


# Xiang Xu, Ph.D.

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🌐 <https://xiangxu-0103.github.io>





## Employment History

2021 – 2023     **Algorithm engineer**, Leapmotor Technologies Co. Ltd.

## Education

2023 – 2027     **Ph.D.** in Computer Science and Technology  
Nanjing University of Aeronautics and Astronautics  
Advisor: Prof. Qingshan Liu

2018 – 2021     **M.S.** in Control Science and Engineering  
Nanjing University of Information Science and Technology  
Advisor: Prof. Qingshan Liu

2014 – 2018     **B.S.** in Electrical Engineering and Automation  
Nanjing University of Information Science and Technology

## Research Publications

### Journal Articles

- 1 L. Zhu, S. Wang, Z. Zhao, **X. Xu**, and Q. Liu, “Ced-net: Contextual encoder-decoder network for 3d face reconstruction,” *Multimedia Systems*, vol. 28, no. 5, pp. 1713–1722, 2022.
- 2 H. Shuai, **X. Xu**, and Q. Liu, “Backward attentive fusing network with local aggregation classifier for 3d point cloud semantic segmentation,” *IEEE Transactions on Image Processing*, vol. 30, pp. 4973–4984, 2021.

### Conference Proceedings

- 1 L. Kong, **X. Xu**, J. Cen, *et al.*, “Calib3d: Calibrating model preferences for reliable 3d scene understanding,” in *IEEE/CVF Winter Conference on Applications of Computer Vision*, 2025.
- 2 **X. Xu**, L. Kong, H. Shuai, *et al.*, “4d contrastive superflows are dense 3d representation learners,” in *European Conference on Computer Vision*, 2024, pp. 58–80.
- 3 H. Shuai, **X. Xu**, and Q. Liu, “Waterfall-net: Waterfall feature aggregation for point cloud semantic segmentation,” in *Chinese Conference on Pattern Recognition and Computer Vision*, 2022, pp. 28–40.
- 4 **X. Xu**, G. Huang, L. Hu, and Y. Wang, “Semantic-aware object detection for 3d point cloud,” in *International Conference on Optics and Machine Vision*, vol. 12173, 2022, pp. 259–265.

### arXiv Preprints


- 1 L. Kong, **X. Xu**, J. Ren, *et al.*, *Multi-modal data-efficient 3d scene understanding for autonomous driving*, 2024. arXiv: 2405.05258.
- 2 J. Sun, C. Qing, **X. Xu**, *et al.*, *An empirical study of training state-of-the-art lidar segmentation models*, 2024. arXiv: 2405.14870.

- 3 X. Wu, **X. Xu**, L. Kong, *et al.*, *Point transformer v3 extreme: 1st place solution for 2024 waymo open dataset challenge in semantic segmentation*, 2024. arXiv: 2407.15282.
- 4 **X. Xu**, L. Kong, H. Shuai, and Q. Liu, *Frnet: Frustum-range networks for scalable lidar segmentation*, 2023. arXiv: 2312.04484.




## Miscellaneous Experience

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### Research Projects

- 2023  **MMDetection3D**: OpenMMLab next-general platform for general 3D object detection  
Work closely with Wenwei Zhang and Lingdong Kong.

### Selected Honors

- 2024  **The first place** in the 2024 Waymo Open Dataset Challenge.
- 2018  **Outstanding Freshman Scholarship**, Nanjing University of Information Science and Technology.
- 2016  **The First Prize of National Undergraduate Electronics Design Contest** in Jiangsu Division.