

# Xiaofeng Lin

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Availability: Feb–Dec 2026

## Education

### Boston University

*Ph.D. in Systems Engineering*

**Boston, MA**

*Aug 2023 – Dec 2027*

### University of Michigan, Ann Arbor

*M.S. in Robotics*

**Ann Arbor, MI**

*Aug 2021 – May 2023*

### Tianjin University

*B.Eng. in Engineering Mechanics*

**Tianjin, China**

*Sep 2016 – Jul 2020*

## Publications

**Xiaofeng Lin\***, Hejian Sang\*, Zhipeng Wang and Xuezhou Zhang. Debunk the myth of SFT Generalization. *Under Review*. [\[paper\]](#)[\[code\]](#)

**Xiaofeng Lin** and Xuezhou Zhang. Efficient Reinforcement Learning in Probabilistic Reward Machines. In *The Thirty-Ninth AAAI Conference on Artificial Intelligence (AAAI)*, 2025. **Oral Presentation**. [\[paper\]](#)[\[code\]](#)

Zian Ning, Yin Zhang, **Xiaofeng Lin** and Shiyu Zhao. A Real-to-Sim-to-Real Approach for Vision-Based Autonomous MAV-Catching-MAV. In *Unmanned Systems*, 2024. [\[paper\]](#)

Zirui Xu\*, **Xiaofeng Lin\*** and Vasileios Tzoumas. Leveraging Untrustworthy Commands for Multi-Robot Coordination in Unpredictable Environments: A Bandit Submodular Maximization Approach. In *American Control Conference (ACC)*, 2024. [\[paper\]](#)[\[code\]](#)

Zirui Xu, **Xiaofeng Lin** and Vasileios Tzoumas. Bandit Submodular Maximization for Multi-Robot Coordination in Unpredictable and Partially Observable Environments. In *Robotics: Science and Systems (RSS)*, 2023. [\[paper\]](#)[\[code\]](#)

## Research Experience

### Boston University

*Debunk the myth of SFT Generalization*

**Advisor: Prof. Xuezhou Zhang**

*May 2025 – Sept 2025*

- Identified frozen-prompt artifacts as a key cause of weak generalization in SFT.
- Showed that prompt diversity and chain-of-thought supervision enable SFT to generalize to unseen tasks and harder regimes.
- Demonstrated that enhanced SFT can match or surpass RL baselines while remaining simpler and more stable.

### Boston University

*Efficient Reinforcement Learning in Probabilistic Reward Machines*

**Advisor: Prof. Xuezhou Zhang**

*Jan 2024 – Aug 2024*

- Developed the first efficient algorithm for reinforcement learning with Probabilistic Reward Machines.
- Established new regret bounds that significantly improve over prior work on Deterministic Reward Machines.
- Introduced a novel simulation lemma for non-Markovian rewards.

## Honors & Awards

**BU Systems Engineering PhD Travel Award**

Feb 2025

**BU Distinguished Systems Engineering Fellowship**

Sept 2023

**Outstanding Graduate of Tianjin University (Top 10%)**

May 2020

**Merit Student of Tianjin University (Top 30%)**

Oct 2018 / May 2020

## Technical Skills

**Programming:** Python; C++; MATLAB; Java/Android; ROS; MAVLink

**Deep Learning and LLM-Training:** PyTorch; HuggingFace Ecosystem; Verl; TRL; SFT; DPO