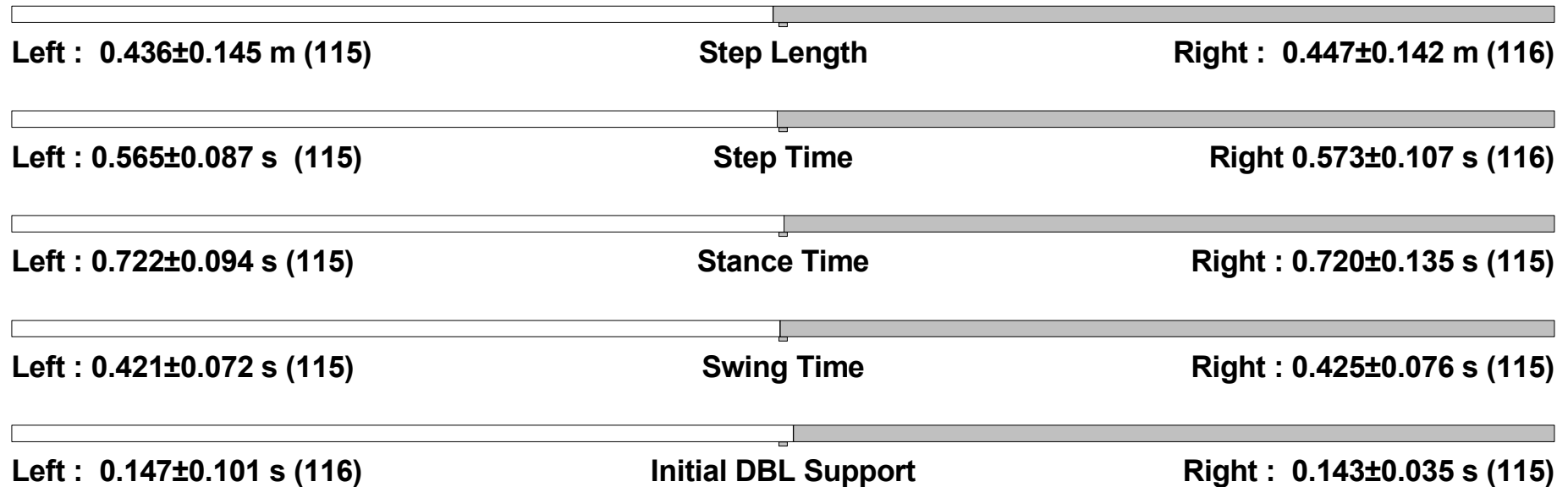


## Gait parameters

<b>Speed</b>	<b>0.790 m/s</b>	<b>0.457 Statures/s</b>
<b>Stride</b>	<b>Wid(230) 0.204±0.012m</b>	<b>Len(230) 0.903±0.149m</b>
<b>Cycle Time</b>	<b>Computed: 1.136 s</b>	<b>Actual (230) 1.144±0.139 s</b>

Measure±StdDev (Count)

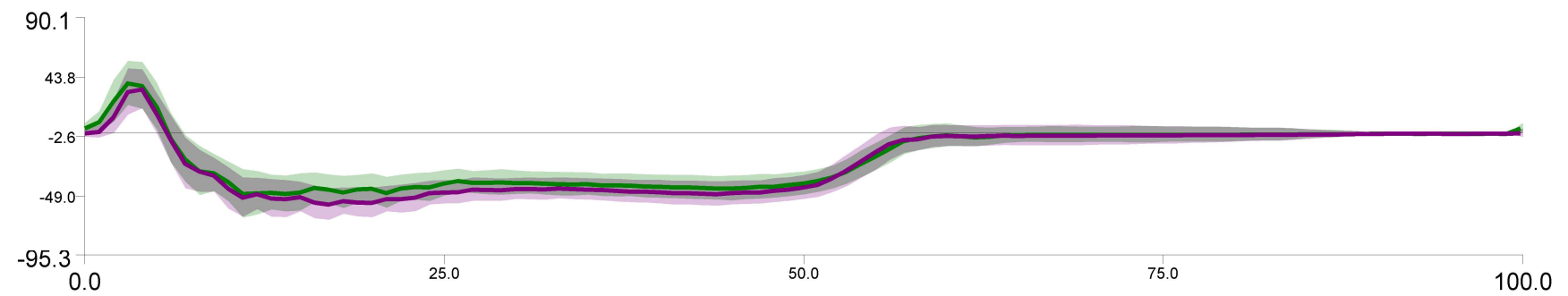
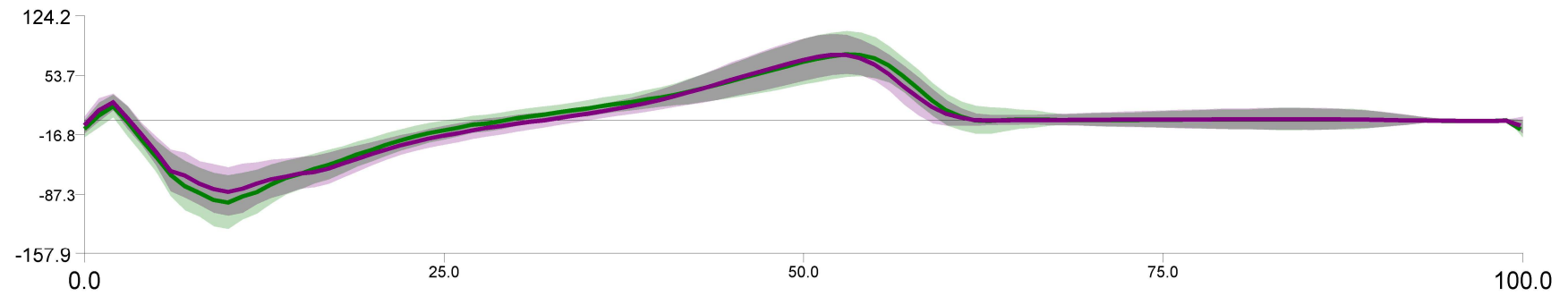
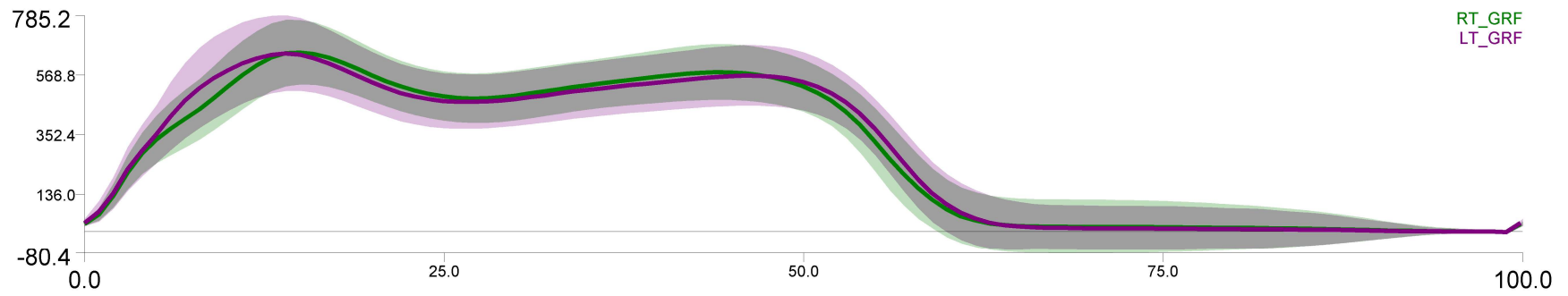
Measure±StdDev (Count)



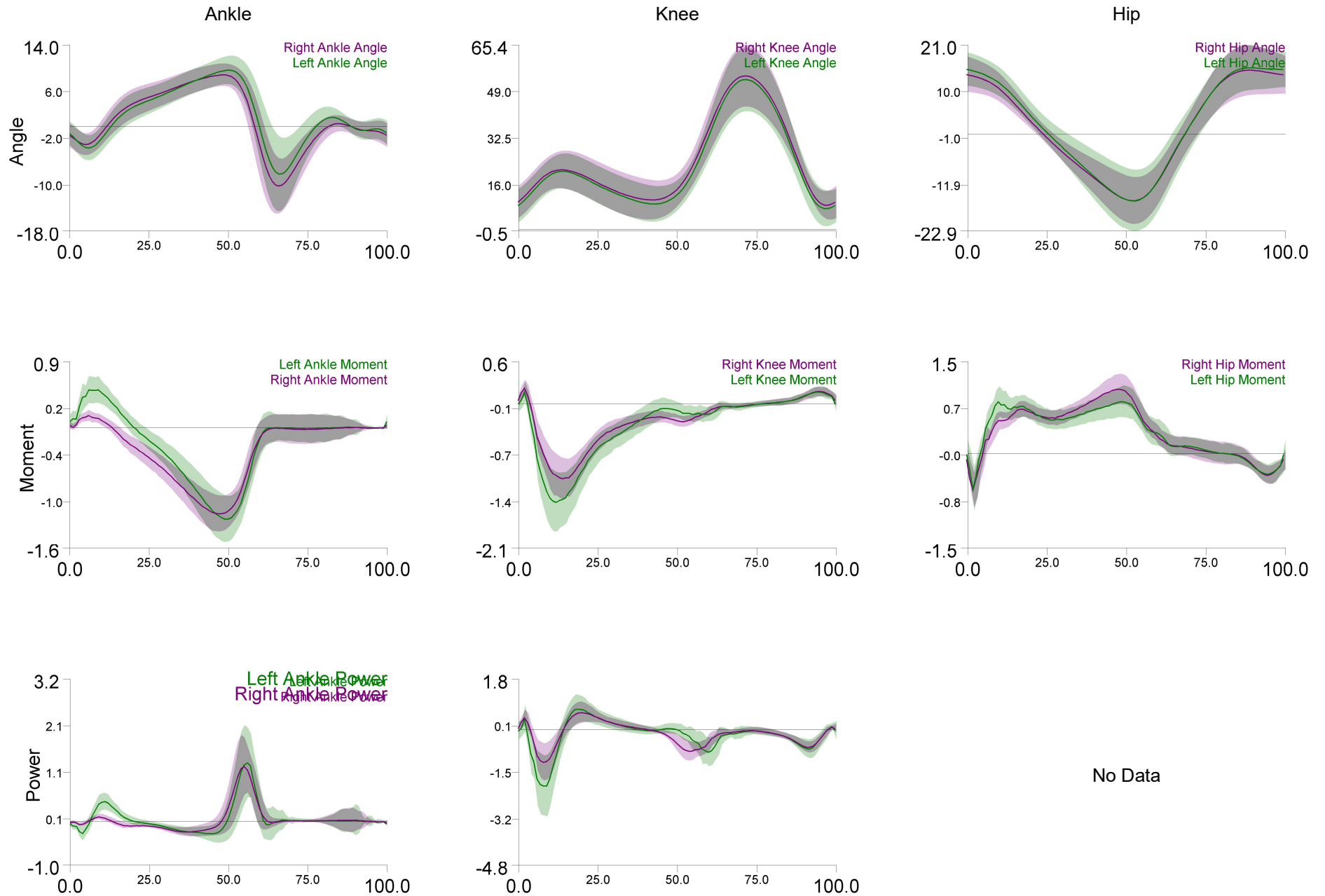
**DbI Limb Support (231)**

**0.290±0.135 s**

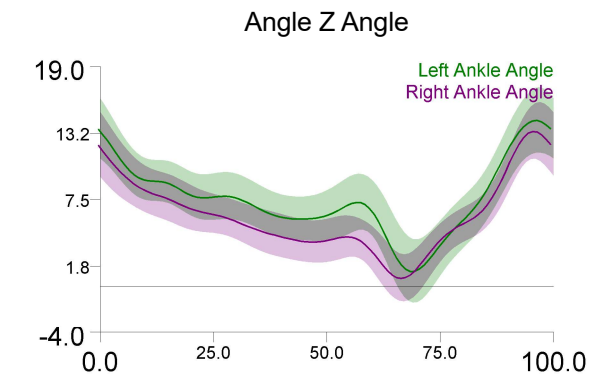
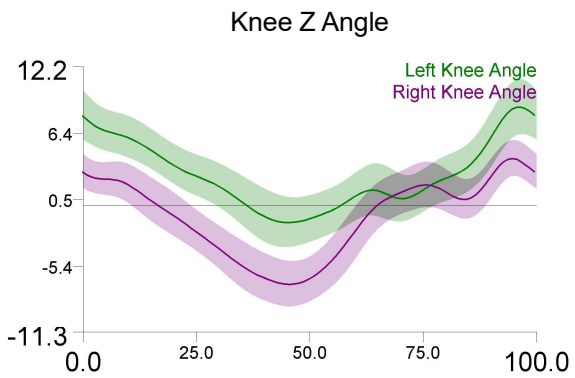
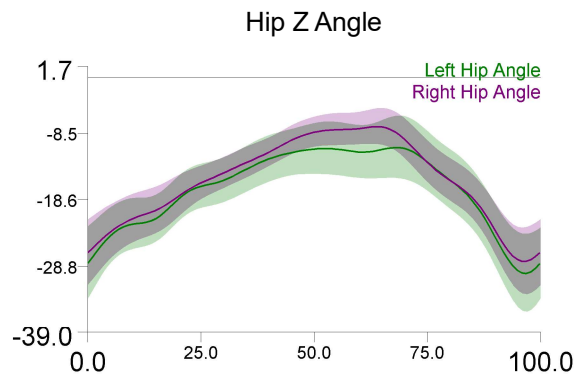
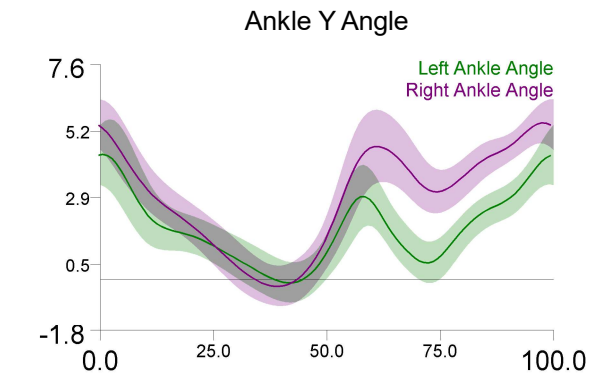
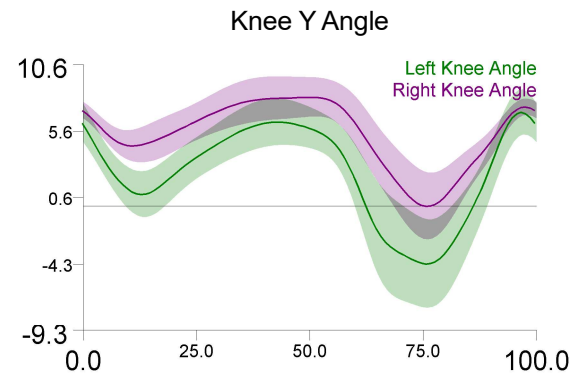
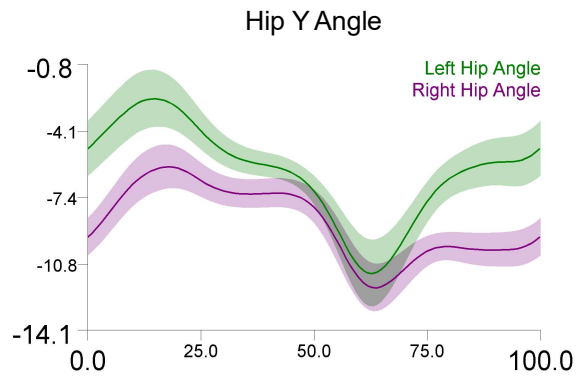
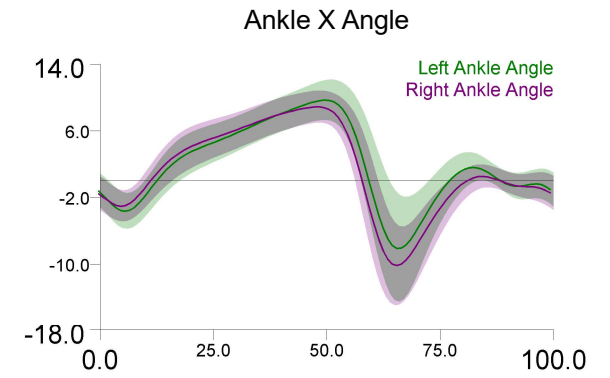
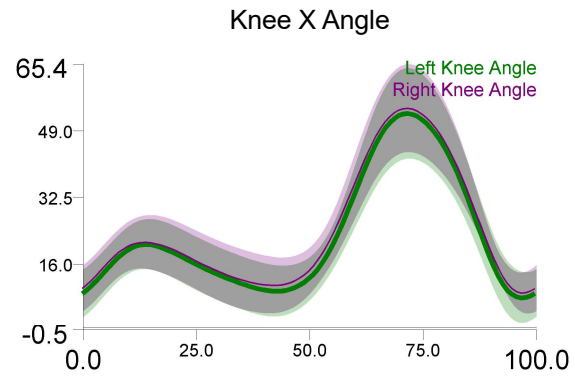
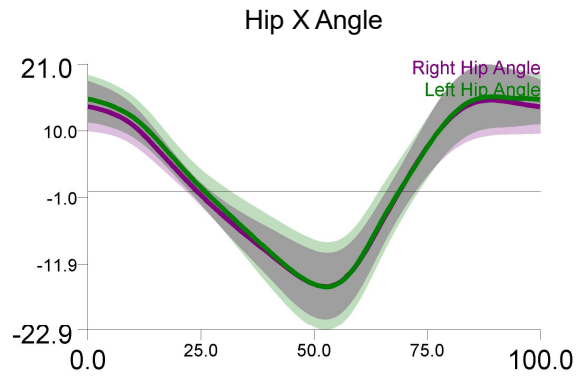
# GRF



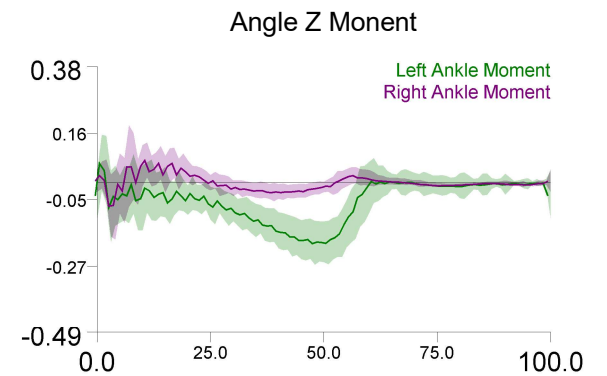
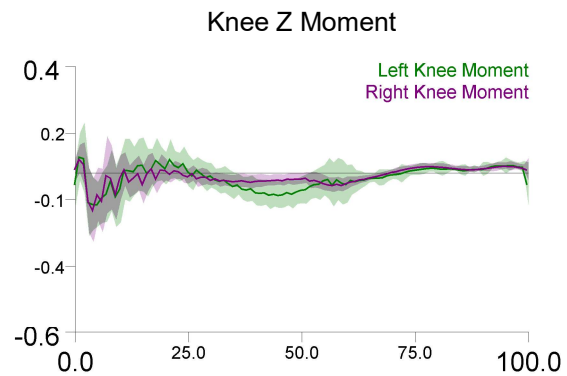
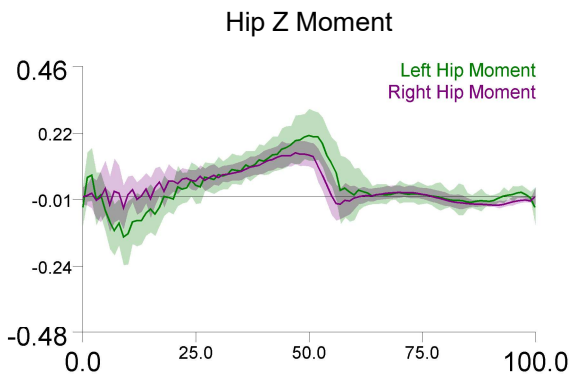
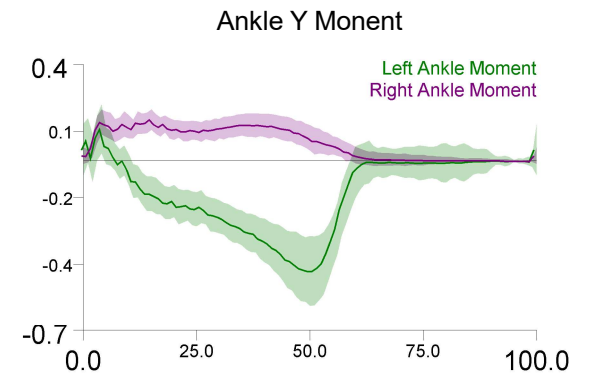
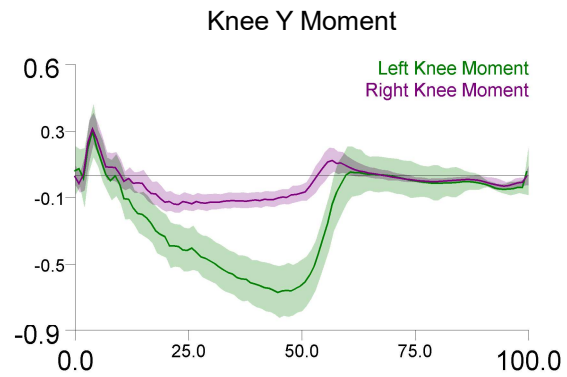
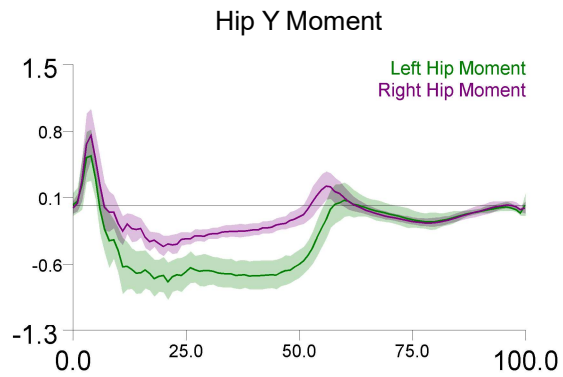
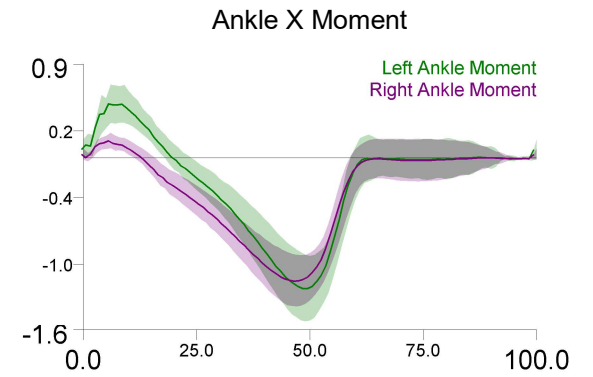
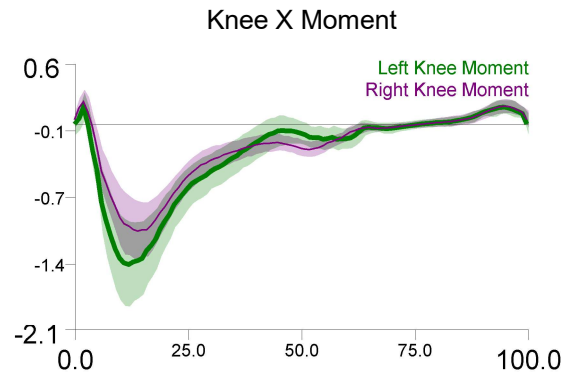
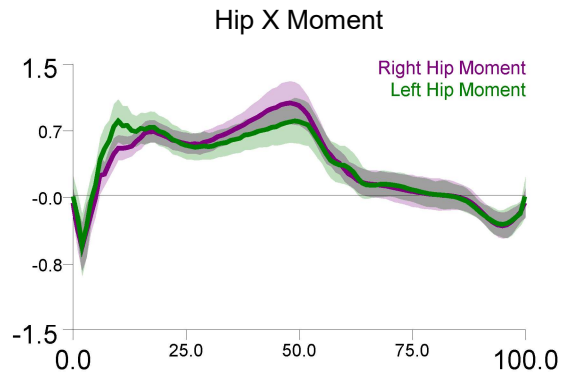
# Lower-limb joint kinematics and kinetics



# ANGLE

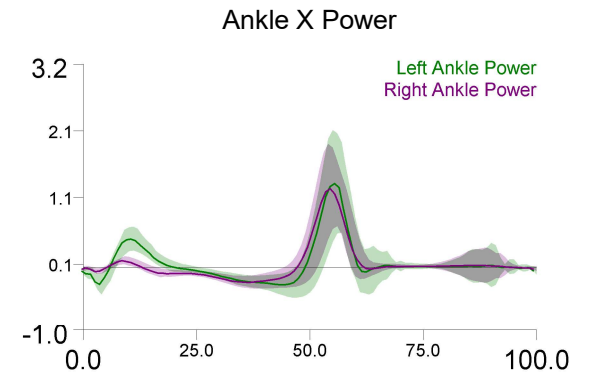
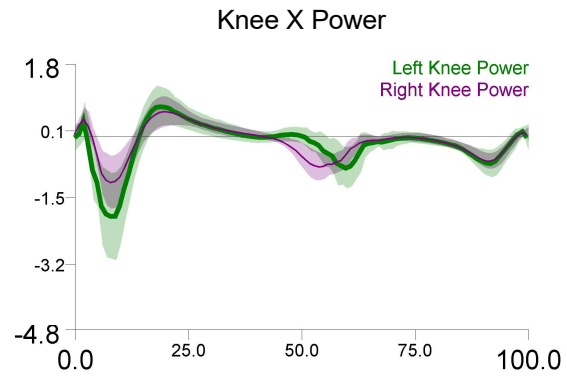


# MOMENT

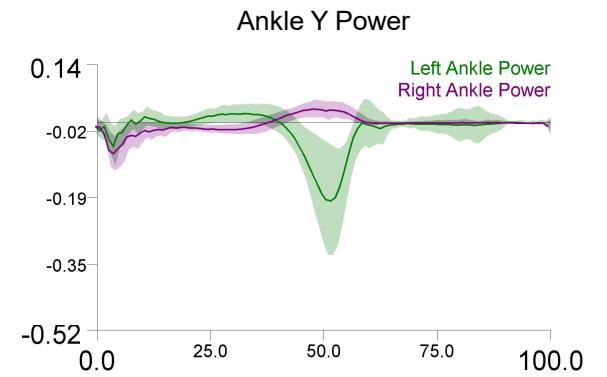
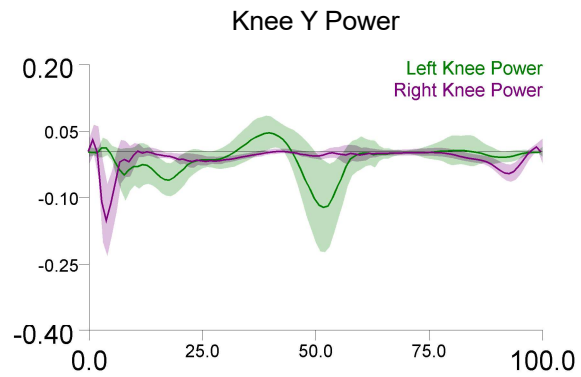


# POWER

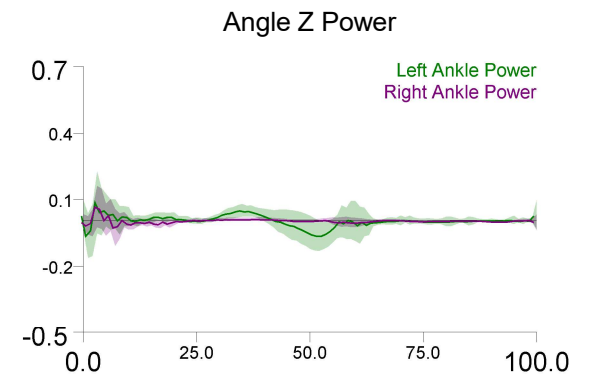
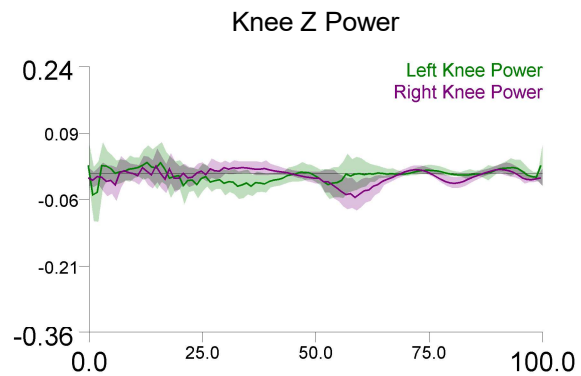
No Data



No Data



No Data



No Data