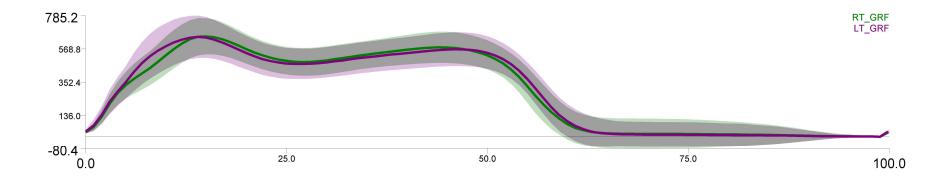
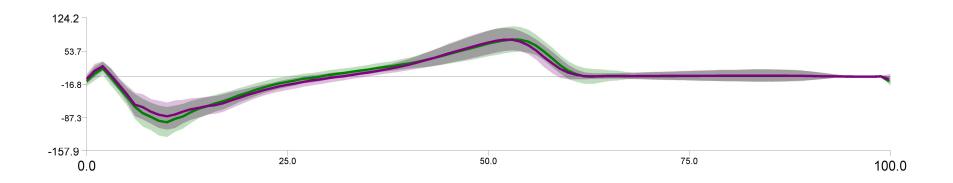
Gait parameters

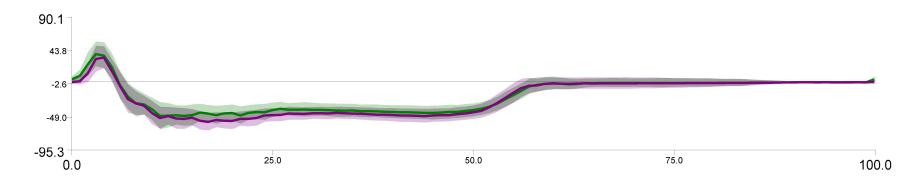
Speed 0.790 m/s 0.457 Statures/s **Stride** Wid(230) 0.204±0.012m Len(230) 0.903±0.149m **Cycle Time** Computed: 1.136 s Actual (230) 1.144±0.139 s Measure±StdDev (Count) Measure±StdDev (Count) **Step Length** Right: 0.447±0.142 m (116) Left: 0.436±0.145 m (115) **Step Time** Left: 0.565±0.087 s (115) Right 0.573±0.107 s (116) **Stance Time** Left: 0.722±0.094 s (115) Right: 0.720±0.135 s (115) **Swing Time** Left: 0.421±0.072 s (115) Right: 0.425±0.076 s (115) **Initial DBL Support** Left: 0.147±0.101 s (116) Right: 0.143±0.035 s (115)

0.290±0.135 s

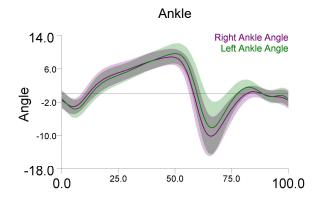
Dbl Limb Support (231)

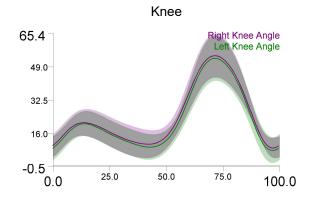


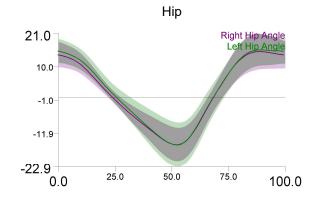


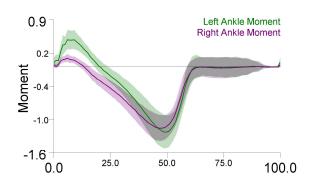


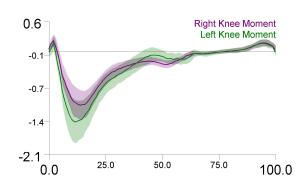
Lower-limb joint kinematics and kinetics

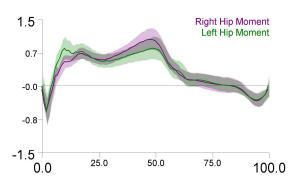


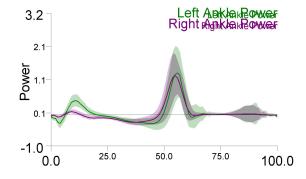


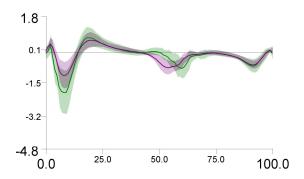






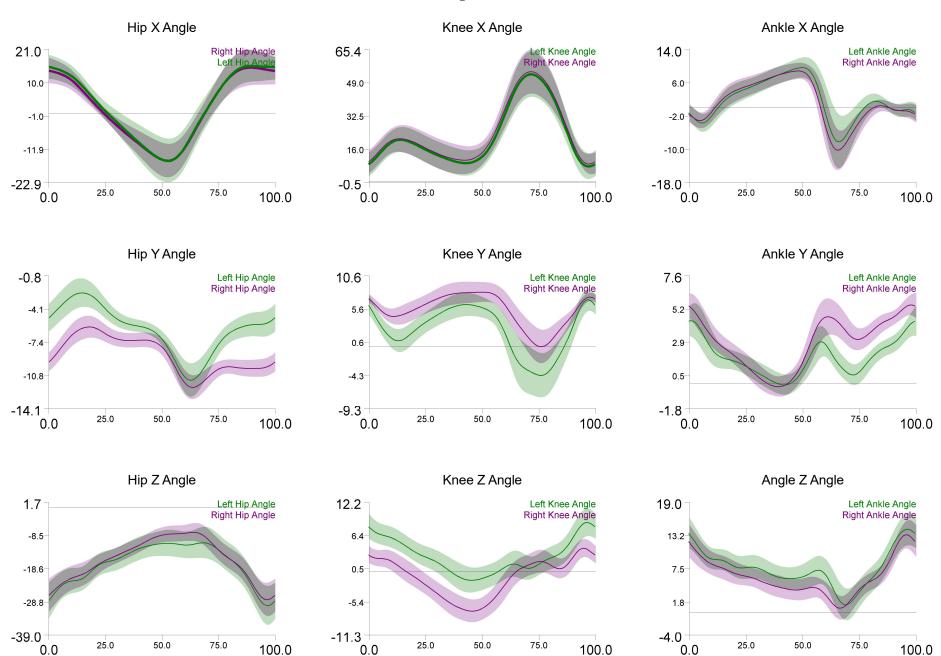




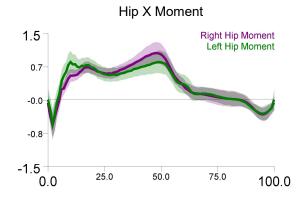


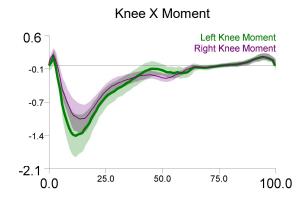
No Data

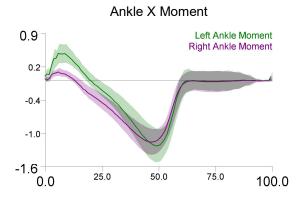
ANGLE

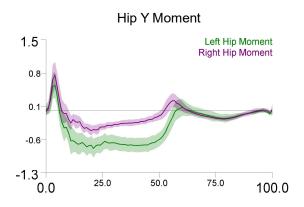


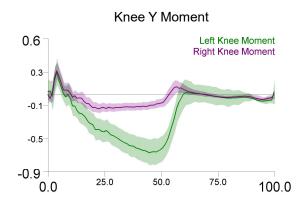
MOMENT

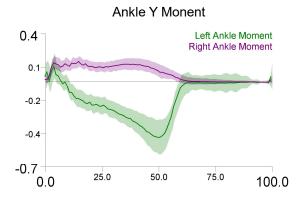


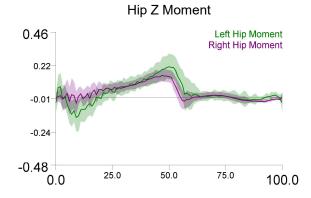


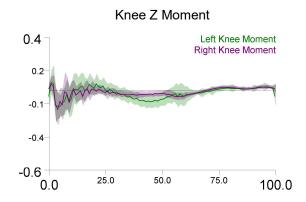


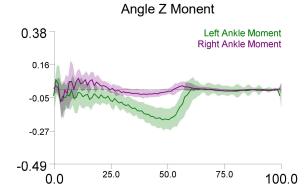




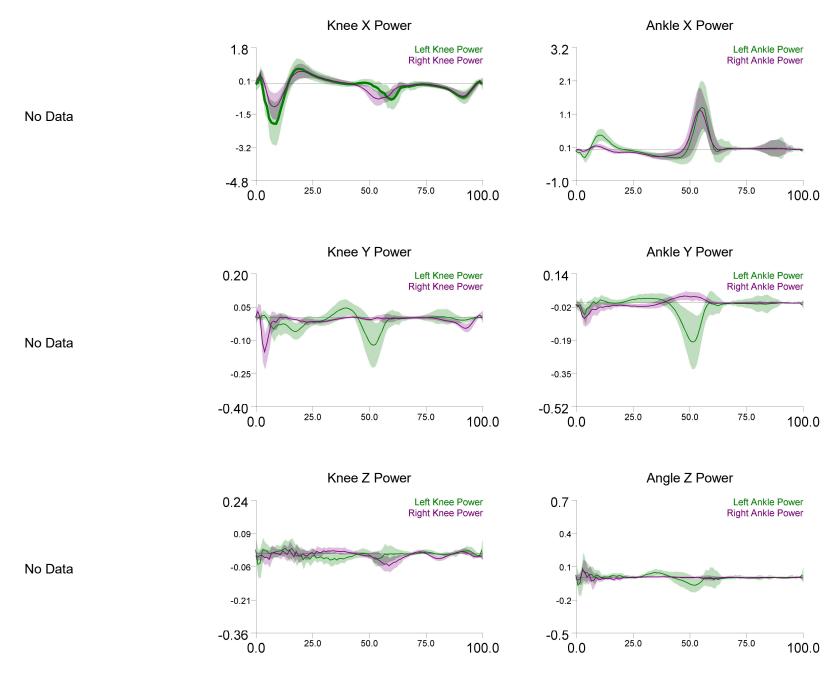








POWER



No Data