$-4x10^{-6}$ 

1. P(z,=L) xP(6|L) xP(F|L) xP(3|F) xP(F|F) xP(1|F) xP(L|F)

xP(2|L) xP(L)L) xP(4)L)

VkH+1) = (ex,x++) max (ax, k', V(t)) The V Matrix

2. t = 1t = 2t = 3 $\frac{1}{6} * \frac{1}{2}$ k = 1(Fair) k = 2(Loaded) observation "4" "6" The Ptr Matrix t = 1t = 2 t = 3k = 10 (Fair) 0 k = 2(Loaded) observation "4" "6" "3"

$$\max_{1} \sqrt{x(n)} = \frac{1}{6} \times \frac{1}{2} \times 0.4 \times \frac{1}{2} \times 0.4 \times \frac{1}{6} = \frac{1}{900}$$

$$P(X, Z^{*}) = \frac{1}{99}$$

$$Z^{*} = (1.2.1)$$

## 3 Feed Forward Neural Networks

```
%% activation tanh.m
function y = activation tanh(alpha)
    y = (exp(alpha) - exp(-alpha)) ./ (exp(alpha) + exp(-
alpha));
end
%% activation tanh gradient.m
function gradient = activation tanh gradient(y)
    gradient = 1 - y .^2;
end
%% feedforward network tanh.m
%clear memory
clear;
%% prepare data and initialize the network
% Generate 1000 training data points
X \text{ all} = [0.001 * (1 : 1000) ' 0.001*(1000-(1:1000))']; % shape
[1000, 2]
y \ all = \cos(3 * pi * X \ all(:, 1)) + \sin(pi * X \ all(:, 2)) +
2; % shape [1000, 1]
n sample = length(X all(:, 1));
% Initialization network parameters.
% The training data are split to many "batches".
% In this lab, each batch has 50 data points
% Model training (the forward-backward propagation)
% is performed on batch-by-batch.
batch size = 50;
W1 = 0.01*randn(2, 256); % shape [2, 256]
W2 = 0.01*randn(256, 256); % shape [256, 256]
W3 = 0.01*randn(256, 1); % shape [256, 1]
% variables for optimization algorithm: AdamSGD
% for this lab, you do not have to know them
% just regard optimizer as a function (blackbox).
m W1 = 0; v W1 = 0;
m W2 = 0; v W2 = 0;
m W3 = 0; v W3 = 0;
step = 0;
%% start training
%prepare to visulize the results
figure = qcf();
%An epoch means an iteration over all 1000 training data
points.
%we let the program to finish after 550 epoches.
for epoch = 1:550
```

```
% permute the training dataset for each epoch
   perm = randperm(1000);
   Xp = X all(perm,:);
   yp = y \ all (perm);
   total error = 0;
   y pred = zeros(n sample, 1); % variable that saves the
prediction
   for i = 1:(n sample/batch size)
       %% Prepare data for the current batch
       d start = batch size * (i - 1);
       X batch = Xp(d start+(1:batch size), :);
       y batch = yp(d start+(1:batch size));
       %% -----FORWARD PROPAGATION-----
       X = X batch; % dense1
       layer1 alpha = weighted sum(X, W1);
       layer1 h = activation tanh(layer1 alpha);
       layer2 alpha = weighted sum(layer1 h, W2);
       layer2 h = activation tanh(layer2 alpha);
       output layer alpha = weighted sum(layer2 h, W3);
       output layer = output layer alpha;
       error = mean((output layer-y batch).^2);
       output_layer_gradient = 2*(output_layer-
y batch)/batch size;
       % calculate gradients w.r.t. W3 and h2 (see defination
of W3 and h2 in the figure of the handout)
       [W3 gradient, layer2 h gradient] =
compute gradient for weights and one layer below(output layer
gradient, W3, layer2 h);
       % add some code below
       % to calculate gradients of error w.r.t. alpha 2 (see
defination of alpha 2 in the figure of the handout)
       layer2 alpha gradient = layer2 h gradient .*
activation_tanh_gradient(layer2 h);
       % calculate gradients w.r.t. W2 and h1 (see defination
of W3 and h2 in the figure of the handout)
       [W2 gradient, layer1 h gradient] =
compute gradient for weights and one layer below(layer2 alpha
gradient, W2, layer1 h);
       % add some code below
       % to calculate gradients of error w.r.t. alpha 1 (see
defination of alpha 1 in the figure of the handout)
```

```
layer1 alpha gradient = layer1 h gradient .*
activation tanh gradient(layer1 h);
        % calculate gradients w.r.t. W1 and X (see defination
of W1 in the figure of the handout)
        [W1 gradient, ~] =
compute gradient for weights and one layer below(layer1 alpha
gradient, W1, X);
        % update error and prediction
        total error = total error + error;
        y pred(d start+(1:batch size)) = output layer;
        % Using optimizer: Adam SGD
       % For reference see: https://arxiv.org/abs/1412.6980
        % for this lab, you do not have to know it
        % just regard optimizer as a function (blackbox).
        step = step + 1;
        m W1 = (0.9 * m W1 + 0.1 * W1 gradient);
        v W1 = (0.999 * v W1 + 0.001 * W1 gradient.^2);
        \overline{W1} = W1 - 0.01 * (m W1/(1-0.9^step)) ./ sqrt(v W1/(1-0.9^step))
0.999^step) + 1e-8);
       m W2 = (0.9 * m W2 + 0.1 * W2 gradient);
       vW2 = (0.999 * vW2 + 0.001 * W2 gradient.^2)/(1-
0.999<sup>step</sup>);
       W2 = W2 - 0.01 * (m W2/(1-0.9^step)) ./ sqrt(v W2/(1-0.9^step))
0.999^step) + 1e-8);
        m W3 = (0.9 * m W3 + 0.1 * W3 gradient);
        v W3 = (0.999 * v W3 + 0.001 * W3 gradient.^2);
       \overline{W3} = W3 - 0.01 * (m W3/(1-0.9^step)) ./ sqrt(v W3/(1-0.9^step))
0.999^step) + 1e-8);
   end
    % visulize the results
    fprintf('Epoch %d ...\n', epoch);
   fprintf('Squared Loss: %.4f\n\n',
total error*(batch size/n sample))
   hold off
   plot(X all(:,1), y all, 'o')
   hold on
   plot(Xp(:,1), y pred, '.')
   axis([-0.1, 1.1, 0.5, 4.5])
   text(0, 4.3, strcat('Epoch ', num2str(epoch), ':'))
    text(0, 4.0, strcat('Loss = ',
num2str(total error*(batch size/n sample))));
    drawnow
```

