

**Goal:** In this lecture we talk about strong convexity and smoothness and their side results.

## 1 Unconstrained optimization

In this lecture (and the following lectures), we focus on studying iterative methods for solving unconstrained convex problems. An important property of this class of problems is that

$\hat{\mathbf{x}}$  is a global minimum if and only if  $\nabla f(\hat{\mathbf{x}}) = 0$ .

In this lecture, we focus on minimizing a strongly convex function and characterize the number of iterations for solving such problems.

## 2 Strong convexity

**Definition 1.** If there exists a constant  $m > 0$  such that

$$f(\mathbf{y}) \geq f(\mathbf{x}) + \langle \nabla f(\mathbf{x}), \mathbf{y} - \mathbf{x} \rangle + \frac{m}{2} \|\mathbf{y} - \mathbf{x}\|^2 \quad (1)$$

for all  $\mathbf{x}, \mathbf{y} \in S$ , then the function  $f$  is  $m$ -strongly convex on  $S$ .

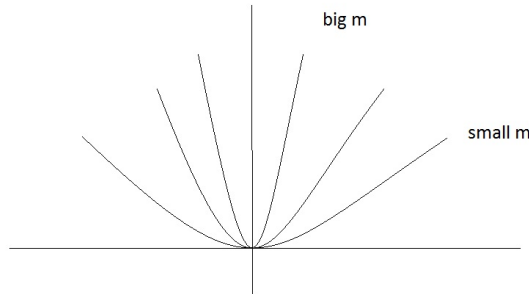


Figure 1: A strongly convex function with different parameter  $m$ . The larger  $m$  is, the steeper the function looks like.

When  $m = 0$ , we recover the basic inequality characterizing convexity; for  $m > 0$ , we obtain a better lower bound on  $f(\mathbf{y})$  than that from convexity alone. The value of  $m$  reflects the shape of convex functions.

Typically as shown in Figure (1), a small  $m$  corresponds to a ‘flat’ convex function while a large  $m$  corresponds to a ‘steep’ convex function.

## 2.1 Side results of strong convexity

Strong convexity has several interesting consequences. We will see that we can bound both  $f^* - f(\mathbf{x})$  and  $\|\mathbf{x} - \mathbf{x}^*\|_2$  in this section.

**Lemma 1.** *Consider a differentiable function  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  that is  $m$ -strongly convex. Then, the objective function sub-optimality  $f(\mathbf{x}) - f^*$  is bounded above by*

$$f(\mathbf{x}) - f(\mathbf{x}^*) \leq \frac{1}{2m} \|\nabla f(\mathbf{x})\|_2^2$$

*Proof.* The righthand side of the strong convexity inequality is a convex quadratic function of  $y$  (for fixed  $x$ ). Setting the gradient with respect to  $y$  equal to zero, we can find the  $\tilde{y}$  that minimizes the right hand side.

$$\begin{aligned} \frac{\partial}{\partial x}(f(x) + \langle \nabla f(x), y - x \rangle + \frac{m}{2} \|y - x\|^2) &= 0 \\ \nabla f(x) - m(y - x) &= 0 \\ y &= x - \frac{1}{m} \nabla f(x) \end{aligned}$$

So  $\tilde{y} = x - (1/m)\nabla f(x)$  minimizes the righthand side. Plug this into the righthand side, we can derive the lower bound of  $f(y)$ , for arbitrary  $y$ .

$$\begin{aligned} f(y) &\geq f(x) + \langle \nabla f(x), y - x \rangle + \frac{m}{2} \|y - x\|^2 \\ &\geq f(x) + \langle \nabla f(x), \tilde{y} - x \rangle + \frac{m}{2} \|\tilde{y} - x\|^2 \\ &= f(x) - \frac{1}{2m} \|\nabla f(x)\|^2 \end{aligned}$$

By substituting  $y$  with  $x^*$ ,

$$f^* \geq f(x) - \frac{1}{2m} \|\nabla f(x)\|^2 \tag{2}$$

and therefore

$$f(\mathbf{x}) - f(\mathbf{x}^*) \leq \frac{1}{2m} \|\nabla f(\mathbf{x})\|^2$$

□

This result allows us to realize how fast you get to a minimum as a function of gradient. If the gradient is small at a point, then the point is nearly optimal. This upper bound also implies that if we find a point  $\hat{\mathbf{x}}$  such that,  $\|\nabla f(\hat{\mathbf{x}})\|_2 \leq \sqrt{2m\epsilon}$ , then we can conclude that  $\hat{\mathbf{x}}$  is  $\epsilon$ -suboptimal, i.e.,  $f(\hat{\mathbf{x}}) - f(\mathbf{x}^*) \leq \epsilon$ .

Similarly, we can also derive an upper bound on  $\|\mathbf{x} - \mathbf{x}^*\|_2$ , the distance between  $x$  and any optimal point  $x^*$ , in terms of  $\|\nabla f(\mathbf{x})\|_2$ :

**Lemma 2.** *Consider a differentiable function  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  that is  $m$ -strongly convex. Then, the optimality distance  $\|\mathbf{x} - \mathbf{x}^*\|_2$  is bounded above by*

$$\|\mathbf{x} - \mathbf{x}^*\|_2 \leq \frac{2}{m} \|\nabla f(\mathbf{x})\|_2 \tag{3}$$

where  $\mathbf{x}^* = \arg \min_{\mathbf{x}} f(\mathbf{x})$  is the unique minimizer of  $f$ .

*Proof.* We apply (1) with  $y = x^*$  to obtain:

$$\begin{aligned} f^* = f(x^*) &\geq f(x) + \langle \nabla f(x), x^* - x \rangle + \frac{m}{2} \|x^* - x\|_2^2 \\ &\geq f(x) - \|\nabla f(x)\|_2 \|x^* - x\|_2 + \frac{m}{2} \|x^* - x\|_2^2, \end{aligned}$$

Since  $f^* \leq f(x)$ , the terms following  $f(x)$  on the righthand side must be negative. We have

$$\begin{aligned} -\|\nabla f(x)\|_2 \|x^* - x\|_2 + \frac{m}{2} \|x^* - x\|_2^2 &\leq 0 \\ \|x - x^*\|_2 &\leq \frac{2}{m} \|\nabla f(x)\|_2 \end{aligned}$$

from which (3) follows.  $\square$

One consequence of (3) is the solution locates within a ball of radius of  $\frac{2}{m} \|\nabla f(x)\|_2$  around the optimal solution.

**Lemma 3.** Consider a differentiable function  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  that is  $m$ -strongly convex. Then, for any  $\mathbf{x}$  and  $\mathbf{y}$  and  $\alpha \in [0, 1]$  we have

$$f(\alpha \mathbf{x} + (1 - \alpha) \mathbf{y}) \leq \alpha f(\mathbf{x}) + (1 - \alpha) f(\mathbf{y}) - \frac{\alpha(1 - \alpha)m}{2} \|\mathbf{x} - \mathbf{y}\|^2$$

and

$$(\nabla f(\mathbf{x}) - \nabla f(\mathbf{y}))^\top (\mathbf{x} - \mathbf{y}) \geq m \|\mathbf{x} - \mathbf{y}\|^2$$

*Proof.* Homework.  $\square$

### 3 Smoothness (Lipschitz continuous gradients)

**Definition 2.** A differentiable function  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is called  $M$ -smooth or has  $M$ -Lipschitz continuous gradients if for some  $M > 0$  we have

$$\|\nabla f(\mathbf{x}) - \nabla f(\mathbf{y})\| \leq M \|\mathbf{x} - \mathbf{y}\|.$$

This condition implies that the derivatives of the function do not change rapidly when two points are close to each other.

**Lemma 4.** If  $f$  is  $M$ -smooth, then the following condition holds

$$f(\mathbf{y}) \leq f(\mathbf{x}) + \nabla f(\mathbf{x})^\top (\mathbf{y} - \mathbf{x}) + \frac{M}{2} \|\mathbf{y} - \mathbf{x}\|^2 \quad (4)$$

*Proof.* We know that

$$\begin{aligned} f(\mathbf{y}) &= f(\mathbf{x}) + \int_0^1 \nabla f(s\mathbf{x} + (1 - s)\mathbf{y})^\top (\mathbf{y} - \mathbf{x}) ds \\ &= f(\mathbf{x}) + \nabla f^\top (\mathbf{y} - \mathbf{x}) + \int_0^1 (\nabla f(s\mathbf{x} + (1 - s)\mathbf{y}) - \nabla f(\mathbf{x}))^\top (\mathbf{y} - \mathbf{x}) ds \end{aligned}$$

Hence,

$$\begin{aligned}
|f(\mathbf{y}) - f(\mathbf{x}) - \nabla f^\top(\mathbf{y} - \mathbf{x})| &\leq \left| \int_0^1 (\nabla f(s\mathbf{x} + (1-s)\mathbf{y}) - \nabla f(\mathbf{x}))^\top (\mathbf{y} - \mathbf{x}) ds \right| \\
&\leq \int_0^1 \left\| \nabla f(s\mathbf{x} + (1-s)\mathbf{y}) - \nabla f(\mathbf{x}) \right\|^\top (\mathbf{y} - \mathbf{x}) \left\| ds \right. \\
&\leq \int_0^1 \left\| \nabla f(s\mathbf{x} + (1-s)\mathbf{y}) - \nabla f(\mathbf{x}) \right\| \|\mathbf{y} - \mathbf{x}\| ds \\
&\leq \|\mathbf{y} - \mathbf{x}\| \int_0^1 M(1-s) \|\mathbf{y} - \mathbf{x}\| ds \\
&= \frac{M}{2} \|\mathbf{y} - \mathbf{x}\|^2
\end{aligned}$$

□

### 3.1 Side results of smoothness

We can use  $M$ -smoothness to derive a lower bound on the suboptimality:

**Lemma 5.** *If the function  $f$  is smooth, then*

$$f(\mathbf{x}) - f^* \geq \frac{1}{2M} \|\nabla f(\mathbf{x})\|_2^2$$

*Proof.* We can minimize both sides of the following inequality with respect to  $\mathbf{y}$

$$\min_{\mathbf{y}} f(\mathbf{y}) \leq \min_{\mathbf{y}} \left( f(\mathbf{x}) + \nabla f(\mathbf{x})^\top (\mathbf{y} - \mathbf{x}) + \frac{M}{2} \|\mathbf{y} - \mathbf{x}\|^2 \right)$$

which implies that the optimal solution for the right hand side  $\tilde{\mathbf{y}}$  is  $\tilde{\mathbf{y}} = \mathbf{x} - \frac{1}{M} \nabla f(\mathbf{x})$ . The optimal value of the left hand side is  $f^*$  and therefore we have

$$f^* \leq f(\mathbf{x}) - \frac{1}{2M} \|\nabla f(\mathbf{x})\|_2^2$$

□

**Lemma 6.** *Consider a differentiable function  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  that is  $M$ -smooth. Then, for any  $\mathbf{x}$  and  $\mathbf{y}$  and  $\alpha \in [0, 1]$  we have*

$$f(\alpha\mathbf{x} + (1-\alpha)\mathbf{y}) \geq \alpha f(\mathbf{x}) + (1-\alpha)f(\mathbf{y}) - \frac{\alpha(1-\alpha)M}{2} \|\mathbf{x} - \mathbf{y}\|^2$$

and

$$(\nabla f(\mathbf{x}) - \nabla f(\mathbf{y}))^\top (\mathbf{x} - \mathbf{y}) \leq M \|\mathbf{x} - \mathbf{y}\|^2$$

*Proof.* Homework.

□

## 4 Strong convexity and smoothness for twice differentiable functions

**Definition 3.** A twice differentiable function is  $m$ -strongly convex if

$$\nabla^2 f(\mathbf{x}) \succeq m\mathbf{I}$$

**Definition 4.** A twice differentiable function is  $M$ -smooth if

$$-M\mathbf{I} \preceq \nabla^2 f(\mathbf{x}) \preceq M\mathbf{I} \quad \Leftrightarrow \quad \|\nabla^2 f(\mathbf{x})\| \leq M$$

Next we show that when a function is twice differentiable, then the definitions of smoothness are equivalent.

For any  $\mathbf{x}$  and  $\mathbf{y}$  we have

$$\begin{aligned} \nabla f(\mathbf{x}) &= \nabla f(\mathbf{y}) + \int_0^1 \nabla^2 f(\mathbf{x} + \tau(\mathbf{y} - \mathbf{x}))(\mathbf{y} - \mathbf{x}) d\tau \\ &= \nabla f(\mathbf{y}) + \left( \int_0^1 \nabla^2 f(\mathbf{x} + \tau(\mathbf{y} - \mathbf{x})) d\tau \right) (\mathbf{y} - \mathbf{x}) \end{aligned}$$

Therefore,

$$\begin{aligned} \|\nabla f(\mathbf{x}) - \nabla f(\mathbf{y})\| &= \left\| \left( \int_0^1 \nabla^2 f(\mathbf{x} + \tau(\mathbf{y} - \mathbf{x})) d\tau \right) (\mathbf{y} - \mathbf{x}) \right\| \\ &\leq \left\| \int_0^1 \nabla^2 f(\mathbf{x} + \tau(\mathbf{y} - \mathbf{x})) d\tau \right\| \|\mathbf{y} - \mathbf{x}\| \\ &\leq \left( \int_0^1 \|\nabla^2 f(\mathbf{x} + \tau(\mathbf{y} - \mathbf{x}))\| d\tau \right) \|\mathbf{y} - \mathbf{x}\| \\ &\leq M\|\mathbf{y} - \mathbf{x}\| \end{aligned}$$

On the other hand, if function  $f$  satisfies  $\|\nabla f(\mathbf{x}) - \nabla f(\mathbf{y})\| \leq M\|\mathbf{x} - \mathbf{y}\|$  then we can show that for any  $\mathbf{s} \in \mathbb{R}^n$  we have

$$\left\| \left( \int_0^\alpha \nabla^2 f(\mathbf{x} + \tau\mathbf{s}) d\tau \right) \cdot \mathbf{s} \right\| = \|\nabla f(\mathbf{x} + \alpha\mathbf{s}) - \nabla f(\mathbf{x})\| \leq \alpha M\|\mathbf{s}\|$$

If we divide this inequality by  $\alpha\|\mathbf{s}\|$  and send  $\alpha \rightarrow 0$ , then we obtain

$$\|\nabla^2 f(\mathbf{x})\| \leq M$$

## 5 Condition Number

From the strong convexity inequality and the smoothness inequality, we have:

$$m\mathbf{I} \preceq \nabla^2 f(\mathbf{x}) \preceq M\mathbf{I} \tag{5}$$

**Definition 5.** If  $m\mathbf{I} \preceq \nabla^2 f(\mathbf{x}) \preceq M\mathbf{I}$  for all  $\mathbf{x} \in S$ , then the **condition number** of  $f$  is  $\kappa = \frac{M}{m}$ .

The condition number is thus a uniform (and hence upper) bound on the condition number of the matrix  $\nabla^2 f(\mathbf{x})$  at any given  $\mathbf{x}$ .

**Definition 6.** When the ratio is close to 1, we call it **well-conditioned**. When the ratio is very large, we call it **ill-conditioned**.