{bmatrix} b \\ d \end{bmatrix} \in \mathbb{R}^{m+2p}$ Apply the theorem of alternative we can have *(a')'s alternative: (b'): $\exists \begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{w} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{k} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{k} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{k} \end{bmatrix} \not= 0$, $\exists \vec{\xi} \in \mathbb{R}^{m+2P}$ s.t. $\begin{bmatrix} \vec{\xi} \\ \vec{k} \end{bmatrix} \not= 0$, we get ZZO, VZV, WZO, A=+ CT(V-W)=0, b=+dT(V-W)<0. (See next page)

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5. Idea: write down the statement in standard form, apply Farkas' Lemma to get the alternative, and show the alternative never hold.

Rewrite the statement as:
(I) $\exists y \in \mathbb{R}^n \text{ s.t. } Ay = b \text{ and } y \ge 0$, where $A = \begin{bmatrix} P - I \\ 1^T \end{bmatrix} \in \mathbb{R}^{(n+1)\times n}, b = \begin{bmatrix} 0 \end{bmatrix} \in \mathbb{R}^{n+1}$ Its alternative is $1 = \begin{bmatrix} \frac{1}{4} \end{bmatrix}$ (I) $\exists x \in \mathbb{R}^{n+1} \text{ s.t. } A^T x = 0, b^T x < 0.$

Let's expand (II) and we have $x = \begin{bmatrix} x_{i,n} \\ x_{n+1} \end{bmatrix}$, $\begin{bmatrix} (P-I)^T \\ x_{n+1} \end{bmatrix} \begin{bmatrix} x_{i,n} \\ x_{n+1} \end{bmatrix} \ge 0$, $\begin{bmatrix} 0 \\ 1 \end{bmatrix} \begin{bmatrix} x_{i,n} \\ x_{n+1} \end{bmatrix} < 0$

which is $(P-I)^{T} \chi_{1,n} + 1 \chi_{n+1} \ge 0, \quad \chi_{n+1} < 0$

This means $\exists x_{in} \in \mathbb{R}^n$ s.t. $(P-I)^T x_{in} > 0$. Recall that P is a matrix with non-negative entries, and each column of P sums up to 1, so, this will never be satisfied. $\frac{1}{2}$ in [0,1]

Thus. (I) always holds.