Problem3

April 19, 2022

1 Problem 3 - PALEO, FLOPs, Platform Percent of Peak (PPP)

This question is based on modeling the execution time of deep learning networks by calculating the floating point operations required at each layer. We looked at two papers in the class, one by Lu et al. and the other by Qi et al.

1.1 1

Why achieving peak FLOPs from hardware devices like GPUs is a difficult propostion in real systems? How does PPP help in capturing this inefficiency captured in Paleo model. (4)

Peak FLOPs is a difficult proposition in real systems: - usually requiring customized libraries developed by organizations with intimate knowledge of the underlying hardware - any computation done outside the scope of PALEO (e.g. job scheduling, data copying) will exacerbate the observed inefficiency in practice.

PPP help in capturing this inefficiency captured in Paleo model: Parameter which captures the average relative inefficiency of the platform compared to peak FLOPS. Highly specialized frameworks (e.g. cuDNN) will in general have a computational PPP that is close to 100%, while frameworks with higher overheads may have PPP constants closer to 50% or less.

In other works, PPP can help us evaluate how much time the computation is at their peak speed.

1.2 2

Lu et al. showed that FLOPs consumed by convolution layers in VG16 account for about 99% of the total FLOPS in the forward pass. We will do a similar analysis for VGG19. Calculate FLOPs for different layers in VGG19 and then calculate fraction of the total FLOPs attributed by convolution layers. (6)

```
[4]: import torch
from torchvision.models import vgg16
from pthflops import count_ops

# Create a network and a corresponding input
device = 'cuda:0'
model = vgg16().to(device)
inp = torch.rand(1,3,224,224).to(device)
```

```
[5]: model
```

```
[5]: VGG(
       (features): Sequential(
         (0): Conv2d(3, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (1): ReLU(inplace=True)
         (2): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
         (3): ReLU(inplace=True)
         (4): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1,
     ceil mode=False)
         (5): Conv2d(64, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
         (6): ReLU(inplace=True)
         (7): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (8): ReLU(inplace=True)
         (9): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
     ceil_mode=False)
         (10): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (11): ReLU(inplace=True)
         (12): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (13): ReLU(inplace=True)
         (14): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (15): ReLU(inplace=True)
         (16): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
     ceil mode=False)
         (17): Conv2d(256, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (18): ReLU(inplace=True)
         (19): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (20): ReLU(inplace=True)
         (21): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (22): ReLU(inplace=True)
         (23): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
     ceil_mode=False)
         (24): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (25): ReLU(inplace=True)
         (26): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (27): ReLU(inplace=True)
         (28): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (29): ReLU(inplace=True)
         (30): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1,
     ceil mode=False)
       )
       (avgpool): AdaptiveAvgPool2d(output_size=(7, 7))
       (classifier): Sequential(
         (0): Linear(in_features=25088, out_features=4096, bias=True)
         (1): ReLU(inplace=True)
         (2): Dropout(p=0.5, inplace=False)
         (3): Linear(in_features=4096, out_features=4096, bias=True)
         (4): ReLU(inplace=True)
         (5): Dropout(p=0.5, inplace=False)
```

```
(6): Linear(in_features=4096, out_features=1000, bias=True)
        )
      )
[44]: | ignore_list = []
      for i, x in enumerate(model.features):
          name = "features_" + str(i)
          if not isinstance(x, torch.nn.modules.conv.Conv2d):
              ignore_list.append(name)
      for i, x in enumerate(model.classifier):
          name = "classifier_" + str(i)
          if not isinstance(x, torch.nn.modules.conv.Conv2d):
              ignore_list.append(name)
[45]: ignore_list
[45]: ['features_1',
       'features_3',
       'features_4',
       'features_6',
       'features_8',
       'features_9',
       'features_11',
       'features_13',
       'features 15',
       'features_16',
       'features_18',
       'features_20',
       'features_22',
       'features_23',
       'features_25',
       'features_27',
       'features_29',
       'features_30',
       'classifier_0',
       'classifier_1',
       'classifier_2',
       'classifier_3',
       'classifier 4',
       'classifier 5',
       'classifier_6']
[46]: conv_res = count_ops(model, inp, ignore_layers=ignore_list)
      total_res = count_ops(model, inp)
      print(conv_res, total_res)
```

```
Operation
              -----
              89915392
features_0
features_2
              1852899328
features 5
              926449664
features_7
              1851293696
features_10
              925646848
features_12
              1850490880
features_14
              1850490880
features_17
              925245440
features_19
              1850089472
features_21
              1850089472
features_24
              462522368
features_26
              462522368
features_28
              462522368
avgpool
              1229312
Input size: (1, 3, 224, 224)
15,361,407,488 FLOPs or approx. 15.36 GFLOPs
Operation
               OPS
features 0
               89915392
features_1
               6422528
features_2
               1852899328
features_3
               6422528
features_4
               2408448
features_5
               926449664
features_6
               3211264
features_7
               1851293696
features_8
               3211264
features_9
               1204224
               925646848
features_10
features_11
               1605632
features_12
               1850490880
features_13
               1605632
features_14
               1850490880
features_15
               1605632
features_16
               602112
features_17
               925245440
features_18
               802816
features_19
               1850089472
features_20
               802816
features_21
               1850089472
features_22
               802816
features_23
               301056
features_24
               462522368
features_25
               200704
features_26
               462522368
```

OPS

```
features_27
                    200704
     features_28
                    462522368
     features_29
                    200704
     features_30
                    75264
     avgpool
                    1229312
     classifier 0
                    102764544
     classifier 1
                    8192
     classifier 3
                    16781312
     classifier_4
                    8192
     classifier 6
                    4097000
     Input size: (1, 3, 224, 224)
     15,516,752,872 FLOPs or approx. 15.52 GFLOPs
     (15361407488, [['features_0', 89915392], ['features_2', 1852899328],
     ['features_5', 926449664], ['features_7', 1851293696], ['features_10',
     925646848], ['features_12', 1850490880], ['features_14', 1850490880],
     ['features_17', 925245440], ['features_19', 1850089472], ['features_21',
     1850089472], ['features_24', 462522368], ['features_26', 462522368],
     ['features_28', 462522368], ['avgpool', 1229312]]) (15516752872, [['features_0',
     89915392], ['features_1', 6422528], ['features_2', 1852899328], ['features_3',
     6422528], ['features 4', 2408448], ['features 5', 926449664], ['features 6',
     3211264], ['features_7', 1851293696], ['features_8', 3211264], ['features_9',
     1204224], ['features_10', 925646848], ['features_11', 1605632], ['features_12',
     1850490880], ['features_13', 1605632], ['features_14', 1850490880],
     ['features_15', 1605632], ['features_16', 602112], ['features_17', 925245440],
     ['features_18', 802816], ['features_19', 1850089472], ['features_20', 802816],
     ['features_21', 1850089472], ['features_22', 802816], ['features_23', 301056],
     ['features_24', 462522368], ['features_25', 200704], ['features_26', 462522368],
     ['features_27', 200704], ['features_28', 462522368], ['features_29', 200704],
     ['features_30', 75264], ['avgpool', 1229312], ['classifier_0', 102764544],
     ['classifier_1', 8192], ['classifier_3', 16781312], ['classifier_4', 8192],
     ['classifier_6', 4097000]])
[47]: ans = "%.2f" % (conv_res[0] / total_res[0] * 100)
      print(f"The percentage of FLOPs attributed by convolution layers in VGG19 is ⊔
```

print(f"The percentage of FLOPs attributed by convolution layers in VGG19 is $_{\Box}$ $_{\Box}$ {ans}% for the forward pass.",)

The percentage of FLOPs attributed by convolution layers in VGG19 is 99.00% for the forward pass.

1.3 3

Study the tables showing timing benchmarks from Alexnet (Table 2), VGG16 (Table 3), Googlenet (Table 5), and Resnet50 (Table 6). Why the measured time and sum of layerwise timings for forward pass did not match on GPUs? What approach was adopted in Sec. 5 of the paper to mitigate the measurement overhead in GPUs. (2+2)

Why the measured time and sum of layerwise timings for forward pass did not match on GPUs?

The reason for the mismatch is that CUDA supports asynchronous programming. Before time measurement, an API (cudaDeviceSynchronize) has to be called to make sure that all cores have finished their tasks. is explicit synchronization is the overhead of measuring time on the GPUs.

In other words, when we calculate the layer-wise time, CUDA need additionnal call which make the measured time larger than the real case.

What approach was adopted in Sec. 5 of the paper to mitigate the measurement overhead in GPUs?

Transforming the computation into matrix multiplication, which can be accelerately measured by BLAS and cuBLAS libraries. Thus we have a way to accurately approximate and measure the calculation time.

1.4 4

In Lu et al. FLOPs for different layers of a DNN are calculated. Use FLOPs numbers for VGG16 (Table 3), Googlenet (Table 5), and Resnet50 (Table 6), and calculate the inference time (time to have a forward pass with one image) using published Tflops number for K80 (Refer to NVIDIA TESLA GPU Accelerators) both for single-precision and double-precision calculations. Use this to calculate the peak (theoretical) throughput achieved with K80 for these 3 models. (6)

1.4.1 VGG16

```
[14]: import sys
      import os
      def get_num(num_str):
          res = os.popen(f"numfmt --from si {num_str}").read()
          res = int(res)
          # res = os.system()
          return res
      # print(res)
      vgg16_total_flops = get_num("15503M")
      googlenet_total_flops = get_num("1606M")
      resnet_total_flops = get_num("3922M")
      k80_single_flops = get_num("8.73T")
      k80_double_flops = get_num("2.91T")
      vgg16 single time = vgg16 total flops / k80 single flops
      vgg16_double_time = vgg16_total_flops / k80_double_flops
      googlenet_single_time = googlenet_total_flops / k80_single_flops
      googlenet_double_time = googlenet_total_flops / k80_double_flops
      resnet_single_time = resnet_total_flops / k80_single_flops
      resnet_double_time = resnet_total_flops / k80_double_flops
```

```
vgg16_single_throughput = 1 / vgg16_single_time
vgg16_double_throughput = 1 / vgg16_double_time
googlenet_single_throughput = 1 / googlenet_single_time
googlenet_double_throughput = 1 / googlenet_double_time
resnet_single_throughput = 1 / resnet_single_time
resnet_double_throughput = 1 / resnet_double_time
print(f"The single-GPU inference time for VGG16 is {vgg16_single_time}s, and ⊔
 →the throughput is {vgg16_single_throughput}.")
print(f"The double-GPU inference time for VGG16 is {vgg16 double time}s, and
 sthe throughput is {vgg16_double_throughput}.")
print(f"The single-GPU inference time for GoogLeNet is⊔
 ⇔{googlenet_single_time}s, and the throughput is⊔
 →{googlenet_single_throughput}.")
print(f"The double-GPU inference time for GoogLeNet is ...
 → {googlenet_double_time}s, and the throughput is_

¬{googlenet_double_throughput}.")
print(f"The single-GPU inference time for ResNet is {resnet_single_time}s, and ⊔
 print(f"The double-GPU inference time for ResNet is {resnet_double time}s, and__
 sthe throughput is {resnet_double_throughput}.")
```

The single-GPU inference time for VGG16 is 0.0017758304696449026s, and the throughput is 563.1168161001096.

The double-GPU inference time for VGG16 is 0.005327491408934708s, and the throughput is 187.7056053667032.

The single-GPU inference time for GoogLeNet is 0.00018396334478808707s, and the throughput is 5435.865504358655.

The double-GPU inference time for GoogLeNet is 0.0005518900343642612s, and the throughput is 1811.9551681195517.

The single-GPU inference time for ResNet is 0.0004492554410080183s, and the throughput is 2225.9051504334525.

The double-GPU inference time for ResNet is 0.001347766323024055s, and the throughput is 741.9683834778174.