# XIAORUI HUANG

## 

Preferred Name: Richard

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# **EXPERIENCE**

# eAl Machine Learning Engineer Qualcomm

**★** May 2023 − Aug 2023

Markham, ON

- Led efforts on Neural Architecture Search (NAS) and model compression within the Edge AI R&D team.
- Developed a NAS framework, leveraging Qualcomm's patented NAS techniques, to optimize arbitrary models for any profiled hardware, harnessing Pytorch's torch.fx extensively.
- Streamlined the NAS workflow for incoming client models, slashing engineering time by 80%.
- Achieved a 50% reduction in model size and a 60% drop in inference latency without compromising accuracy across benchmark models.
- Engaged in lab meetings focused on cutting-edge model compression research, particularly **Quantization**.
- Delivered a comprehensive presentation on the NAS framework to the broader eAI team.

 (NAS)
 (Quantization)
 (Pytorch)
 (torch.fx)
 (ONNX)

# RPA Backend Developer IBM

Markham, ON

- Worked on backend development for IBM's Robotics Process Automation (RPA) platform.
- Augmented IBM RPA's WAL programming language, introducing a reflection feature resembling Java and C#.
- Collaborated with cross-functional teams, achieving a **15**% reduction in customer issues and defects per release.
- Employed **agile methodologies**, showed both independent and collaborative competencies in a hybrid environment.
- Articulated and presented solution strategies to RPA's senior architects and product teams.

C# Pragramming Language Design Agile Visual Studio

## **EDUCATION**

# University of Toronto 🏛

#### Candidate for HBSc. in Computer Science

**=** 2019 − Expected June 2024

- CSC317 Computer Graphics (97%) Ray Tracing, Mass Spring Systems, BVH, Meshes, Kinematics, OpenGL Shaders in C++ using Eigen and libig!
- CSC367 Parallel Computing (In Progress) Parallel Arch & Algo, threading & OpenMP, Distributed Computing w/ MPI, CUDA Arch & Reduction Algo, Cloud Computing
- CSC420 Computer Vision (85%) Convolution, Feature Extraction (SIFT), Optical Flow, Feature Matching (RANSAC), Camera, Stereo, Homography, Object Detection
- CSC413 Deep Learning (96%) Transformers, CNN, RNN, GAN, VAE, GNN, RL, Model Tuning techniques

NLP Probabilistic ML Parallel Computing Computer Security

## RESEARCH

# ML Research Intern embARC Research Group

- **i** Jan 2024 Now
- University of Toronto
- Research on 3D Gaussian Splatting & NeRF with real-time SLAM systems on data captured on embedde devices.
- Provides incremental Point Cloud initialization and dataset sampling techniques to improve real time reconstruction performance.
- Supervised by Prof. Nandita Vijaykumar

3D Gaussian Splatting SLAM NeRF Pytorch CUDA

### Linearly Explored Learning Rate Scheduler

- We introduced the LES method to automate and refine the resource-intensive task of learning rate tuning.
- LES achieves a final error rate of 8% on par with other commonly used optimizer and schedulers on pycls code base without the need for learning rate tuning.
- Developed a custom SGD with momentum algorithm to facilitate exploration of various backpropagation strategies during LES creation.

## **PROJECTS**

### **CUDA** Ray Tracing

### **Almost Real Time Ray Tracing**

- Implemented a CUDA ray tracer with BVH acceleration structure, with Blinn-Phong shading.
- Achieved real-time ray-tracing of 30 FPS and 2000x Speedup on RTX3060-Ti from CPU.
- Incorporated dynamically loaded Scene generation to allow for future interactivity.

CUDA C/C++ CMake

#### Woodoku Learn

### Reinforcement Learning Model

- 苗 Jul 2022 😯 EdwardHaoranLee/WoodokuLearn
- Replicated the mobile game Woodoku for the terminal using Python, enabling both human and Al gameplay through dedicated environment APIs.
- Employed Q-Learning, a Reinforcement Learning approach with Pytorch, targeting top scores on the Woodoku leaderboard.

RL Pytorch OOP Agile

## **SKILLS**

#### **Programming Languages**

 ♣ Python
 C/C++
 CUDA
 C#
 ❸ Rust
 ⑤ Java

 上下X
 R
 TypeScript
 HTML&CSS
 SQL

#### Skills, Frameworks & Development Environments

