DTS202TC Fundamentals of Parallel Computing

Week 2 - 2 Advanced MPI Programming

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Recall from last lecture

- Hardware architecture:
 - SISD, SIMD, MIMD
- Pointer to pointer communication
 - MPI_Send and MPI_Receive
- Collective communication
 - MPI_Reduce, MPI_Allreduce
- Debugging MPI parallel application



Review MPI Send MPI Recv

```
1 #include <stdio.h>
   #include <string.h> /* For strlen
                         /* For MPI functions, etc */
   #include <mpi.h>
   const int MAX_STRING = 100:
   int main(void) {
                  greeting[MAX_STRING];
       char
                  comm_sz; /* Number of processes */
                  my_rank; /* My process rank
10
       int
11
                                              All MPI use must be between init
      MPI_Init(NULL, NULL);
12
                                              and finalise
      MPI_Comm_size(MPI_COMM_WORLD, &comm_sz);
13
      MPI_Comm_rank(MPI_COMM_WORLD, &my_rank);
14
15
      if (my_rank != 0) {
16
17
          sprintf(greeting, "Greetings from process %d of %d!",
                my_rank, comm_sz);
18
          MPI_Send(greeting, strlen(greeting)+1, MPI_CHAR, 0, 0,
19
                MPI_COMM_WORLD);
20
21
       } else {
          printf("Greetings from process %d of %d!\n", my_rank,
22
              comm_sz):
          for (int q = 1; q \neq comm_sz; q++) {
23
             MPI_Recv(greet/ng, MAX_STRING, MPI_CHAR, q,
24
                O, MPI_COMM_WORLD, MPI_STATUS_IGNORE);
25
             printf("%s\n/, greeting);
26
27
28
29
30
      MPI_Finalize():
31
       return 0:
32
       /* main */
```

What if MPI Recv is called before MPI Send?



Collective vs. Point-to-Point Communications

- All the processes in the communicator must call the same collective function. For example, a program that attempts to match a call to MPI Reduce on one process with a call to MPI Recv on another process is erroneous, and, in all likelihood, the program will hang or crash.
- Point-to-point communications are matched on the basis of tags and communicators. Collective communications don't use tags, so they're matched solely on the basis of the communicator and the order in which they're called.

Time	Process 0	Process 1	Process 2	
0	a = 1; c = 2	a = 1; $c = 2$	a = 1; c = 2	
1	MPI_Reduce(&a, &b,)	MPI_Reduce(&c, &d,)	MPI_Reduce(&a, &b,)	
2	MPI_Reduce(&c, &d,)	MPI_Reduce(&a, &b,)	MPI_Reduce(&c, &d,)	

Today's Goals

- Review last lecture
- More collective MPI
 - MPI_Scatter
 - MPI_Gather
- MPI matrix-vector multiplication
- MPI Performance measurement
- Live Demo



Broadcast

 Data belonging to a single process is sent to all of the processes in the communicator

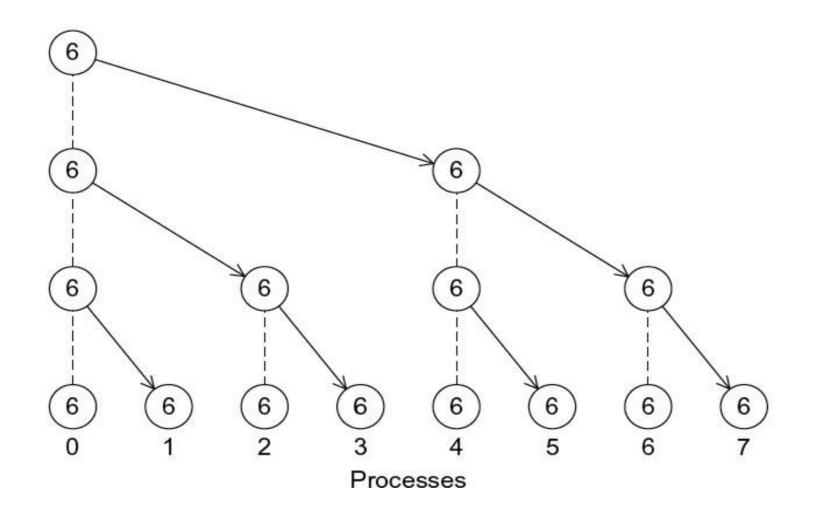
```
MPI_BCAST(buffer, count, datatype, root, comm)
  INOUT
            buffer
                                         starting address of buffer (choice)
                                         number of entries in buffer (non-negative integer)
           count
  IN
           datatype
                                         datatype of buffer (handle)
  IN
                                         rank of broadcast root (integer)
            root
  IN
                                         communicator (handle)
            comm
C binding
int MPI_Bcast(void *buffer, int count, MPI_Datatype datatype, int root,
               MPI_Comm comm)
```



A Version of Get_input that Uses MPI_Bcast

```
void Get_input(int my_rank, int comm_sz, double* a_p, double* b_p,
       int* n_p) {
   if (my_rank == 0) {
       printf("Enter a, b, and n\n");
       scanf("%lf %lf %d", a_p, b_p, n_p);
                                                                         if (mv_rank == 0) {
                                                                            printf("Enter a, b, and n\n");
                                                                            scanf("%lf %lf %d", a_p, b_p, n_p);
   MPI_Bcast(a_p, 1, MPI_DOUBLE, 0, MPI_COMM_WORLD);
                                                                            for (dest = 1; dest < comm_sz; dest++) {</pre>
   MPI_Bcast(b_p, 1, MPI_DOUBLE, 0, MPI_COMM_WORLD);
                                                                              MPI_Send(a_p, 1, MPI_DOUBLE, dest, 0, MPI_COMM_WORLD);
   MPI_Bcast(n_p, 1, MPI_INT, 0, MPI_COMM_WORLD);
                                                                              MPI_Send(b_p, 1, MPI_DOUBLE, dest, 0, MPI_COMM_WORLD);
                                                                              MPI_Send(n_p, 1, MPI_INT, dest, 0, MPI_COMM_WORLD);
} /* Get_input */
                                                                         } else { /* my_rank != 0 */
                                                                            MPI_Recv(a_p, 1, MPI_DOUBLE, 0, 0, MPI_COMM_WORLD,
                                                                                 MPI_STATUS_IGNORE);
                                                                            MPI_Recv(b_p, 1, MPI_DOUBLE, 0, 0, MPI_COMM_WORLD,
                                                                                 MPI_STATUS_IGNORE);
                          What is the problem of this version?
                                                                            MPI_Recv(n_p, 1, MPI_INT, 0, 0, MPI_COMM_WORLD,
                                                                                 MPI_STATUS_IGNORE);
```

A Tree-structured Broadcast



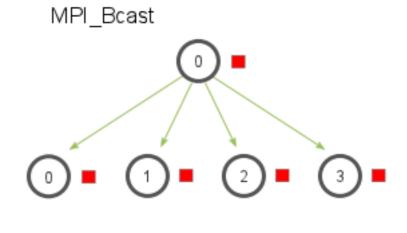


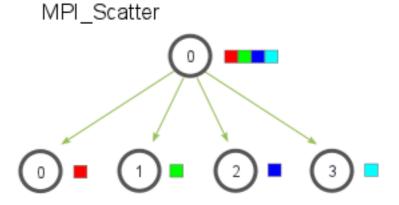
MPI_Scatter

 Similar to MPI_Bcast, however, instead of sending the same piece of data to all processes, MPI_Scatter sends chunks of an array to different processes.

MPI_SCATTER(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, root, comm)

IN	sendbuf	address of send buffer (choice, significant only at root)
IN	sendcount	number of elements sent to each process (non-negative integer, significant only at root)
IN	sendtype	datatype of send buffer elements (handle, significant only at root)
OUT	recvbuf	address of receive buffer (choice)
IN	recvcount	number of elements in receive buffer (non-negative integer)
IN	recvtype	datatype of receive buffer elements (handle)
IN	root	rank of sending process (integer)
IN	comm	communicator (handle)







MPI_Scatter example in mpi_vector_add.c

```
if (my_rank == 0) {
  a = malloc( size: n*sizeof(double));
  if (a == NULL) local_ok = 0;
  Check_for_error(local_ok, fname, "Can't allocate temporary vector",
         comm);
   printf("Enter the vector %s\n", vec_name);
  for (i = 0; i < n; i++)
      scanf("%lf", &a[i]);
  MPI_Scatter(a, local_n, MPI_DOUBLE, local_a, local_n, MPI_DOUBLE, 0,
      comm);
  free(a);
```

MPI_Gather

MPI_Gather is the inverse of MPI_Scatter

MPI_GATHER(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, root, comm)

IN sendbuf starting address of send buffer (choice)

IN sendcount number of elements in send buffer (non-negative

integer)

IN sendtype datatype of send buffer elements (handle)

OUT recvbuf address of receive buffer (choice, significant only at

root)

IN recvcount number of elements for any single receive

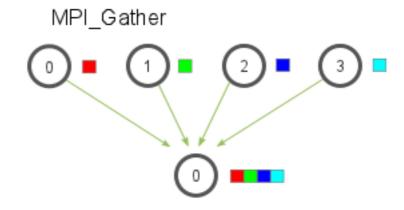
(non-negative integer, significant only at root)

IN recvtype datatype of recv buffer elements (handle, significant

only at root)

IN root rank of receiving process (integer)

IN comm communicator (handle)





MPI_Gather Example in mpi_vector_add.c

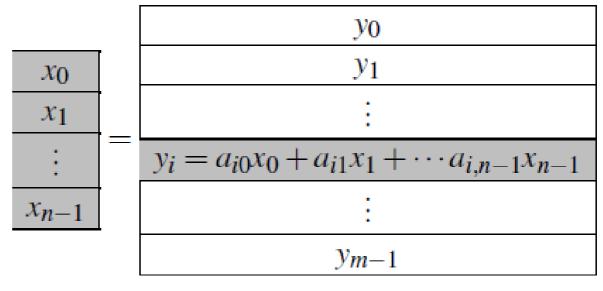
```
if (my_rank == 0) {
   b = malloc( size: n*sizeof(double));
   if (b == NULL) local_ok = 0;
   Check_for_error(local_ok, fname, "Can't allocate temporary vector",
        comm);
  MPI_Gather(local_b, local_n, MPI_DOUBLE, b, local_n, MPI_DOUBLE,
        0, comm);
   printf("%s\n", title);
   for (i = 0; i < n; i++)
     printf("%f ", b[i]);
   printf("\n");
   free(b);
} else {
   Check_for_error(local_ok, fname, "Can't allocate temporary vector",
         comm);
   MPI_Gather(local_b, local_n, MPI_DOUBLE, b, local_n, MPI_DOUBLE, 0,
     comm);
```

MPI_Allgather

 Concatenates the contents of each process' send_buf_p and stores this in each process' recv_buf_p.

Matrix-vector multiplication

a ₀₀	a_{01}	•	$a_{0,n-1}$
a_{10}	a_{11}	•	$a_{1,n-1}$
:	:		:
a_{i0}	a_{i1}	• • •	$a_{i,n-1}$
<i>a</i> _{i0} :	<i>a</i> _{i1} :	•••	$a_{i,n-1}$:



Multiply a matrix by a vector – pseudo-code

```
/* For each row of A */
for (i = 0; i < m; i++) {
  /* Form dot product of ith row with x */
   v[i] = 0.0;
   for (j = 0; j < n; j++)
      y[i] += A[i][j]*x[j];
```

Serial matrix-vector multiplication

```
void Mat_vect_mult(
     double A[] /* in */,
     double x[] /* in */,
     double y[] /* out */,
     int m /*in */,
     int n /* in */) {
  int i, j;
  for (i = 0; i < m; i++) {
     y[i] = 0.0;
     for (j = 0; j < n; j++)
        y[i] += A[i*n+j]*x[j];
 /* Mat_vect_mult */
```

An MPI matrix-vector multiplication function (1)

```
void Mat_vect_mult(
    double local_A[] /* in */,
    double local_x[] /* in */,
    double local_y[] /* out */,
    int local_m /* in */,
    int n /*in */,
    int local_n /* in */,
    MPI_Comm comm /* in */) {
  double * x;
  int local_i, j;
  int local_ok = 1;
```

An MPI matrix-vector multiplication function (2)

```
x = malloc(n*sizeof(double));
MPI_Allgather(local_x, local_n, MPI_DOUBLE,
      x, local_n, MPI_DOUBLE, comm);
for (local_i = 0; local_i < local_m; local_i++) {
   local_y[local_i] = 0.0;
   for (j = 0; j < n; j++)
      local_y[local_i] += local_A[local_i*n+j]*x[j];
free(x);
/* Mat_vect_mult */
```

Timing Serial Program

```
#include "time.h"
double start, finish;
GET_TIME(start);
/* Code to be timed */
GET_TIME(finish);
printf("Elapsed time = %e seconds \n", finish - start);
```



Elapsed MPI Time

```
double start, finish;
...
MPI_Barrier(MPI_COMM_WORLD);
start = MPI_Wtime();

/* Code to be timed */
...
finish = MPI_Wtime();
printf("Proc %d > Elapsed time = %e seconds \n", my_rank, finish - start);
```

MPI_Wtime does not include the idol time, e.g. time of waiting for a message to come.

Make sure only print out in Master process

Speedup and Efficiency

 Speedup: Ratio of execution time on one process to that on p processes

$$Speedup = \frac{t_1}{t_p}$$

• Efficiency: Speedup per process

Efficiency =
$$\frac{t_1}{t_p \times p}$$

Speedups of a Parallel Application

	Order of Matrix				
comm_sz	1024	2048	4096	8192	16,384
1	1.0	1.0	1.0	1.0	1.0
2	1.8	1.9	1.9	1.9	2.0
4	2.1	3.1	3.6	3.9	3.9
8	2.4	4.8	6.5	7.5	7.9
16	2.4	6.2	10.8	14.2	15.5

Efficiencies of a Parallel Application

	Order of Matrix				
comm_sz	1024	2048	4096	8192	16,384
1	1.00	1.00	1.00	1.00	1.00
2	0.89	0.94	0.97	0.96	0.98
4	0.51	0.78	0.89	0.96	0.98
8	0.30	0.61	0.82	0.94	0.98
16	0.15	0.39	0.68	0.89	0.97

Scalability

 A program is scalable if the problem size can be increased at a rate so that the efficiency doesn't decrease as the number of processes increase



Scalability (Cont.)

- Programs that can maintain a constant efficiency without increasing the problem size are sometimes said to be strongly scalable
- Programs that can maintain a constant efficiency if the problem size increase at the same rate as the number of processes are sometimes said to be weakly scalable

Safety in MPI Programs

- The MPI standard allows MPI_Send to behave in two different ways:
 - it can simply copy the message into an MPI managed buffer and return,
 - or it can block until the matching call to MPI_Recv starts.

Safety in MPI Programs

- Many implementations of MPI set a threshold at which the system switches from buffering to blocking.
- Relatively small messages will be buffered by MPI_Send.
- Larger messages, will cause it to block.

Safety in MPI Programs

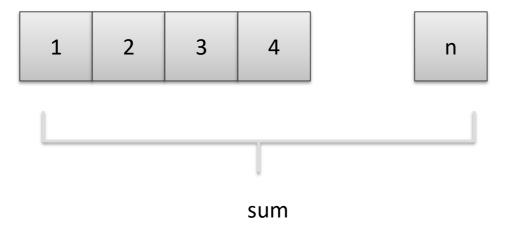
- If the MPI_Send executed by each process blocks, no process will be able to start executing a call to MPI_Recv, and the program will hang or deadlock.
- Each process is blocked waiting for an event that will never happen.

MPI Sendrecv

- An alternative to scheduling the communications ourselves.
- Carries out a blocking send and a receive in a single call.
- The dest and the source can be the same or different.
- Especially useful because MPI schedules the communications so that the program won't hang or crash.

Live coding demo

Summing up an array





Wrap up

