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7. 解

$$egin{aligned} \mathbb{E}(\xi(t)) &= \mathbb{E}(X)\mathbb{E}(\sin(Yt)) \ &= rac{1}{2} \int_0^1 \sin(yt) \ dy \ &= rac{1-\cos(yt)}{2t} \ R_{\xi}(s,t) &= \mathbb{E}(\xi(t)\xi(s)) \ &= \mathbb{E}(X^2)\mathbb{E}(\sin(Yt)\sin(Ys)) \end{aligned}$$

$$egin{aligned} R_{\xi}(s,t) &= \mathbb{E}(\zeta(t)\zeta(s)) \ &= \mathbb{E}(X^2)\mathbb{E}(\sin(Yt)\sin(Ys)) \ &= rac{1}{6}\mathbb{E}\left(\cos(Y(t-s)) - \cos(Y(t+s))
ight) \ &= rac{1}{6}(rac{\sin(t-s)}{t-s} - rac{\sin(t+s)}{t+s}) \end{aligned}$$

因此, 该过程不是**平稳过程; 连续且可导**

8.解

$$egin{aligned} \mathbb{E}(Y) &= \mathbb{E}(T^{-1} \int_0^T X(s) ds) \ &= T^{-1} \int_0^T \mathbb{E}(X(s)) ds \ &= m \end{aligned} \ Var(Y) &= E\left\{Y^2\right\} - [E\{Y\}]^2 = E\left\{Y^2\right\} - m^2 \ &= E\left\{\left[T^{-1} \int_0^T X(s) ds\right] \cdot \left[T^{-1} \int_0^T X(u) du\right]\right\} - m^2 \ &= T^{-2} \int_0^T \int_0^T E\{X(s) X(u)\} ds du - m^2 \ &= T^{-2} \int_0^T \int_0^T R_X(s-u) ds du - m^2 \ &= T^{-2} \int_0^T \int_0^T \left[C_X(s-u) + m^2\right] ds du - m^2 \ &= T^{-2} \int_0^T \int_0^T a e^{-b|s-u|} ds du \ &= 2a \left[(bT)^{-1} - (bT)^{-2} \left(1 - e^{-bT}\right)\right] \end{aligned}$$

9.解

(1)

$$egin{aligned} \mathbb{E}(X(t)) &= \mathbb{E}(X) + t \mathbb{E}(Y) \ &= 0 \end{aligned} \ \mathbb{E}(Y(t)) &= \int_0^t \mathbb{E}(X(u)) du \ &= 0 \end{aligned} \ Cov(X(s), X(t)) &= \mathbb{E}(X(s)X(t)) \ &= \mathbb{E}(X^2) + (s+t)\mathbb{E}(XY) + st\mathbb{E}(Y^2) \ &= \sigma_1^2 +
ho(s+t)\sigma_1\sigma_2 + st\sigma_2^2 \end{aligned}$$

$$egin{align} \mathbb{E}(Z(t)) &= \int_0^t \mathbb{E}(X^2(u)) du \ &= \int_0^t (\sigma_1^2 + 2
ho\sigma_1\sigma_2 u + \sigma_2^2 u^2) du \ &= \sigma_1^2 t +
ho\sigma_1\sigma_2 t^2 + rac{1}{3}\sigma_2^2 t^3 \end{split}$$

$$egin{split} Cov(Y(s),Y(t)) &= \mathbb{E}(Y(s)Y(t)) \ &= \mathbb{E}(\int_0^s X(u)du \int_0^t X(v)dv) \ &= \int_0^s du \int_0^t \mathbb{E}(X(u)X(v))dv \ &= \sigma_1^2 st + rac{1}{2}
ho\sigma_1\sigma_2 st(s+t) + rac{1}{4}\sigma_2^2 s^2 t^2 \end{split}$$

(2)

由

$$R_{X(t)}(s,t) = \sigma_1^2 +
ho(s+t)\sigma_1\sigma_2 + st\sigma_2^2$$

可知,X(t)均方连续且均方可导

(3)

$$\mathbb{E}(Y'(t)) = \frac{d}{dt}\mathbb{E}(Y(t)) = 0$$

$$R_{Y'}(s,t) = \frac{\partial R_Y(s,t)}{\partial s \partial t} = \sigma_1^2 + \rho \sigma_1 \sigma_2(s+t) + \sigma_2^2 st$$

$$\mathbb{E}(Z'(t)) = \frac{d}{dt}\mathbb{E}(Z(t)) = \sigma_1^2 + 2\rho \sigma_1 \sigma_2 t + \sigma_2^2 t^2$$

10.解

(1)

$$egin{aligned} R_Y(s,t) &= \mathbb{E}(Y(t+ au)Y(t)) \ &= \mathbb{E}(|X(t+ au)X(t)|) \ &= rac{2R_X(0)[arphi\sinarphi+\cosarphi]}{ au} \end{aligned}$$

其中 $\sin \varphi = rac{R_x(au)}{R_X(0)}$

因此, Y(t)是平稳过程

(2)

$$\mathbb{E}(Y(t))=\int_R|x|f_X(x)dx=2\int_0^{-\infty}xf_X(x)=\sqrt{rac{2R_x(0)}{\pi}} \ D(Y(t))=\mathbb{E}(Y^2(t))-\mathbb{E}^2(Y(t))=(1-rac{2}{\pi})R_X(0)$$

(3)

$$egin{aligned} F_Y(y) &= P(|X(t)| \leq y) \ &= \int_{-y}^y f_X(x) dx \end{aligned}$$

因此

$$f_{Y}(y) = f_{X}(y) + f_{X}(-y) = rac{2}{\sqrt{2\pi R_{X}(0)}} \mathrm{exp} \left\{ -rac{y^{2}}{2R_{X}(0)}
ight\}, \quad y > 0$$