XIAORUI HUANG

Availability: From May 2024
Preferred Name: Richard

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ML Research Intern embARC Research Group

RESEARCH

i Jan 2024 - Now

University of Toronto

- Research on 3D Gaussian Splatting with real-time SLAM systems on data captured from embedde devices.
- · Supervised by Prof. Nandita Vijaykumar

 $\begin{tabular}{ll} \hline (3D \ Gaussian \ Splatting) & \hline (SLAM) & Pytorch) & \hline (C/C++) & \hline (CUDA) \\ \hline \end{tabular}$

eAl Machine Learning Engineer

Qualcomm

★ May 2023 — Aug 2023

EXPERIENCE

Markham, ON

- Led efforts on Neural Architecture Search (NAS) and model compression within the Edge AI R&D team.
- Developed a NAS framework, leveraging Qualcomm's patented NAS techniques, to optimize arbitrary models¹ for any profiled hardware, harnessing Pytorch's torch.fx extensively.
- Streamlined the NAS workflow for incoming client models, slashing **engineering time** by **80%**.
- Achieved a 50% reduction in model size and a 60% drop in inference latency without compromising accuracy across benchmark models².
- Engaged in lab meetings focused on cutting-edge model compression research, particularly **Quantization**.
- Delivered a comprehensive presentation on the NAS framework to the broader eAI team.

 $\begin{array}{c|c} \hline {\sf NAS} & \hline {\sf Quantization} & \hline {\sf Pytorch} & \hline {\sf (torch.fx)} & \hline {\sf ONNX} & \hline {\sf R\&D} \\ \hline \end{array}$

RPA Backend Developer IBM

May 2022 — Apr 2023

Markham, ON

- Worked on backend development for IBM's Robotics Process Automation (RPA) platform.
- Augmented IBM RPA's WAL programming language, introducing a reflection feature resembling Java and **C#**.
- Collaborated with cross-functional teams, achieving a 15% reduction in customer issues and defects per release.
- Employed agile methodologies, showed both independent and collaborative competencies in a hybrid environment.
- Articulated and presented solution strategies to RPA's senior architects and product teams.

C# Pragramming Language Design Agile Visual Studio

Linearly Explored Learning Rate Scheduler

- We introduced the LES method to automate and refine the resource-intensive task of learning rate tuning.
- LES achieves a final error rate of 8% on par with other commonly used optimizer and schedulers on pycls code base without the need for learning rate tuning.
- Developed a custom SGD with momentum algorithm to facilitate exploration of various backpropagation strategies during LES creation.

PROJECTS

CUDA Ray Tracing

Almost Real Time Ray Tracing

- Implemented a **CUDA** ray tracer with **BVH** acceleration structure, with **Blinn-Phong** shading.
- Achieved real-time ray-tracing of 30 FPS and 2000x Speedup on RTX3060-Ti from CPU.
- Incorporated dynamically loaded Scene generation to allow for future interactivity.

CUDA C/C++ CMake

Woodoku Learn

Reinforcement Learning Model

- Replicated the mobile game Woodoku for the terminal using Python, enabling both human and AI gameplay through dedicated environment APIs.
- Employed Q-Learning, a Reinforcement Learning approach with Pytorch, targeting top scores on the Woodoku leaderboard.

Pytorch OOP Agile

EDUCATION

University of Toronto 🏛

Candidate for B.Sc. in Computer Science

■ 2019 – Expected June 2024

Relevant Courses

- CSC367 Parallel Computing (In Progress) Parallel Arch & Algo, threading & OpenMP, Distributed Computing w/ MPI, CUDA Arch & Reduction Algo, Cloud Computing
- CSC413 Deep Learning (96%) Transformers, CNN, RNN, GAN, VAE, GNN, RL. original research on optimization strategy as final course project. RolandGao/pycls

Probabilistic Learning (CV) (NLP) (Computer Security)

¹NAS support is required for NN layers E.g. nn.Conv2d is supported

²Results vary; models include MobileNetV2, ResNet50, BERT

SKILLS

Programming Languages



Other Frameworks & Development Environments

Idiomatic in English and in Mandarin Chinese