## XIAORUI HUANG

### Always Fascinated

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- ▼ Toronto, Canada
- Xiaorui-Huang

## **EXPERIENCE**

# Low Power Al Machine Learning Engineer Qualcomm

- **★** May 2023 − Aug 2023
- Markham, Canada
- Led efforts on **Neural Architecture Search (NAS)** and model compression within the Edge AI R&D team.
- Developed a NAS framework, leveraging Qualcomm's patented NAS techniques, optimizes a given models on a pre-profiled hardware, built with Pytorch's torch.fx
- Achieved 50% reduction in model size and 60% drop in inference latency without compromising accuracy across benchmark models, while reducing engineering time compared to manually applied NAS.
- Engaged in team-wide discussions on next-generation eNPU software stack, focusing on quantization and attention mechanisms.

NAS	Quantization	Pytorch	torch.fx	Model Compression

## RPA Backend Developer

- **May 2022** Apr 2023
- Markham, Canada
- Worked on backend development for IBM's Robotics Process Automation (RPA) platform, written in C# OOP.
- Augmented IBM RPA's WAL programming language, introducing a reflection feature resembling Java and C#.
- Collaborated with cross-functional teams, achieving a 15% reduction in customer issues and defects per release.
- Employed **agile methodologies**, showed both independent and collaborative competencies in a hybrid environment.
- Presented solution strategies to RPA's senior architects and product teams.



## **EDUCATION**

## University of Toronto <u>m</u>

### Honors BSc. in Computer Science

- **Sep 2019 Jun 2024**
- CSC367 Parallel Computing (83%) CUDA Arch & Reduction Algo, Parallel Arch & Algo, threading & OpenMP,
  Distributed Computing w/ MPI, Cloud Computing
- CSC317 Computer Graphics (97%) Ray Tracing, Mass Spring Systems, BVH, Meshes, Kinematics, OpenGL Shaders in C++ using Eigen and libigl
- ECE568 Computer Security (83%) Buffer Overflow & Control Hijacking, Cache Side-Channel Attacks, Network Security, Cryptography, Web Security (C) (x86)
- CSC413 Deep Learning (96%) Transformers, CNN, RNN, GAN, VAE, RL, GNN, Model Tuning techniques

CSC369 OS CSC401 NLP CSC420 CV CSC412 Probabilistic ML

### RESEARCH

## Distributed Online 3D Reconstruction embARC Research Group

- **i** Jan 2024 July 2024
- University of Toronto
- DISORF a real-time Gaussian Splatting & NeRF framework for online 3D reconstruction and visualization of scenes captured by resource-constrained mobile robots and edge devices.
- Proposed a novel shifted exponential frame sampling method to address the degradation in rendering quality caused by naive image sampling during online training
- Integrates novel techniques such as adaptive initalization to overcome challenges in real-time incremental learning.
- Paper is under review for RA-L and availble on arXiv and
  Xiaorui-Huang/DISORF

(3D Gaussian Splatting)	SLAM	(NeRF)	Pytorch
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## **PROJECTS**

### **CUDA Ray Tracing**

- Nov 2023 A Xiaorui-Huang/cuda-ray-tracing
- Implemented a CUDA ray tracer with BVH acceleration structure, with Blinn-Phong shading.
- Achieved real-time ray-tracing of 30 FPS and 2000x Speedup on RTX3060-Ti compared to CPU.
- Designed framework for scene construction, allowing for rendering of new scenes via config and existing assets.



#### Woodoku Learn

- Jul 2022 EdwardHaoranLee/WoodokuLearn
- Replicated the mobile game Woodoku for the terminal using Python, enabling both human and AI gameplay through dedicated environment APIs.
- Employed Q-Learning, a Reinforcement Learning approach with Pytorch, targeting top scores on the Woodoku leaderboard

RL	Pytorch OOP Agile (	CMake

### Doodle Jumps in MIPS Assembly

- 苗 Dec 2021 🞧 Xiaorui-Huang/doodle-jump
- Created a Minecraft-themed version of the Doodle Jump game using MIPS Assembly.
- Implemented game logic for player movement, collision detection, and scoring, key controls & graphic design.

MIPS Assembly	Game Development	Emulation
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### SKILLS

#### **Programming Languages**



#### Skills, Frameworks & Development Environments

