CS131 Foreground-Background Segmentation via Clustering

Alan Luo November 10, 2015

Justin Johnson PA2 Session 1 12-Nov-15

Overview

- Use clustering algorithms to segment images
- Evaluate by segmenting cats out of images
- Not a lot of code! (< 100 lines)
- Focus on experimentation

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Prerequisite: Implement clustering algorithms

Input: an image

- 1. Compute a feature vector for each pixel
- 2. Cluster the feature vectors
- 3. Assign pixels to segments based on the clusters
- 4. Choose some subset of segments as "foreground"
- 5. Transfer foreground to another image
- 6. Compare foreground with ground truth

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Clustering Algorithms

You need to implement 2 clustering methods:

- K-Means Clustering
 - KMeansClustering.m
 - Covered in Lecture 13
- Hierarchical Agglomerative clustering
 - HAClustering.m
 - Covered in Lecture 12

Section 2 of assignment

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Clustering Algorithms: Interface

```
function idx = KMeansClustering(X, k, visualize2D)
function idx = HAClustering(X, k, visualize2D)
```

X: Matrix where each row is a point

k: Number of clusters

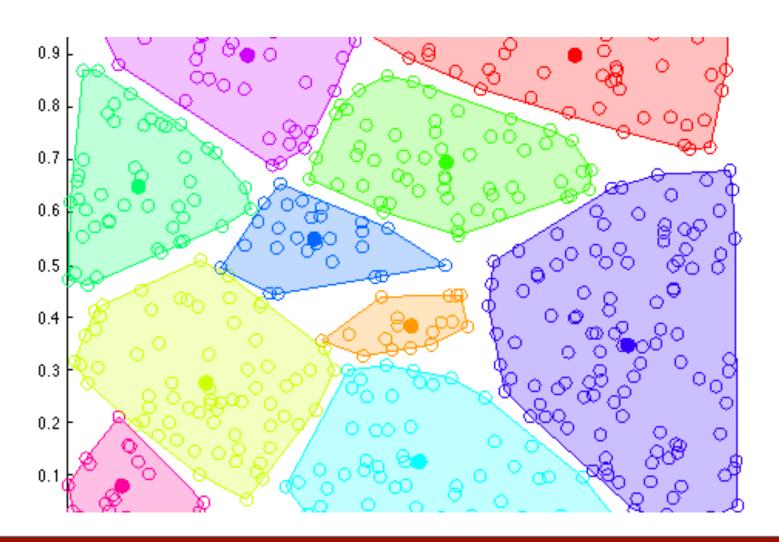
visualize2D: If clustering 2D points, set this to true to see

a visualization

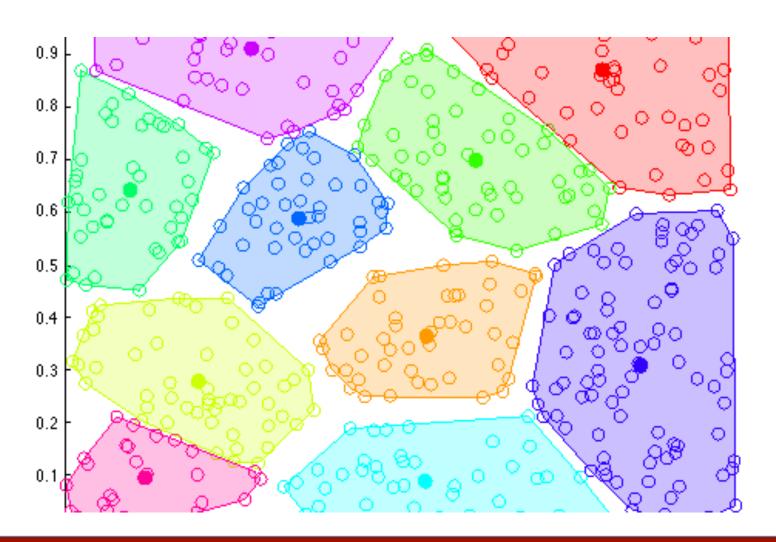
idx: Vector giving computed assignments of points to clusters

Note: KMeansClustering has an additional parameter centers that you don't need to worry about

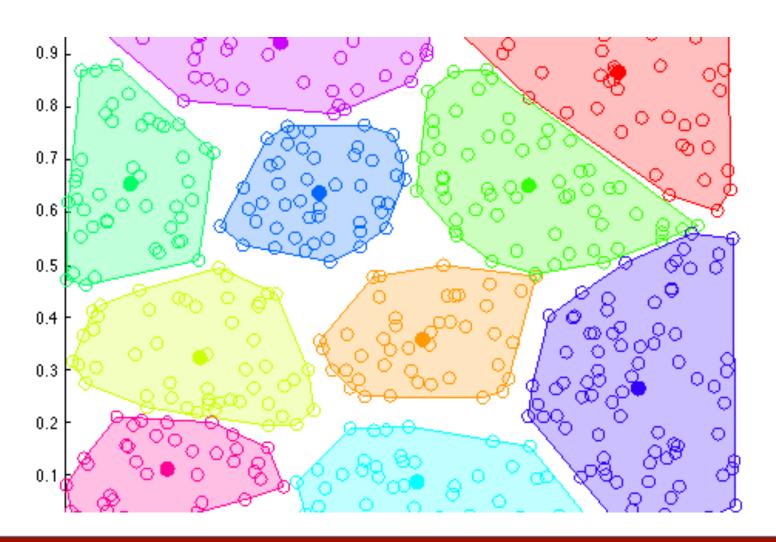
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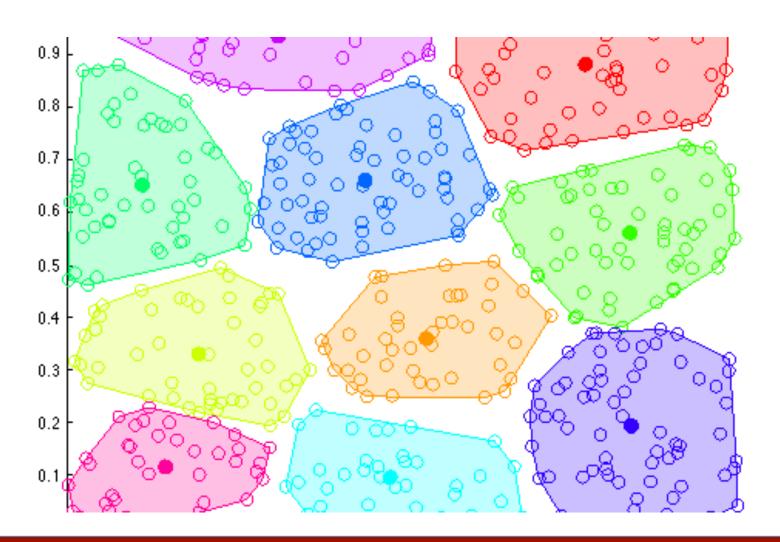
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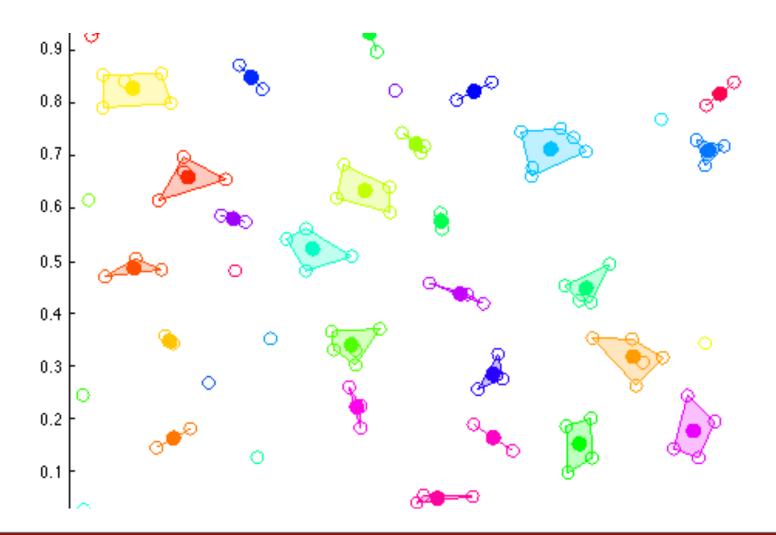
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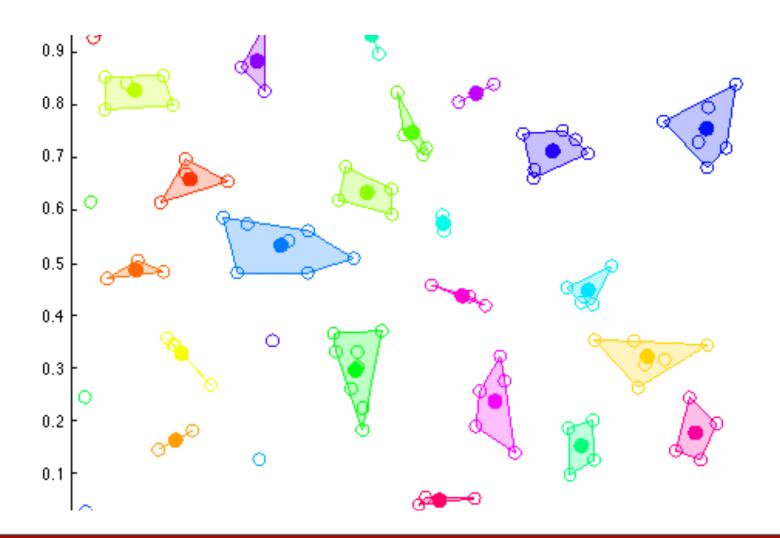
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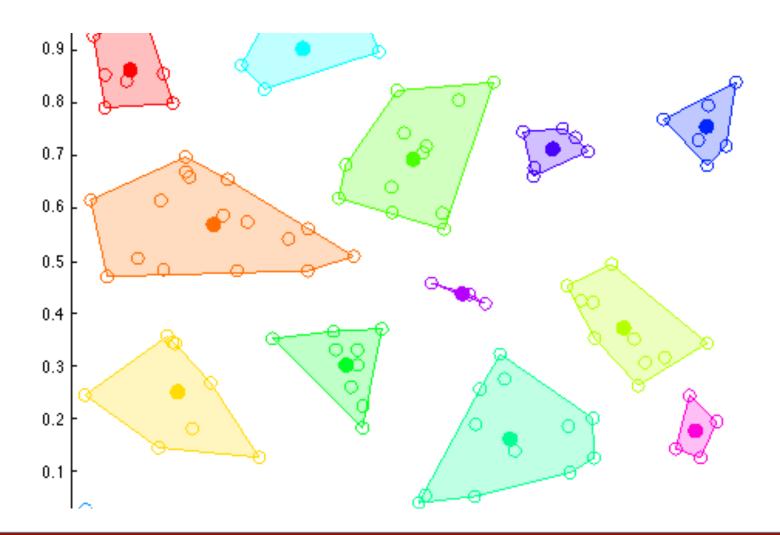
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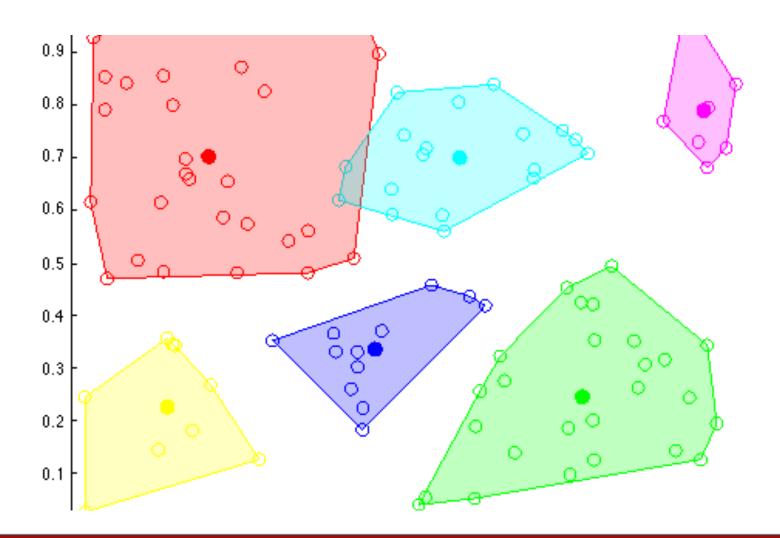
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Clustering: Efficiency Matters!

- For loops are SLOW in MATLAB; avoid them wherever possible!
- Useful MATLAB functions: min, mean, pdist2, ind2sub, randperm
- HAClustering.m:
 - Your code can be written with no for loops
 - For reference: clustering 5000 5D points on my laptop
 (3 year old MBP) takes about 90 seconds
- KMeansClustering.m
 - For reference: clustering 5000 5D points on my laptop takes < 1 second

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Prerequisite: Implement clustering algorithms

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Pixel Feature Vectors

You need to at least two types of features:

- Color features: (r, g, b)
 - Done for you
 - ComputeColorFeatures.m
- Color and position features: (r, g, b, x, y)
 - You need to implement this
 - ComputePositionColorFeatures.m

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Pixel Feature Vectors: Normalization

- Normalization is applied to feature vectors before clustering as a preprocessing step
- There are many types of normalization
- For this assignment we will normalize each feature to have zero mean and unit variance:

$$\mu_j = \frac{1}{n} \sum_{i=1}^n f_{ij}$$

$$\sigma_j^2 = \frac{1}{n-1} \sum_{i=1}^n (f_{ij} - \mu_j)^2$$

$$ilde{f}_{ij} = rac{f_{ij} - \mu_j}{\sigma_j}$$

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Pixel Feature Vectors: Extra Credit

Implement your own feature vectors and see how they perform

Some ideas:

- Gradients
- Edges
- SIFT descriptors

Use ComputeFeatures.mas a starting point

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Pixel Feature Vectors: Interface

```
function features = ComputeColorFeatures(img)
function features = ComputePositionColorFeatures(img)
img: h x w x 3 matrix of pixel data for image
features: h x w x d matrix of features for each pixel
```

Any custom feature vectors you write should have the same interface!

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Prerequisite: Implement clustering algorithms

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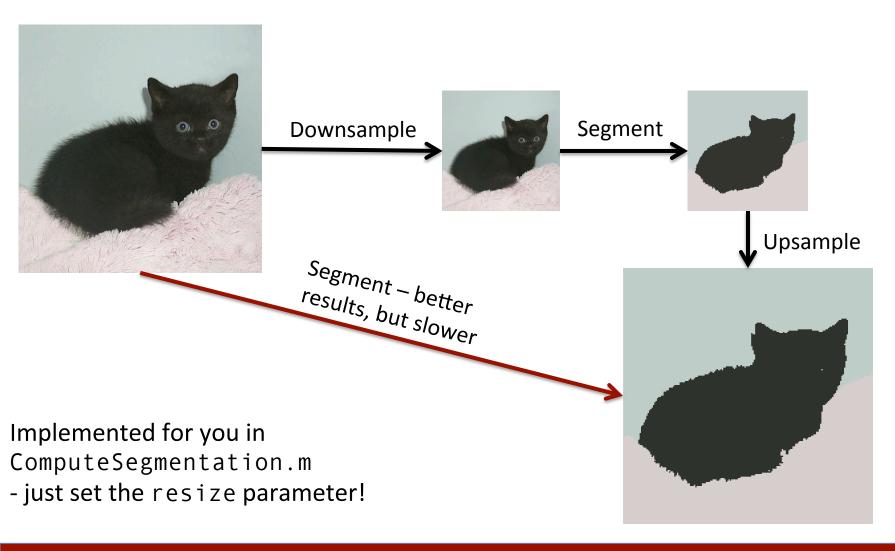
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Cluster Feature Vectors + Assign Pixels

- This is done for you in ComputeSegmentation.m and MakeSegments.m
- ComputeSegmentation.m has many tunable parameters – read the documentation in the file!
- The data structure used to store a segmentation is described in MakeSegments.m
- Use RunComputeSegmentation.m as a starting point for your custom feature vectors

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Resizing to Speed up Segmentation



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Prerequisite: Implement clustering algorithms Input: an image

- 1. Compute a feature vector for each pixel
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Choose Foreground Segments

- After segmenting an image, foreground object may be split across several segments
- Use ChooseSegments.m to pick a subset of segments as foreground











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Prerequisite: Implement clustering algorithms

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Transfer Foreground

 Just use ChooseSegments.m but pass in a background image







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Prerequisite: Implement clustering algorithms

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Compare with Ground Truth

- We provide a small dataset of 17 pictures of cats with correct segmentations
- The accuracy of a segmentation is the fraction of pixels that are correctly labeled as foreground / background
- EvaluateSegmentation.m computes the accuracy of a segmentation
- Use EvaluateAllSegmentations.m as a starting point to evaluate your method on all images in the dataset

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Compare with Ground Truth

Original image



Kmeans segmentatior (Accuracy = 0.8877)



Ground truth segmentation



HAC segmentation (Accuracy = 0.8784)



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What to do in writeup

- Answer all questions from the "In your Writeup" sections
- Focus on experimentation
 - Vary the segmentation parameters: feature transform, feature normalization, clustering algorithm, number of clusters, resize
 - How do your results change? (Qualitatively and quantitatively)

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