

相贤泰

1. 证

根据链式法则，有

$$\frac{\partial^2 f}{\partial x^2} = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x'} \frac{\partial x'}{\partial x} + \frac{\partial f}{\partial y'} \frac{\partial y'}{\partial x} \right) = \frac{\partial^2 f}{\partial x'^2} \cos^2(\theta) + 2 \frac{\partial^2 f}{\partial x' \partial y'} \cos(\theta) \sin(\theta) + \frac{\partial^2 f}{\partial y'^2} \sin^2(\theta)$$

同理，有

$$\frac{\partial^2 f}{\partial y^2} = \frac{\partial^2 f}{\partial x'^2} \sin^2(\theta) - 2 \frac{\partial^2 f}{\partial x' \partial y'} \cos(\theta) \sin(\theta) + \frac{\partial^2 f}{\partial y'^2} \cos^2(\theta)$$

则

$$\nabla^2 f(x, y) = (\cos^2(\theta) + \sin^2(\theta)) \frac{\partial^2 f}{\partial x'^2} + (\sin^2(\theta) + \cos^2(\theta)) \frac{\partial^2 f}{\partial y'^2} = \frac{\partial^2 f}{\partial x'^2} + \frac{\partial^2 f}{\partial y'^2}$$

即拉普拉斯算子是各向同性的。

2. 证

由二维傅里叶变换可知

$$F(u, v) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) e^{-j2\pi(ux+vy)} dx dy$$

考虑平移函数

$$g(x, y) = f(x - x_0, y - y_0)$$

其对应的傅里叶变换为

$$\begin{aligned} G(u, v) &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x, y) e^{-j2\pi(ux+vy)} dx dy \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x - x_0, y - y_0) e^{-j(u(x+x_0)+v(y+y_0))} dx dy \\ &= e^{-j2\pi(ux_0+vy_0)} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x', y') e^{-j2\pi(u'x'+v'y')} dx' dy' \\ &= e^{-j2\pi(ux_0+vy_0)} F(u, v) \end{aligned}$$

换元得

$$\begin{aligned} G(u, v) &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x', y') e^{-j2\pi(u(x'+x_0)+v(y'+y_0))} dx' dy' \\ &= e^{-j2\pi(ux_0+vy_0)} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x', y') e^{-j2\pi(u'x'+v'y')} dx' dy' \\ &= e^{-j2\pi(ux_0+vy_0)} F(u, v) \end{aligned}$$

离散化即为书中表达式。

3. 解

1. 乘上 $(-1)^{(x+y)}$:

$$f_1(x, y) = f(x, y) \times (-1)^{x+y}$$

实质是用棋盘格进行图像调制;

2. 对调制图像进行DFT:

$$F_1(u, v) = \text{DFT}[f_1(x, y)]$$

3. 取复共轭:

将 $F_1(u, v)$ 写作 $A(u, v)e^{j\theta(u, v)}$, 则其复共轭为

$$F_1^*(u, v) = A(u, v)e^{-j\theta(u, v)}, \text{ 改变了该图像频率的相位信息}$$

4. 傅里叶反变换:

$$f_2(x, y) = \text{IDFT}[F_1^*(u, v)]$$

这使得相位信息变为原来的2倍, 这也使得空域图像得到了反转的效果

5. 再次乘 $(-1)^{(x+y)}$:

$$f_3(x, y) = f_2(x, y) \times (-1)^{x+y}, \text{ 对图像进行解调。}$$