# Xiangbo Gao

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#### **EDUCATION**

University of California, Irvine (GPA-3.720)

2018.9 - Present

Double Majors: Computer Science, Mathematics

BS expected 2023.3

ICS Honor Program, Dean's List

University of California, Berkeley, Summer Session (GPA-3.8)

Berkeley, CA

Core Courses: Python (CS 61A), Data Structure (CS 61B), Intro to AI (CS188) 2019.6-2019.9

# **PUBLICATIONS**

- 1. **X Gao**<sup>1</sup>, et al. "Scale-free and Task-agnostic Attack: Generating Photo-realistic Adversarial Patterns with Patch Quilting Generator" arXiv:2208.06222, 2022 (On Submission)
- M Liu, X Li, X Gao<sup>3</sup>, J Chen, L Shen, & H Wu "Sample hardness based gradient loss for long-tailed cervical cell detection", International Conference on Medical Image Computing and Computer-Assisted Intervention, pp. 109-119. Springer, Cham, 2022

## **RESEARCH EXPERIENCE & LEADERSHIP**

University of California, Irvine, CA

A Self-supervised graphical model in the autonomous driving system

2022.5 ~ Present

Advisor: Prof. Mohammad Al Faruque, Dept of EECS

- Designed and created a multi-domain autonomous driving dataset for different driving scenarios using CARLA simulator
- Designed a probabilistic LSTM structure that encodes states to variational embeddings.
- Transferred the knowledge from PointNet to encode the unordered lane marks information.
- Evaluating the model performance and cross-domain transferability by various metrics and comparing them with other motion prediction algorithms (MTP, PGP, Trajectron++, etc.)

# **Goal-conditional Reinforcement Learning**

2022.2 ~ 2022.6

Advisor: Prof. Roy Fox, Dept of CS

- Reviewed literature on imitation learning and general reinforcement learning
- Come up with spring loss which uses the idea of contrastive learning that aligns the embeddings in linear distance.
- Visualization by the PCA dimension reduction method shows that the learned embedding better aligns with the real-world trajectory.

### **ZerO Waste Anteaters**

2020.9 ~ 2022.4

Advisor: Prof. Sharad Mehrotra

- Led a team of 8 members to explore waste recognition solutions
- Trained light-weight models for waste image classification (Mobilenetv3, ShuffleNet, and EfficientNet) and waste object detection (Faster-RCNN and YOLOv5); achieved ~0.94 classification accuracy and ~0.76 mean precision error
- Deployed the waste recognition models to resource-limited machines (Jetson Nano)

Institute of Computer Vision, Shenzhen University, China

# Adversarial Attack with Semantic Pattern (Publication 1)

2021.4 ~ 2022.3

Advisor: Prof. WeiCheng Xie

- Proposed a novel Patch Quilting Generative Adversarial Network (PQ-GAN) training strategy that learned a set of cascaded generators to manipulate image patterns of varying scales without distortion or discontinuity
- Applied the PQ-GAN to adversarial attacks that delivered state-of-the-art attack strength and robustness with respect to various types of defense algorithms

# Long-tailed Cervical Cell Detection (Publication 2)

2021.5 ~ 2022.1

Advisor: Prof. Linlin Shen

- Assisted to propose a Grad-Libra Loss that leverages the gradients to dynamically calibrate the hardness of each sample and rebalanced their gradients.

#### **SUMMER INTERNS**

Intern, Tandll Investment Management Limited, China

2020.06 ~ 2020.08

Position: Full-stack Software developer

Personal contribution

 Built a quantitative trading support website using Python (Django & React) and MySQL, which supported high-level trading management, model parameters modification, and historical data & behaviors Visualization

# **COMPETITIONS**

Competition, University of California, Irvine, CA, USA	2020.4
1st place in Machine Learning Hackathon at UCI	
Google Hash Code 2020 Algorithms Competition, Irvine, CA	2020.2
Result: 2 <sup>nd</sup> place / 13 at UCI	
Netease Hackathon Competition	2020.6
Outstanding Award	

# INDEPENDENT RESEARCH

2022.5-2022.7

Multi-modal 3D Object Detection

- Literature review of existing general 3D object detection algorithms including camerabased, point-based, voxel-based, and multi-model algorithms
- Run experiments on multi-model 3D object detection algorithms (Lidar Painting, Bev fusion)

#### **ACTIVITIES**

**UCI Rock Climbing Group** 

- Regularly join the indoor rock-climbing activities at the UCI anteater recreation center.
- Regularly Join the outdoor adventure trips with group members including rock climbing, camping, and backpacking.

# **SKILLS**

Programming Language: Python, C/C++, Java, C#, JavaScript, SQL Software: PyTorch, OpenMMlab, RLlib, TorchGeometry, TensorFlow