DTS203TC Design and Analysis of Algorithms

Lecture 9: Dynamic Programming

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Learning outcome

- Understand the basic idea of dynamic programming
- Able to apply dynamic programming to compute Fibonacci numbers
- Able to apply dynamic programming to solve the assembly line scheduling problem



Dynamic programming an efficient way to implement some divide and conquer algorithms

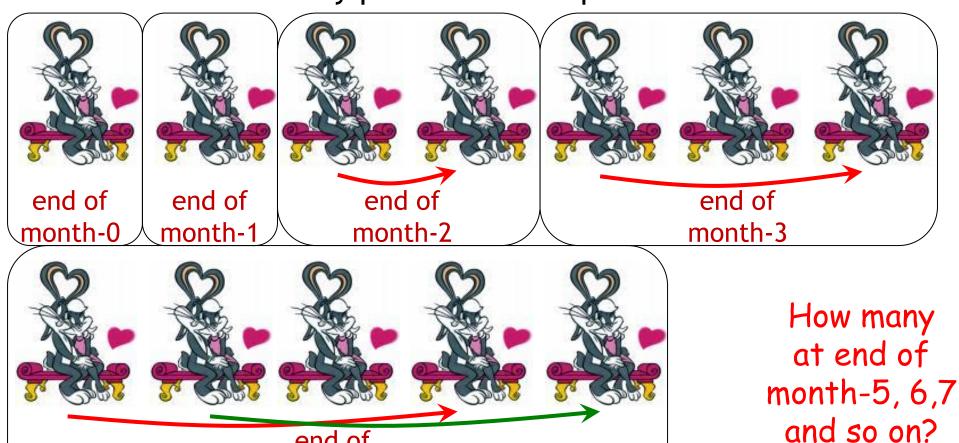


Fibonacci numbers



Fibonacci's Rabbits

A pair of rabbits, one month old, is too young to reproduce. Suppose that in their second month, and every month thereafter, they produce a new pair.



end of

month-4



Petals on flowers



1 petal: white calla lily



2 petals: euphorbia



3 petals: trillium



5 petals: columbine



8 petals: bloodroot



13 petals: black-eyed susan



21 petals: shasta daisy



34 petals: field daisy



Fibonacci Numbers in Nature

Fibonacci number

Fibonacci number F(n)

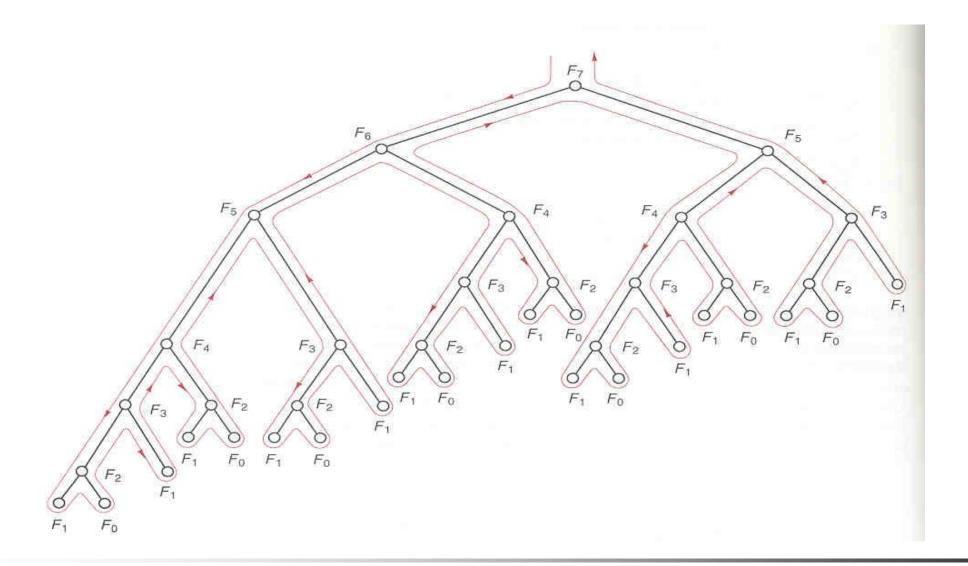
$$F(n) = \begin{cases} 1 & \text{if } n = 0 \text{ or } 1 \\ F(n-1) + F(n-2) & \text{if } n > 1 \end{cases}$$

n	0	1	2	3	4	5	6	7	8	9	10
F(n)	1	1	2	3	5	8	13	21	34	55	89

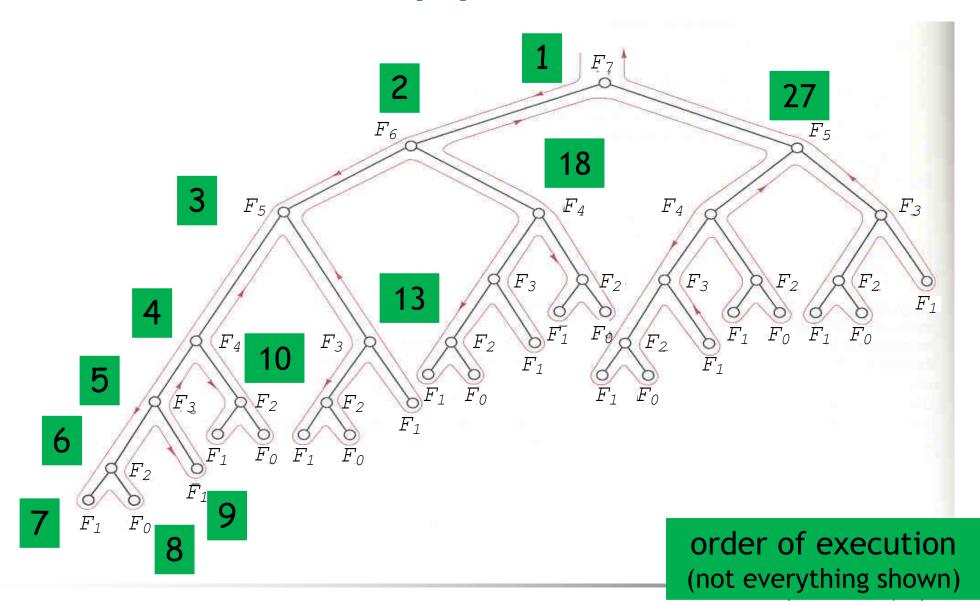
Pseudo code for the recursive algorithm:

```
Algorithm F(n)
if n==0 or n==1 then
return 1
else
return F(n-1) + F(n-2)
```

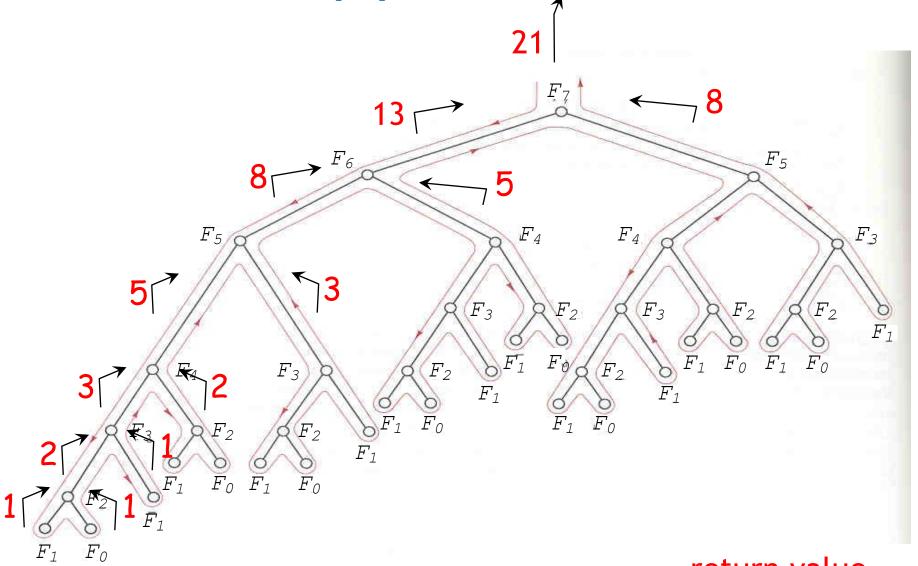






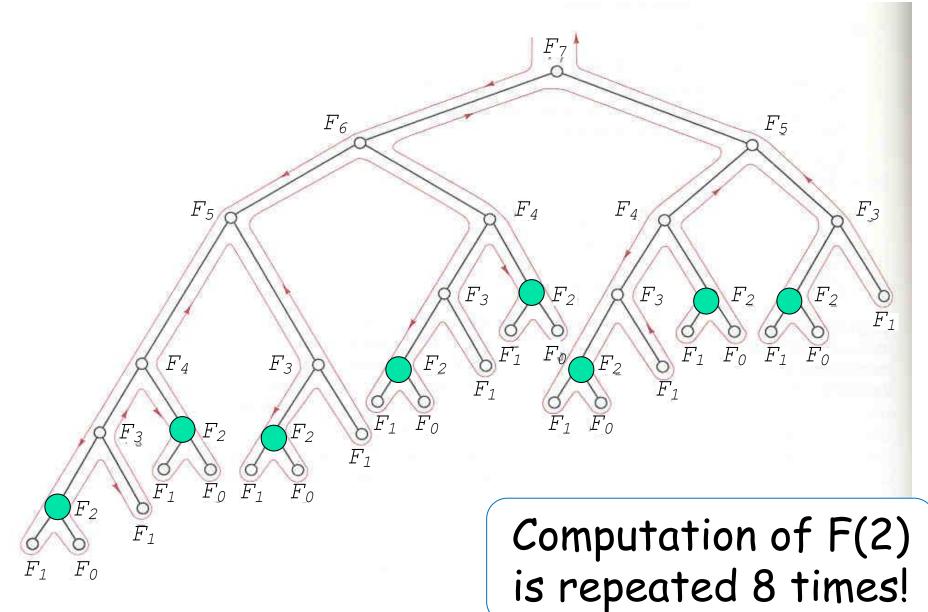




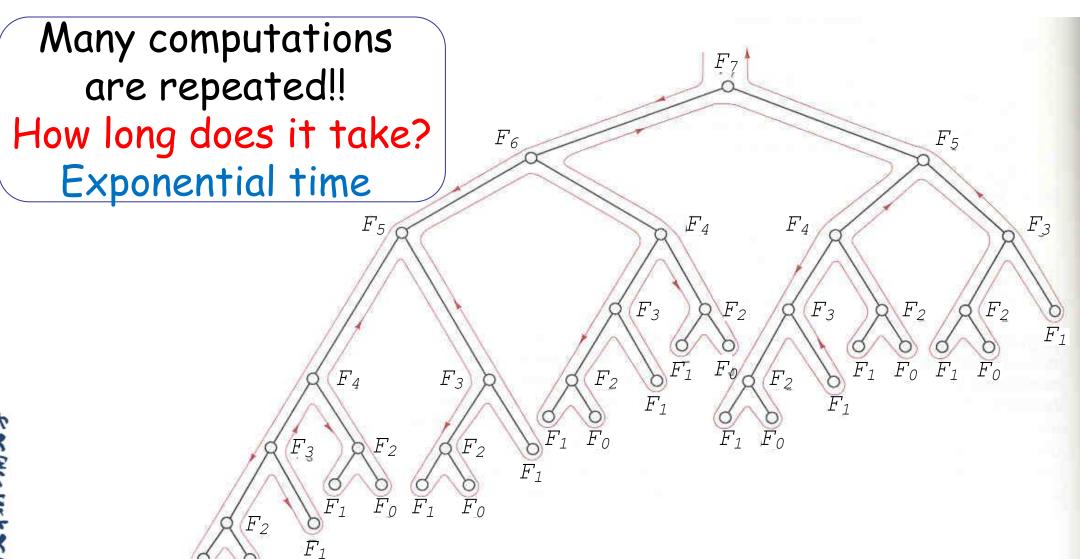




return value (not everything shown)









Idea for improvement

Memoization:

- Store F(i) somewhere after we have computed its value
- Afterward, we don't need to re-compute F(i); we can retrieve its value from our memory.

```
[] refers to array() is parameter for calling a procedure
```

```
Procedure F(n)

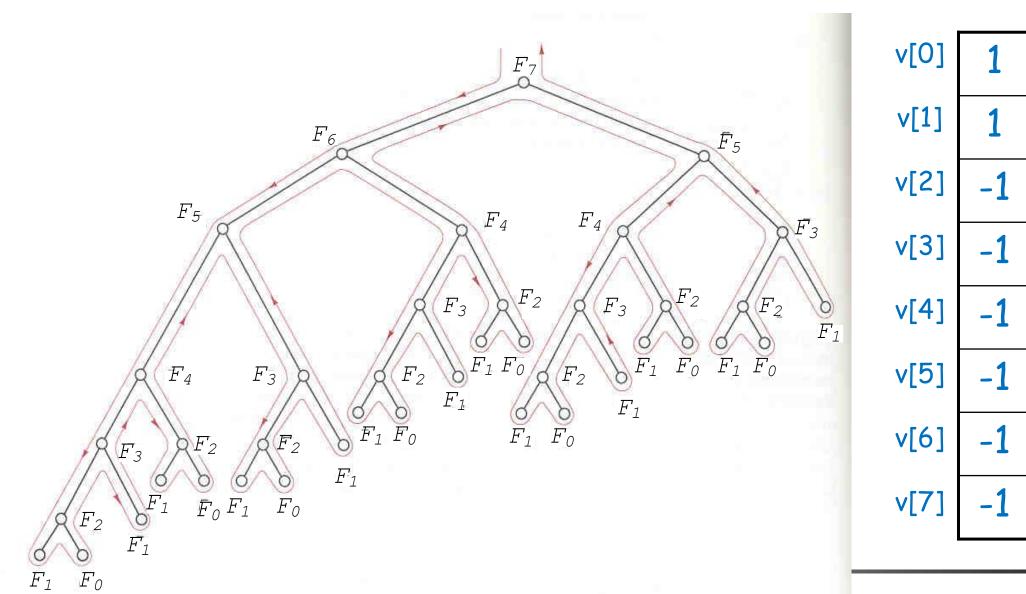
if (v[n] < 0) then

v[n] = F(n-1)+F(n-2)

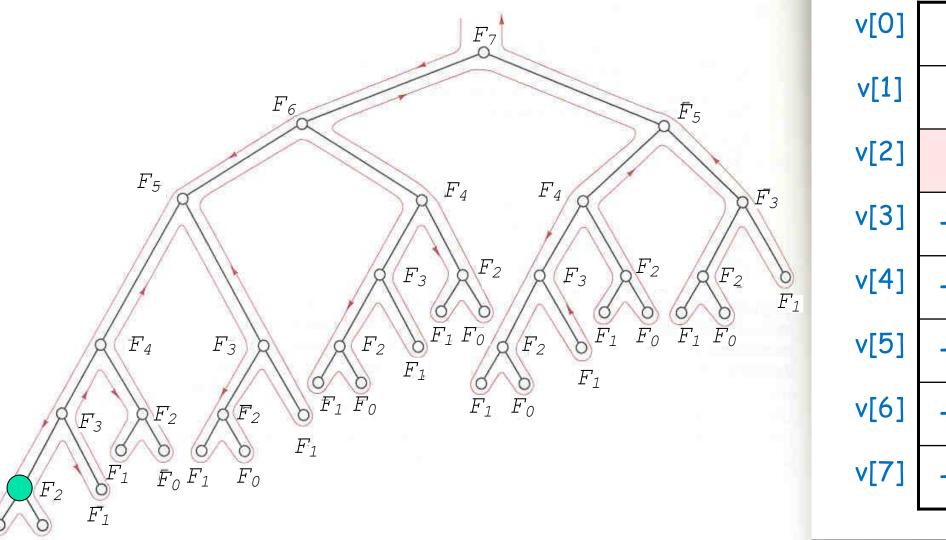
return v[n]
```

```
Main
set v[0] = v[1] = 1
for i = 2 to n do
v[i] = -1
output F(n)
```

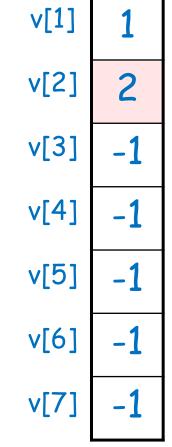


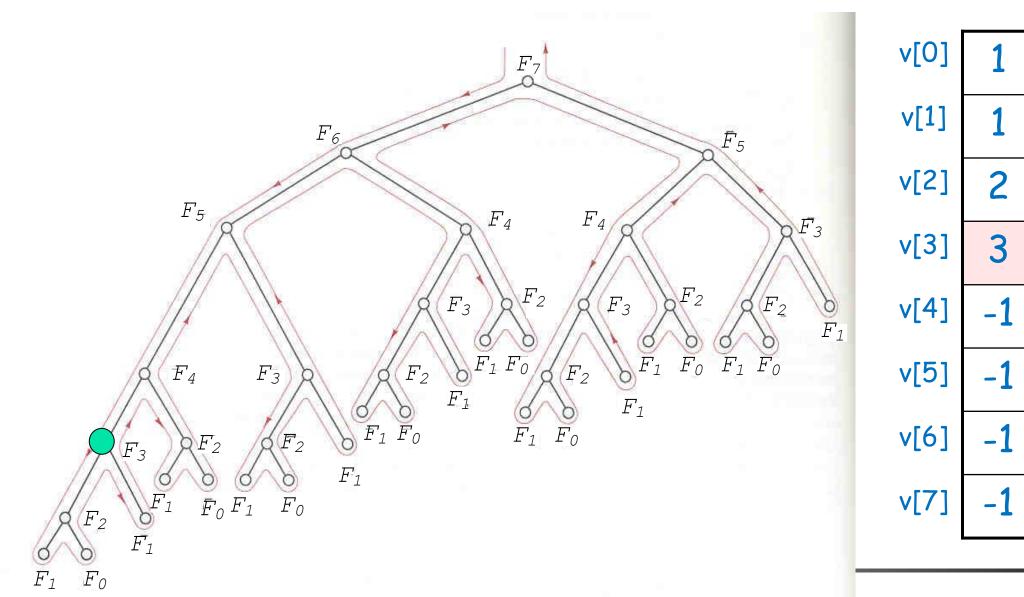




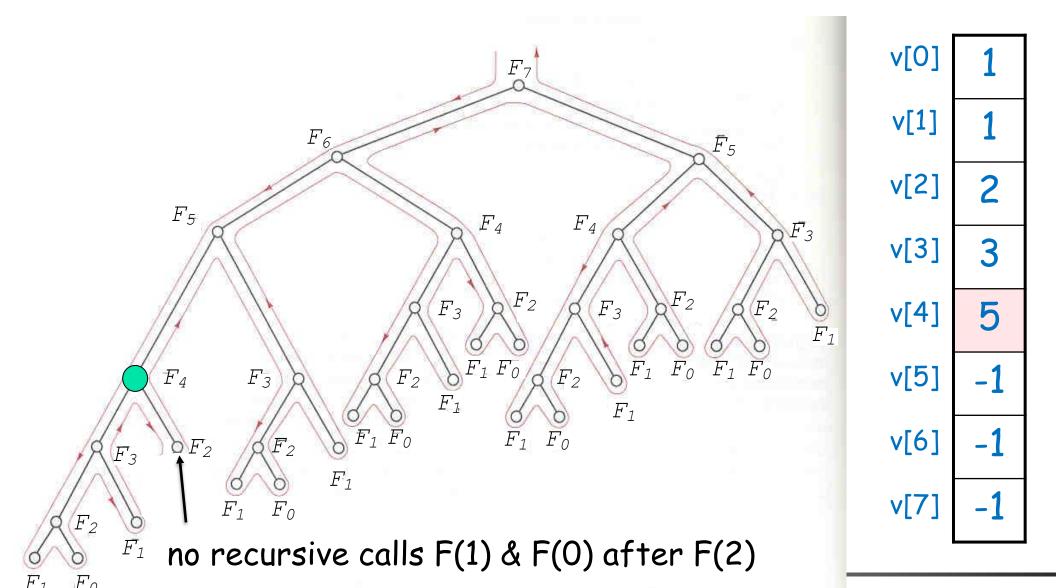




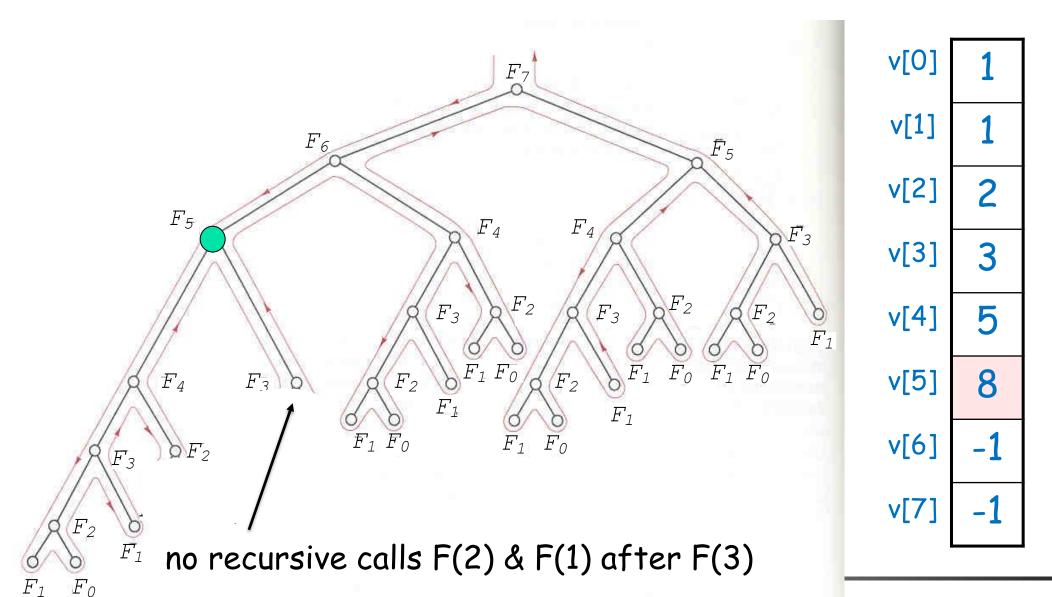




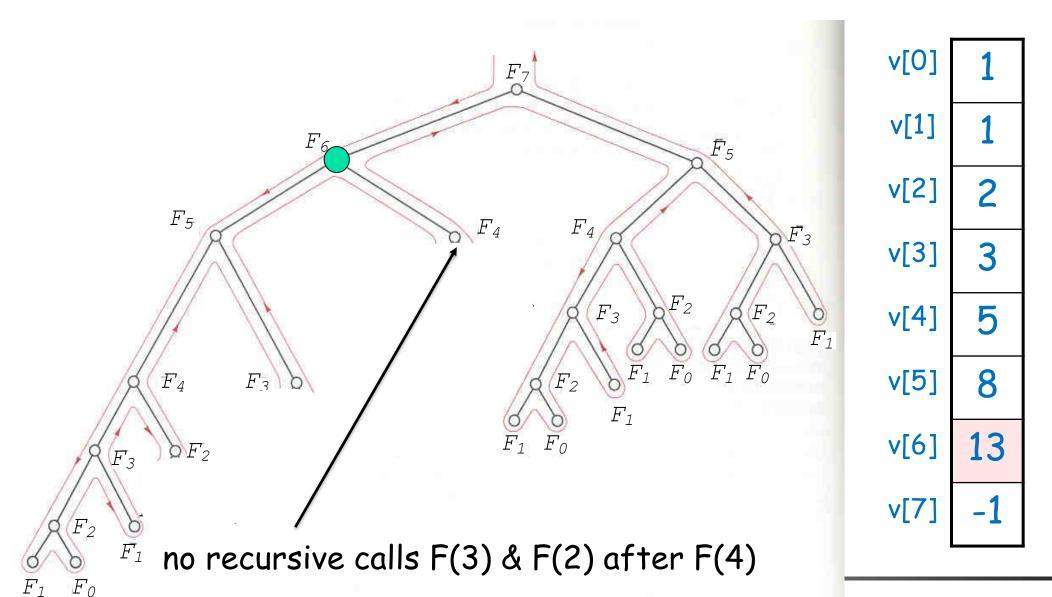




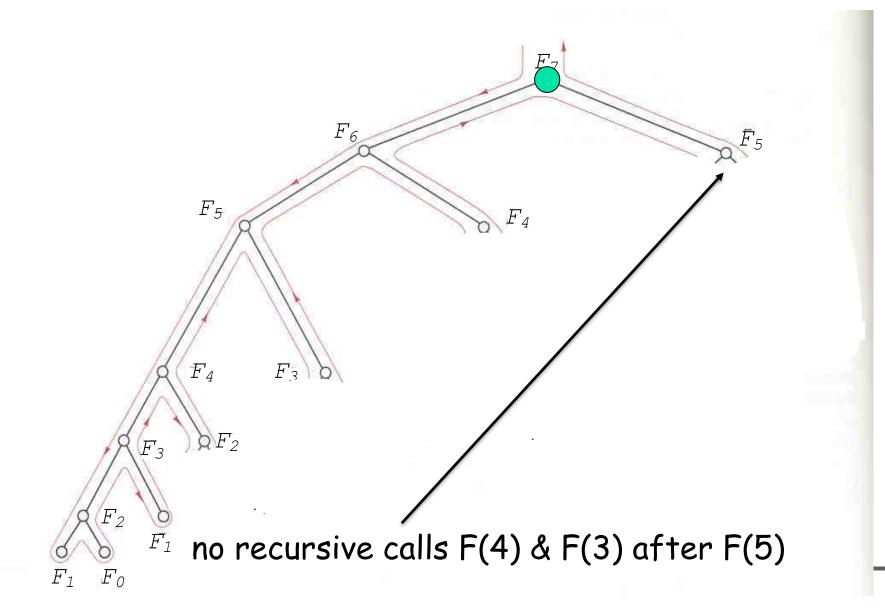


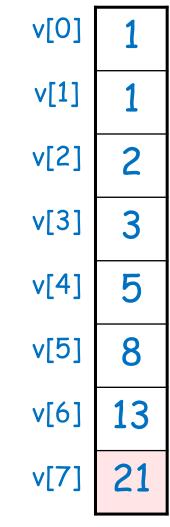














Can we do better?

Observation

- The 2nd version stills make many function calls, and each wastes times in parameters passing, dynamic linking, ...
- In general, to compute F(i), we need F(i-1) & F(i-2) only

Idea to further improve

- Compute the values in bottom-up fashion.
- That is, compute F(2) (we already know F(0)=F(1)=1), then F(3), then F(4)...

```
Procedure F(n)

Set A[0] = A[1] = 1

for i = 2 to n do

A[i] = A[i-1] + A[i-2]

return A[n]
```



Recursive vs DP approach

Recursive version:

```
Procedure F(n)
  if n==0 or n==1 then
    return 1
  else
    return F(n-1) + F(n-2)
```



Dynamic Programming version:

```
Procedure F(n)
   Set A[0] = A[1] = 1
   for i = 2 to n do
        A[i] = A[i-1] + A[i-2]
   return A[n]
```







Summary of the methodology

- Write down a formula that relates a solution of a problem with those of sub-problems.
 - E.g. F(n) = F(n-1) + F(n-2).
- Index the sub-problems so that they can be <u>stored</u> and <u>retrieved</u> easily in a table (i.e., array)
- Fill the table in some bottom-up manner; start filling the solution of the smallest problem.
 - This ensures that when we solve a particular sub-problem, the solutions of all the smaller sub-problems that it depends are available.

For historical reasons, we call such methodology **Dynamic Programming**.

In the late 40's (when computers were rare), programming refers to the "tabular method".



Exercise

Consider the following function

$$G(n) = \begin{cases} 1 & \text{if } 0 \le n \le 2 \\ G(n-1) + G(n-2) + G(n-3) & \text{if } n > 2 \end{cases}$$

- 1. Draw the execution tree of computing G(6) recursively
- 2. Using dynamic programming, write a pseudo code to compute G(n) efficiently
- 3. What is the time complexity of your algorithm?



Exercise

$$G(n) = \begin{cases} 1 & \text{if } 0 \le n \le 2 \\ G(n-1) + G(n-2) + G(n-3) & \text{if } n > 2 \end{cases}$$

Recursive version:

```
Procedure G(n)
   if n \ge 0 and n \le 2 then
      return 1
   return G(n-1) + G(n-2) + G(n-3)
```

Dynamic Programming version:

Procedure G(n)



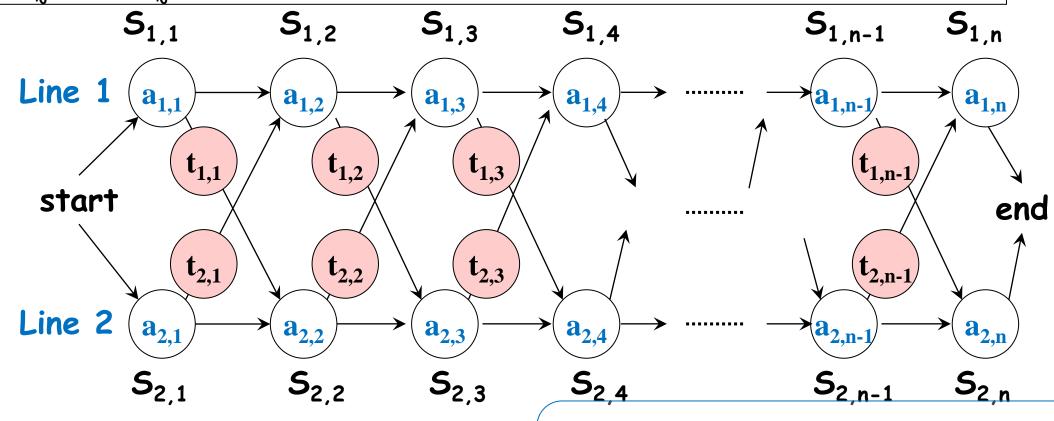


Assembly line scheduling



Assembly line scheduling

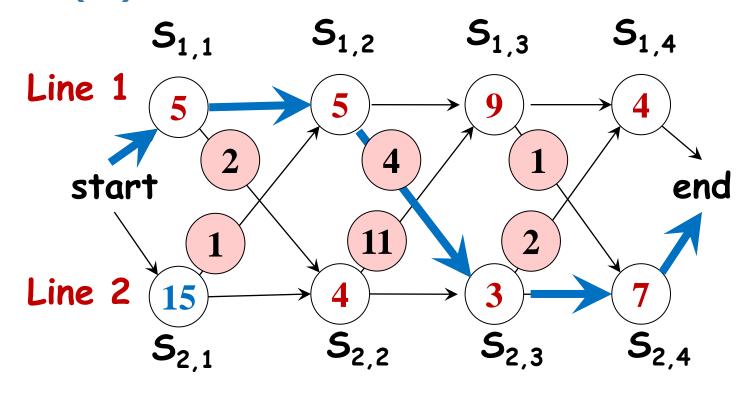
2 assembly lines, each with n stations ($S_{i,j}$: line i station j) $S_{1,j}$ and $S_{2,j}$ perform same task but time taken is different



 $\mathbf{a}_{i,j}$: assembly time at $\mathbf{S}_{i,j}$ $\mathbf{t}_{i,j}$: transfer time after $\mathbf{S}_{i,j}$ Problem: To determine which stations to go in order to minimize the total time through the n stations



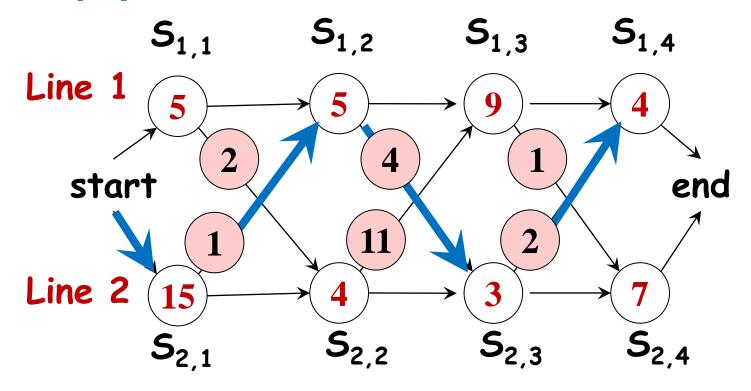
Example (1)



stations chosen:	$S_{1,1}$	S _{1,2}	S _{2,3}	S _{2,4}
time require <mark>d:</mark>	5	5 4	3	7 = 24

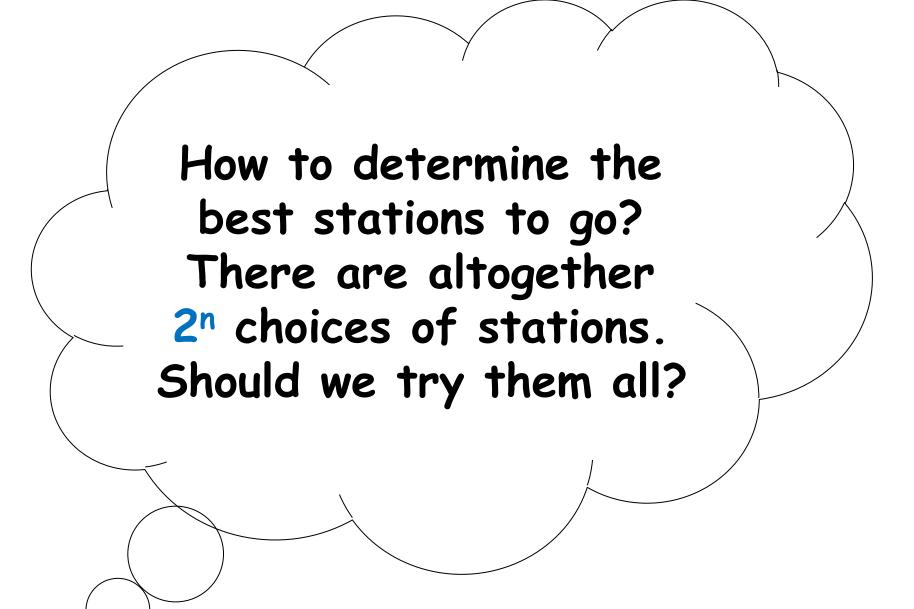


Example (2)



stations chosen:	S _{1,1}		S _{1,2}		S _{2,3}		S _{2,4}		
time req <mark>uired:</mark>	5		5	4	3		7	= 24	
stations chosen:	S _{2,1}		S _{1,2}		S _{2,3}		S _{1,4}		
time req <mark>uired:</mark>	15	1	5	4	3	2	4	= 34	-



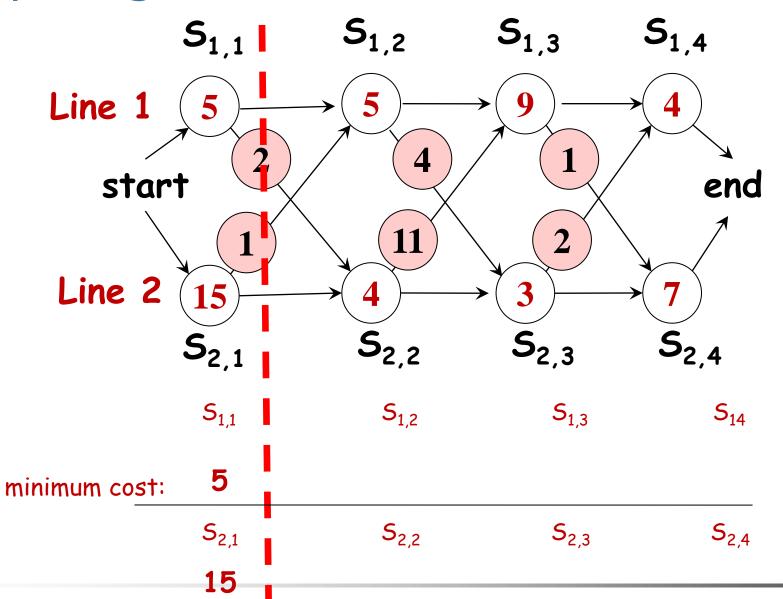




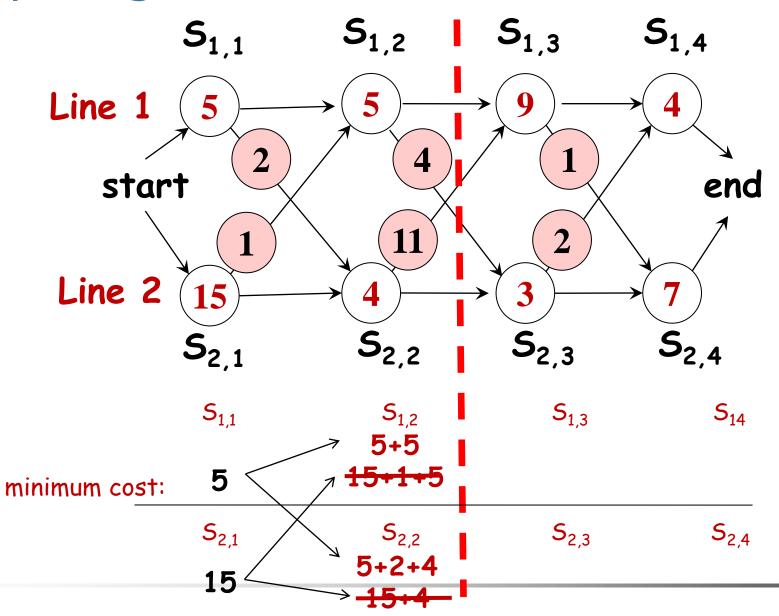
Good news: Dynamic Programming

- We don't need to try all possible choices.
- We can make use of dynamic programming:
 - 1. If we can compute the fastest ways to get thro' station $S_{1,n}$ and $S_{2,n}$, then the faster of these two ways is the overall fastest way.
 - 2. To compute the fastest ways to get thro' $S_{1,n}$ (similarly for $S_{2,n}$), we need to know the fastest way to get thro' $S_{1,n-1}$ and $S_{2,n-1}$
 - 3. In general, we want to know the fastest way to get thro' $S_{1,j}$ and $S_{2,j}$, for all j.

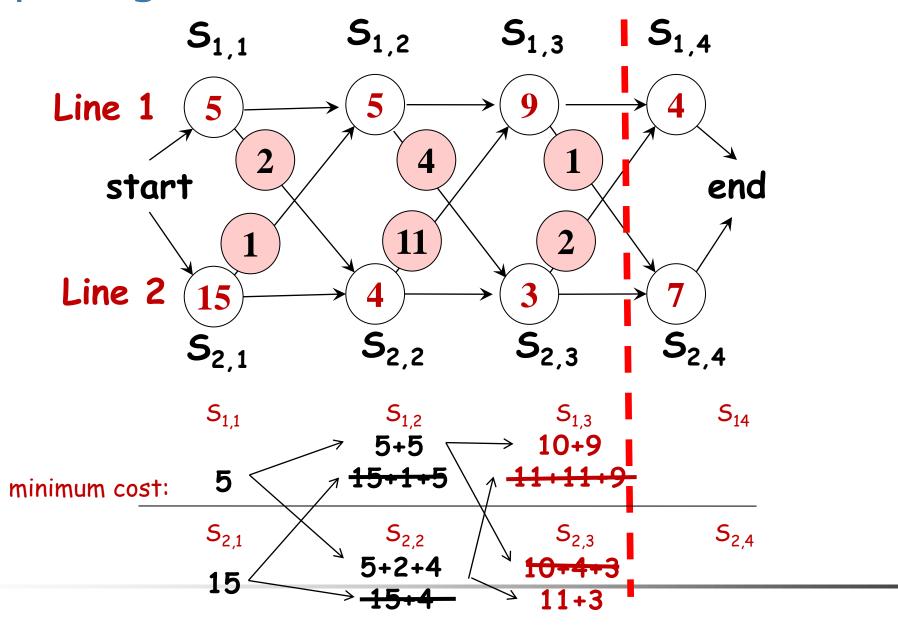




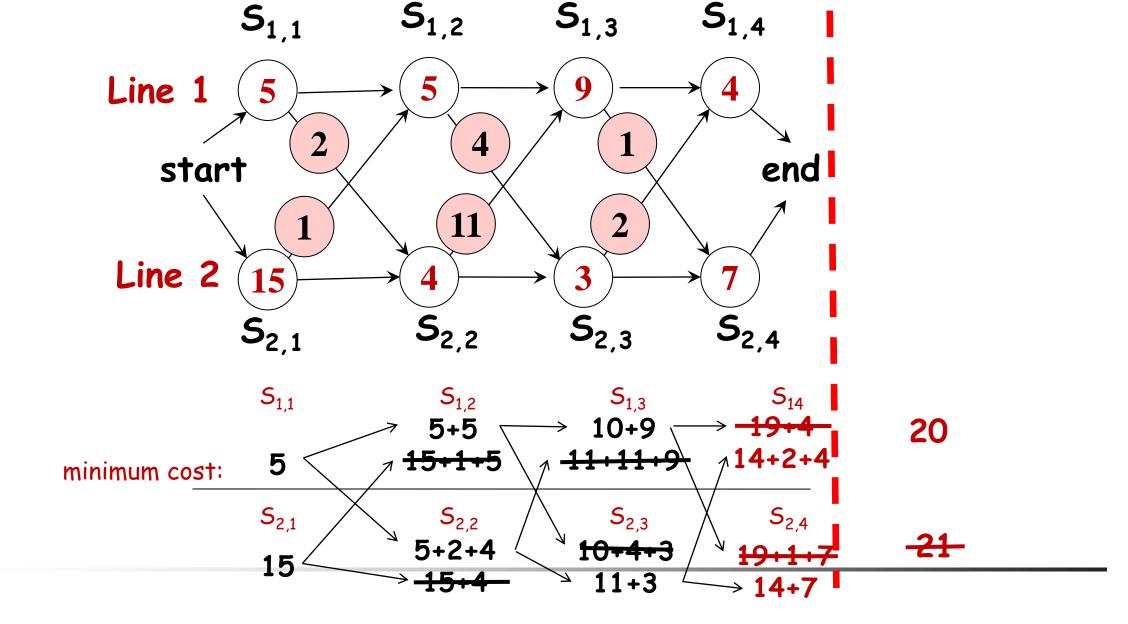














A dynamic programming solution

What are the sub-problems?

- ullet given j, what is the fastest way to get thro' $S_{1,j}$
- ullet given j, what is the fastest way to get thro' $S_{2,j}$

Definitions:

- $f_1[j]$ = the fastest time to get thro' $S_{1,j}$
- $f_2[j]$ = the fastest time to get thro' $S_{2,j}$

The final solution equals to min $\{f_1[n], f_2[n]\}$

Task:

• Starting from $f_1[1]$ and $f_2[1]$, compute $f_1[j]$ and $f_2[j]$ incrementally

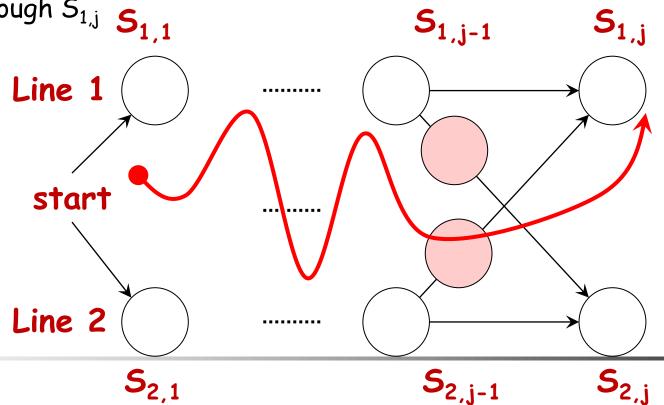


Q1: what is the fastest way to get thro' $S_{1,i}$?

A: either

• the fastest way thro' $S_{1,j-1}$, then <u>directly</u> to $S_{1,j}$, or

• the fastest way thro' $S_{2,j-1}$, a <u>transfer</u> from line 2 to line 1, and then through $S_{1,j}$ $S_{1,1}$





Q1: what is the fastest way to get thro' $S_{1,i}$?

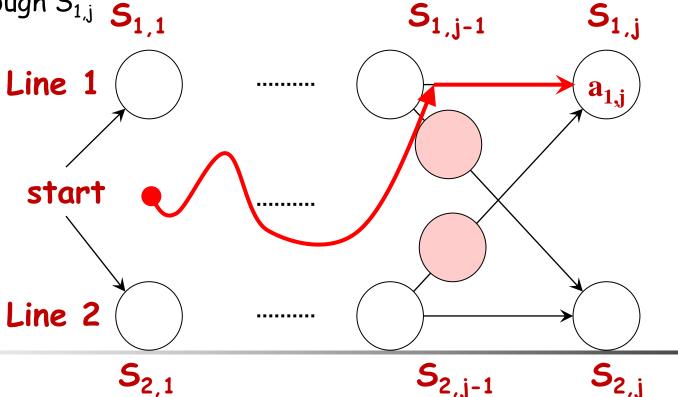
A: either

• the fastest way thro' $S_{1,j-1}$, then <u>directly</u> to $S_{1,j}$, or

• the fastest way thro' $S_{2,j-1}$, a <u>transfer</u> from line 2 to line 1, and then through $S_{1,j}$ $S_{1,1}$

Time required -f [i-1] + 2

$$=\mathbf{f}_{1}[\mathbf{j-1}] + \mathbf{a}_{1,\mathbf{j}}$$





Q1: what is the fastest way to get thro' $S_{1,i}$?

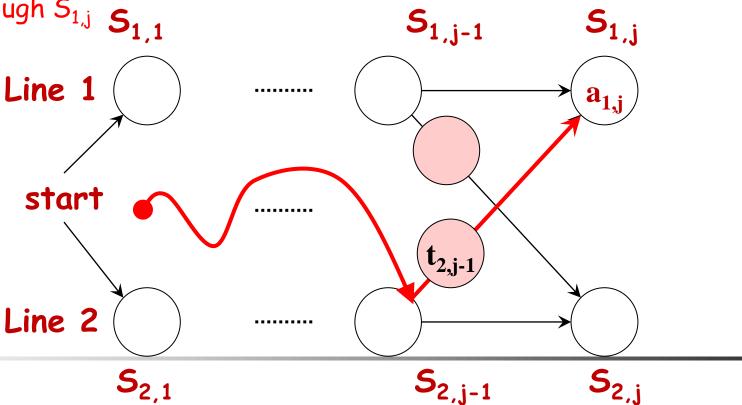
A: either

• the fastest way thro' $S_{1,j-1}$, then <u>directly</u> to $S_{1,j}$, or

• the fastest way thro' $S_{2,j-1}$, a <u>transfer</u> from line 2 to line 1, and then through $S_{1,j}$ $S_{1,1}$

Time required

$$=\mathbf{f}_{2}[\mathbf{j-1}] + \mathbf{t}_{2,\mathbf{j-1}} + \mathbf{a}_{1,\mathbf{j}}$$





Q1: what is the fastest way to get thro' $S_{1,j}$?

A: either

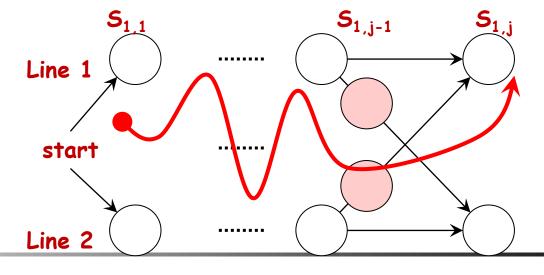
- the fastest way thro' $S_{1,j-1}$, then directly to $S_{1,j}$, or
- the fastest way thro' $S_{2,j-1}$, a transfer from line 2 to line 1, and then through $S_{1,i}$

Conclusion:

$$f_1[j] = \min(f_1[j-1] + a_{1,j}, f_2[j-1] + t_{2,j-1} + a_{1,j})$$

Boundary case:

$$f_1[1] = a_{1,1}$$



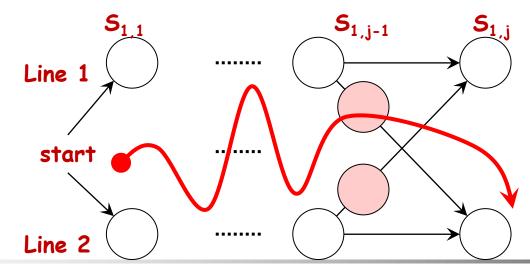
Q2: what is the fastest way to get thro' $S_{2,i}$?

By exactly the same analysis, we obtain the formula for the fastest way to get thro' S_{2i} :

$$f_2[j] = \min(f_2[j-1] + a_{2,j}, f_1[j-1] + t_{1,j-1} + a_{2,j})$$

Boundary case:

$$f_2[1] = a_{2,1}$$

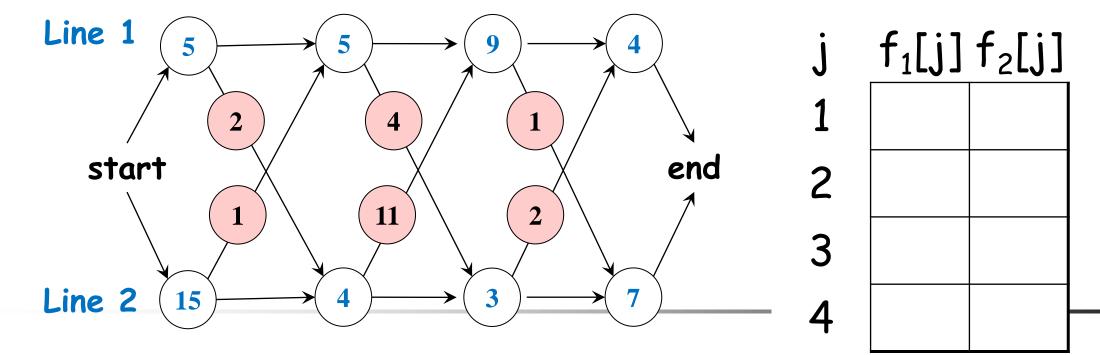




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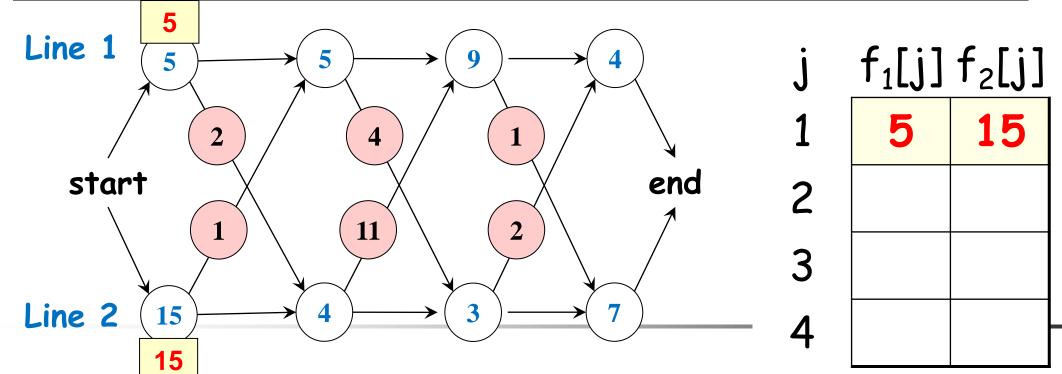
$$\begin{split} f_1[j] &= \left\{ \begin{array}{ll} a_{1,1} & \text{if } j{=}1, \\ \min \; (\; f_1[j{-}1]{+}a_{1,j} \; , \; f_2[j{-}1]{+}t_{2,j{-}1}{+}a_{1,j}) & \text{if } j{>}1 \\ \\ f_2[j] &= \left\{ \begin{array}{ll} a_{2,1} & \text{if } j{=}1, \\ \min \; (\; f_2[j{-}1]{+}a_{2,j} \; , \; f_1[j{-}1]{+}t_{1,j{-}1}{+}a_{2,j}) & \text{if } j{>}1 \\ \\ f^* &= \min (\; f_1[n] \; , f_2[n] \;) \\ \end{split} \right. \end{split}$$



$$f_{1}[j] = \begin{cases} a_{1,1} & \text{if } j=1, \\ \min \left(f_{1}[j-1] + a_{1,j} \right), \ f_{2}[j-1] + t_{2,j-1} + a_{1,j} \right) & \text{if } j>1 \end{cases}$$

$$f_{2}[j] = \begin{cases} a_{2,1} & \text{if } j=1, \\ \min \left(f_{2}[j-1] + a_{2,j} \right), \ f_{1}[j-1] + t_{1,j-1} + a_{2,j} \right) & \text{if } j>1 \end{cases}$$

$$f^{*} = \min(f_{1}[n], f_{2}[n])$$

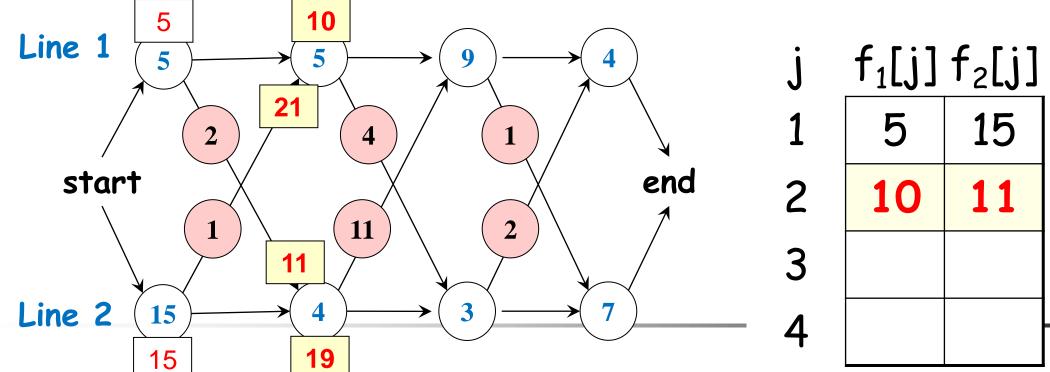




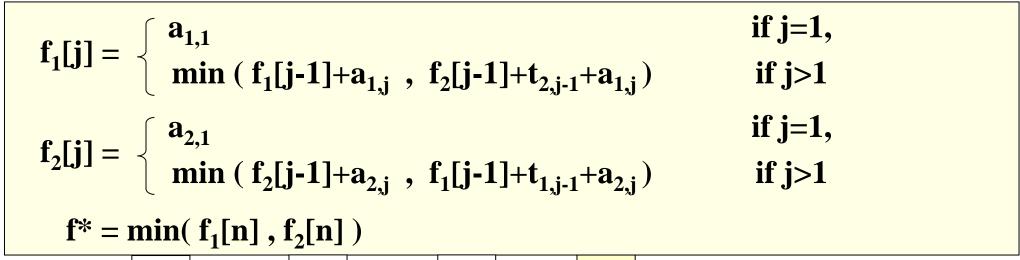
$$f_{1}[j] = \begin{cases} a_{1,1} & \text{if } j=1, \\ \min \left(f_{1}[j-1] + a_{1,j} \right), \ f_{2}[j-1] + t_{2,j-1} + a_{1,j} \right) & \text{if } j>1 \end{cases}$$

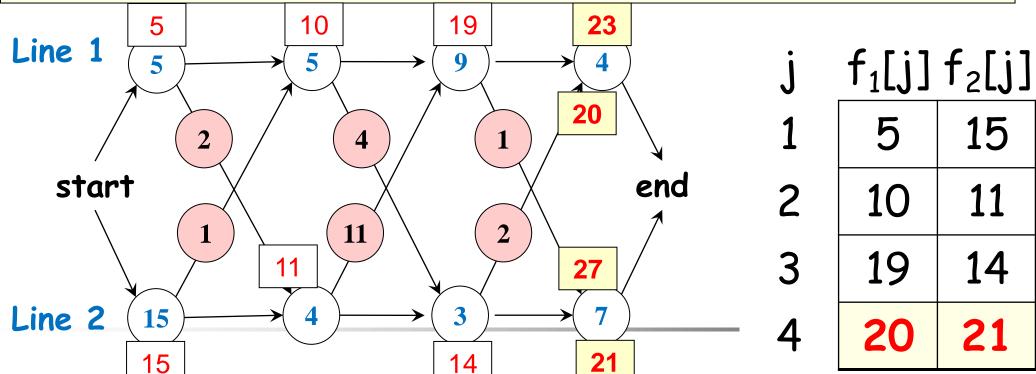
$$f_{2}[j] = \begin{cases} a_{2,1} & \text{if } j=1, \\ \min \left(f_{2}[j-1] + a_{2,j} \right), \ f_{1}[j-1] + t_{1,j-1} + a_{2,j} \right) & \text{if } j>1 \end{cases}$$

$$f^{*} = \min(f_{1}[n], f_{2}[n])$$

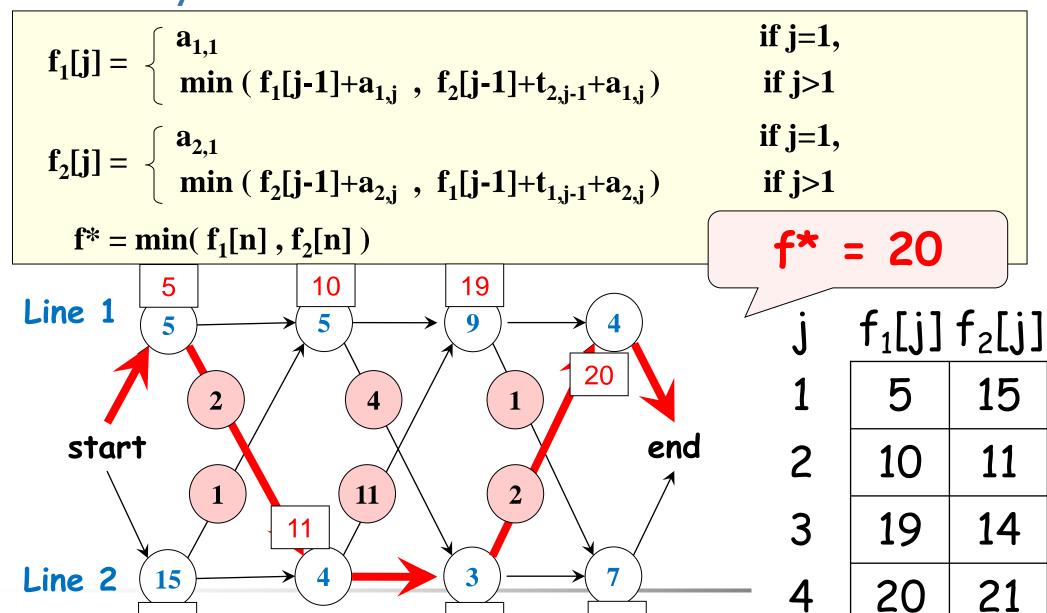














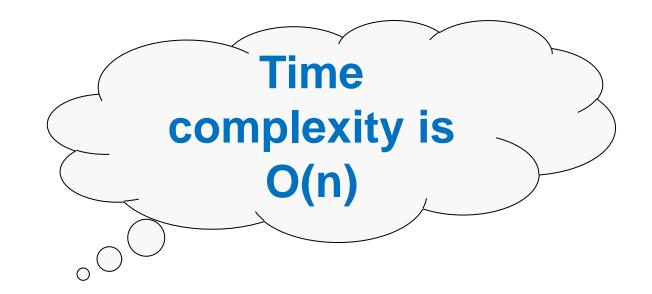
Pseudo code

```
set f_1[1] = a_{1,1}

set f_2[1] = a_{2,1}

for j = 2 to n do

begin
```



```
set f_1[j] = min(f_1[j-1] + a_{1,j}, f_2[j-1] + t_{2,j-1} + a_{1,j})
set f_2[j] = min(f_2[j-1] + a_{2,j}, f_1[j-1] + t_{1,j-1} + a_{2,j})
```

end

```
set f^* = \min (f_1[n], f_2[n])
```

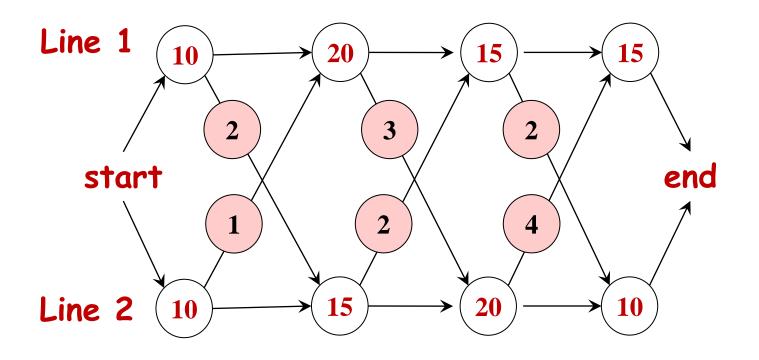


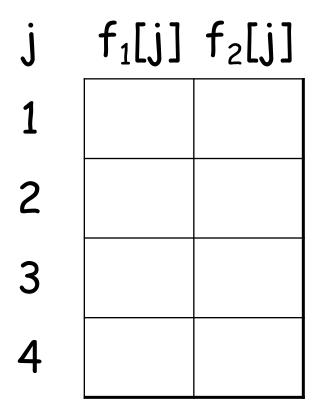
How to apply Dynamic Programming?

- Step 1: Identify sub-problems and optimal substructure.
- Step 2: Find a recursive formulation
- Step 3: Use dynamic programming (typically in a bottom-up fashion) to compute the value of an optimal solution
- Step 4: If needed, keep track of some additional info to get the optimal solution

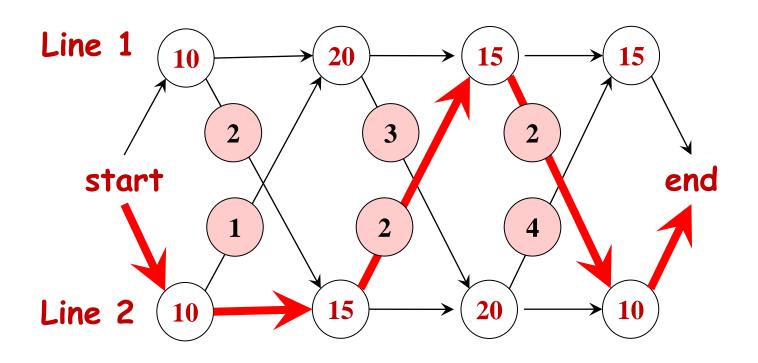


Exercise





Exercise - solution





j	f ₁ [j]	f ₂ [j]
1	10	10
2	30	25
3	42	45
4	57	54

What if there are 3 or more lines?

- Pseudo code?
 - Calculate f[i][j]
 - Find optimal cost
 - Find optimal path
- Time complexity?





Exercise

Given an $m \times n$ grid filled with integers representing "rewards". There is a robot placed at the top left cell and need to find a way to the bottom right cell. The robot can only move either down or right. What is the maximum reward the robot could collect through its path from top left to bottom right? Solve this problem with dynamic programming.

Example:

1	3	4
7	5	8
2	6	3

Output: 24

Explanation: The path 1->7->5->8->3 gives the maximum reward.

Learning outcomes

- Understand the basic idea of dynamic programming
- Able to apply dynamic programming to compute Fibonacci numbers
- Able to apply dynamic programming to solve the assembly line scheduling problem

