

AMATH516 - hw1

XIANGYU GAO 1826374

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1 Chapter 1

Exercise 1.1

From definition:

$$\mathcal{A}(X) := (\langle A_1, X \rangle, \langle A_2, X \rangle, \dots, \langle A_l, X \rangle), Y := (y_1, y_2, \dots, y_l)$$

$$\langle \mathcal{A}(X), Y \rangle = \sum_{i=1}^l \langle A_i, X \rangle y_i = \sum_{i=1}^l \langle y_i A_i, X \rangle = \left\langle \sum_{i=1}^l y_i A_i, X \right\rangle$$

For any linear mapping $\mathcal{A} : \mathbf{E} \rightarrow \mathbf{Y}$, there exists a unique linear mapping $\mathcal{A}^* : \mathbf{Y} \rightarrow \mathbf{E}$, called the adjoint, satisfying

$$\langle \mathcal{A}x, y \rangle = \langle x, \mathcal{A}^*y \rangle \quad \text{for all points } x \in \mathbf{E}, y \in \mathbf{Y}$$

Therefore, $\mathcal{A}^*Y = \sum_{i=1}^l y_i A_i = y_1 A_1 + y_2 A_2 + \dots + y_l A_l$

Exercise 1.2

An inner-product on \mathbf{E} is an assignment $\langle \cdot, \cdot \rangle : \mathbf{E} \times \mathbf{E} \rightarrow \mathbf{R}$ satisfying three properties for all $x, y, z \in \mathbf{E}$ and scalars $a, b \in \mathbf{R}$:

(1) Symmetry: $\langle v, w \rangle_{\mathcal{A}} := \langle \mathcal{A}v, w \rangle = \langle v, \mathcal{A}^*w \rangle = \langle \mathcal{A}w, v \rangle = \langle \mathcal{A}w, v \rangle$, because \mathcal{A} is symmetric $\mathcal{A} = \mathcal{A}^*$

(2) Bilinearity: $\langle av + bw, z \rangle_{\mathcal{A}} := \langle \mathcal{A}(av + bw), z \rangle = a\langle \mathcal{A}v, z \rangle + b\langle \mathcal{A}w, z \rangle = a\langle v, z \rangle_{\mathcal{A}} + b\langle w, z \rangle_{\mathcal{A}}$

(3) Positive definiteness: $\langle v, v \rangle_{\mathcal{A}} = \langle \mathcal{A}v, v \rangle > 0$ for all $0 \neq v \in \mathbf{E}$, because \mathcal{A} is positive definite operator

The inner product in the Euclidean space \mathbf{E} always induces a norm $\|x\| := \sqrt{\langle x, x \rangle}$. Thus, $\|v\|_{\mathcal{A}} = \sqrt{\langle v, v \rangle_{\mathcal{A}}} = \sqrt{\langle \mathcal{A}v, v \rangle}$

The dual norm

$$\begin{aligned}
\|v\|_{\mathcal{A}}^* &= \max \{ \langle v, x \rangle : \|x\|_{\mathcal{A}} \leq 1 \} \\
&= \max \{ \langle v, x \rangle : \sqrt{\langle \mathcal{A}x, x \rangle} \leq 1 \} \\
&= \max \left\{ \left\langle v, \mathcal{A}^{-\frac{1}{2}}x \right\rangle : \sqrt{\left\langle \mathcal{A}^{\frac{1}{2}}x, \mathcal{A}^{-\frac{1}{2}}x \right\rangle} \leq 1 \right\} \\
&= \max \left\{ \left\langle \mathcal{A}^{-\frac{1}{2}}v, x \right\rangle : \sqrt{\left\langle \mathcal{A}^{\frac{1}{2}}x, \mathcal{A}^{-\frac{1}{2}}x \right\rangle} \leq 1 \right\} \\
&= \max \left\{ \left\langle \mathcal{A}^{-\frac{1}{2}}v, x \right\rangle : \sqrt{\langle x, x \rangle} \leq 1 \right\} \\
&= \|\mathcal{A}^{-\frac{1}{2}}v\| \|x\| \text{ since the Cauchy-Schwarz inequality} \\
&= \|\mathcal{A}^{-\frac{1}{2}}v\| \\
&= \left\langle \mathcal{A}^{-\frac{1}{2}}v, \mathcal{A}^{-\frac{1}{2}}v \right\rangle \\
&= \sqrt{\langle \mathcal{A}^{-1}v, v \rangle} \\
&= \|v\|_{\mathcal{A}^{-1}}
\end{aligned}$$

Exercise 1.3

The induced matrix norm implies, $\|\mathcal{A}\|_{a,b} := \max_{x: \|x\|_a \leq 1} \|\mathcal{A}x\|_b$.

Thus, $\|\mathcal{A}\|_1 := \max_{x: \|x\|_1 \leq 1} \|\mathcal{A}x\|_1 = \|\mathcal{A}x\|_1$, with $\|x\|_1 = 1$.

For $x \in R^n$ and $\|x\|_1 = 1$,

$$\|\mathcal{A}x\|_1 = \left\| \sum_{j=1}^n x_j a_j \right\|_1 \leq \sum_{j=1}^n |x_j| \|a_j\|_1 \leq \max_{1 \leq j \leq n} \|a_j\|_1 \|x\|_1 = \max_{1 \leq j \leq n} \|a_j\|_1$$

Similarly, $\|\mathcal{A}\|_{\infty} := \max_{x: \|x\|_{\infty} \leq 1} \|\mathcal{A}x\|_{\infty} = \|\mathcal{A}x\|_{\infty}$, with $\|x\|_{\infty} = 1$

For $x \in R^n$ and $\|x\|_{\infty} = 1$,

$$\|\mathcal{A}x\|_{\infty} = \max_{1 \leq i \leq m} |a_i x| \leq \max_{1 \leq i \leq m} \|a_i^T\|_1 \|x\|_{\infty}$$

Exercise 1.6

$$(1) f(x) = \frac{1}{2} \langle \frac{1}{2}(\mathcal{A} + \mathcal{A}^*)x, x \rangle + \langle v, x \rangle + c = \frac{1}{4} \langle \mathcal{A}x + \mathcal{A}^*x, x \rangle + \langle v, x \rangle + c = \frac{1}{4} \langle \mathcal{A}x, x \rangle + \frac{1}{4} \langle \mathcal{A}^*x, x \rangle + \langle v, x \rangle + c$$

Because of the definition of adjoint: $\langle \mathcal{A}x, x \rangle = \langle x, \mathcal{A}^*x \rangle$

$$\text{Thus } f(x) = \frac{1}{4} \langle \mathcal{A}x, x \rangle + \frac{1}{4} \langle \mathcal{A}^*x, x \rangle + \langle v, x \rangle + c = \frac{1}{2} \langle \mathcal{A}x, x \rangle + \langle v, x \rangle + c$$

$$(2) f(x) = \frac{1}{2} \langle \mathcal{A}x, x \rangle + \langle v, x \rangle + c = \frac{1}{2} (\mathcal{A}x)^T x + v^T x + c = \frac{1}{2} x^T \mathcal{A}^T x + v^T x + c$$

$$\nabla f(x) = \frac{\partial f(x)}{\partial x} = \frac{1}{2} (\mathcal{A} + \mathcal{A}^T)x + v = \mathcal{A}x + v, \text{ because } \mathcal{A} \text{ is self adjoint } \mathcal{A} = \mathcal{A}^*$$

$$\nabla^2 f(x) = \frac{\partial \nabla f(x)}{\partial x} = \mathcal{A}$$

(3) From part 1, when \mathcal{A} is replaced by the self-adjoint operator $(\mathcal{A} + \mathcal{A}^*)/2$, the function values $f(x)$ remain unchanged.

$$\text{Thus let } f(x) = \frac{1}{2} \langle \frac{1}{2}(\mathcal{A} + \mathcal{A}^*)x, x \rangle + \langle v, x \rangle + c.$$

$$\text{From part 2, } \nabla f(x) = \frac{1}{2}(\mathcal{A} + \mathcal{A}^*)x + v, \nabla^2 f(x) = \frac{1}{2}(\mathcal{A} + \mathcal{A}^*)$$

Exercise 1.7

$f(x) = \frac{1}{2} \|F(x)\|^2$, where $F : \mathbf{E} \rightarrow \mathbf{Y}$ is a C^1 -smooth mapping.

$$f(x) = \frac{1}{2} \langle F(x), F(x) \rangle, \text{ from the derivative chain rule,}$$

$$\nabla f(x) = \frac{\partial f(x)}{\partial x} = \frac{\partial f}{\partial F} \frac{\partial F}{\partial x} = \nabla F(x)^* F(x)$$

Exercise 1.8

Consider a function $f : U \rightarrow \mathbf{R}$ and a linear mapping $\mathcal{A} : \mathbf{Y} \rightarrow \mathbf{E}$ and define the composition $h(x) = f(\mathcal{A}x)$

(1) Denote by J_g the Jacobian matrix of any function g . Applying the chain rule leads to $J_q(x) = J_f(\phi(x))J_\phi(x)$

Since $J_\phi(x) = A$, and $\nabla g = (J_g)^T$ for any scalar function g , this boils down to $(\nabla h(x))^T = (\nabla f(Ax + b))^T A$

$$\text{Finally, we find: } \nabla h(x) = A^T \nabla f(Ax + b)$$

(2) Similarly, if f is twice differentiable at Ax , then

$$(\nabla^2 h(x))^T = A^T (\nabla^2 f(Ax + b))^T A$$

$$\nabla^2 h(x) = A^T \nabla^2 f(Ax + b) A$$

Exercise 1.9

H is differentiable at x , so we have $H(x+l) = H(x) + \langle \nabla H(x), l \rangle + o(\|l\|)$. G is differentiable at $H(x)$, we have $G(H(x)+h) = G(H(x)) + \langle \nabla G(H(x)), h \rangle + o(\|h\|)$. Therefore

$$\begin{aligned} \nabla F(x) &= \lim_{l \rightarrow 0} \frac{F(x+l) - F(x)}{l} \\ &= \lim_{l \rightarrow 0} \frac{G(H(x+l)) - G(H(x))}{l} \\ &= \lim_{l \rightarrow 0} \frac{G(H(x) + \langle \nabla H(x), l \rangle + o(\|l\|)) - G(H(x))}{l} \end{aligned}$$

Let $h = \langle \nabla H(x), l \rangle + o(\|l\|)$, we have

$$\begin{aligned}\nabla F(x) &= \lim_{l \rightarrow 0} \frac{G(H(x) + \langle \nabla H(x), l \rangle + o(\|l\|)) - G(H(x))}{l} \\ &= \lim_{l \rightarrow 0} \frac{\langle \nabla G(H(x)), h \rangle + o(\|h\|)}{l} \\ &= \nabla G(H(x)) \nabla H(x), \text{ since } h = \langle \nabla H(x), l \rangle + o(\|l\|)\end{aligned}$$

Exercise 1.10

Consider the two functions $f : \mathbf{R}_{++}^n \rightarrow \mathbf{R}$ and $F : \mathbf{S}_{++}^n \rightarrow \mathbf{R}$ given by
 $f(x) = -\sum_{i=1}^n \log x_i$ and $F(X) = -\ln \det(X)$

(1) For $x \in \mathbf{R}_{++}^n$

$$\begin{aligned}\nabla f(x) &= \begin{pmatrix} \frac{\partial f(x)}{\partial x_1} \\ \frac{\partial f(x)}{\partial x_2} \\ \vdots \\ \frac{\partial f(x)}{\partial x_n} \end{pmatrix} = \begin{pmatrix} \frac{\partial -\sum_{i=1}^n \log x_i}{\partial x_1} \\ \frac{\partial -\sum_{i=1}^n \log x_i}{\partial x_2} \\ \vdots \\ \frac{\partial -\sum_{i=1}^n \log x_i}{\partial x_n} \end{pmatrix} = \begin{pmatrix} -\frac{1}{x_1} \\ -\frac{1}{x_2} \\ \vdots \\ -\frac{1}{x_i} \end{pmatrix} \\ \nabla^2 f(x) &= \begin{pmatrix} \frac{1}{x_1^2} \\ \frac{1}{x_2^2} \\ \vdots \\ \frac{1}{x_i^2} \end{pmatrix}\end{aligned}$$

(2)

$$\begin{aligned}F(X + tV) - F(X) + t \langle X^{-1}, V \rangle &= -\ln \det(X + tV) + \ln \det(X) + t \langle X^{-1}, V \rangle \\ &= -\ln \det(X + tV) + \ln \det(X) + t \langle X^{-1}, V \rangle \\ &= -\ln \det(I + tX^{-1/2}VX^{-1/2}) + t \langle X^{-1/2}VX^{-1/2}, X^{-1/2}VX^{-1/2} \rangle \\ &= -\ln(1 + \text{tr}(tX^{-1/2}VX^{-1/2})) + o(\|tX^{-1/2}VX^{-1/2}\|) + t \langle X^{-1/2}VX^{-1/2}, X^{-1/2}VX^{-1/2} \rangle \\ &= -(t \text{tr}(X^{-1/2}VX^{-1/2}) + o(\|t^2\|)) + t \langle X^{-1/2}VX^{-1/2}, X^{-1/2}VX^{-1/2} \rangle \\ &= o(t)\end{aligned}$$

Hence, $\nabla F(X) = -X^{-1}$

To compute the Hessian, observe $(X+V)^{-1} = X^{-1/2}(I + X^{-1/2}VX^{-1/2})^{-1}X^{-1/2}$
and $(I+A)^{-1} = I - A + A^2 - A^3 + \dots = I - A + O(\|A\|_{op}^2)$ whenever $\|A\|_{op} < 1$.

We have

$$\begin{aligned}\nabla F(X + tV) - \nabla F(X) &= -(X + tV)^{-1} + (X)^{-1} \\ &= -X^{-1/2} \left(I + X^{-1/2}tVX^{-1/2} \right)^{-1} X^{-1/2} + (X)^{-1} \\ &= -X^{-1/2} \left(I - X^{-1/2}tVX^{-1/2} + O(t) \right) X^{-1/2} + (X)^{-1} \\ &= X^{-1}tVX^{-1} + O(t)\end{aligned}$$

So, $\nabla^2 F(X)[V] = X^{-1}VX^{-1}$

$$\begin{aligned}
(3) \quad & \langle \nabla^2 F(X)[V], V \rangle = \text{tr}((\nabla^2 F(X)[V])^T V) = \text{tr}(X^{-1} V X^{-1} V^T) \\
& = \text{tr}((X^{-\frac{1}{2}})^T X^{-\frac{1}{2}} V (X^{-\frac{1}{2}})^T X^{-\frac{1}{2}} V^T) \\
& = \text{tr}((X^{-\frac{1}{2}} V X^{-\frac{1}{2}})^T X^{-\frac{1}{2}} V X^{-\frac{1}{2}}) \\
& = \left\| X^{-\frac{1}{2}} V X^{-\frac{1}{2}} \right\|_F^2, \text{ for any } X > 0 \text{ and } V \in \mathcal{S}^n \\
& \langle \nabla^2 F(X)[V], V \rangle = \left\| X^{-\frac{1}{2}} V X^{-\frac{1}{2}} \right\|_F^2 > 0, \text{ for any } X > 0, V \neq 0. \text{ So, } \nabla^2 F(X) : \\
& \mathbf{S}^n \rightarrow \mathbf{S}^n \text{ is positive definite.}
\end{aligned}$$

Exercise 1.11

Consider a function $f : U \rightarrow \mathbf{R}$ and two points $x, y \in U$. Define the univariate function $\varphi : [0, 1] \rightarrow \mathbf{R}$ given by $\varphi(t) = f(x + t(y - x))$ and let $x_t := x + t(y - x)$ for any t .

(1) if f is C^1 -smooth, then according to the chain rule,

$$\varphi'(t) = (\nabla f(x_t))^T (y - x) = \langle \nabla f(x_t), y - x \rangle, \text{ holds for any } t \in (0, 1)$$

(2) if f is C^2 -smooth, then according to the chain rule,

$$\begin{aligned}
\varphi''(t) &= \frac{\partial \varphi'(t)}{\partial t} = ((\nabla^2 f(x_t))^T (y - x))^T (y - x) = (y - x)^T \nabla^2 f(x_t) (y - x) \\
&= \langle \nabla^2 f(x_t) (y - x), y - x \rangle, \text{ holds for any } t \in (0, 1)
\end{aligned}$$

Exercise 1.15

Consider a C^1 -smooth mapping $F : U \rightarrow \mathbf{R}^m$ and two points $x, y \in U$.

Define the univariate function $\varphi(t) = F(x + t(y - x))$. The fundamental theorem of calculus yields the relation

$$\varphi(1) - \varphi(0) = \int_0^1 \varphi'(t) dt, \text{ where } \varphi(1) = F(y), \varphi(0) = F(x).$$

$$\text{According to the result of Exercise 1.11, } \varphi'(t) = \langle \nabla F(x_t), y - x \rangle$$

$$\text{Thus, } F(y) - F(x) = \int_0^1 \nabla F(x + t(y - x))(y - x) dt$$

$$F(y) = F(x) + \int_0^1 (\nabla F(x + t(y - x)) - \nabla F(x)) (y - x) dt$$

$$= F(x) + \nabla F(x)(y - x) + \int_0^1 (\nabla F(x + t(y - x)) - \nabla F(x))(y - x) dt$$

Exercise 1.16

A C^1 -smooth mapping $F : U \rightarrow Y$ is L -Lipschitz continuous satisfies:

$$|F(y) - F(x)| \leq L\|y - x\|, \text{ for all } y \text{ and } x.$$

$$\text{Take } y = x + \nabla F(x), \quad L\|\nabla F(x)\| = L\|y - x\| \geq |F(y) - F(x)|$$

For a convex function F and two points x, y in its domain, we have $F(y) \geq l(x, y) = F(x) + \langle y - x, \nabla F(x) \rangle$, then $|F(y) - F(x)| \geq |\langle \nabla F(x), \nabla F(x) \rangle|$

So, $L\|\nabla F(x)\| \geq |\langle \nabla F(x), \nabla F(x) \rangle| = \|\nabla F(x)\|^2$, which gives $\|\nabla F(x)\| \leq L$.

If f is defined on a convex set and x is an interior point, the same argument but with $y = x + \eta \nabla f(x)$ for some small $\eta > 0$ gives us the same bound.

2 Chapter 2

Exercise 2.4*

We first assume $f(x)$ is convex and show its epigraph must be convex:

Let (x_1, y_1) and (x_2, y_2) be in the epigraph of $f(x)$.

Let $(\tilde{x}, \tilde{y}) := \lambda(x_1, y_1) + (1 - \lambda)(x_2, y_2)$, with $\lambda \in [0, 1]$. Then we have,

$$\begin{aligned} \tilde{y} &= \lambda y_1 + (1 - \lambda)y_2 \\ &\geq \lambda f(x_1) + (1 - \lambda)f(x_2) \quad \text{since points are in epigraph} \\ &\geq f(\lambda x_1 + (1 - \lambda)x_2) \quad \text{since } f(x) \text{ is convex} \\ &= f(\tilde{x}) \end{aligned}$$

Hence, the point (\tilde{x}, \tilde{y}) is also in epigraph, and epigraph is convex.

Now we assume the epigraph is convex and show the function must be convex:

Let $x_1, x_2 \in C$, let $\lambda \in [0, 1]$. Then the points $(x_1, f(x_1))$ and $(x_2, f(x_2))$ are in the epigraph of $f(x)$. Since the epigraph is convex, the point $\lambda(x_1, f(x_1)) + (1 - \lambda)(x_2, f(x_2))$ is also in epigraph.

So $f(\lambda x_1 + (1 - \lambda)x_2) \leq \lambda f(x_1) + (1 - \lambda)f(x_2)$, f is convex.

Exercise 2.5*

If f is convex, according to last exercise, the $\text{epi } f := \{(x, r) \in U \times \mathbf{R} : f(x) \leq r\}$ is convex. Pick arbitrary $(x_1, r_1), \dots, (x_k, r_k) \in \text{epi } f$, and any $\lambda_1, \dots, \lambda_k \in [0, 1]$ with $\sum_i \lambda_i = 1$. By convexity of the epigraph, it follows that,

$$\sum_i \lambda_i (x_i, r_i) = (\sum_i \lambda_i x_i, \sum_i \lambda_i r_i) \text{ also belongs to the epigraph. Therefore,}$$

$$\sum_i \lambda_i f(x_i) \geq f(\sum_i \lambda_i x_i).$$

Let $\Gamma = \text{epi}(f)$. Let $(x_1, r_1), \dots, (x_n, r_n) \in \Gamma$. For any $\lambda_1, \dots, \lambda_n \in [0, 1]$ with $\sum_i \lambda_i = 1$, the point $(x, r) = \sum_i \lambda_i (x_i, r_i) = (\sum_i \lambda_i x_i, \sum_i \lambda_i r_i)$ has:

$$r = \sum_i \lambda_i r_i \geq \sum_i \lambda_i f(x_i) \geq f(\sum_i \lambda_i x_i) = f(x)$$

Hence $(x, r) \in \Gamma$, and Γ is convex. According to the results of last exercise, f is convex.

Exercise 2.6*

Consider an arbitrary set T and a family of convex functions $f_t : U \rightarrow (-\infty, +\infty]$ for $t \in T$.

Because a function $f : U \rightarrow (-\infty, +\infty]$ is convex if and only if the epigraph $\text{epi } f := \{(x, r) \in U \times \mathbf{R} : f(x) \leq r\}$ is a convex subset of $\mathbf{E} \times \mathbf{R}$.

$\text{epi } f = \cap_{t \in T} \text{epi } f_t$ is convex because all $\text{epi } f_t$ is convex.

Hence the function $f(x) := \sup_{t \in T} f_t(x)$ is convex since $\text{epi } f$ is convex.

Exercise 2.8*

Define the two sets

$$\mathbf{R}_{++}^n := \{x \in \mathbf{R}^n : x_i > 0 \text{ for all } i = 1, \dots, n\}$$

$$\mathbf{S}_{++}^n := \{X \in \mathbf{S}^n : X > 0\}$$

Consider the two functions $f : \mathbf{R}_{++}^n \rightarrow \mathbf{R}$ and $F : \mathbf{S}_{++}^n \rightarrow \mathbf{R}$ given by $f(x) = -\sum_{i=1}^n \log x_i$ and $F(X) = -\ln \det(X)$

$$\text{For } x \in \mathbf{R}_{++}^n, \nabla f(x) = -\sum_{i=1}^n \frac{1}{x_i}, \nabla^2 f(x) = \sum_{i=1}^n \frac{1}{x_i^2}$$

For any $y > x$, $\nabla f(y) > \nabla f(x)$, satisfying the monotonicity of gradient, hence f is convex.

From exercise 1.10, the operator $\nabla^2 F(X) : \mathbf{S}^n \rightarrow \mathbf{S}^n$ is positive definite, since $\langle \nabla^2 F(X)[V], V \rangle = \left\| X^{-\frac{1}{2}} V X^{-\frac{1}{2}} \right\|_F^2$ for any $X > 0$ and $V \in \mathbf{S}^n$.

Hence, according to the Theo2.12 (d), F is convex.

Exercise 2.9

$$(1) 0 \leq f(y) - f(x) - \langle \nabla f(x), y - x \rangle \leq \frac{\beta}{2} \|x - y\|^2$$

$f(y) \geq f(x) + \langle \nabla f(x), y - x \rangle$ for all $x, y \in U$ is equivalent to f is convex

Given any β -smooth function $f : U \rightarrow \mathbf{R}$, for any points $x, y \in U$ the inequality $|f(y) - l(x; y)| \leq \frac{\beta}{2} \|y - x\|^2$ holds

$$\text{Hence } f(y) - f(x) - \langle \nabla f(x), y - x \rangle \leq \frac{\beta}{2} \|y - x\|^2$$

$$(2) f(x) + \langle \nabla f(x), y - x \rangle + \frac{1}{2\beta} \|\nabla f(x) - \nabla f(y)\|^2 \leq f(y)$$

Suppose now 1 holds and define the function $\phi(y) = f(y) - \langle \nabla f(x), y \rangle$.

Since $0 \leq f(y) - f(x) - \langle \nabla f(x), y - x \rangle = \phi(y) - \phi(x)$, $\phi(y)$ is mono increasing function.

Since f is β -smooth, $\nabla f(y) - \nabla f(x) \leq \beta(y - x)$,
 $x \leq y - \frac{1}{\beta}(\nabla f(y) - \nabla f(x)) = y - \frac{1}{\beta}\nabla \phi(y)$

So $\phi(x) = \min \phi \leq \phi\left(y - \frac{1}{\beta}\nabla \phi(y)\right) = f(y - \frac{1}{\beta}\nabla \phi(y)) - \langle \nabla f(x), y - \frac{1}{\beta}\nabla \phi(y) \rangle$
 $= f(y - \frac{1}{\beta}\nabla \phi(y)) - f(y) + f(y) - \langle \nabla f(x), y \rangle + \langle \nabla f(x), \frac{1}{\beta}\nabla \phi(y) \rangle$
 $= \phi(y) + f(y - \frac{1}{\beta}\nabla \phi(y)) - f(y) + \langle \nabla f(x), \frac{1}{\beta}\nabla \phi(y) \rangle$
 $= \phi(y) + f(y - \frac{1}{\beta}\nabla \phi(y)) - f(y) - \langle \nabla f(y), -\frac{1}{\beta}\nabla \phi(y) \rangle + \langle \nabla f(y), -\frac{1}{\beta}\nabla \phi(y) \rangle +$
 $\langle \nabla f(x), \frac{1}{\beta}\nabla \phi(y) \rangle$
 $\leq \phi(y) + \frac{1}{2\beta}\|\nabla \phi(y)\|^2 + \langle \nabla f(x) - \nabla f(y), \frac{1}{\beta}\nabla \phi(y) \rangle$, since (1)
 $\leq \phi(y) + \frac{1}{2\beta}\|\nabla \phi(y)\|^2 + \langle \beta(x - y), \frac{1}{\beta}\nabla \phi(y) \rangle$, since the β -smooth
 $\leq \phi(y) + \frac{1}{2\beta}\|\nabla \phi(y)\|^2 + \langle -\frac{1}{\beta}\nabla \phi(y), \frac{1}{\beta}\nabla \phi(y) \rangle$, since the definition of $\phi(x)$
 $\leq \phi(y) - \frac{1}{2\beta}\|\nabla \phi(y)\|^2$
Hence $f(x) + \langle \nabla f(x), y - x \rangle + \frac{1}{2\beta}\|\nabla f(x) - \nabla f(y)\|^2 \leq f(y)$
Obviously, f is convex.

(3) $\frac{1}{\beta}\|\nabla f(x) - \nabla f(y)\|^2 \leq \langle \nabla f(x) - \nabla f(y), x - y \rangle$
according to (2), $f(x) + \langle \nabla f(x), y - x \rangle + \frac{1}{2\beta}\|\nabla f(x) - \nabla f(y)\|^2 \leq f(y)$
reverse x and y , $f(y) + \langle \nabla f(y), x - y \rangle + \frac{1}{2\beta}\|\nabla f(y) - \nabla f(x)\|^2 \leq f(x)$
add this two inequality, get $\frac{1}{\beta}\|\nabla f(x) - \nabla f(y)\|^2 \leq \langle \nabla f(x) - \nabla f(y), x - y \rangle$

Next applying Cauchy-Schwartz to (3)
 $\frac{1}{\beta}\|\nabla f(x) - \nabla f(y)\|^2 \leq \langle \nabla f(x) - \nabla f(y), x - y \rangle \leq \|\nabla f(x) - \nabla f(y)\| \|x - y\|$
Hence f is β -smooth, $\|\nabla f(x) - \nabla f(y)\| \leq \beta\|x - y\|$
Also f is convex, since $\langle \nabla f(x) - \nabla f(y), x - y \rangle \geq 0$

(4) $0 \leq \langle \nabla f(x) - \nabla f(y), x - y \rangle \leq \beta\|x - y\|^2$

From (3), $\langle \nabla f(x) - \nabla f(y), x - y \rangle \geq 0$
From (1), $f(y) - f(x) - \langle \nabla f(x), y - x \rangle \leq \frac{\beta}{2}\|x - y\|^2$
Reverse x and y , $f(x) - f(y) - \langle \nabla f(y), x - y \rangle \leq \frac{\beta}{2}\|y - x\|^2$
Add this two inequalities, get (4).

To deduce (1) from (4), let $\phi(x) = -f(x) + \frac{\beta}{2}\|x\|^2$
The gradient of $\phi(x)$ is, $\nabla \phi(x) = -\nabla f(x) + \beta x$
Similarly, $\nabla \phi(y) = -\nabla f(y) + \beta y$
 $(\nabla \phi(x) - \nabla \phi(y))(x - y) = \beta\|x - y\|^2 - \langle \nabla f(x) - \nabla f(y), x - y \rangle \geq 0$, since
(4).

Thus, $\nabla \phi(x)$ is monotone and therefore $\phi(x)$ is convex.

From the gradient inequality of $\phi(x)$, $\phi(y) \geq \phi(x) + \langle \nabla \phi(x), y - x \rangle$

since $\nabla\phi(x) = -\nabla f(x) + \beta x$, $\nabla\phi(y) = -\nabla f(y) + \beta y$, we can get $f(y) - f(x) - \langle \nabla f(x), y - x \rangle \leq \frac{\beta}{2} \|x - y\|^2$

Exercise 2.11

Consider a C^1 -smooth convex function $f : \mathbf{E} \rightarrow \mathbf{R}$. Fix a linear subspace $\mathcal{L} \subset \mathbf{E}$ and $g : \mathbf{L} \rightarrow \mathbf{R}$, $f_{\mathcal{L}} = f$.

First, assume $x \in \mathcal{L}$ minimizes the restriction $f_{\mathcal{L}} : \mathcal{L} \rightarrow \mathbf{R}$.

Based on the Corollary 2.10, we know that $\nabla f_{\mathcal{L}}(x) = 0$.

We have $\nabla f(x) = (\nabla f_{\mathcal{L}}(x), \nabla f_{\mathbf{E}-\mathcal{L}}(x))$. Let $x = (x_{\mathcal{L}}, 0) \in \mathcal{L}$, we have $\nabla f(x)x = 0$. Hence the gradient $\nabla f(x)$ is orthogonal to \mathcal{L} .

Second, assume the gradient $\nabla f(x)$ is orthogonal to \mathcal{L} . From the reverse of the above statement, we can derive $\nabla f_{\mathcal{L}}(x) = 0$, so x is a critical point of $f_{\mathcal{L}}$. According to Corollary 2.10, $x \in \mathcal{L}$ minimizes the restriction $f_{\mathcal{L}} : \mathcal{L} \rightarrow \mathbf{R}$.

Exercise 2.13

Suppose $g(x) = f(x) - \frac{\alpha}{2} \|x\|^2$ is convex. The gradient of $g(x)$ is $\nabla g(x) = \nabla f(x) - \alpha x$

According to the gradient inequality, $g(y) \geq g(x) + \langle \nabla g(x), y - x \rangle$

$$f(y) - \frac{\alpha}{2} \|y\|^2 \geq f(x) - \frac{\alpha}{2} \|x\|^2 + \langle \nabla f(x) - \alpha x, y - x \rangle$$

$$\text{Hence } f(y) \geq f(x) + \langle \nabla f(x), y - x \rangle + \frac{\alpha}{2} \|y - x\|^2$$

Suppose $f : U \rightarrow \mathbf{R}$ is α -strongly convex, then

$$f(y) \geq f(x) + \langle \nabla f(x), y - x \rangle + \frac{\alpha}{2} \|y - x\|^2 \quad \text{holds for all } x, y \in U$$

$$\text{Revise } x \text{ and } y, \text{ we get } f(x) \geq f(y) + \langle \nabla f(y), x - y \rangle + \frac{\alpha}{2} \|x - y\|^2$$

$$\text{Add this two inequalities, we get } \langle \nabla f(x) - \nabla f(y), y - x \rangle + \alpha \|y - x\|^2 \leq 0$$

To prove the $g(x)$ is convex, we could prove $\langle \nabla g(y) - \nabla g(x), y - x \rangle \geq 0$ for all $x, y \in U$.

$$\langle \nabla g(y) - \nabla g(x), y - x \rangle = \langle \nabla f(y) - \alpha y - (\nabla f(x) - \alpha x), y - x \rangle = \langle \nabla f(y) - \nabla f(x), y - x \rangle - \alpha \|y - x\|^2 \geq 0, \text{ since the inequality we deduced above.}$$

Hence $\nabla g(x)$ is monotone and therefore $g(x)$ is convex.

Exercise 2.18*

Consider a differentiable convex function, $f : \mathbf{E} \rightarrow \mathbf{R}$ and let x^* be any of its minimizers.

Consider the gradient descent iterates $x_{k+1} = x_k - \gamma_k \nabla f(x_k)$, for some sequence $\alpha_k \geq 0$

$$(1) \|x_{k+1} - x^*\|^2 = \|(x_{k+1} - x_k) + (x_k - x^*)\|^2$$

$$\frac{1}{2} \|x_{k+1} - x^*\|^2 = \frac{1}{2} \|x_k - x^*\|^2 + \|x_{k+1} - x_k\| \|x_k - x^*\| + \frac{\gamma_k^2}{2} \|\nabla f(x_k)\|^2$$

$$\begin{aligned}
&= \frac{1}{2} \|x_k - x^*\|^2 + \gamma_k \|\nabla f(x_k)\| \|x_k - x^*\| + \frac{\gamma_k^2}{2} \|\nabla f(x_k)\|^2 \\
&= \frac{1}{2} \|x_k - x^*\|^2 + \gamma_k \langle \nabla f(x_k), x_k - x^* \rangle + \frac{\gamma_k^2}{2} \|\nabla f(x_k)\|^2 \\
&= \frac{1}{2} \|x_k - x^*\|^2 + \gamma_k (\langle \nabla f(x_k), x_k - x^* \rangle + f(x_k) - f(x^*)) + \frac{\gamma_k^2}{2} \|\nabla f(x_k)\|^2 \\
&\leq \frac{1}{2} \|x_k - x^*\|^2 + \gamma_k (f(x^*) - f(x_k)) + \frac{\gamma_k^2}{2} \|\nabla f(x_k)\|^2, \text{ since the inequality of} \\
&\text{gradient}
\end{aligned}$$

$$\text{Hence, } \frac{1}{2} \|x_{k+1} - x^*\|^2 \leq \frac{1}{2} \|x_k - x^*\|^2 - \gamma_k (f(x_k) - f(x^*)) + \frac{\gamma_k^2}{2} \|\nabla f(x_k)\|^2$$

$$(2) \quad \frac{1}{2} \|x_{k+1} - x^*\|^2 \leq \frac{1}{2} \|x_k - x^*\|^2 - \gamma_k (f(x_k) - f(x^*)) + \frac{\gamma_k^2}{2} \|\nabla f(x_k)\|^2$$

$$\text{To minimize the right hand of this inequality, let } F(\gamma_k) = \frac{1}{2} \|x_k - x^*\|^2 - \gamma_k (f(x_k) - f(x^*)) + \frac{\gamma_k^2}{2} \|\nabla f(x_k)\|^2$$

$$\text{Take } \nabla F(\gamma_k) = 0, \text{ get } -(f(x_k) - f(x^*)) + \gamma_k \|\nabla f(x_k)\| = 0$$

$$\text{Hence, } \gamma_k = \frac{f(x_k) - f^*}{\|\nabla f(x_k)\|}$$

Substitute γ_k to the initial inequality, thereby yielding the guarantee

$$\|x_{k+1} - x^*\|^2 \leq \|x_k - x^*\|^2 - \left(\frac{f(x_k) - f^*}{\|\nabla f(x_k)\|} \right)^2$$

(3) since f is β -smooth, we have

$$\begin{aligned}
f(x_{k+1}) &\leq f(x_k) - \langle \nabla f(x_k), \alpha_k \nabla f(x_k) \rangle + \frac{\beta}{2} \|\alpha_k \nabla f(x_k)\|^2 \\
&= f(x_k) - (f(x_k) - f^*) + \frac{\beta}{2} \frac{(f(x_k) - f^*)^2}{\|\nabla f(x_k)\|^2} \\
&= f^* + \frac{\beta}{2} \frac{(f(x_k) - f^*)^2}{\|\nabla f(x_k)\|^2} \\
&\leq f^* + \frac{\beta}{2} \left(\|x_k - x^*\|^2 - \|x_{k+1} - x^*\|^2 \right)
\end{aligned}$$

Sum up from 0 to $k-1$, we have

$$\sum_{i=0}^{k-1} f(x_{i+1}) - kf^* \leq \frac{\beta}{2} \left(\|x_0 - x^*\|^2 - \|x_k - x^*\|^2 \right)$$

Setting $\lim_{k \rightarrow \infty} x_k = x^*$ and considering f is convex, we have

$$f\left(\frac{1}{k} \sum_{i=0}^{k-1} x_i\right) - f^* \leq \frac{1}{k} \sum_{i=0}^{k-1} f(x_{i+1}) - f^* \leq \frac{\beta \|x_0 - x^*\|^2}{2k}$$

If f is in addition α -strongly convex, we have

$$\begin{aligned}
\|x_{k+1} - x^*\|^2 &= \|x_k - x^* - \alpha_k \nabla f(x_k)\|^2 \\
&= \|x_k - x^*\|^2 + 2\alpha_k \langle \nabla f(x_k), x^* - x_k \rangle + \alpha_k^2 \|\nabla f(x_k)\|^2 \\
&\leq \|x_k - x^*\|^2 + 2\alpha_k \left(f^* - f(x_k) - \frac{\alpha}{2} \|x_k - x^*\|^2 \right) + \alpha_k^2 \|\nabla f(x_k)\|^2 \\
&= (1 - \alpha\alpha_k) \|x_k - x^*\|^2 + \alpha_k \left(2f^* - 2f(x_k) + \alpha_k \|\nabla f(x_k)\|^2 \right)
\end{aligned}$$

$$\begin{aligned}
&= (1 - \alpha\alpha_k) \|x_k - x^*\|^2 + \left(\frac{f(x_k) - f^*}{\|\nabla f(x_k)\|} \right)^2 \\
&\leq (2 - \alpha\alpha_k) \|x_k - x^*\|^2 - \|x_{k+1} - x^*\|^2
\end{aligned}$$

So we have

$$\begin{aligned}
\|x_{k+1} - x^*\|^2 &\leq \left(1 - \frac{\alpha}{2}\alpha_k \right) \|x_k - x^*\|^2 \\
&= \left(1 - \frac{\alpha}{2} \frac{f(x_k) - f^*}{\|\nabla f(x_k)\|^2} \right) \|x_k - x^*\|^2
\end{aligned}$$

Based on strong convex, we know that $f(x_k) - f^* \geq \frac{\alpha}{2} \|x_k - x^*\|^2$

Based on β -smooth, we know that $\|\nabla f(x) - \nabla f(y)\|_2 \leq \beta \|x - y\|_2$

That is, $\|\nabla f(x_k)\|^2 \leq \beta^2 \|x_k - x^*\|^2$, since $\nabla f(x^*) = 0$

Put it in the above equation, we have $\|x_{k+1} - x^*\|^2 \leq \left(1 - \frac{\alpha^2}{\beta^2} \right) \|x_k - x^*\|^2$

Exercise 2.22 (1)

$$f_k(z_1, z_2, \dots, z_n) = \frac{\beta}{4} \left(\frac{1}{2} (z_1^2 + \sum_{i=1}^{k-1} (z_i - z_{i+1})^2 + z_k^2) - z_1 \right)$$

Take the derivative

$$\begin{aligned}
\frac{\partial f_k}{\partial z_1} &= \frac{\beta}{4} \left(\frac{1}{2} (2z_1 + 2(z_1 - z_2)) - 1 \right) \\
&= \frac{\beta}{4} (z_1 - z_2 - 1) \\
\frac{\partial f_k}{\partial z_{i, 2 \leq i \leq k-1}} &= \frac{\beta}{4} \left(\frac{1}{2} (2(z_i - z_{i+1}) - 2(z_{i-1} - z_i)) \right) \\
&= \frac{\beta}{4} (2z_i - z_{i-1} - z_{i+1})
\end{aligned}$$

For $k \leq i$

$$\begin{aligned}
\frac{\partial f_k}{\partial z_k} &= \frac{\beta}{4} \left(\frac{1}{2} (-2(z_{k-1} - z_k) + 2z_k) \right) \\
&= \frac{\beta}{4} (2z_k - z_{k-1})
\end{aligned}$$

$$\frac{\partial f_k}{\partial z_{i, i > k}} = 0$$

Let $x_1 = z_1 = 1 - \frac{1}{k+1}$, we can deduct that

$$\bar{x}_{k,i} = \begin{cases} 1 - \frac{i}{k+1}, & \text{if } i = 1, \dots, k \\ 0 & \text{if } i = k+1, \dots, n \end{cases}$$

Substitute the \bar{x}_k value to the equation, we have

$$\begin{aligned}
&f_k(\bar{x}_{k,1}, \bar{x}_{k,2}, \dots, \bar{x}_{k,n}) \\
&= \frac{\beta}{4} \left(\frac{1}{2} \left(\bar{x}_{k,1}^2 + \sum_{i=1}^{k-1} (\bar{x}_{k,i} - \bar{x}_{k,i+1})^2 + \bar{x}_{k,k}^2 \right) - \bar{x}_{k,1} \right)^2 + \left(1 - \frac{k}{k+1} \right)^2 - \left(1 - \frac{1}{k+1} \right)
\end{aligned}$$

$$= \frac{\beta}{8} \left(-1 + \frac{1}{k+1} \right)$$

(2)

$$\begin{aligned} \|\bar{x}_k\|^2 &= \sum_{i=1}^k \left(1 - \frac{i}{k+1} \right)^2 \\ &= \frac{1}{(k+1)^2} \sum_{i=1}^k ((k+1)^2 - 2i(k+1) + i^2) \\ &= \frac{1}{(k+1)^2} \left(k(k+1)^2 - 2(k+1) \frac{k(k+1)}{2} + \sum_{i=1}^k (i^2) \right) \\ &\leq \frac{1}{3}(k+1) \end{aligned}$$

(3)

Let $x = (x_1, x_2, \dots, x_i, 0, 0 \dots 0) \in \mathbf{R}^i \times \{0\}^{n-i}$. Substitute to the function, we have:

$$\begin{aligned} f_j(x_1, x_2, \dots, x_n) &= \frac{\beta}{4} \left(\frac{1}{2} \left(x_1^2 + \sum_{k=1}^{j-1} (x_k - x_{k+1})^2 + x_j^2 \right) - x_1 \right) \\ &= \frac{\beta}{4} \left(\frac{1}{2} \left(x_1^2 + \sum_{k=1}^{i-1} (x_k - x_{k+1})^2 + 0 + x_i^2 \right) - x_1 \right) \\ &= \frac{\beta}{4} \left(\frac{1}{2} \left(x_1^2 + \sum_{k=1}^{i-1} (x_k - x_{k+1})^2 + x_i^2 \right) - x_1 \right) \\ &= f_i(x_1, x_2, \dots, x_n) \end{aligned}$$

Based on the gradient result at question (1), we know that the gradient $\nabla f_k(x)$ lies in $\mathbf{R}^i \times \{0\}^{n-(i)} \in \mathbf{R}^{i+1} \times \{0\}^{n-(i+1)}$

Exercise 2.23*

For any point $x \in \mathbf{R}^n$,

$$\begin{aligned} \text{The equality } f(x) - f^* &= \frac{1}{2} \langle Ax, x \rangle - \langle b, x \rangle - \left(\frac{1}{2} \langle Ax^*, x^* \rangle - \langle b, x^* \rangle \right) \\ &= \frac{1}{2} (\langle Ax, x \rangle - \langle Ax, x^* \rangle + \langle Ax, x^* \rangle - \langle Ax^*, x^* \rangle) - \langle b, x - x^* \rangle \\ &= \frac{1}{2} (\langle Ax, x - x^* \rangle + \langle Ax^*, x - x^* \rangle) - \langle b, x - x^* \rangle \\ &= \frac{1}{2} (\langle A(x + x^*), x - x^* \rangle) - \langle b, x - x^* \rangle \\ &= \frac{1}{2} (\langle A(x + x^*) - 2b, x - x^* \rangle) \\ &= \frac{1}{2} (\langle A(x - x^*), x - x^* \rangle), \text{ since } Ax^* = b \\ &= \frac{1}{2} \|x - x^*\|_A^2 \end{aligned}$$

Exercise 2.24*

$$t_k = \operatorname{argmin}_t f(x_k + tv_k).$$

From optimal conditions, let $\nabla f(x_k + tv_k) = 0$

Then, $A(x_k + tv_k) - b)v_k = 0$, we get $t = \frac{bv_k - Ax_kv_k}{Av_k^2} = \frac{\langle r_k, v_k \rangle}{\|v_k\|_A^2}$

Exercise 2.30

Assuming $a_k \leq \frac{2}{k+2}$, $k > 0$, then if we can prove $a_{k+1} \leq \frac{2}{k+2}$, it will show that there is a bound $a_k \leq \frac{2}{k+2}$, for each $k \geq 0$

$$\text{Since } a_{k+1} = \frac{\sqrt{a_k^4 + 4a_k^2} - a_k^2}{2} \leq \frac{a_k^2 + 2a_k - a_k^2}{2} \leq a_k \leq \frac{2}{k+2}$$

Not sure how to use tighter bound to prove $a_{k+1} \leq \frac{2}{k+3}$

Exercise 2.42*

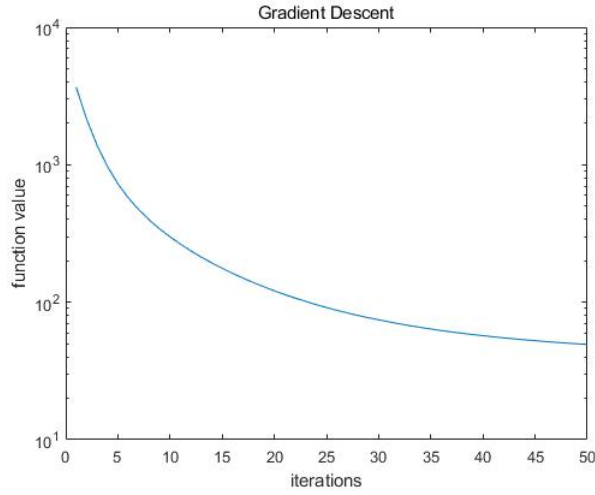


Figure 1:

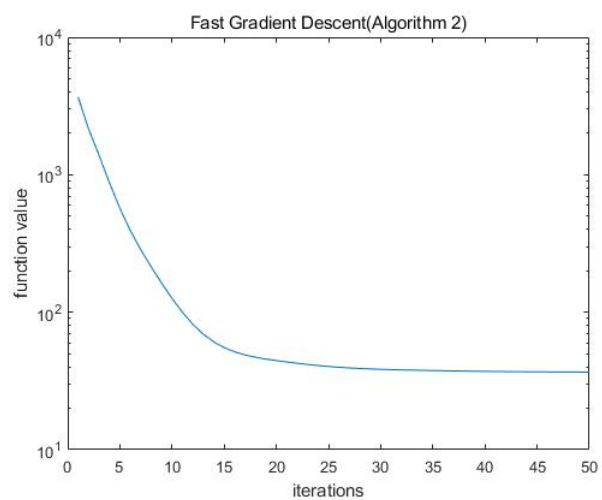


Figure 2:

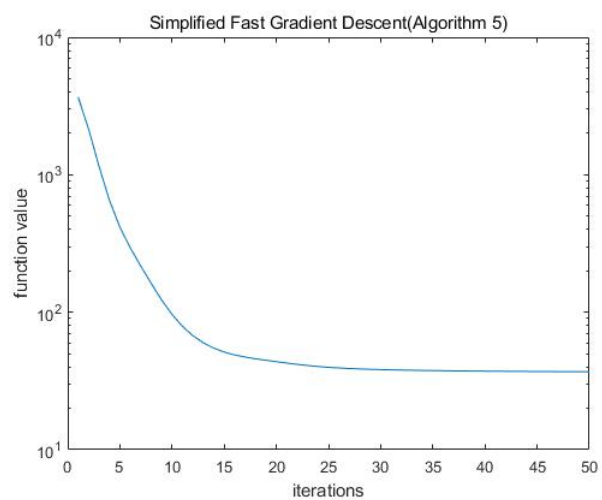


Figure 3:

Exercise 2.43

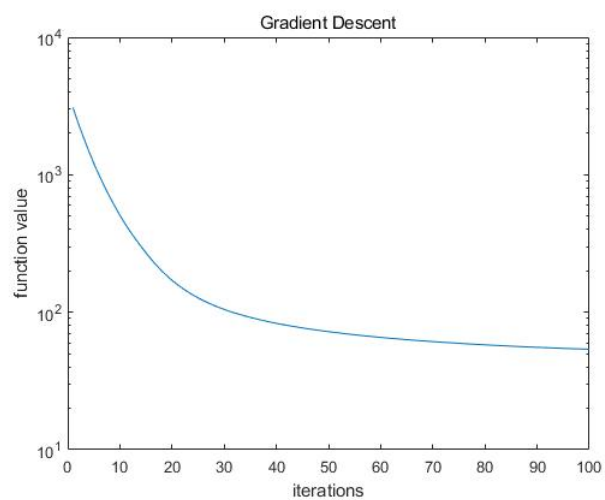


Figure 4:

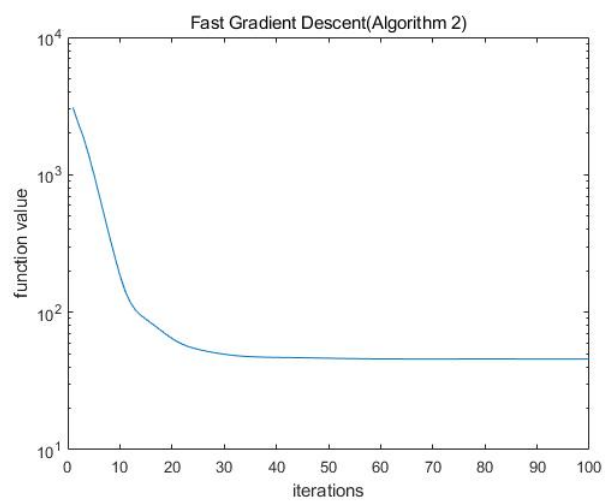


Figure 5:

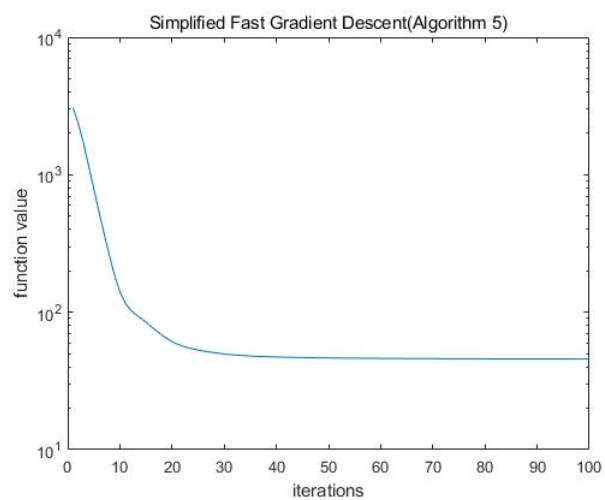


Figure 6:

*Exercise 2.44**

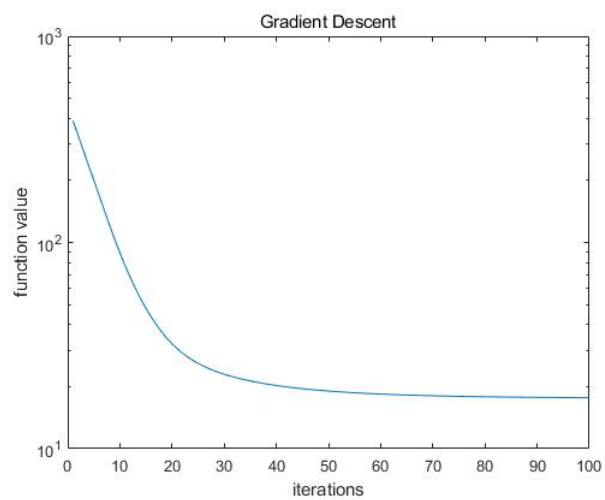


Figure 7:

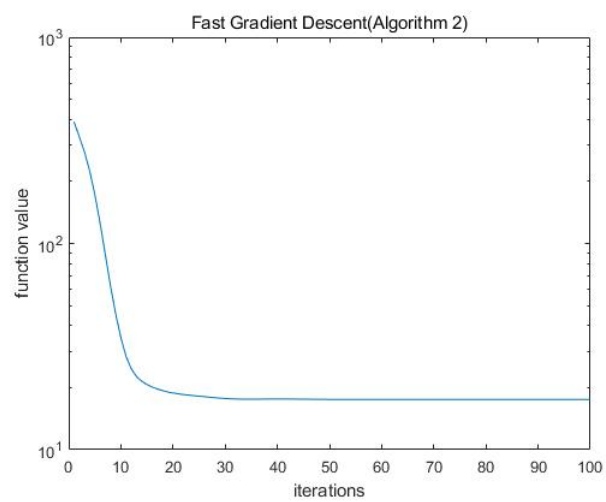


Figure 8:

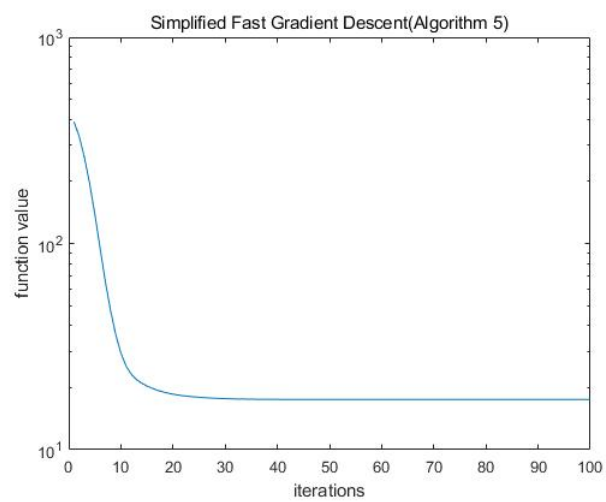


Figure 9: