#### Lec 8: Regularized Learning

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## **Agenda**

- Newton-Raphson Method
- Summary: Classical Learning
- Regularized Learning Roadmap
- Overfitting
- Ridge Regression
- Lasso Regression

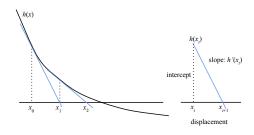
#### **Newton-Raphson**

Suppose we want to solve h(x) = 0. At  $x_t$ , we take the first order Taylor expansion

$$h(x) \doteq h(x_t) + h'(x_t)(x - x_t).$$

Each iteration, we find the root of the linear surrogate function

$$x_{t+1} = x_t - \frac{h(x_t)}{h'(x_t)}.$$



## **Newton-Raphson**

Suppose we want to find the mode of f(x), we can solve f'(x) = 0.

Using Newton-Raphson, we have

$$x_{t+1} = x_t - \frac{f'(x_t)}{f''(x_t)}.$$

Each iteration maximizes a quadratic approximation to the original function at  $x_t$ ,

$$f(x) \doteq f(x_t) + f'(x_t)(x - x_t) + \frac{1}{2}f''(x_t)(x - x_t)^2.$$

 $f''(x_t)$  is the curvature of f at  $x_t$ .

- If the curvature is big, the step size should be small.
- If the curvature is small, the step size can be made larger.

### **Newton Raphson**

If the variable is a vector  $x = (x_1, x_2, \dots, x_n)^{\top}$ , let

$$f'(x) = \left(\frac{\partial f}{\partial x_i}\right)_{n \times 1} \quad f''(x) = \left(\frac{\partial f}{\partial x_i \partial x_j}\right)_{n \times n},$$

 $f''(x_t)$  is called the Hessian matrix, we have

$$x_{t+1} = x_t - f''(x_t)^{-1} f'(x_t).$$

 $f''(x_t)$  tells us the local shape of f around  $x_t$ .

 $f''(x_t)^{-1}f'(x_t)$  gives us better direction than  $f'(x_t)$ . The Newton-Raphson is a second order algorithm.

## Newton-Raphson vs Gradient Descent

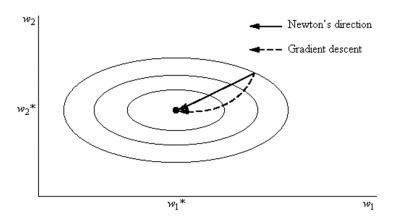


Figure 2: Newton-Raphson gives better direction

### Newton-Raphson is IRLS for logistic regression

For maximum likelihood estimate of  $\beta$  in logistic regression, the second derivative of the log likelihood function

$$I''(\beta) = -\sum_{i=1}^{n} p_i (1 - p_i) X_i X_i^{\top}.$$

We can update  $\beta$  by

$$\beta^{(t+1)} = \beta^{(t)} + I''(\beta^{(t)})^{-1}I'(\beta^{(t)}).$$

$$\beta^{(t+1)} = \left(\sum_{i=1}^n w_i X_i X_i^{\top}\right)^{-1} \left(\sum_{i=1}^n w_i X_i \hat{y}_i\right)$$

Let  $w_i = p_i(1 - p_i)$ 

## Newton-Raphson is IRLS for logistic regression

we can rewrite the update equation as

$$\beta^{(t+1)} = \beta^{(t)} + \left[ \sum_{i=1}^{n} p_i (1 - p_i) X_i X_i^{\top} \right]^{-1} (y_i - p_i) X_i$$

$$= \left( \sum_{i=1}^{n} w_i X_i X_i^{\top} \right)^{-1} \left[ \sum_{i=1}^{n} w_i X_i X_i^{\top} \beta^{(t)} + (y_i - p_i) X_i \right]$$

$$= \left( \sum_{i=1}^{n} w_i X_i X_i^{\top} \right)^{-1} \left[ \sum_{i=1}^{n} w_i X_i \left( X_i^{\top} \beta^{(t)} + \frac{y_i - p_i}{w_i} \right) \right].$$

Let  $\bar{y}_i = X_i^{\top} \beta^{(t)} + \frac{y_i - p_i}{w_i}, \tilde{X}_i = X_i \sqrt{w_i}, \tilde{y}_i = \bar{y}_i \sqrt{w_i}$ , we can rewrite the equation above as follows:

$$\beta^{(t+1)} = \left(\sum_{i=1}^{n} w_i X_i X_i^{\top}\right)^{-1} \left(\sum_{i=1}^{n} w_i X_i \bar{y}_i\right)$$

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#### **IRLS** Revisited

$$\beta^{(t+1)} = \left(\sum_{i=1}^{n} w_i X_i X_i^{\top}\right)^{-1} \left(\sum_{i=1}^{n} w_i X_i \bar{y}_i\right)$$
$$= \left(\sum_{i=1}^{n} \tilde{X}_i \tilde{X}_i^{\top}\right)^{-1} \left(\sum_{i=1}^{n} \tilde{X}_i \tilde{y}_i\right).$$

Consider the flow:

$$\beta^{(t)} \to \eta_i = X_i^{\top} \beta^{(t)} \to p_i = \sigma(\eta_i) \to w_i = p_i (1 - p_i) \to \bar{y}_i = \eta_i + \frac{y_i - p_i}{w_i}$$
$$\to \tilde{X}_i = X_i \sqrt{w_i}, \tilde{y}_i = \bar{y}_i \sqrt{w_i} \to \beta^{(t+1)}.$$

# **Classical learning**

- Linear Regression
- Gauss-Jordan Elimination
- Sweep Operator
- QR Decomposition
- Orthogonal Matrix
- Householder Reflections
- Linear Regression by QR
- Eigen Decomposition and Diagonalization
- Power Method
- Gram-Schimdt
- Principle Component Analysis and Singular Value Decomposition
- Logistic Regression
- Gradient Ascent
- Iterated Reweighted Least Squares (IRLS)
- Newton-Raphson

# Roadmap for Regularized Learning

- Ridge regression
- Lasso regression
- Coordinate descent
- Spline regression
- Least angle regression
- Stagewise regression for epsilon learning
- Bayesian regression
- Perceptron
- SVM
- Adaboost

Note: We will have midterm after regularized learning! (Est. Nov.7 - 11)

### **Overfitting**

For the simplest regression model

obs	$X_{n\times 1}$	$\mathbf{Y}_{n \times 1}$
1 2	<i>X</i> <sub>1</sub>	<i>y</i> <sub>1</sub>
2	$X_2$	<i>y</i> 2
n	X <sub>n</sub>	Уn

## **Overfitting**

For the simplest regression model

obs	$X_{n\times 1}$	$\mathbf{Y}_{n\times 1}$
1	<i>X</i> <sub>1</sub>	<i>y</i> 1
2	$X_2$	<i>y</i> <sub>2</sub>
n	$X_n$	Уn

Model:  $y_i = X_i \beta + \epsilon_i$ , where  $\epsilon_i \sim N(0, \sigma^2)$ 

$$\hat{\beta_{LS}} = \frac{\sum_{i=1}^{n} X_i y_i}{\sum_{i=1}^{n} X_i^2} ; \text{ if } y_i = \epsilon_i, \ \hat{\beta_{LS}} = \frac{\sum_{i=1}^{n} X_i \epsilon_i}{\sum_{i=1}^{n} X_i^2}$$

Overfitting: model absorbs noise.

There is always a certain amount of overfitting in  $\hat{\beta}$  , even if true  $\beta=0$ 

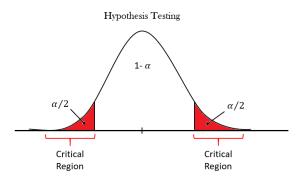
# Ways to avoid overfitting

- Hypothesis test
- Regularization (ML treatment)

# Hypothesis test for linear regression

 $H_0: \beta = 0$  Null hypothesis: simper model

 $H_{\alpha}: \beta \neq 0$  Alternative hypothesis: more complex



Type I Error:  $\alpha$ , usually taken as 5%

p value: how extreme  $\hat{eta_{LS}}$  is relative to  $H_0$ 

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# Hypothesis test for logistic regression

$$H_0: \beta = 0 \to \eta_i = X_i \beta$$
 
$$p_i = \frac{e^{\eta_i}}{1 + e^{\eta_i}} = \frac{1}{2} \to y_i \sim \textit{Bernoulli}(\frac{1}{2}) \; \text{It's a coin flip event.}$$

Noise in the logistic regression (classification) is an over interpretation of a coin flipping as opposed to Gaussian noise observed in linear regression.

# Regularization, ML treatment

Ridge regression

The ridge regression estimates  $\beta$  by

$$\hat{\boldsymbol{\beta}}_{\lambda} = \arg\min_{\boldsymbol{\beta}} \left[ \|\mathbf{Y} - \mathbf{X}\boldsymbol{\beta}\|_{\ell_2}^2 + \lambda \|\boldsymbol{\beta}\|_{\ell_2}^2 \right] = (\mathbf{X}^{\top}\mathbf{X} + \lambda \mathbf{I}_{\rho})^{-1}\mathbf{X}^{\top}\mathbf{Y}$$

for a tuning parameter  $\lambda>0$ . The  $\lambda\|\beta\|_{\ell_2}^2$  term is a penalty or regularization term.

The resulting estimator is called the shrinkage estimator.

The computation can be accomplished by the sweep operator.

#### R code

```
myRidge <- function(X, Y, lambda)</pre>
  n = dim(X)[1]
  p = dim(X)[2]
  Z = cbind(rep(1, n), X, Y)
  A = t(Z) \% * \% Z
  D = diag(rep(lambda, p+2))
  D[1, 1] = 0
  D[p+2, p+2] = 0
  A = A + D
  S = mySweep(A, p+1)
  beta = S[1:(p+1), p+2]
  return(beta)
```

### **Lasso Regression**

The Lasso regression estimate  $\beta$  by

$$\hat{\beta}_{\lambda} = \arg\min_{\beta} \left[ \frac{1}{2} \|\mathbf{Y} - \mathbf{X}\beta\|_{\ell_2}^2 + \lambda \|\beta\|_{\ell_1} \right],$$

where  $\|\beta\|_{\ell_1} = \sum_{j=1}^{p} |\beta_j|$ .

Lasso stands for least absolute shrinkage and selection operator.

We have closed form solution for p = 1, where **X** is an  $n \times 1$  vector,

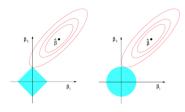
$$\hat{\beta}_{\lambda} = \begin{cases} (\langle \mathbf{Y}, \mathbf{X} \rangle - \lambda) / \|\mathbf{X}\|_{\ell_{2}}^{2}, & \text{if } \langle \mathbf{Y}, \mathbf{X} \rangle > \lambda; \\ (\langle \mathbf{Y}, \mathbf{X} \rangle + \lambda) / \|\mathbf{X}\|_{\ell_{2}}^{2}, & \text{if } \langle \mathbf{Y}, \mathbf{X} \rangle < -\lambda; \\ 0 & \text{if } |\langle \mathbf{Y}, \mathbf{X} \rangle| < \lambda. \end{cases}$$

We can write it as

$$\hat{eta}_{\lambda} = \mathrm{sign}(\hat{eta}) \max(0, |\hat{eta}| - \lambda / \|\mathbf{X}\|_{\ell_2}^2),$$

Npte: There is no closed form solution for general p.

## Ridge vs Lasso



The primal form of Lasso:  $\min \|\mathbf{Y} - \mathbf{X}\beta\|_{\ell_2}^2/2$  subject to  $\|\beta\|_{\ell_1} \leq t$ .

The dual form of Lasso :  $\min \|\mathbf{Y} - \mathbf{X}\beta\|_{\ell_2}^2/2 + \lambda \|\beta\|_{\ell_1}$ .

The primal form also reveals the sparsity inducing property of  $\ell_1$  regularization in that the  $\ell_1$  ball has low-dimensional corners, edges, and faces, but is still barely convex.

## Coordinate descent for Lasso solution path

Update one component at a time:

For multi-dimensional  $\mathbf{X} = (\mathbf{X}_j, j = 1, ..., p)$ , given the current values of  $\beta = (\beta_j, j = 1, ..., p)$ , let  $\mathbf{R}_j = \mathbf{Y} - \sum_{k \neq j} \mathbf{X}_k \beta_k$ , we can update  $\beta_j = \mathrm{sign}(\hat{\beta}_j) \max(0, |\hat{\beta}_j| - \lambda/\|\mathbf{X}\|_{\ell_2}^2)$ , where  $\hat{\beta}_j = \langle \mathbf{R}_j, \mathbf{X}_j \rangle / \|\mathbf{X}_j\|_{\ell_2}^2$ .

Solution path of Lasso:

Start from a big  $\lambda$  so that all of the estimated  $\beta_j$  are zeros. Then we gradually reduce  $\lambda$ . For each  $\lambda$ , we cycle through j=1,...,p for coordinate descent until convergence, and then we lower  $\lambda$ . This gives us  $\hat{\beta}(\lambda)$  for the whole range of  $\lambda$ .

The whole process is a forward selection process, which sequentially selects new variables and occasionally removes selected variables.

#### R Code

```
n = 50
p = 200
s = 10
T = 10
lambda all = (100:1)*10
L = length(lambda_all)
X = matrix(rnorm(n*p), nrow=n)
beta_true = matrix(rep(0, p), nrow = p)
beta_true[1:s] = 1:s
Y = X %*% beta true + rnorm(n)
beta = matrix(rep(0, p), nrow = p)
beta all = matrix(rep(0, p*L), nrow = p)
R = Y
ss = rep(0, p)
for (j in 1:p)
    ss[j] = sum(X[, j]^2)
err = rep(0, L)
for (1 in 1:L)
    lambda = lambda all[1]
    for (t in 1:T)
      for (j in 1:p)
        db = sum(R*X[, j])/ss[j]
        b = beta[i]+db
        b = sign(b)*max(0, abs(b)-lambda/ss[j])
```