

Pattern Recognition

Lecture 03(a). Review of Probability Theory

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Review of Probability Theory

Probability theory is the study of uncertainty.



Elements of probability

- Sample space Ω : The set of all the outcomes of a random experiment. Here, each outcome $\omega \in \Omega$ can be thought of as a complete description of the state of the real world at the end of the experiment.
- Set of events (or event space) \mathcal{F} : A set whose elements $A \in \mathcal{F}$ (called events) are subsets of Ω (i.e., $A \subseteq \Omega$ is a collection of possible outcomes of an experiment)
- Probability measure : A function $P : \mathcal{F} \rightarrow \mathbb{R}$ that satisfies the following properties,
 - $P(A) \geq 0$ for all $A \in \mathcal{F}$
 - $P(\Omega) = 1$
 - If A_1, A_2, \dots are disjoint events (i.e., $A_i \cap A_j = \emptyset$ whenever $i \neq j$), then $P(\cup_i A_i) = \sum_i P(A_i)$

Conditional probability

Let B be an event with non-zero probability. The conditional probability of any event A given B is defined as

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

In other words, $P(A|B)$ is the probability measure of the event A after observing the occurrence of event B .

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Random Variables

- **discrete random variable:** takes either finite or countably infinite values.
- **continuous random variable:** takes infinite number of possible values.



(a)



(b)

Discrete Random Variable

Experiment:

Consider an experiment in which we flip 10 coins, and we want to know the number of coins that come up heads. Here, the elements of the sample space Ω are 10-length sequences of heads and tails. For example, we might have $\omega_0 = \langle H, H, T, H, T, H, H, T, T, T \rangle \in \Omega$.

Example: In our experiment above, suppose that X is the number of heads which occur in the sequence of tosses ω . Given that only 10 coins are tossed, X can take only a finite number of values, so it is known as a **discrete random variable**. Here, the probability of the set associated with a random variable X taking on some specific value k is.

$$P(X = k)$$

Continuous Random Variable

Suppose that X is a random variable indicating the amount of time it takes for a radioactive particle to decay. In this case, X takes on an infinite number of possible values, so it is called a **continuous random variable**. The probability that X takes on a value between two real constants a and b (where $a < b$) is denoted as

$$p(a \leq X \leq b)$$

CDFs, PDFs, PMFs

- CDF cumulative distribution function
- PDF Probability Density Function
- PMF probability mass function

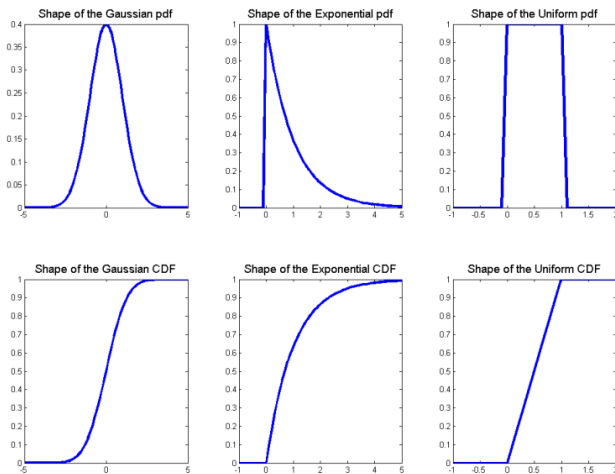


Figure 1: PDF and CDF of a couple of random variables.

measures

- expectation
- variance

Summary of some of the properties of common distributions

Distribution	PDF or PMF	Mean	Variance
<i>Bernoulli</i> (p)	$\begin{cases} p, & \text{if } x = 1 \\ 1 - p, & \text{if } x = 0. \end{cases}$	p	$p(1 - p)$
<i>Binomial</i> (n, p)	$\binom{n}{k} p^k (1 - p)^{n-k}$ for $0 \leq k \leq n$	np	npq
<i>Geometric</i> (p)	$p(1 - p)^{k-1}$ for $k = 1, 2, \dots$	$\frac{1}{p}$	$\frac{1-p}{p^2}$
<i>Poisson</i> (λ)	$e^{-\lambda} \lambda^x / x!$ for $k = 1, 2, \dots$	λ	λ
<i>Uniform</i> (a, b)	$\frac{1}{b-a} \quad \forall x \in (a, b)$	$\frac{a+b}{2}$	$\frac{(b-a)^2}{12}$
<i>Gaussian</i> (μ, σ^2)	$\frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$	μ	σ^2
<i>Exponential</i> (λ)	$\lambda e^{-\lambda x} \quad x \geq 0, \lambda > 0$	$\frac{1}{\lambda}$	$\frac{1}{\lambda^2}$

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The Gaussian distribution

The normal distribution, also called the Gaussian distribution, is a probability distribution commonly used to model phenomena such as physical characteristics (e.g. height, weight, etc.) and test scores.

Why always Gaussian?

- it fits many natural phenomena
- the normal distribution exhibits a number of nice simplifying characteristics
- central limit theorem: the distribution of sample means approximates a normal distribution as the sample size gets larger, regardless of the population's distribution

The Gaussian distribution

Question:

Which of the following is/are true of normal distribution?

- A. They are always symmetric
- B. They are never fat-tailed
- C. They always have a mean of 0

The Gaussian distribution

The *Gaussian(or Normal)* distribution is the most commonly encountered (and easily analysed) continuous distribution.

$$p(x|\mu, \sigma^2) = N(x; \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x - \mu)^2}{2\sigma^2}\right)$$

The Gaussian is described by two parameters: the mean μ (location), and the variance σ^2 (dispersion).

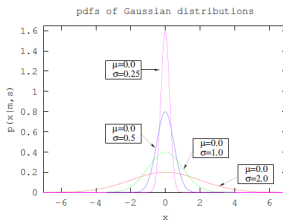


Figure 2: Four Gaussian pdfs with zero mean and different standard deviations.

The multivariate Gaussian distribution and covariance

The univariate(one-dimensional) Gaussian may be extended to the multivariate(multi-dimensional) case. The D -dimensional Gaussian is parameterised by a mean vector, $\mu = (\mu_1, \dots, \mu_D)^T$, and a *covariance matrix* $\Sigma = (\sigma_{ij})$ (Note that Σ is a D by D square matrix, and σ_{ij} or Σ_{ij} denotes its element at i 'th row and j 'th column.) The probability density is

$$p(x|\mu, \Sigma) = \frac{1}{(2\pi)^{D/2} |\Sigma|^{1/2}} \exp\left(-\frac{1}{2}(x - \mu)^T \Sigma^{-1} (x - \mu)\right)$$

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The multivariate Gaussian distribution and covariance

multivariate Gaussian distribution pdf:

$$p(x|\mu, \Sigma) = \frac{1}{(2\pi)^{D/2} |\Sigma|^{1/2}} \exp\left(-\frac{1}{2}(x - \mu)^T \Sigma^{-1}(x - \mu)\right)$$

Exercise:

Consider a 2-dimensional Gaussian distribution with a mean vector $\mu = (0, 0)^T$ and a diagonal covariance matrix, i.e. $\Sigma = \begin{bmatrix} \sigma_{11} & 0 \\ 0 & \sigma_{22} \end{bmatrix}$, show that its pdf can be simplified to the product of two pdfs, each of which corresponds to a one-dimensional Gaussian distribution.

$$p(x|\mu, \Sigma) = p(x_1|\mu_1, \sigma_{11})p(x_2|\mu_2, \sigma_{22})$$

Solution

hint:

With

$$\Sigma^{-1} = \begin{bmatrix} \sigma_{11} & 0 \\ 0 & \sigma_{22} \end{bmatrix}^{-1} = \begin{bmatrix} \frac{1}{\sigma_{11}} & 0 \\ 0 & \frac{1}{\sigma_{22}} \end{bmatrix}$$

We have,

$$\begin{aligned} (x - \mu)^T \Sigma^{-1} (x - \mu) &= \begin{bmatrix} x_1 - \mu_1 & x_2 - \mu_2 \end{bmatrix} \Sigma^{-1} \begin{bmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \end{bmatrix} \\ &= \begin{bmatrix} x_1 & x_2 \end{bmatrix} \Sigma^{-1} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \frac{x_1^2}{\sigma_{11}} + \frac{x_2^2}{\sigma_{22}} \end{aligned}$$

Then,

$$\begin{aligned} \exp\left(-\frac{1}{2}(x - \mu)^T \Sigma^{-1} (x - \mu)\right) &= \exp\left(-\frac{1}{2}\left(\frac{x_1^2}{\sigma_{11}} + \frac{x_2^2}{\sigma_{22}}\right)\right) \\ &= \exp\left(-\frac{1}{2} \frac{x_1^2}{\sigma_{11}}\right) \exp\left(-\frac{1}{2} \frac{x_2^2}{\sigma_{22}}\right) \end{aligned}$$

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Thank You !
Q & A