# XIAORUI HUANG

## 

Availability: From May 2024
Preferred Name: Richard

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# ▼ Toronto, Canada♀ Xiaorui-Huang

### EXPERIENCE

# eAl Machine Learning Engineer Qualcomm

★ May 2023 — Aug 2023

Markham, ON

- Led efforts on **Neural Architecture Search (NAS)** and model compression within the **Edge AI R&D** team.
- Developed a NAS framework, leveraging Qualcomm's patented NAS techniques, to optimize arbitrary models<sup>1</sup> for any profiled hardware, harnessing Pytorch's torch.fx extensively.
- Streamlined the NAS workflow for incoming client models, slashing **engineering time** by **80%**.
- Achieved a 50% reduction in model size and a 60% drop in inference latency without compromising accuracy across benchmark models<sup>2</sup>.
- Engaged in lab meetings focused on cutting-edge model compression research, particularly **Quantization**.
- Delivered a comprehensive presentation on the NAS framework to the broader eAI team.

 $\begin{tabular}{lll} NAS & Quantization & torch.fx & Pytorch & ONNX & R&D \\ \end{tabular}$ 

# RPA Backend Developer IBM

**★** May 2022 − Apr 2023

Markham, ON

- Worked on backend development for IBM's Robotics Process Automation (RPA) platform.
- Augmented IBM RPA's WAL programming language, introducing a reflection feature resembling Java and **C#**.
- Collaborated with cross-functional teams, achieving a **15%** reduction in customer issues and defects per release.
- Employed **agile methodologies**, showed both independent and collaborative competencies in a hybrid environment.
- Articulated and presented solution strategies to RPA's senior architects and product teams.

C# (Pragramming Language Design) (Agile) (Visual Studio)

## **EDUCATION**

# University of Toronto 🏛

Candidate for B.Sc. in Computer Science

**ii** 2019 − Now (Exp 2024) **•** Toro

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#### **Relevant Courses**

- CSC317 Computer Graphics (97%) Ray Tracing, Mass Spring Systems, Bounding Volume Hierarchy, Meshes, Kinematics, OpenGL Shaders in C++ using Eigen and libigl
- CSC413 Deep Learning (96%) Transformers, CNN, RNN, GAN, VAE, GNN, RL. original research on optimization strategy as final course project. RolandGao/pycls

C++ Pytorch Linear Algebra Algorithms Stats & Probablity

### RESEARCH

# ML Research Intern embARC Research Group

**i** Jan 2024 - Now

- University of Toronto
- Research on 3D Gaussian Splatting with real-time SLAM systems on data captured from embedde devices.
- · Supervised by Prof. Nandita Vijaykumar

3D Gaussian Splatting SLAM Pytorch C/C++ CUDA

# Linearly Explored Learning Rate Scheduler (LES)

- We introduced the LES method to automate and refine the resource-intensive task of learning rate tuning.
- LES achieves a final error rate of 8% on par with other commonly used optimizer and schedulers on pycls code base without the need for learning rate tuning.
- Developed a custom SGD with momentum algorithm to facilitate exploration of various backpropagation strategies during LES creation.

### **PROJECTS**

### **CUDA** Ray Tracing

### **Almost Real Time Ray Tracing**

- Implemented a CUDA ray tracer with BVH acceleration structure, with Blinn-Phong shading.
- Achieved real-time ray-tracing of 1000+ triangles with 30 FPS
- Incorporated dynamically loaded Scene generation to allow for future interactivity.

CUDA C/C++ CMake

#### Woodoku Learn

#### **Reinforcement Learning Model**

- Jul 2022 C EdwardHaoranLee/WoodokuLearn
- Replicated the mobile game Woodoku for the terminal using Python, enabling both human and AI gameplay through dedicated environment APIs.
- Employed Q-Learning, a Reinforcement Learning approach with Pytorch, targeting top scores on the Woodoku leaderboard.

Pytorch OOP Agile

### SKILLS

#### **Programming Languages**



### Other Frameworks & Development Environments

Pytorch (torch.fx) Docker & WSL (git) (Vim) (VSCode

Idiomatic in English and in Mandarin Chinese

<sup>&</sup>lt;sup>1</sup>NAS support is required for NN layers E.g. nn.Conv2d is supported

<sup>&</sup>lt;sup>2</sup>Results vary; models include MobileNetV2, ResNet50, BERT