

# Lec 3: Linear Regression

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# Agenda

- Multiple Regression and Least Square
- Maximum Likelihood Estimation
- Gauss Jordan Elimination
- The Sweep Operator

# Linear Regression

The dataset of linear regression consists of an  $n \times p$  matrix  $\mathbf{X} = (x_{ij})$ , and a  $n \times 1$  vector  $\mathbf{Y} = (y_i)$ .

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- $[\mathbf{X}, \mathbf{Y}]$  is called the training data
- $y_i$  is called response variable, outcome, dependent variable.
- $x_{ij}$  is called predictor, regressor, covariate, independent variable, or simple variable.
- In the experimental design setting,  $\mathbf{X}$  is called the design matrix.

# Linear Regression

obs	$\mathbf{X}_{n \times p}$	$\mathbf{Y}_{n \times 1}$
1	$x_{11}, x_{12}, \dots, x_{1p}$	$y_1$
2	$x_{21}, x_{22}, \dots, x_{2p}$	$y_2$
...		
$n$	$x_{n1}, x_{n2}, \dots, x_{np}$	$y_n$

- 1 Explanation: understanding the relationship between  $y_i$  and  $(x_{ij}, j = 1, \dots, p)$ .
- 2 Prediction: learn to predict  $y_i$  based on  $(x_{ij}, j = 1, \dots, p)$ , so that in the testing stage, if we are given the predictor variables, we should be able to predict the outcome.

# Row Vector treatment

obs	$\mathbf{X}_{n \times p}$	$\mathbf{Y}_{n \times 1}$
1	$X_1^\top$	$y_1$
2	$X_2^\top$	$y_2$
...		
$n$	$X_n^\top$	$y_n$

$$X_i^\top = (x_{ij}, j = 1, \dots, p)$$

where  $X_i^\top$  is the  $i$ -th row of  $\mathbf{X}$ .

Here  $X_i$  is not in bold font.

We can write the model as  $y_i = \langle X_i, \beta \rangle + \epsilon_i = X_i^\top \beta + \epsilon_i$ , where  $\beta = (\beta_j, j = 1, \dots, p)^\top$ .



# Least Square Method

Least square loss function:  $Loss(\beta) = \frac{1}{2} \sum_{i=1}^n \epsilon_i^2$

$\epsilon_i = y_i - s_i$ , where  $s_i = \sum_{j=1}^p x_{ij} \beta_j$

$$\frac{\partial Loss(\beta)}{\partial \beta_k} = \sum_{i=1}^n \epsilon_i \frac{\partial \epsilon_i}{\partial s_i} \frac{\partial s_i}{\partial \beta_k} = - \sum_{i=1}^n \epsilon_i x_{ik}$$

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$$\frac{\partial Loss(\beta)}{\partial \beta_k} = - \sum_{i=1}^n X_i (y_i - X_i^\top \beta) = 0$$

Question: what is the dimensionality of  $X_i y_i$  and  $X_i X_i^\top$ ?

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# Maximum Likelihood

More general than least square  $\epsilon_i \sim N(0, \sigma^2)$

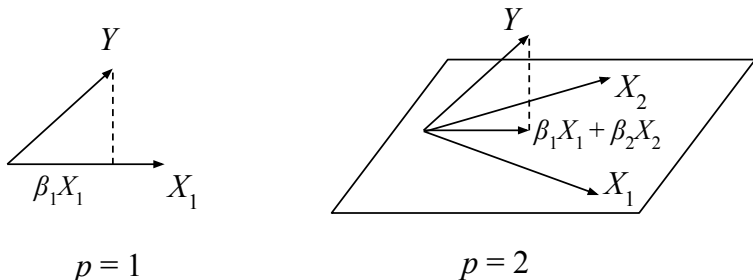
$$likelihood(\beta) = \prod_{i=1}^n p(y_i | s_i)$$

Since  $y_i = s_i + \epsilon_i$ ,  $[y_i | s_i] \sim N(s_i, \sigma^2)$

# Column Vector Treatment

obs	$\mathbf{X}_{n \times p}$	$\mathbf{Y}_{n \times 1}$
1	$\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_p$	$\mathbf{y}$
2		
...		
$n$		

# Geometric Explanation



**Figure 1:** Least squares projection

Summary: Solve  $\beta$  from  $(\mathbf{X}^\top \mathbf{X})\beta = \mathbf{X}^\top \mathbf{Y}$

$$\beta = (\mathbf{X}^\top \mathbf{X})^{-1}(\mathbf{X}^\top \mathbf{Y})$$

# Gauss Jordan Elimination - Example

$$\begin{cases} x_1 + x_2 + x_3 = 5 \\ 2x_1 + 3x_2 + 5x_3 = 9 \\ 4x_1 + 5x_3 = 2 \end{cases}$$

# Gauss Jordan Elimination

$$\text{GJ}[1 : n][A|b] = [I|A^{-1}b] = A^{-1}[A|b],$$

$$\text{GJ}[1 : n][A|I] = [I|A^{-1}] = A^{-1}[A|I].$$



# Gauss Jordan Elimination

For a system of linear equations  $Ax = b$

$A = (a_{ij})$  is  $n \times n$ ,  $x = (x_i)$  is  $n \times 1$ , and  $b = (b_i)$  is  $n \times 1$

we can solve  $x = A^{-1}b$  by Gauss-Jordan elimination.

Specifically, for any matrix  $A$  (any  $n \times N$  matrix)

let  $\tilde{A} = \text{GJ}[k]A$ , then

$$\begin{aligned}\tilde{A}_k &= A_k / a_{kk}, \\ \tilde{A}_i &= A_i - a_{ik} \tilde{A}_k, \quad i \neq k,\end{aligned}$$

$A_k$  is the  $k$ -th row of  $A$ .  $\tilde{a}_{kk} = 1$ , and  $\tilde{a}_{ik} = 0$  for  $i \neq k$ .

- Apply Gauss-Jordan sequentially:  $\text{GJ}[1 : m]$  means we apply Gauss-Jordan for  $k = 1 : m$ .
- Gauss-Jordan is linear:  $\tilde{A} = \text{GJ}[k]A \rightarrow \tilde{A} = G_k A$  for a matrix  $G_k$ .

# R code for Gauss Jordan

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```
myGaussJordan <- function(A, m)
{
  n <- dim(A)[1]
  B <- cbind(A, diag(rep(1, n)))
  for (k in 1:m)
  {
    a <- B[k, k]
    for (j in 1:(n*2))
      B[k, j] <- B[k, j]/a
    for (i in 1:n)
      if (i != k)
      {
        a <- B[i, k]
        for (j in 1:(n*2))
          B[i, j] <- B[i, j] - B[k, j]*a;
      }
  }
  return(B)
}

A = matrix(c(1,2,3,7,11,13,17,21,23), 3,3)
myGaussJordan(A,3)
```

```
##      [,1] [,2] [,3] [,4] [,5] [,6]
## [1,]    1    0    0  1.00 -3.0  2.00
## [2,]    0    1    0 -0.85  1.4 -0.65
## [3,]    0    0    1  0.35 -0.4  0.15
```

# Computing Efficiency

What is the time complexity?

Can we get rid of any loop?

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